Equations of Motion from the Action

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From my previous notes, I had calculated the Variations on the total action:

$$\delta_{V}S_{tot} = \frac{M_{Pl}^{2}}{2} \int R^{cd} \wedge V^{b} \epsilon_{abcd} \wedge \delta V^{a}$$

$$+ \frac{1}{2} \int (\partial^{a} \vartheta d\vartheta \wedge (V_{a} \wedge V_{b}) \wedge \delta V^{b} + \partial_{b} \vartheta d\vartheta \wedge \delta V^{b})$$

$$- 2nf \int d\vartheta \wedge dV_{a} \wedge \delta V^{a} + d\vartheta \wedge \omega_{bc} \wedge V^{b} \wedge \delta V^{c}$$

$$(1)$$

$$\delta_{\omega} S_{tot} = \frac{M_{Pl}^2}{2} \int \epsilon_{abcd} V^a \wedge V^b \wedge \omega^{fd} \wedge \delta \omega_f^c + \frac{nf}{2} \int d\vartheta \wedge V_a \wedge V_c \wedge \delta \omega^{ac} \quad (2)$$

$$\delta_{\vartheta} S_{tot} = -\int \delta \vartheta \, \mathrm{d}^{\star} \mathrm{d}\vartheta + nf \int \mathrm{d}(T^a \wedge V_a) \wedge \delta \vartheta$$
(3)

1 Vielbein

$$\int \frac{M_{Pl}^2}{2} R^{cd} \wedge V^b \epsilon_{abcd} \wedge \delta V^a + \frac{1}{2} (\partial^a \vartheta d\vartheta \wedge {}^{\star} (V_a \wedge V_b) \wedge \delta V^b + \partial_b \vartheta^{\star} d\vartheta \wedge \delta V^b)$$
$$-2nf(d\vartheta \wedge dV_a \wedge \delta V^a + d\vartheta \wedge \omega_{bc} \wedge V^b \wedge \delta V^c) = 0$$

Relabeling indices:

$$\int \frac{M_{Pl}^2}{2} R^{cd} \wedge V^b \epsilon_{abcd} \wedge \delta V^a + \frac{1}{2} (\partial^b \vartheta d\vartheta \wedge {}^*(V_b \wedge V_a) \wedge \delta V^a + \partial_a \vartheta^* d\vartheta \wedge \delta V^a)$$

$$-2nf (d\vartheta \wedge dV_a \wedge \delta V^a + d\vartheta \wedge \omega_{ba} \wedge V^b \wedge \delta V^a) = 0$$

$$\int \frac{M_{Pl}^2}{2} R^{cd} \wedge V^b \epsilon_{abcd} \wedge \delta V^a + \frac{1}{2} (\partial^b \vartheta d\vartheta \wedge {}^*(V_b \wedge V_a) + \partial_a \vartheta^* d\vartheta) \wedge \delta V^a$$

$$-2nf (d\vartheta \wedge dV_a + d\vartheta \wedge \omega_{ba} \wedge V^b) \wedge \delta V^a = 0$$

$$\int (\frac{M_{Pl}^2}{2} R^{cd} \wedge V^b \epsilon_{abcd} + \frac{1}{2} (\partial^b \vartheta d\vartheta \wedge {}^*(V_b \wedge V_a) + \partial_a \vartheta^* d\vartheta)$$

$$-2nf (d\vartheta \wedge dV_a + d\vartheta \wedge \omega_{ba} \wedge V^b) \wedge \delta V^a = 0$$

Since δV^a is arbitrary:

$$\frac{M_{Pl}^2}{2} R^{cd} \wedge V^b \epsilon_{abcd} + \frac{1}{2} (\partial^b \vartheta d\vartheta \wedge {}^*(V_b \wedge V_a) + \partial_a \vartheta^* d\vartheta)
-2nf(d\vartheta \wedge dV_a + d\vartheta \wedge \omega_{ba} \wedge V^b) = 0$$
(4)

so, the Equation of Motion:

$$\frac{M_{Pl}^2}{2} R^{cd} \wedge V^b \epsilon_{abcd} - 2nf (d\vartheta \wedge dV_a + d\vartheta \wedge \omega_{ba} \wedge V^b)
= -\frac{1}{2} (\partial^b \vartheta d\vartheta \wedge {}^*(V_b \wedge V_a) + \partial_a \vartheta^* d\vartheta)$$
(5)

2 Spin Connection

$$\int \frac{M_{Pl}^2}{2} \epsilon_{abcd} V^a \wedge V^b \wedge \omega^{fd} \wedge \delta \omega_f^c + \int \frac{nf}{2} d\vartheta \wedge V_a \wedge V_c \wedge \delta \omega^{ac} = 0$$
$$\int \frac{M_{Pl}^2}{2} \epsilon_{abcd} V^a \wedge V^b \wedge \omega_f^d \wedge \delta \omega^{fc} + \int \frac{nf}{2} d\vartheta \wedge V_a \wedge V_c \wedge \delta \omega^{ac} = 0$$

Relabeling indices:

$$\int \frac{M_{Pl}^2}{2} \epsilon_{abcd} V^a \wedge V^b \wedge \omega_f^d \wedge \delta \omega^{fc} + \int \frac{nf}{2} d\vartheta \wedge V_f \wedge V_c \wedge \delta \omega^{fc} = 0$$
$$\int \left(\frac{M_{Pl}^2}{2} \epsilon_{abcd} V^a \wedge V^b \wedge \omega_f^d + \frac{nf}{2} d\vartheta \wedge V_f \wedge V_c \right) \wedge \delta \omega^{fc} = 0$$

So,

$$\frac{M_{Pl}^2}{2} \epsilon_{abcd} V^a \wedge V^b \wedge \omega_f^d + \frac{nf}{2} \, d\vartheta \wedge V_f \wedge V_c = 0$$

3 Scalar Field

$$-\int \delta \vartheta \, \mathrm{d}^* \mathrm{d}\vartheta + nf \int \mathrm{d}(T^a \wedge V_a) \wedge \delta \vartheta = 0$$

Simplifying:

$$\int \delta \vartheta \left(-d^* d\vartheta + nf d(T^a \wedge V_a) \right) = 0$$

This implies:

$$-d^*d\vartheta + nf d(T^a \wedge V_a) = 0$$
$$nf d(T^a \wedge V_a) = d^*d\vartheta$$

Writing this in terms of the D'Alembert operator, which can be written as $\Box \vartheta = \delta \vartheta = {}^{\star} d^{\star} d\vartheta$ since ϑ is a 0-form. Therefore: $d^{\star} d\vartheta = \Box \vartheta^{\star} 1$. The equation above is written as:

$$\Box \vartheta = {}^{\star} (\mathrm{d}(T^a \wedge V_a)) n f$$

$$\frac{1}{\sqrt{|g|}} \partial_{\mu} \left(\sqrt{|g|} g^{\mu\nu} \partial_{\nu} \vartheta \right) = n f \frac{1}{4! \sqrt{|g|}} \epsilon^{\mu\nu\rho\sigma} \left(\mathrm{d}(T^a \wedge V_a) \right)_{\mu\nu\rho\sigma}$$

$$\partial_{\mu} \left(\sqrt{|g|} g^{\mu\nu} \partial_{\nu} \vartheta \right) = \frac{n f}{4!} \epsilon^{\mu\nu\rho\sigma} \left(\mathrm{d}(T^a \wedge V_a) \right)_{\mu\nu\rho\sigma}$$