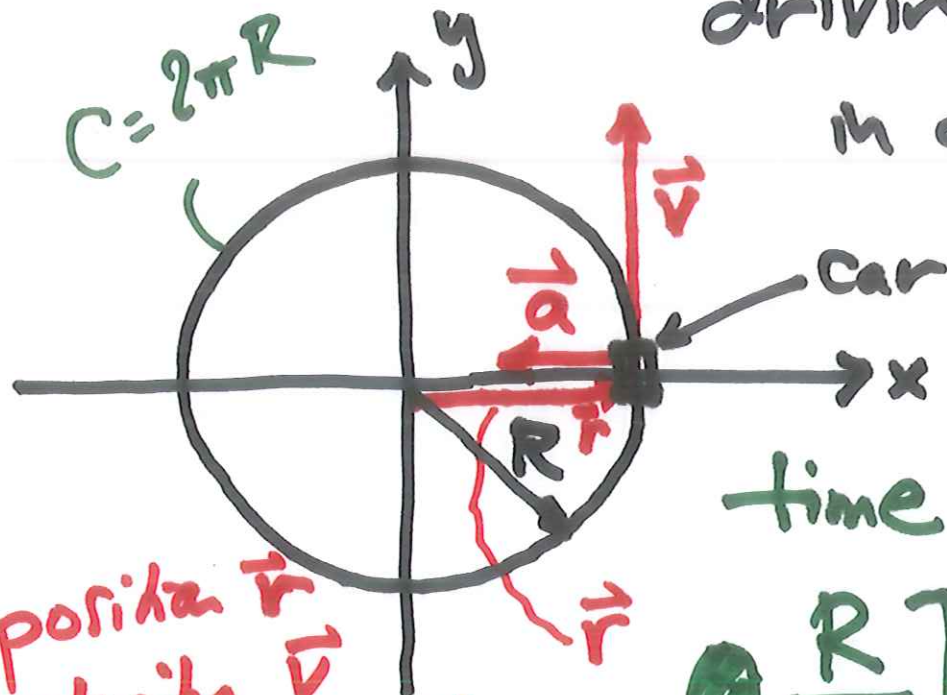


NYU Physics I — 2016-09-15.

Agenda — Exams — postponed  
— scope

- Qs.
- Circular motion.
- Forces acting on a car.
- (Gaia)

driving @ constant speed  $v$   
in a circle of radius  $R$ .



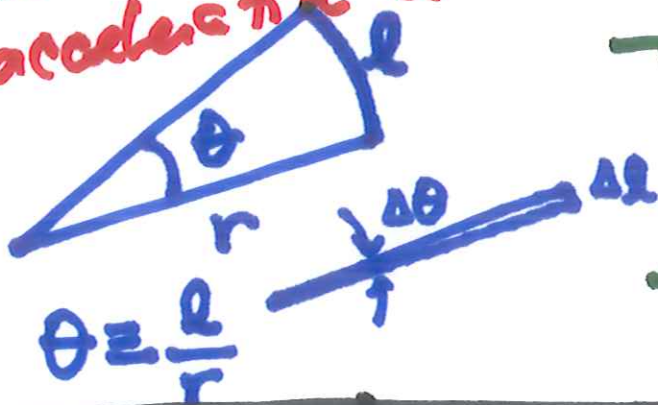
$$v \equiv |\vec{v}|$$

time?

acceleration?

$$\left[ \frac{R}{v} \right]$$

position  $\vec{r}$   
velocity  $\vec{v}$   
acceleration  $\vec{a}$



$$\left[ \frac{2\pi R}{v} \right] \text{ period}$$

$$\frac{7! R}{v}$$

$$\frac{v^2}{R}$$

$$\frac{v}{T}$$

$$T = \frac{R}{v} \rightarrow \frac{v^2}{R}$$

$$\frac{R}{T^2}$$

$$T = \frac{R}{v} \rightarrow \frac{v^2}{R}$$

$\frac{d\vec{r}}{dt} = \vec{v}$	$\frac{d\vec{v}}{dt} = \vec{a}$
---------------------------------	---------------------------------



$$\vec{\Delta r} = \vec{r}_{t+\Delta t} - \vec{r}_t$$

$$\vec{\Delta r} = \vec{v} \Delta t \leftarrow \textcircled{1}$$

$$\vec{v} \equiv \lim_{\Delta t \rightarrow 0} \frac{[\vec{r}_{t+\Delta t} - \vec{r}_t]}{\Delta t}$$

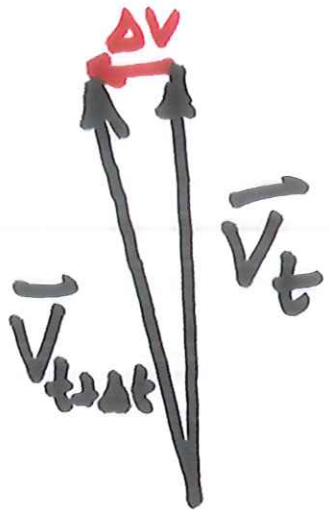
$$\textcircled{1} \vec{v} \equiv \lim_{\Delta t \rightarrow 0} \frac{\vec{\Delta r}}{\Delta t}$$

$$|\vec{\Delta r}| = |\vec{r}| \cdot \Delta \theta$$

$$\Delta \theta = \frac{2\pi}{T} \Delta t$$

$$\Delta \theta = \frac{v}{R} \Delta t$$

angular frequency..  
radians  
second  $\equiv \omega$



$$\Delta \vec{v} = \vec{a} \Delta t$$

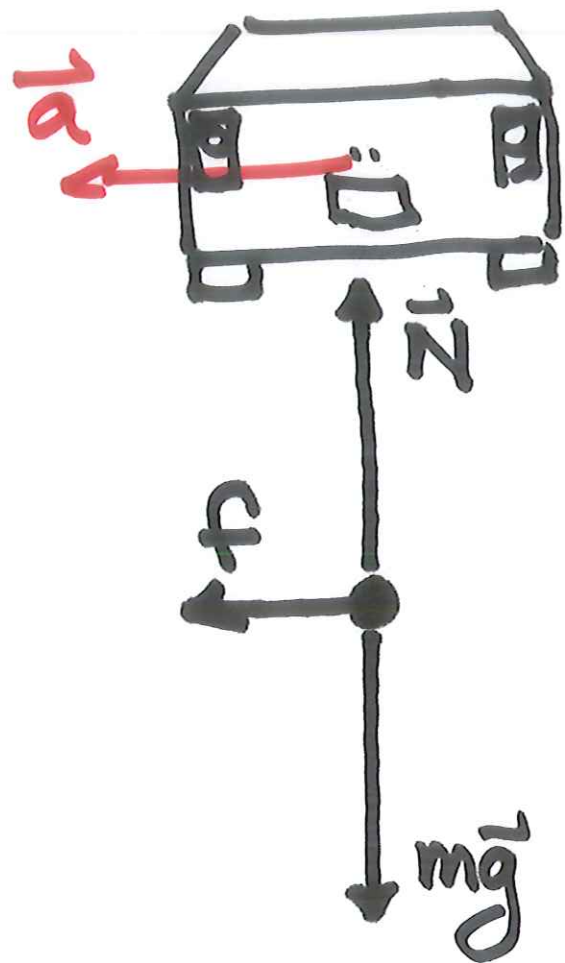
$$\Delta \theta = \frac{v}{R} \Delta t$$

$$|\Delta \vec{v}| = |\vec{v}| \Delta \theta = \underbrace{|\vec{v}| \frac{v}{R}}_{\frac{v^2}{R}} \Delta t$$

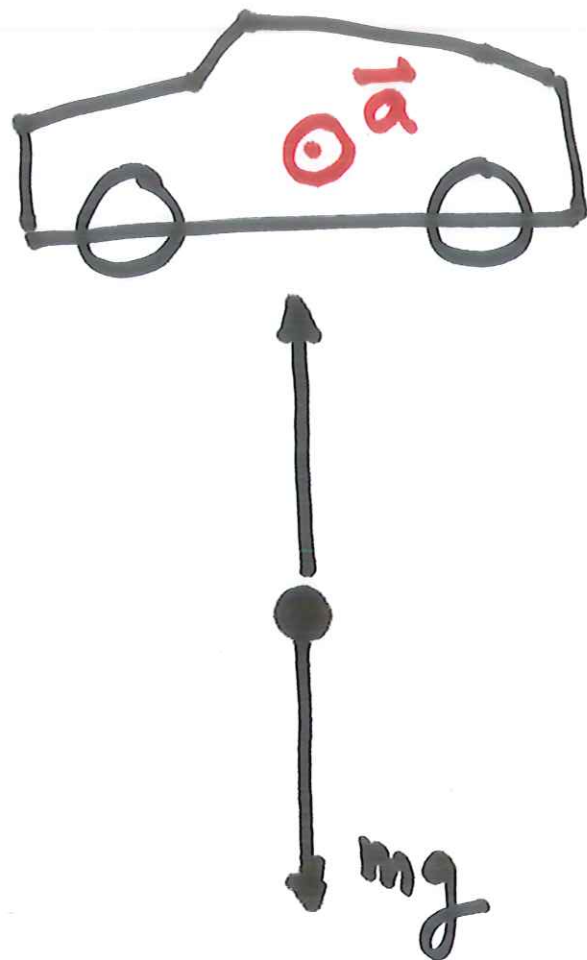
$$|\vec{a}| = \left| \frac{\Delta \vec{v}}{\Delta t} \right| = \frac{v^2}{R}$$

$$\begin{cases} x(t) = R \cos\left(\frac{2\pi t}{T}\right) \\ y(t) = R \sin\left(\frac{2\pi t}{T}\right) \end{cases}$$

$$\begin{cases} v_x(t) = -\frac{2\pi R}{T} \sin\left(\frac{2\pi t}{T}\right) \\ v_y(t) = \frac{2\pi R}{T} \cos\left(\frac{2\pi t}{T}\right) \end{cases}$$



$$F_{net} = ma$$



⊙ out  
 ⊗ in

