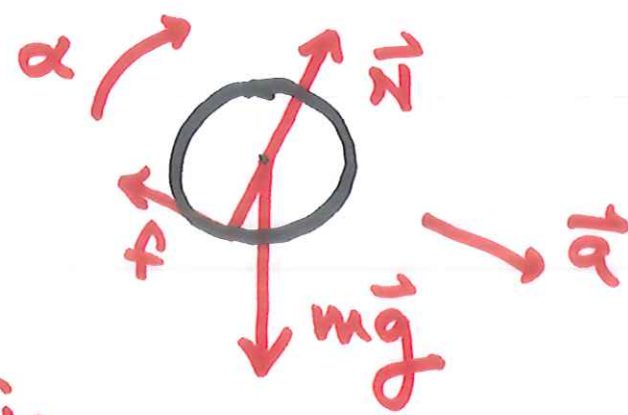
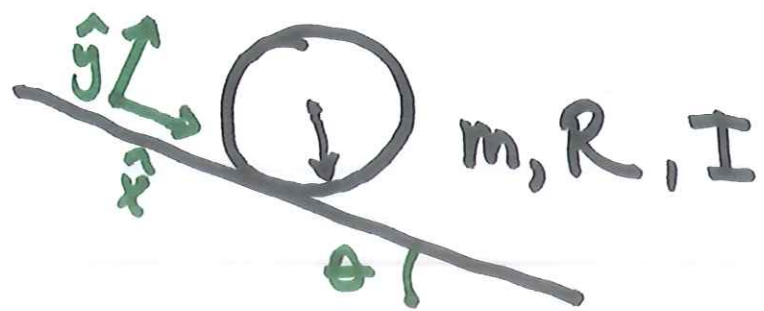


NYU Physics I — 2016-11-10

Agenda — Reading —

— finish rolling.

— collisions of extended objects.



① $\hat{y}: |\vec{N}| - m|\vec{g}|\cos\theta = 0$ ← kinematic beliefs!

② $\hat{x}: m|\vec{g}|\sin\theta - f = m|\vec{a}|$ ←

③ angular: $fR = I\alpha$

④ rolling without slipping: $|\vec{a}| = \alpha R$

③: $f = \frac{I\alpha}{R}$ ④: $f = \frac{I|\vec{a}|}{R^2}$

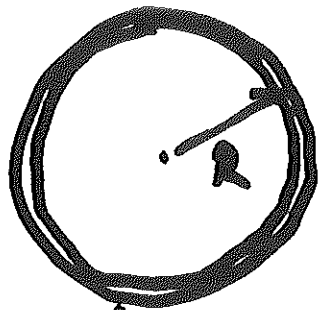
②: $mg\sin\theta - \frac{Ia}{R^2} = ma$

$mg\sin\theta = m\left[a + \frac{Ia}{mR^2}\right] = ma\left[1 + \frac{I}{mR^2}\right]$

Answer:

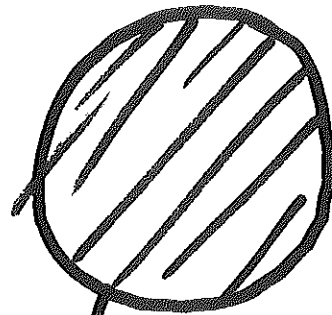
$$a = \frac{g\sin\theta}{\left[1 + \frac{I}{mR^2}\right]}$$

Moments of inertia:



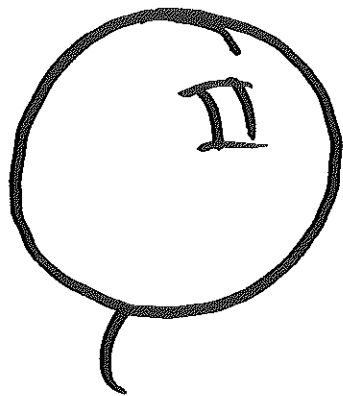
thin
hoop
 $I = mR^2$

~ empty can



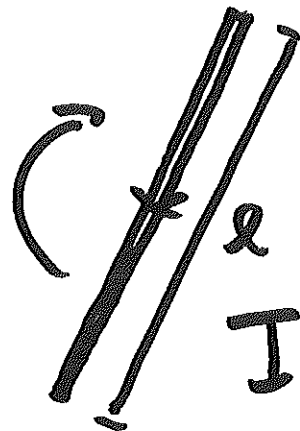
solid
disk
 $I = \frac{1}{2} mR^2$

~ Snickers (tm) Jar .

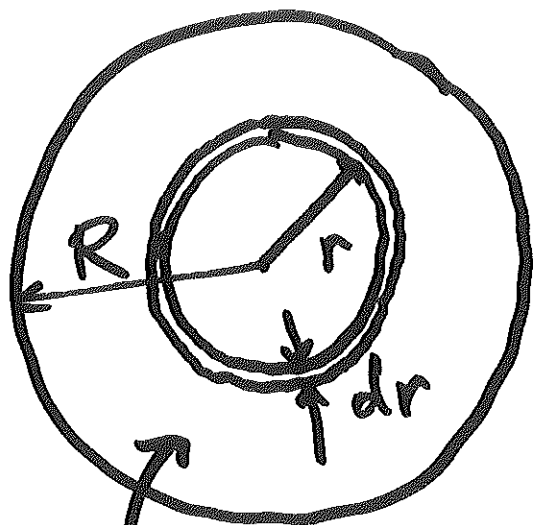


Solid
Sphere
 $I = \frac{2}{5} mR^2$?

~ cue ball



thin
rod
 $I = \frac{1}{12} ml^2$



area πR^2
mass M

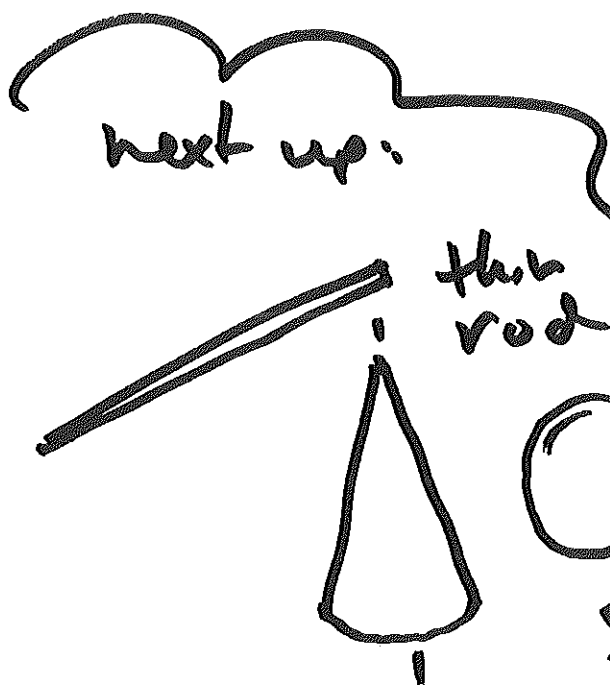
Solid, uniform cylinder (deth)

$$dA = \frac{2\pi R^2}{dr} \cdot \frac{dr}{2\pi r} = 2\pi r dr$$

$$dm = M \cdot \frac{2\pi r}{\pi R^2} dr$$

$$dI = dm r^2 = M \cdot \frac{2\pi r^3}{\pi R^2} dr$$

$$I = \int dI = \int_0^R M \cdot \frac{2r^3}{R^2} dr$$



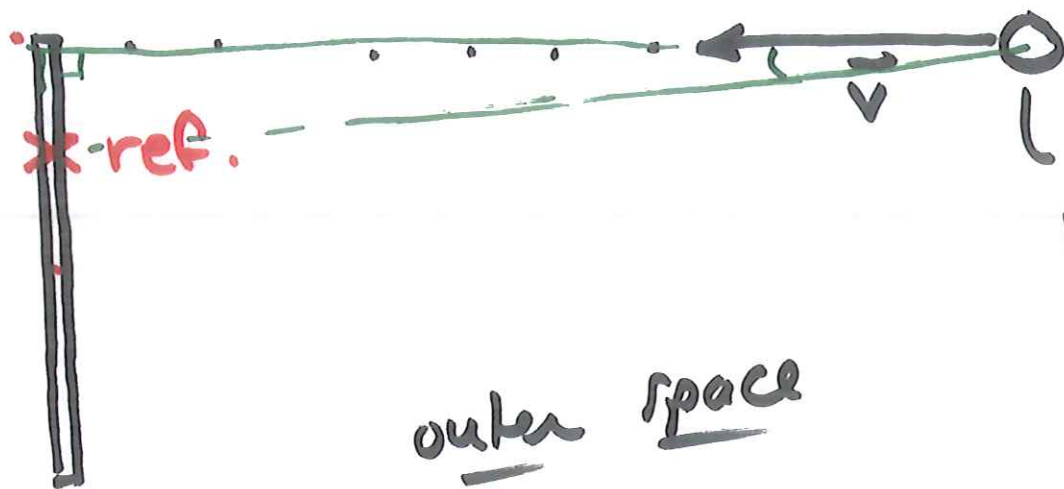
thin rod

spherical shell

solid sphere

$$= \frac{2M}{R^2} \left[\frac{r^4}{4} \right]_0^R = \frac{1}{2} MR^2$$

rectangular parallel piped



blob of
putty of
mass $M = m$
compact.

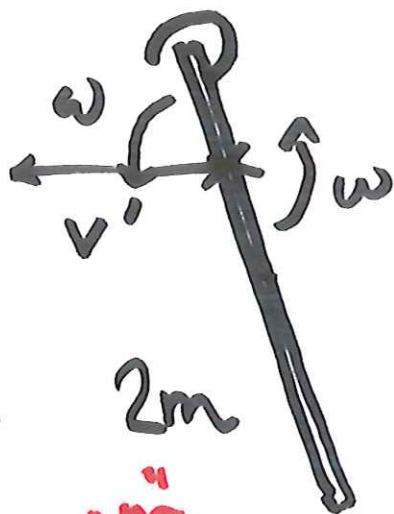
outer space

rod of
length l ,
mass m

before
after

$$I = \underbrace{\frac{1}{12} m l^2}_{\text{rod}} + \underbrace{m \left(\frac{l}{4}\right)^2}_{\text{shift}} + \underbrace{m \left(\frac{l}{4}\right)^2}_{\text{putty}}$$

read:
"parallel
axis
theorem"



Before:

$$\vec{p} = m\vec{v} + 0$$

$$K = \frac{1}{2} m v^2 + 0$$

$$L = |\vec{r} \times \vec{p}| = \frac{l}{4} m v$$

$$I = \frac{5}{24} m l^2$$

After: $\vec{p} = 2m\vec{v}'$

$$K = \frac{1}{2}(2m)v'^2 + \frac{1}{2}I\omega^2$$

stick + putty = $\frac{5}{24}ml^2$

$$L = I\omega = \frac{5}{24}ml^2\omega$$

no external force
 $\vec{p}_{\text{after}} = \vec{p}_{\text{before}}$

$$m\vec{v} = 2m\vec{v}'$$

$$\boxed{\vec{v}' = \frac{\vec{v}}{2}}$$

no external torque
 $L_{\text{after}} = L_{\text{before}}$

$$\frac{l}{4}mv = \frac{5}{24}ml^2\omega$$

$$\boxed{\omega = \frac{6}{5}\frac{v}{l}}$$