

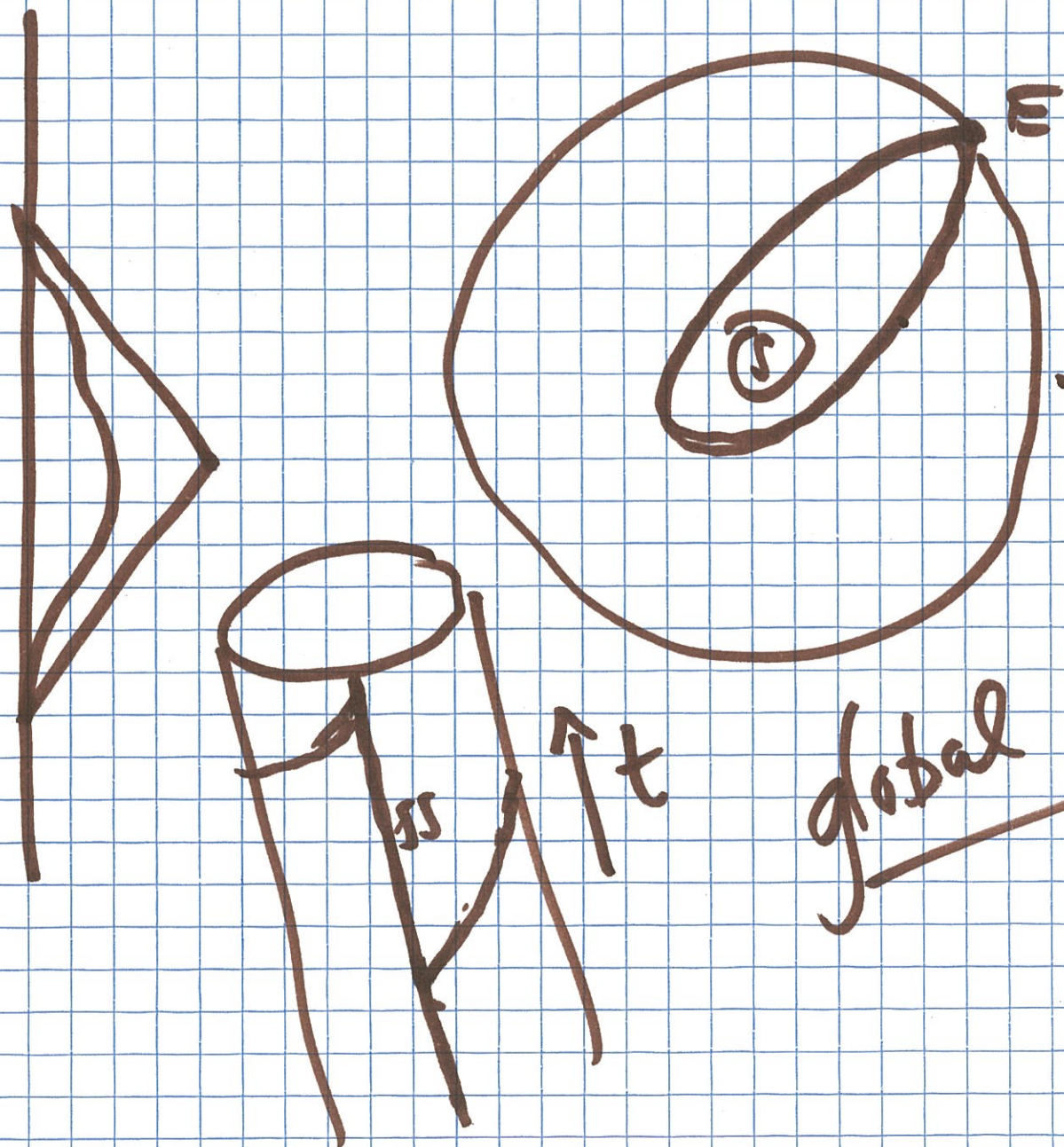
NYU Physics I 2017-12-07

Agenda — Reading Chs 4, 5, 6

— Qs

— 4-vectors.

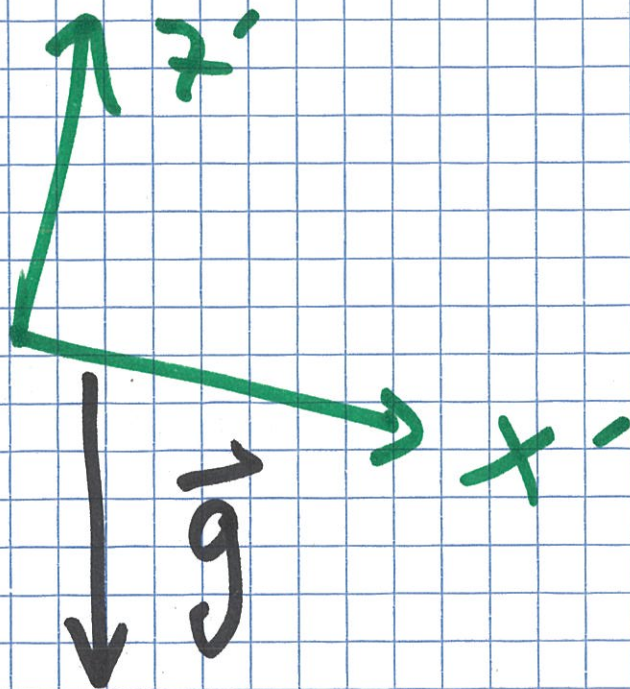
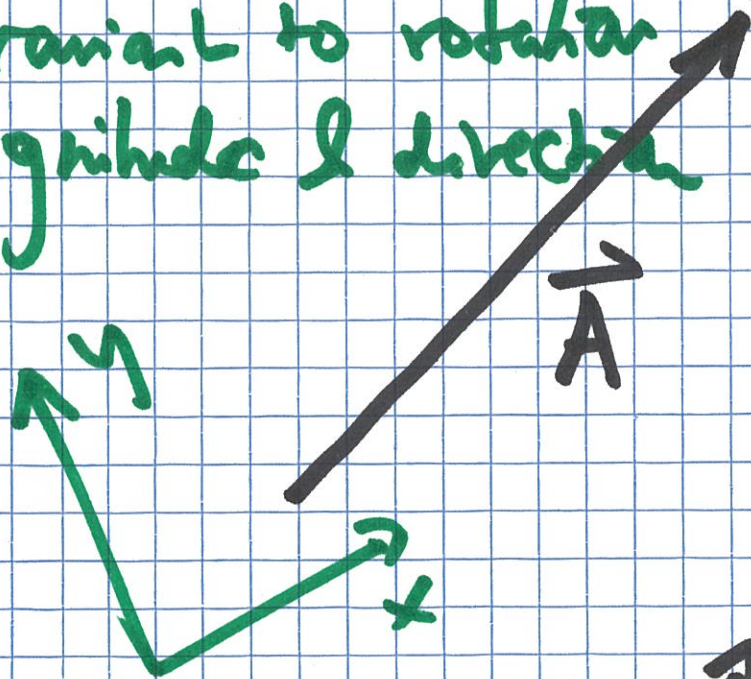
— Exam 6



global geodesic

"3-vectors"

- invariant to rotation
- magnitude & direction.



$$|\vec{g}| = \sqrt{\vec{g} \cdot \vec{g}}$$

$$\vec{g} \cdot \vec{A}$$

$$\arccos\left(\frac{\vec{g} \cdot \vec{A}}{|\vec{g}| |\vec{A}|}\right) = \theta_{gA}$$

4-vectors

- ~~- have a time component, 3 spatial components.~~
- have a space-time direction & "magnitude"
- invariant to boosts — Lorentz transforms.
(& 3-space rotations)

4-displacement $\vec{\Delta S} = (c\Delta t, \Delta x, \Delta y, \Delta z)$

"magnitude"

$$\begin{aligned}\Delta S^2 &= (c\Delta t)^2 - \Delta x^2 - \Delta y^2 - \Delta z^2 \\ &= (c\Delta t)^2 - (\Delta \vec{r})^2\end{aligned}$$

4-velocity $\vec{u} = (u_t, u_x, u_y, u_z)$
 $(\gamma c, \gamma v_x, \gamma v_y, \gamma v_z)$

$$|\vec{u}|^2 = u_t^2 - u_x^2 - u_y^2 - u_z^2 = \gamma^2 c^2 - \gamma^2 (v_x^2 + v_y^2 + v_z^2) \\ = \gamma^2 c^2 \left[1 - \frac{v^2}{c^2} \right] = c^2$$

4-momentum $\vec{p} = m_0 \vec{u} = (E, p_x, p_y, p_z)$

Energy conservation — time symmetry

Momentum conservation — translational symmetry