Experiments are performed by a two layer NN with ReLU activation and Softmax Loss at the end. The skeleton of the model has been provided by Stanford CS231n. I do not give the codes because it is an active assignment for the students and I don't want to violate the honor code.

```
In [ ]:
            # Create some toy data to check your implementations
            input size = 4
            hidden size = 10
            num_classes = 3
            num inputs = 5
            def init_toy_model():
              model = {}
              model['W1'] = np.linspace(-0.2, 0.6, num=input_size*hidden_size).res
            hape(input_size, hidden_size)
              model['b1'] = np.linspace(-0.3, 0.7, num=hidden size)
              model['W2'] = np.linspace(-0.4, 0.1, num=hidden size*num classes).re
            shape(hidden size, num classes)
              model['b2'] = np.linspace(-0.5, 0.9, num=num classes)
              return model
            def init toy data():
              X = np.linspace(-0.2, 0.5, num=num inputs*input size).reshape(num in
            puts, input size)
              y = np.array([0, 1, 2, 2, 1])
              return X, y
            model = init_toy_model()
            X, y = init_toy_data()
```

Train the network

Here we compare naive sgd, momentum, rmsprop and rmsprop+momentum

In [10]: from cs231n.classifier trainer import ClassifierTrainer model = init_toy_model() trainer = ClassifierTrainer() # call the trainer to optimize the loss # Notice that we're using sample_batches=False, so we're performing Gr adient Descent (no sampled batches of data) best_model, loss_history, _, _ = trainer.train(X, y, X, y, model, two layer net, reg=0.001, learning_rate=1e-1, momen tum=0.0, learning_rate_decay=1, update='sgd', sample batc hes=False, num epochs=100, verbose=False) print 'Final loss with vanilla SGD: %f' % (loss_history[-1],) starting iteration starting iteration 10 starting iteration 20 starting iteration 30 starting iteration 40 starting iteration 50 starting iteration 60 starting iteration 70

Momentum Update

starting iteration 80 starting iteration 90

Final loss with vanilla SGD: 0.940686

```
In [18]:
            model = init toy model()
            trainer = ClassifierTrainer()
            # call the trainer to optimize the loss
            # Notice that we're using sample_batches=False, so we're performing Gr
            adient Descent (no sampled batches of data)
             best_model, loss_history, _, _ = trainer.train(X, y, X, y,
                                                          model, two layer net,
                                                          reg=0.001,
                                                          learning rate=1e-1, momen
            tum=0.9, learning_rate_decay=1,
                                                          update='momentum', sample
            _batches=False,
                                                          num epochs=100,
                                                          verbose=False)
             correct loss = 0.494394
            print 'Final loss with momentum SGD: %f' % (loss_history[-1])
            starting iteration
```

```
starting iteration 0
starting iteration 10
starting iteration 20
starting iteration 30
starting iteration 40
starting iteration 50
starting iteration 60
starting iteration 70
starting iteration 80
starting iteration 90
Final loss with momentum SGD: 0.494394
```

RMSprop

```
In [17]:
            model = init toy model()
            trainer = ClassifierTrainer()
            # call the trainer to optimize the loss
            # Notice that we're using sample_batches=False, so we're performing Gr
            adient Descent (no sampled batches of data)
            best_model, loss_history, _, _ = trainer.train(X, y, X, y,
                                                          model, two layer net,
                                                          reg=0.001,
                                                          learning_rate=1e-1, momen
            tum=0.9, learning_rate_decay=1,
                                                          update='rmsprop', sample_
            batches=False,
                                                          num epochs=100,
                                                          verbose=False)
            correct_loss = 0.439368
            print 'Final loss with RMSProp: %f' % (loss_history[-1])
            starting iteration 0
            starting iteration
                               10
            starting iteration 20
            starting iteration 30
            starting iteration 40
            starting iteration 50
            starting iteration 60
            starting iteration 70
            starting iteration 80
            starting iteration 90
```

RMS+Momentum best of the this naive experiment

Final loss with RMSProp: 0.439368

```
model = init toy model()
In [14]:
            trainer = ClassifierTrainer()
            # call the trainer to optimize the loss
            # Notice that we're using sample_batches=False, so we're performing Gr
            adient Descent (no sampled batches of data)
             best_model, loss_history, _, _ = trainer.train(X, y, X, y,
                                                          model, two layer net,
                                                          reg=0.001,
                                                          learning rate=1e-1, momen
            tum=0.9, learning_rate_decay=1,
                                                          update='rmsprop+momentum'
             , sample_batches=False,
                                                          num epochs=100,
                                                          verbose=False)
             correct loss = 0.439368
            print 'Final loss with RMSProp+momentum: %f' % (loss history[-1])
            starting iteration
            starting iteration 10
```

```
starting iteration 20
starting iteration 30
starting iteration 40
starting iteration 50
starting iteration 60
starting iteration 70
starting iteration 80
starting iteration 90
Final loss with RMSProp+momentum: 0.435519
```

AdaGrad is better than SGD but not that RMS and Momentum

```
model = init_toy_model()
In [42]:
            trainer = ClassifierTrainer()
            # call the trainer to optimize the loss
            # Notice that we're using sample batches=False, so we're performing Gr
            adient Descent (no sampled batches of data)
            best model, loss_history, _, _ = trainer.train(X, y, X, y,
                                                          model, two_layer_net,
                                                          reg=0.001,
                                                          learning rate=1e-1, momen
            tum=0.9, learning_rate_decay=1,
                                                          update='adagrad', sample
             batches=False,
                                                          num epochs=100,
                                                          verbose=False)
             correct loss = 0.439368
             print 'Final loss with Adagrad: %f' % (loss_history[-1])
```

Final loss with Adagrad: 0.643385

RESULT: Even in a very simple toy dataset results are so demanding for the favor of

RMSprop and Momentum against SGD. Best performance is observed by RMSprop+Momentum

Load the data

```
In [20]:
            from cs231n.data utils import load CIFAR10
            def get CIFAR10 data(num training=49000, num validation=1000, num test
            =1000):
                Load the CIFAR-10 dataset from disk and perform preprocessing to p
            repare
                it for the two-layer neural net classifier. These are the same ste
            ps as
                we used for the SVM, but condensed to a single function.
                # Load the raw CIFAR-10 data
                cifar10 dir = 'cs231n/datasets/cifar-10-batches-py'
                X train, y train, X test, y test = load CIFAR10(cifar10 dir)
                # Subsample the data
                mask = range(num_training, num_training + num_validation)
                X val = X train[mask]
                y_val = y_train[mask]
                mask = range(num training)
                X_train = X_train[mask]
                y_train = y_train[mask]
                mask = range(num_test)
                X_test = X_test[mask]
                y_test = y_test[mask]
                # Normalize the data: subtract the mean image
                mean_image = np.mean(X_train, axis=0)
                X_train -= mean_image
                X_val -= mean_image
                X test -= mean image
                # Reshape data to rows
                X train = X train.reshape(num training, -1)
                X_val = X_val.reshape(num_validation, -1)
                X_test = X_test.reshape(num_test, -1)
                return X train, y train, X val, y val, X test, y test
            # Invoke the above function to get our data.
            X_train, y_train, X_val, y_val, X_test, y_test = get_CIFAR10_data()
            print 'Train data shape: ', X_train.shape
            print 'Train labels shape: ', y_train.shape
            print 'Validation data shape: ', X_val.shape
            print 'Validation labels shape: ', y_val.shape
            print 'Test data shape: ', X_test.shape
            print 'Test labels shape: ', y_test.shape
            Train data shape: (49000, 3072)
            Train labels shape: (49000,)
            Validation data shape: (1000, 3072)
            Validation labels shape: (1000,)
```

(1000

Tact data chama.

Test labels shape: (1000,)

Train a network

Train this simple model with different update rules.

```
In [55]:
```

```
Finished epoch 0 / 20: cost 2.302593, train: 0.120000, val 0.158000, l
r 1.000000e-05
Finished epoch 1 / 20: cost 2.302591, train: 0.129000, val 0.130000, l
r 9.500000e-06
Finished epoch 2 / 20: cost 2.302589, train: 0.139000, val 0.174000, 1
r 9.025000e-06
Finished epoch 3 / 20: cost 2.302574, train: 0.166000, val 0.177000, l
r 8.573750e-06
Finished epoch 4 / 20: cost 2.302539, train: 0.170000, val 0.193000, l
r 8.145063e-06
Finished epoch 5 / 20: cost 2.302430, train: 0.188000, val 0.199000, 1
r 7.737809e-06
Finished epoch 6 / 20: cost 2.302224, train: 0.195000, val 0.193000, l
r 7.350919e-06
Finished epoch 7 / 20: cost 2.301709, train: 0.177000, val 0.181000, l
r 6.983373e-06
Finished epoch 8 / 20: cost 2.300819, train: 0.165000, val 0.179000, l
r 6.634204e-06
Finished epoch 9 / 20: cost 2.296373, train: 0.151000, val 0.181000, l
r 6.302494e-06
Finished epoch 10 / 20: cost 2.290793, train: 0.169000, val 0.197000,
lr 5.987369e-06
Finished epoch 11 / 20: cost 2.284688, train: 0.184000, val 0.187000,
lr 5.688001e-06
Finished epoch 12 / 20: cost 2.244895, train: 0.184000, val 0.193000,
lr 5.403601e-06
Finished epoch 13 / 20: cost 2.196050, train: 0.156000, val 0.180000,
lr 5.133421e-06
Finished epoch 14 / 20: cost 2.254494, train: 0.135000, val 0.183000,
lr 4.876750e-06
Finished epoch 15 / 20: cost 2.185508, train: 0.196000, val 0.185000,
lr 4.632912e-06
Finished epoch 16 / 20: cost 2.192414, train: 0.163000, val 0.186000,
lr 4.401267e-06
Finished epoch 17 / 20: cost 2.227328, train: 0.179000, val 0.188000,
lr 4.181203e-06
Finished epoch 18 / 20: cost 2.073986, train: 0.181000, val 0.188000,
```

lr 3.972143e-06

Finished epoch 19 / 20: cost 2.080279, train: 0.186000, val 0.190000,

lr 3.773536e-06

Finished epoch 20 / 20: cost 2.142814, train: 0.198000, val 0.199000,

lr 3.584859e-06

finished optimization. best validation accuracy: 0.199000

```
In [56]:
```

```
Finished epoch 0 / 20: cost 2.302593, train: 0.110000, val 0.109000, l
r 1.000000e-05
Finished epoch 1 / 20: cost 2.273101, train: 0.133000, val 0.154000, l
r 9.500000e-06
Finished epoch 2 / 20: cost 2.057101, train: 0.201000, val 0.241000, 1
r 9.025000e-06
Finished epoch 3 / 20: cost 1.888748, train: 0.311000, val 0.288000, l
r 8.573750e-06
Finished epoch 4 / 20: cost 1.839703, train: 0.344000, val 0.339000, l
r 8.145063e-06
Finished epoch 5 / 20: cost 1.942659, train: 0.333000, val 0.366000, 1
r 7.737809e-06
Finished epoch 6 / 20: cost 1.847249, train: 0.361000, val 0.389000, l
r 7.350919e-06
Finished epoch 7 / 20: cost 1.742119, train: 0.407000, val 0.391000, l
r 6.983373e-06
Finished epoch 8 / 20: cost 1.523142, train: 0.392000, val 0.397000, l
r 6.634204e-06
Finished epoch 9 / 20: cost 1.710355, train: 0.411000, val 0.411000, l
r 6.302494e-06
Finished epoch 10 / 20: cost 1.675986, train: 0.426000, val 0.417000,
lr 5.987369e-06
Finished epoch 11 / 20: cost 1.759964, train: 0.449000, val 0.433000,
lr 5.688001e-06
Finished epoch 12 / 20: cost 1.400295, train: 0.445000, val 0.430000,
lr 5.403601e-06
Finished epoch 13 / 20: cost 1.473600, train: 0.441000, val 0.430000,
lr 5.133421e-06
Finished epoch 14 / 20: cost 1.665528, train: 0.437000, val 0.447000,
lr 4.876750e-06
Finished epoch 15 / 20: cost 1.608525, train: 0.471000, val 0.445000,
lr 4.632912e-06
Finished epoch 16 / 20: cost 1.420895, train: 0.454000, val 0.450000,
lr 4.401267e-06
Finished epoch 17 / 20: cost 1.560292, train: 0.472000, val 0.444000,
lr 4.181203e-06
```

Finished epoch 18 / 20: cost 1.585418, train: 0.450000, val 0.449000,

lr 3.972143e-06

Finished epoch 19 / 20: cost 1.623252, train: 0.503000, val 0.445000,

lr 3.773536e-06

Finished epoch 20 / 20: cost 1.554016, train: 0.476000, val 0.454000,

lr 3.584859e-06

finished optimization. best validation accuracy: 0.454000

```
In [57]:
```

```
Finished epoch 0 / 20: cost 2.302593, train: 0.102000, val 0.098000, l
r 1.000000e-05
Finished epoch 1 / 20: cost 1.948840, train: 0.356000, val 0.329000, l
r 9.500000e-06
Finished epoch 2 / 20: cost 1.933427, train: 0.383000, val 0.359000, 1
r 9.025000e-06
Finished epoch 3 / 20: cost 1.866497, train: 0.390000, val 0.395000, 1
r 8.573750e-06
Finished epoch 4 / 20: cost 1.748220, train: 0.420000, val 0.414000, l
r 8.145063e-06
Finished epoch 5 / 20: cost 1.647285, train: 0.417000, val 0.427000, l
r 7.737809e-06
Finished epoch 6 / 20: cost 1.636752, train: 0.406000, val 0.438000, l
r 7.350919e-06
Finished epoch 7 / 20: cost 1.683645, train: 0.433000, val 0.439000, l
r 6.983373e-06
Finished epoch 8 / 20: cost 1.727223, train: 0.455000, val 0.444000, l
r 6.634204e-06
Finished epoch 9 / 20: cost 1.771403, train: 0.446000, val 0.454000, l
r 6.302494e-06
Finished epoch 10 / 20: cost 1.662157, train: 0.484000, val 0.450000,
lr 5.987369e-06
Finished epoch 11 / 20: cost 1.783750, train: 0.451000, val 0.451000,
lr 5.688001e-06
Finished epoch 12 / 20: cost 1.572829, train: 0.455000, val 0.459000,
lr 5.403601e-06
Finished epoch 13 / 20: cost 1.539926, train: 0.457000, val 0.459000,
lr 5.133421e-06
Finished epoch 14 / 20: cost 1.699544, train: 0.439000, val 0.458000,
lr 4.876750e-06
Finished epoch 15 / 20: cost 1.600255, train: 0.443000, val 0.463000,
lr 4.632912e-06
Finished epoch 16 / 20: cost 1.619370, train: 0.468000, val 0.464000,
lr 4.401267e-06
Finished epoch 17 / 20: cost 1.571197, train: 0.476000, val 0.464000,
lr 4.181203e-06
```

Finished epoch 18 / 20: cost 1.608766, train: 0.468000, val 0.469000,

lr 3.972143e-06

Finished epoch 19 / 20: cost 1.630492, train: 0.484000, val 0.477000,

lr 3.773536e-06

Finished epoch 20 / 20: cost 1.481858, train: 0.489000, val 0.470000,

lr 3.584859e-06

finished optimization. best validation accuracy: 0.477000

```
In [58]:
```

```
Finished epoch 0 / 20: cost 2.302593, train: 0.166000, val 0.165000, l
r 1.000000e-05
Finished epoch 1 / 20: cost 1.800040, train: 0.373000, val 0.390000, l
r 9.500000e-06
Finished epoch 2 / 20: cost 1.636812, train: 0.459000, val 0.437000, l
r 9.025000e-06
Finished epoch 3 / 20: cost 1.609279, train: 0.472000, val 0.450000, l
r 8.573750e-06
Finished epoch 4 / 20: cost 1.540035, train: 0.467000, val 0.451000, l
r 8.145063e-06
Finished epoch 5 / 20: cost 1.507733, train: 0.487000, val 0.460000, l
r 7.737809e-06
Finished epoch 6 / 20: cost 1.642292, train: 0.518000, val 0.473000, l
r 7.350919e-06
Finished epoch 7 / 20: cost 1.497452, train: 0.504000, val 0.468000, l
r 6.983373e-06
Finished epoch 8 / 20: cost 1.533577, train: 0.502000, val 0.473000, l
r 6.634204e-06
Finished epoch 9 / 20: cost 1.442068, train: 0.482000, val 0.464000, l
r 6.302494e-06
Finished epoch 10 / 20: cost 1.549564, train: 0.486000, val 0.473000,
lr 5.987369e-06
Finished epoch 11 / 20: cost 1.494527, train: 0.502000, val 0.471000,
lr 5.688001e-06
Finished epoch 12 / 20: cost 1.462458, train: 0.495000, val 0.483000,
lr 5.403601e-06
Finished epoch 13 / 20: cost 1.515679, train: 0.543000, val 0.480000,
lr 5.133421e-06
Finished epoch 14 / 20: cost 1.510962, train: 0.525000, val 0.485000,
lr 4.876750e-06
Finished epoch 15 / 20: cost 1.541044, train: 0.508000, val 0.492000,
lr 4.632912e-06
Finished epoch 16 / 20: cost 1.577317, train: 0.536000, val 0.493000,
lr 4.401267e-06
Finished epoch 17 / 20: cost 1.525123, train: 0.538000, val 0.491000,
lr 4.181203e-06
```

Finished epoch 18 / 20: cost 1.351778, train: 0.552000, val 0.503000, lr 3.972143e-06

Finished epoch 19 / 20: cost 1.590443, train: 0.536000, val 0.499000,

lr 3.773536e-06

Finished epoch 20 / 20: cost 1.448961, train: 0.530000, val 0.507000,

lr 3.584859e-06

finished optimization. best validation accuracy: 0.507000

```
In [59]:
```

```
Finished epoch 0 / 20: cost 2.302593, train: 0.117000, val 0.108000, l
r 1.000000e-02
Finished epoch 1 / 20: cost 1.976317, train: 0.375000, val 0.393000, l
r 9.500000e-03
Finished epoch 2 / 20: cost 1.819465, train: 0.396000, val 0.360000, l
r 9.025000e-03
Finished epoch 3 / 20: cost 1.946780, train: 0.393000, val 0.396000, l
r 8.573750e-03
Finished epoch 4 / 20: cost 1.948320, train: 0.429000, val 0.388000, l
r 8.145062e-03
Finished epoch 5 / 20: cost 1.817160, train: 0.445000, val 0.463000, l
r 7.737809e-03
Finished epoch 6 / 20: cost 1.781161, train: 0.433000, val 0.433000, l
r 7.350919e-03
Finished epoch 7 / 20: cost 1.726162, train: 0.437000, val 0.431000, l
r 6.983373e-03
Finished epoch 8 / 20: cost 1.945575, train: 0.467000, val 0.438000, l
r 6.634204e-03
Finished epoch 9 / 20: cost 1.717542, train: 0.463000, val 0.468000, l
r 6.302494e-03
Finished epoch 10 / 20: cost 1.653255, train: 0.472000, val 0.443000,
lr 5.987369e-03
Finished epoch 11 / 20: cost 1.757400, train: 0.487000, val 0.448000,
lr 5.688001e-03
Finished epoch 12 / 20: cost 1.612132, train: 0.487000, val 0.470000,
lr 5.403601e-03
Finished epoch 13 / 20: cost 1.575829, train: 0.462000, val 0.453000,
lr 5.133421e-03
Finished epoch 14 / 20: cost 1.739385, train: 0.465000, val 0.471000,
lr 4.876750e-03
Finished epoch 15 / 20: cost 1.649168, train: 0.497000, val 0.461000,
lr 4.632912e-03
Finished epoch 16 / 20: cost 1.844438, train: 0.482000, val 0.483000,
lr 4.401267e-03
Finished epoch 17 / 20: cost 1.755178, train: 0.502000, val 0.466000,
lr 4.181203e-03
```

```
Finished epoch 18 / 20: cost 1.623927, train: 0.494000, val 0.476000, lr 3.972143e-03
Finished epoch 19 / 20: cost 1.760897, train: 0.502000, val 0.474000, lr 3.773536e-03
Finished epoch 20 / 20: cost 1.795621, train: 0.501000, val 0.469000, lr 3.584859e-03
finished optimization. best validation accuracy: 0.483000
```

RESULT: In a real dataset perfomance differences are more significant. SGD gets 0.18 and we can scale ti to up to 0.46 by RMSprop+Momentum with the smae number of iterations.

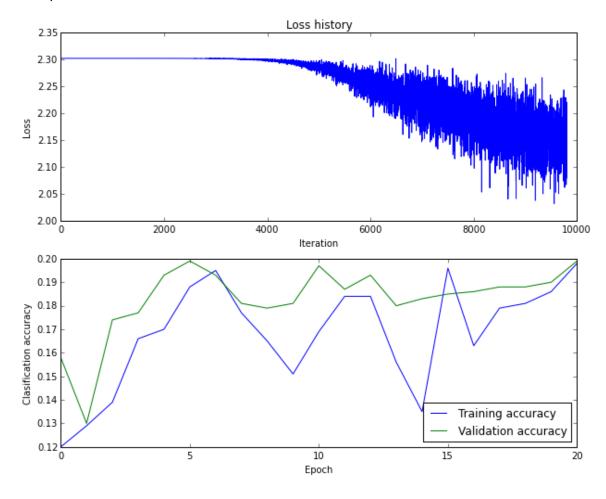
Look at the results

SGD results ---

Plots show that SGD takes so much time to reduce the loss and it only achives 0.19 accuracy at validation set. In addition, train and validation accuracies are very dispersed at many segments of the learning. I think SGD is not very reliable by these observations.

In [60]: # Plot the loss function and train / validation accuracies plt.subplot(2, 1, 1) plt.plot(loss_history1) plt.title('Loss history') plt.xlabel('Iteration') plt.ylabel('Loss') plt.subplot(2, 1, 2) plt.plot(train_acc1) plt.plot(val_acc1) plt.legend(['Training accuracy', 'Validation accuracy'], loc='lower ri ght') plt.xlabel('Epoch') plt.ylabel('Clasification accuracy')

Out[60]: <matplotlib.text.Text at 0x7fbb51db12d0>

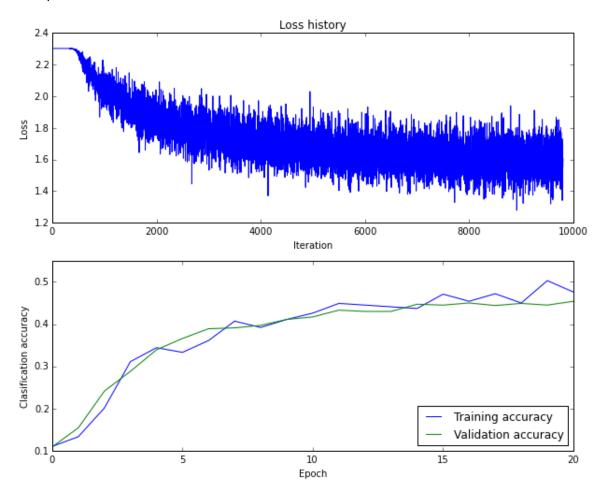


Momentum Results ---

Better than SGD. However, still it needs a set of epochs to find a way to the minima. It is observed through the stationary Loss at the begining. Validation and Train accurcies much more correlated as well.

In [61]: # Plot the loss function and train / validation accuracies plt.subplot(2, 1, 1) plt.plot(loss_history2) plt.title('Loss history') plt.xlabel('Iteration') plt.ylabel('Loss') plt.subplot(2, 1, 2) plt.plot(train_acc2) plt.plot(val_acc2) plt.legend(['Training accuracy', 'Validation accuracy'], loc='lower ri ght') plt.xlabel('Epoch') plt.ylabel('Clasification accuracy')

Out[61]: <matplotlib.text.Text at 0x7fbb51f9d890>

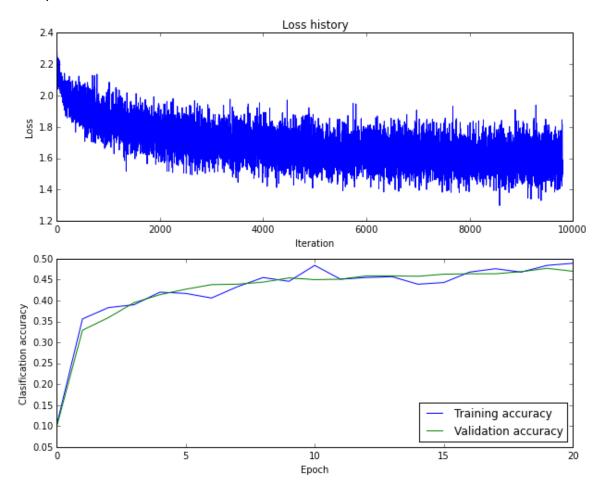


RMSprop results

Main difference here is the convergende of the algorithm compared to others. You can see a very declined slope at he beginning of the Loss value. It starts to optimize very quickly. Also, accuracy is peaked from the beginning of the training.

In [62]: # Plot the loss function and train / validation accuracies plt.subplot(2, 1, 1) plt.plot(loss_history3) plt.title('Loss history') plt.xlabel('Iteration') plt.ylabel('Loss') plt.subplot(2, 1, 2) plt.plot(train_acc3) plt.plot(val_acc3) plt.legend(['Training accuracy', 'Validation accuracy'], loc='lower ri ght') plt.xlabel('Epoch') plt.ylabel('Clasification accuracy')

Out[62]: <matplotlib.text.Text at 0x7fbb51d82a10>

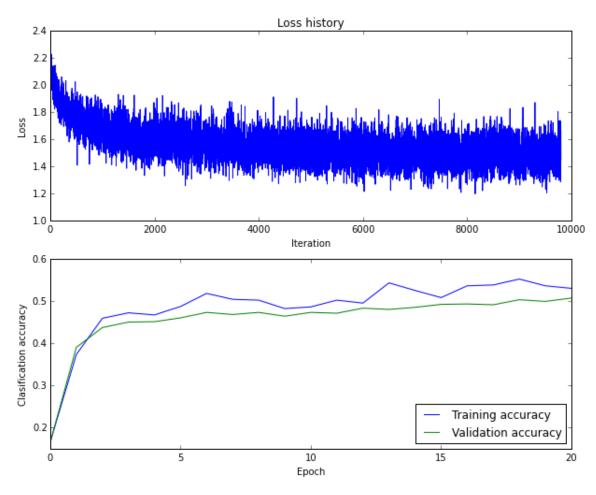


RMS+Momentum Observations

Much better convergence and best performance. It peaks the validation accuracy almost at the 5th epoch and we see only a little improvement there after.

In [63]: # Plot the loss function and train / validation accuracies plt.subplot(2, 1, 1) plt.plot(loss_history4) plt.title('Loss history') plt.xlabel('Iteration') plt.ylabel('Loss') plt.subplot(2, 1, 2) plt.plot(train_acc4) plt.plot(val_acc4) plt.legend(['Training accuracy', 'Validation accuracy'], loc='lower ri ght') plt.xlabel('Epoch') plt.ylabel('Clasification accuracy')

Out[63]: <matplotlib.text.Text at 0x7fbb515bbb90>



AdaGrad Observations

AdaGrad is known as a optimization method that is robust to learning rate choice andeven you give a initial learning rate value, it finds a way to tune it to a optimal value in the couse of training, at least theoretically.

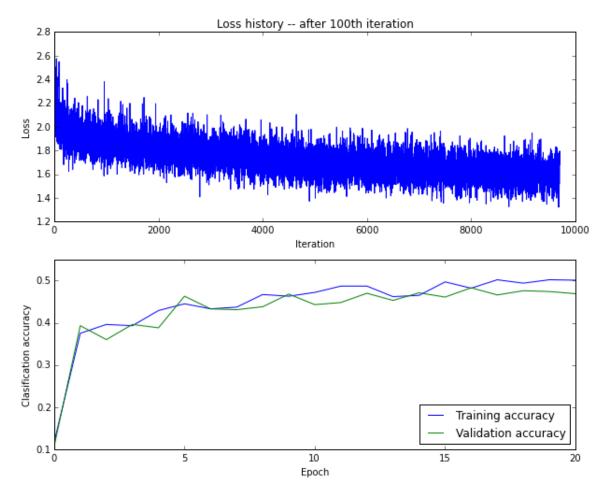
I used much greater learning rate for AdaGrad traning since it cannot improve the accuracy or the loss value otherwise.

One improtant behaviour of AdaGrad is , it needs a initial period to tune the learning to a good value. Therfore, we observe a non-decreasing even wildly increasing Loss value initially but it functions well at the end. It takes the second best accuracy as well after RMSprop+Momentum

```
In [85]: # Plot the loss function and train / validation accuracies
    plt.subplot(2, 1, 1)
    plt.plot(loss_history5[100:])
    plt.title('Loss history -- after 100th iteration')
    plt.xlabel('Iteration')
    plt.ylabel('Loss')

plt.subplot(2, 1, 2)
    plt.plot(train_acc5)
    plt.plot(val_acc5)
    plt.legend(['Training accuracy', 'Validation accuracy'], loc='lower ri ght')
    plt.xlabel('Epoch')
    plt.ylabel('Clasification accuracy')
```

Out[85]: <matplotlib.text.Text at 0x7fbb51116290>



AdaGrad updates takes some epochs to tune learning rate. I printed loss values for first 50 epochs to see this effect.

loss_history5[0:50] In [68]: Out[68]: [2.3025928278904635, 75.934736079622795, 92.182474572629786, 100.5019278755542, 84.844181635490045, 49.409391098629875, 43.328290141355289, 35.325688200166425, 25.519854900507241, 21.356402138599851, 26.218600967478551, 31.59622812204384, 26.22040589643569, 23.227517734307192, 17.767912373878527, 16.157541492684935, 12.608468084163864, 12.321226053503693, 13.24122535188368, 12.928515216653592, 10.796928215446016, 9.1984105449830302, 11.298781826011448, 10.804694477862794, 12.568968109093376, 10.56363563705977, 7.9977924016860049, 7.34338664646741, 6.6929796435282283, 7.1677274578861159, 7.2066434970512532, 6.7933009055358866, 6.7913307562240677, 6.6829018897838459, 7.0043970733245429, 7.3813129930707051, 6.4100443076342426, 5.7477095369608451, 7.3967044022923663, 5.8068102116770044, 6.1110745504385751, 5.4339376326257485, 5.3695441754045357, 4.6965492787415659, 5.7784881299439856, 5.4864936711432595, 4.4452802054476042, 4.7502021504025134, 5.2173199263390639, 3.9212560040704405]

Conclusion

Despite the simplicity of the both Momentum and RMSprop tricks, performance improvement is very high compared to naive SGD. Also from the above figures, you can see the problems that I've been told in my blog post http://bit.ly/1FGKb4K (http://bit.ly/1FGKb4K). If we look at the loss changes of SGD it is very unstable and after we apply Momentum it is stabilized relatively. Then implication of RMSprop makes things better and modest.

Another fact is the convergence rates of the methods. As you can see RMSprop+Momentum reaches the very solid values after only the first epoch.

I add AdaGrad to experiments lately. As I stated above, if you like to see good values in a short time AdaGrad is not the choice but in some way or another it concludes a good model, if you are patient enough.

The accuracy values of train and validation are also more correlated as we improve the SGD with the additional tricks. Of course, I didn't suppose that this model is the best and you can see that we can increase the number of learning epochs or make the model larger since there is no gap between train and validation accuracies yet after 5th epoch.

As a side note, this notebook and the blog post is inspired as I was working on Stanford CS231n assignment2. Therefore I did not provide any replicable code for the sake of honor code.