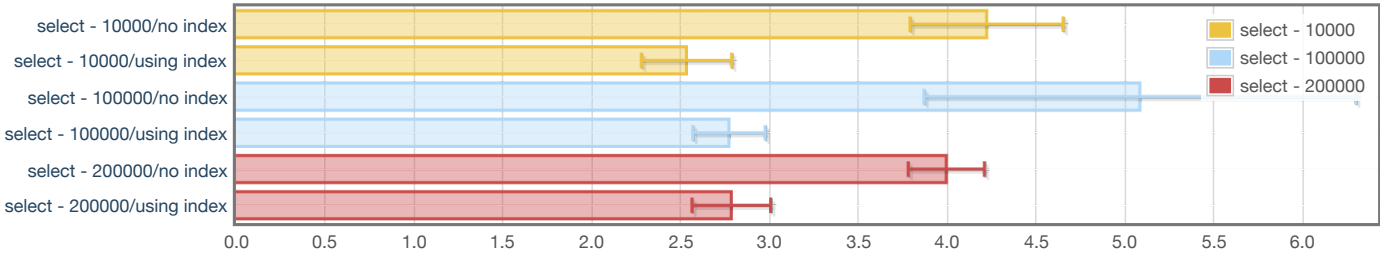


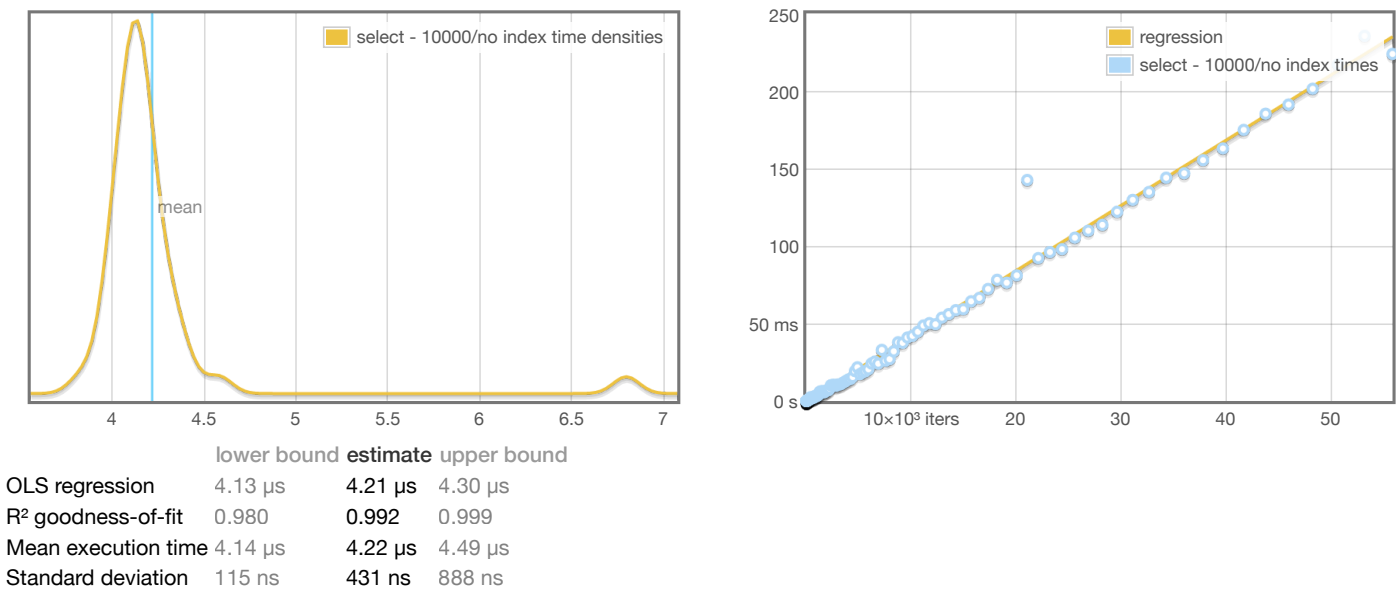
# critterion performance measurements

## overview

want to understand this report?

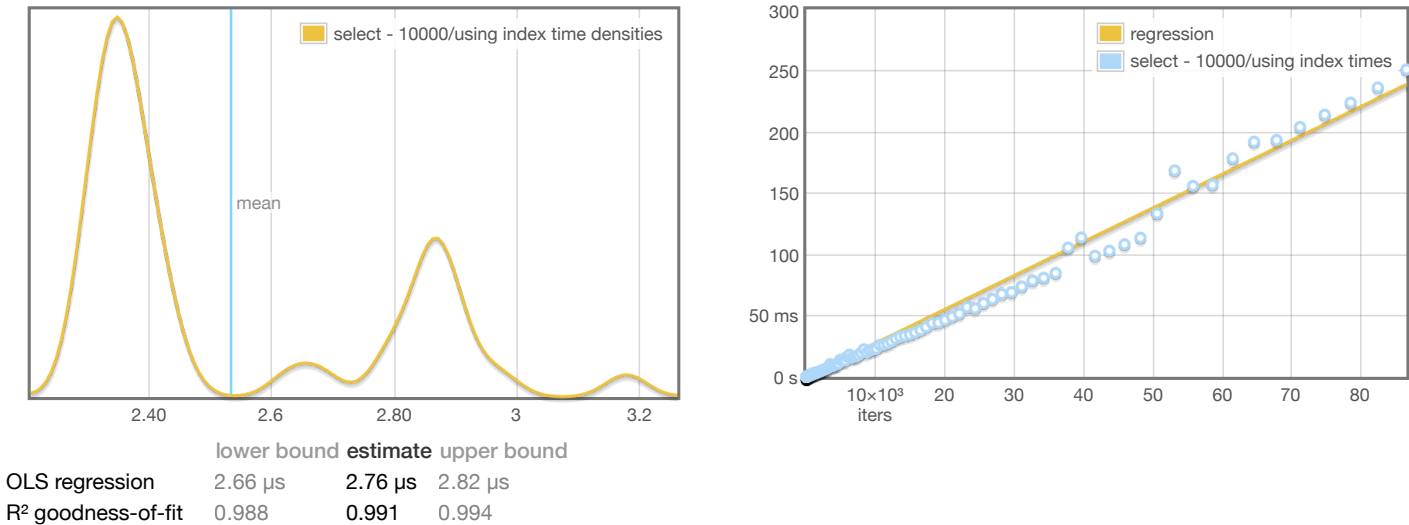


## select - 10000/no index



Outlying measurements have severe (87.8%) effect on estimated standard deviation.

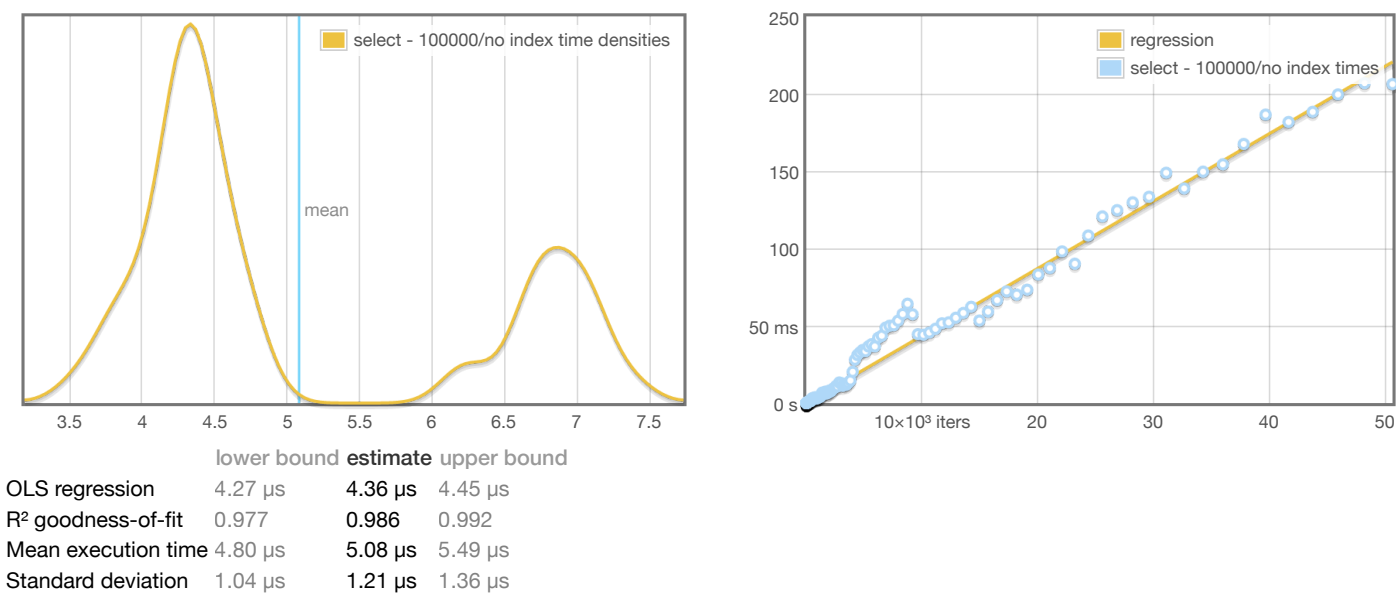
## select - 10000/using index



	lower bound	estimate	upper bound
Mean execution time	2.46 $\mu$ s	2.53 $\mu$ s	2.61 $\mu$ s
Standard deviation	207 ns	254 ns	299 ns

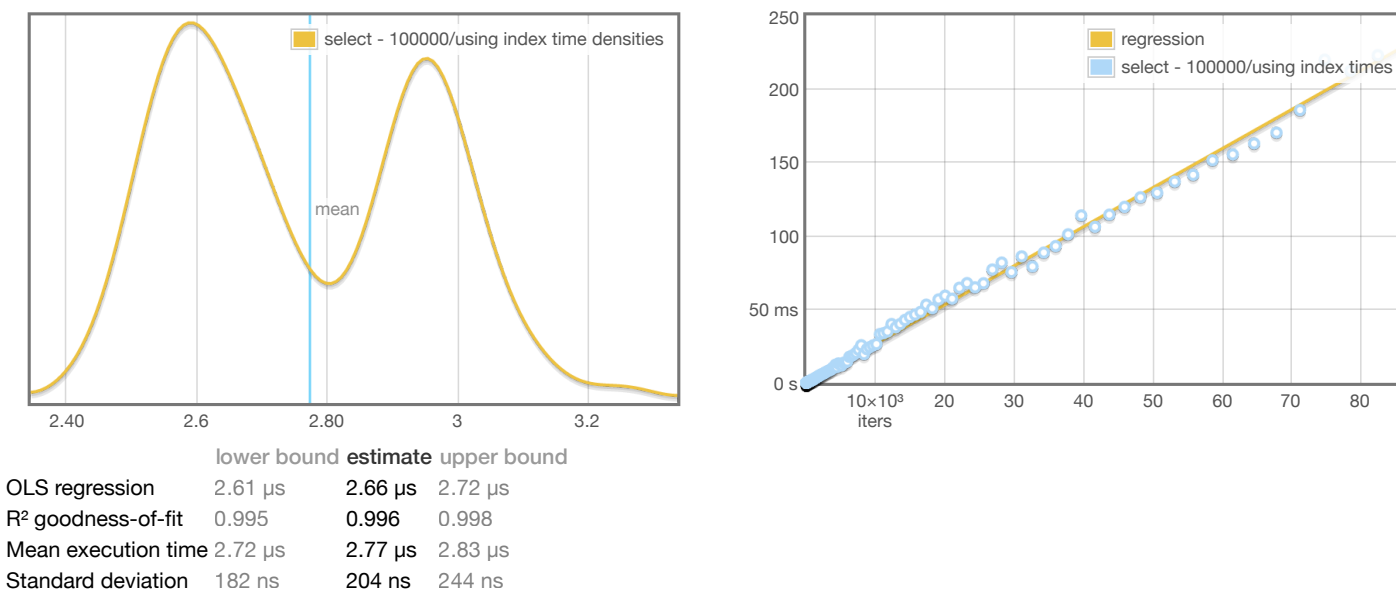
Outlying measurements have severe (87.8%) effect on estimated standard deviation.

select - 100000/no index



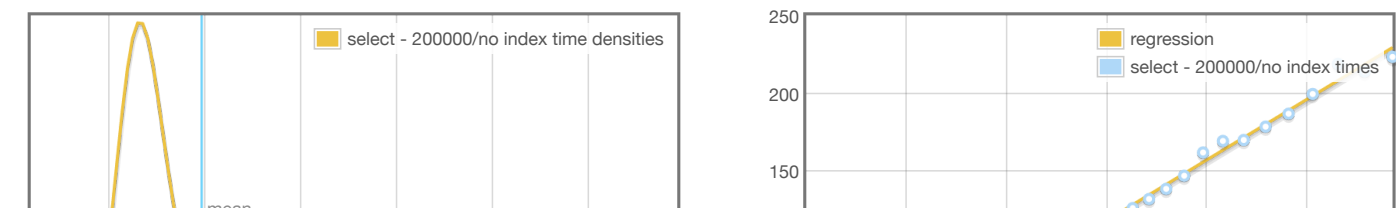
Outlying measurements have severe (97.6%) effect on estimated standard deviation.

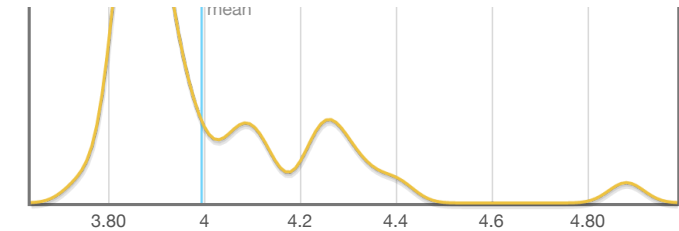
select - 100000/using index



Outlying measurements have severe (79.6%) effect on estimated standard deviation.

select - 200000/no index

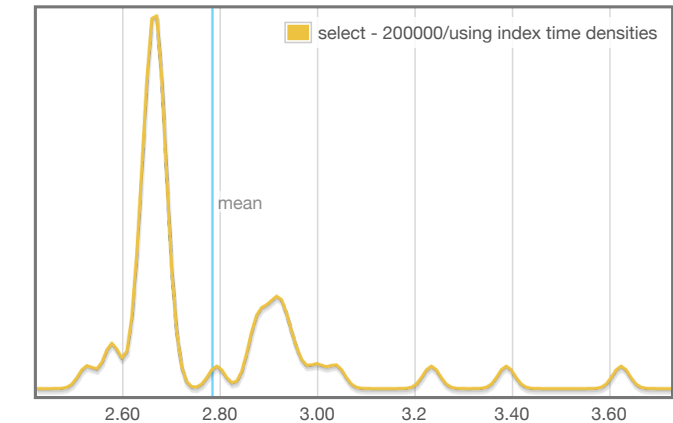




	lower bound	estimate	upper bound
OLS regression	3.87 $\mu$ s	3.91 $\mu$ s	3.98 $\mu$ s
R <sup>2</sup> goodness-of-fit	0.998	0.999	0.999
Mean execution time	3.94 $\mu$ s	3.99 $\mu$ s	4.07 $\mu$ s
Standard deviation	153 ns	214 ns	303 ns

Outlying measurements have severe (66.4%) effect on estimated standard deviation.

## select - 200000/using index



	lower bound	estimate	upper bound
OLS regression	2.70 $\mu$ s	2.82 $\mu$ s	2.93 $\mu$ s
R <sup>2</sup> goodness-of-fit	0.984	0.990	0.997
Mean execution time	2.74 $\mu$ s	2.79 $\mu$ s	2.87 $\mu$ s
Standard deviation	160 ns	221 ns	328 ns

Outlying measurements have severe (81.7%) effect on estimated standard deviation.

## understanding this report

In this report, each function benchmarked by criterion is assigned a section of its own. The charts in each section are active; if you hover your mouse over data points and annotations, you will see more details.

- The chart on the left is a [kernel density estimate](#) (also known as a KDE) of time measurements. This graphs the probability of any given time measurement occurring. A spike indicates that a measurement of a particular time occurred; its height indicates how often that measurement was repeated.
- The chart on the right is the raw data from which the kernel density estimate is built. The x axis indicates the number of loop iterations, while the y axis shows measured execution time for the given number of loop iterations. The line behind the values is the linear regression prediction of execution time for a given number of iterations. Ideally, all measurements will be on (or very near) this line.

Under the charts is a small table. The first two rows are the results of a linear regression run on the measurements displayed in the right-hand chart.

- *OLS regression* indicates the time estimated for a single loop iteration using an ordinary least-squares regression model. This number is more accurate than the *mean* estimate below it, as it more effectively eliminates measurement overhead and other constant factors.
- *R<sup>2</sup> goodness-of-fit* is a measure of how accurately the linear regression model fits the observed measurements. If the measurements are not too noisy, R<sup>2</sup> should lie between 0.99 and 1, indicating an excellent fit. If the number is below 0.99, something is confounding the accuracy of the linear model.
- *Mean execution time* and *standard deviation* are statistics calculated from execution time divided by number of iterations.

We use a statistical technique called the [bootstrap](#) to provide confidence intervals on our estimates. The bootstrap-derived upper and lower bounds on estimates let you see how accurate we believe those estimates to be. (Hover the mouse over the table headers to see the confidence levels.)

A noisy benchmarking environment can cause some or many measurements to fall far from the mean. These outlying measurements can have a significant inflationary effect on the estimate of the standard deviation. We calculate and display an estimate of the extent to which the standard deviation has been inflated by outliers.

## colophon

This report was created using the criterion benchmark execution and performance analysis tool.

Criterion is developed and maintained by Bryan O'Sullivan.