Critical Section

1. (a) Describe the three key requirements that must be satisfied by any solution to the critical section problem.

Critical Section

- The three key requirements are as follows:
 - 1. Mutual Exclusion. No more than one process can be executing in its critical section.
 - **2. Progress**. The selection of the processes that will enter the critical section next cannot be postponed indefinitely.
 - 3. Bounded Waiting. A bound must exist on the number of times that other processes are allowed to enter their critical sections after a process has made a request to enter its critical section and before that request is granted.

1 (b) Consider the following user-level solution to the critical section problem, where **flag** and **turn** are shared variables initialized to **false** and **0**, respectively.

```
Process P0Process P1while(1){<br/>flag=true;<br/>while(turn==1);<br/>critical-section<br/>turn=1;<br/>remainder-sectionwhile(1){<br/>turn=0;<br/>while(flag and turn==0);<br/>critical-section<br/>flag=false;<br/>remainder-section
```

Determine which of the three requirements in part (a) are not satisfied. Justify your answer.

Critical Section (1 (b))

- This solution does not guarantee mutual exclusion.
 Consider the following sequence:
- 1. P1: turn=0;
- P1: while(flag and turn==0);
- 3. P1: critical-section
- 4. Context switch from P1 to P0
- 5. P0: flag=true;
- 6. P0: while(turn==1);
- 7. critical-section
 - \rightarrow P0 and P1 are both in the critical section \otimes

Critical Section (1 (b))

 This solution does not guarantee progress. Consider the following sequence:

- 1. P0: executes the while loop once and turn becomes 1
- 2. P0: flag=true;
- 3. P0: while(turn==1); // loop forever
 - → Progress is not satisfied for process P0 ⊗

Critical Section (1 (b))

This solution satisfies bounded waiting.

P0: waiting @ while(turn==1);

In this case, PO will enter the moment P1 executes the first statement inside its while loop. So P1 can enter its critical section 0 times after P0 has requested access.

2. P1: waiting @ while(flag and turn==0);

In this case, P1 will enter the moment P0 executes turn=1 statement after its critical section. So P0 can enter its critical section 1 time after P1 has requested access.

2. Indicate whether the following statements are true or false. Justify your answers.

- a) Race condition only occurs because a single highlevel C instruction (e.g., counter++;) is translated into multiple low-level assembly instructions (e.g., register=counter; register=register+1; counter=register).
- b) Mutual exclusion can be achieved by disabling interrupts during the critical section.
- c) If a solution to a critical section problem satisfies progress, then it also satisfies bounded waiting.

a) Race condition only occurs because a single highlevel C instruction (e.g., counter++;) is translated into multiple low-level assembly instructions (e.g., register=counter; register=register+1; counter=register).

→ False.

Justification: Race condition can also occur in the producerconsumer example of the lecture if the increment to **counter** is done using a **temp** variable

```
temp = counter;
temp = temp+1;
counter = temp;
```

In this case, race condition occurs irrespective of how these highlevel instructions are translated. b) Mutual exclusion can be achieved by disabling interrupts during the critical section.

\rightarrow True.

Justification: By disabling interrupts, no other process, including the operating system, will be able to run during the critical section.

c) If a solution to a critical section problem satisfies progress, then it also satisfies bounded waiting.

→ False.

Justification: A solution that always favors a process P0 over another process P1 can satisfy progress without satisfying bounded waiting. In this case, the bounded waiting requirement for process P1 will be violated. Consider the following, with flag initialized to false and timeout some large value.

Process PO

while(flag);

flag=true;

critical section;

flag=false;

Process P1

while(flag) {wait(timeout);}

flag=true;

critical section;

flag=false;

TestAndSet

3. Consider a computer that does not have a *TestAndSet* instruction, but has an instruction to **swap** the contents of a register and memory word in a single atomic command. Show how it can be used to implement the *entry section* and *exit section* which are before and after the critical section.

swap (boolean lock, registers);

```
while (1) {

entry section

critical section

exit section

remainder section
```

Swap

boolean lock is a shared memory variable and initialized to false.

```
entry section:
    register = true;
    while (register){
        swap(lock, register);
    }

exit section:
    lock: = false;
```