



Part 3: Process Scheduling

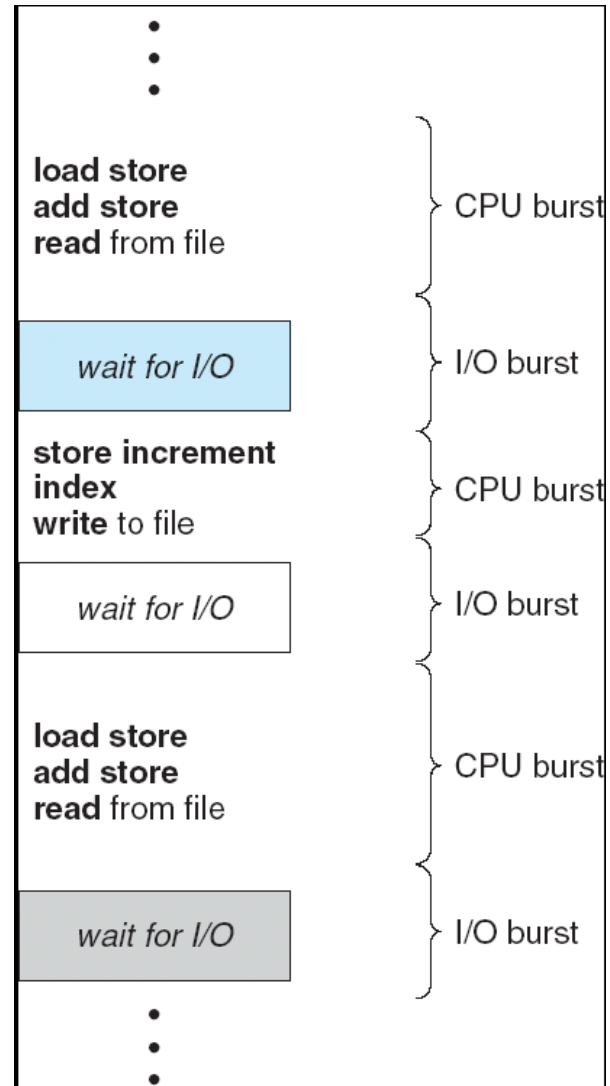
- Basic Concepts
- Scheduling Criteria
- Scheduling Algorithms
 - Uniprocessor (single-core) scheduling
 - Multiprocessor (multi-core) scheduling



Basic Concepts

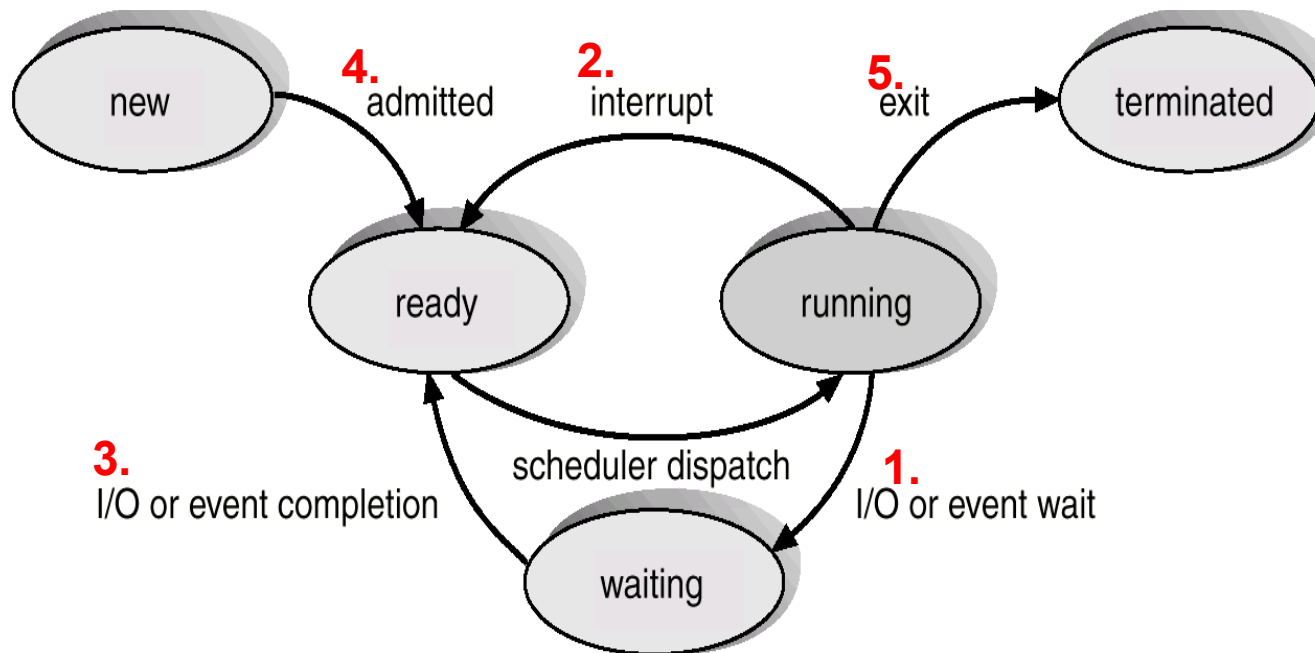
- **CPU–I/O Bursts:** Process execution alternates between CPU executions and I/O operations
 - **CPU burst:** Duration of one CPU execution cycle
 - **I/O burst:** Duration of one I/O operation (wait time)
- **CPU scheduling objective:** Keep the CPU busy as much as possible (i.e., using multiprogramming)
- For simplicity, we focus on the concepts of **short-term (ready queue) scheduler for both uni- and multi-processor CPUs**

Alternating Sequence of CPU And I/O Bursts



CPU Scheduler (Short-Term)

- **Goal:** Select one or more of the processes in the ready queue, and allocate it to the CPU (**one process per core**)
- Scheduler may run whenever a process changes state



In which case(s) does CPU scheduling have to occur in order to keep the CPU cores busy?

Answer:
Only 1 and 5



Types of CPU Schedulers

- 1. Nonpreemptive** means that once the CPU has been allocated to a process, the process keeps the CPU until it **voluntarily releases the CPU** either by terminating or requesting I/O/event wait
 - Scheduling is nonpreemptive if it happens **only** for transitions 1 and 5 (also 4, when a CPU core is idle)
- 2. Preemptive** means that the CPU can be taken away from a running process **at any time** by the scheduler
 - Scheduling is preemptive if it **also** happens for transitions 2, 3, 4 or at any other time instant



Scheduling Objectives

System-wide Objectives:

- 1. Max. CPU Utilization:** Keep the CPU as busy as possible
 - Percentage of time during which the CPU cores are busy executing processes.
 - (Sum of execution time on each core) divided by (total time multiplied by number of cores)
- 2. Max. Throughput:** Number of processes that complete their execution per unit of time
 - Number of “**exit**” transitions per unit of time



Scheduling Objectives (Cont.)

Individual Process Objectives:

- 1. Min. Turnaround Time:** Amount of time to execute a particular process, i.e., from the time of creation to the time of termination
 - Time elapsed between “**admitted**” and “**exit**” transitions for a process
 - Average over all processes is denoted as **average turnaround time**

Scheduling Objectives (Cont.)

- 2. Min. Waiting Time:** Amount of time a process has been waiting in the “ready” state
- We do not consider time in “waiting” state; why?
 - Turnaround time components: CPU burst (running), I/O burst (waiting) and waiting time (ready)
 - If all processes have a single CPU burst (no I/O), then waiting time = turnaround time – CPU burst
- 3. Min. Response Time:** Time from a request submission (“admitted” transition) until the first response is produced (we assume first response coincides with start of execution)

Scheduling Algorithms: Uniprocessor System

1. First-Come, First-Served (FCFS)
2. Shortest Job First (SJF)
3. Priority-based Scheduling
4. Round Robin (RR)
5. Multilevel Queue Scheduling

We assume a single CPU burst for each process, a single CPU core and focus on the average waiting time

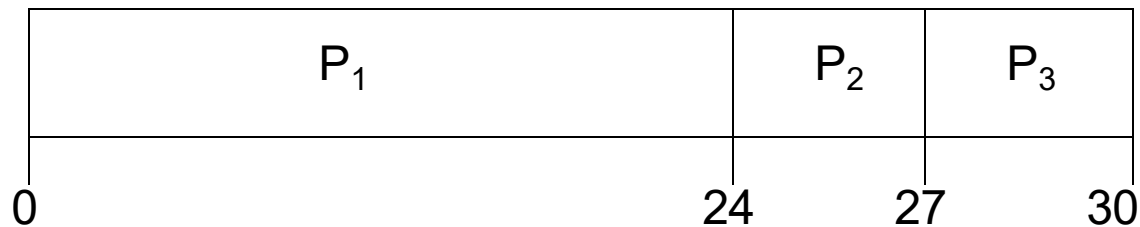
First-Come, First-Served (FCFS) Scheduling

- **Example:**

<u>Process</u>	<u>CPU Burst Length</u>
P_1	24
P_2	3
P_3	3

- Suppose that processes arrive in the order P_1, P_2, P_3 , all at time 0

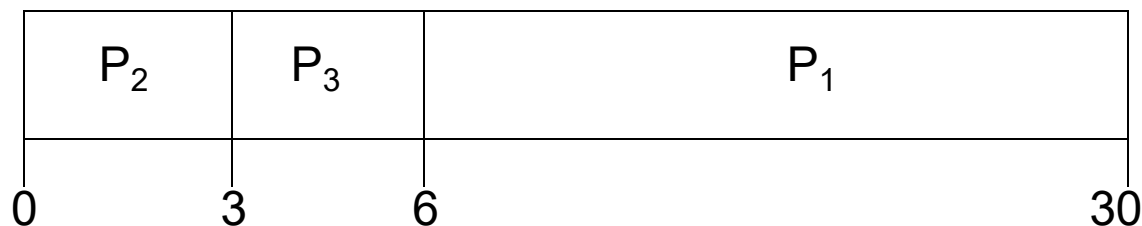
- **The Gantt Chart for the schedule is:**



- Waiting time for $P_1 = 0$; $P_2 = 24$; $P_3 = 27$
- Average waiting time: $(0 + 24 + 27)/3 = 17$

FCFS Scheduling (Cont.)

- Suppose that the processes arrive in the order P_2 , P_3 , P_1 , again all at time 0
- The Gantt chart for the schedule is:



- Waiting time for $P_1 = 6$; $P_2 = 0$; $P_3 = 3$
- Average waiting time: $(6 + 0 + 3)/3 = 3$
 - Much better than the previous case

FCFS Scheduling: Properties

- Is FCFS preemptive or nonpreemptive?
 - Nonpreemptive, because processes have to voluntarily release the CPU once allocated
- Main problem with FCFS is the **convoy effect**
 - Short processes suffer increased waiting times due to an earlier arrived long process
 - We saw this effect in the previous example - P1 increased the waiting times of P2 and P3



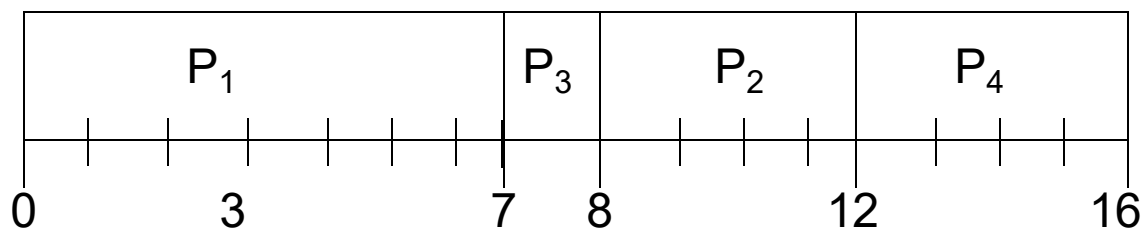
Shortest-Job-First (SJF) Scheduling

- Prioritize processes based on their CPU burst lengths
 - Shorter burst implies higher priority
 - Intuitive way to handle the convoy effect of FCFS
- Two schemes:
 1. **Nonpreemptive**: Once core is given to a process, it cannot be preempted until it completes its CPU burst
 2. **Preemptive (also known as Shortest Remaining-Time First or SRTF)**: If a newly created process has CPU burst length less than the remaining CPU burst of currently running process, then preemption will occur
- SJF/SRTF is optimal for minimizing average waiting time

Example of Nonpreemptive SJF

<u>Process</u>	<u>Arrival Time</u>	<u>Burst Time</u>
P_1	0.0	7 ✓
P_2	2.0	4 ✓
P_3	4.0	1 ✓
P_4	5.0	4 ✓

- SJF (Nonpreemptive) Gantt Chart:**

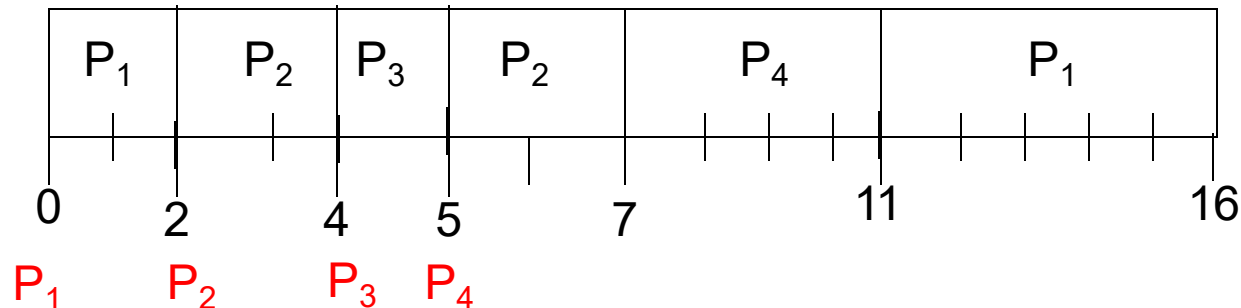


- Average waiting time = $(0 + 6 + 3 + 7)/4 = 4$

Example of Preemptive SJF (SRTF)

<u>Process</u>	<u>Arrival Time</u>	<u>Burst Time</u>
P_1	0.0	7 \rightarrow 5 \rightarrow 0
P_2	2.0	4 \rightarrow 2 \rightarrow 0
P_3	4.0	1 \rightarrow 0
P_4	5.0	4 \rightarrow 0

- SJF (Preemptive) Gantt Chart:**



- Average waiting time = $(9 + 1 + 0 + 2)/4 = 3$



Priority-based Scheduling

- A **priority number (integer)** is associated with each process
- **CPU is allocated to the process with the highest priority**
 - Usually, smallest integer implies highest priority
 - **Two schemes:** Preemptive and nonpreemptive
 - FCFS: Priority based on arrival order
 - SJF: Priority based on CPU burst length
- **Problem of Starvation:** Lower priority processes may never execute in a heavily loaded system
 - **Solution is Aging:** As time progresses, slowly increase the priority of processes that are not able to execute

Round Robin (RR) Scheduling

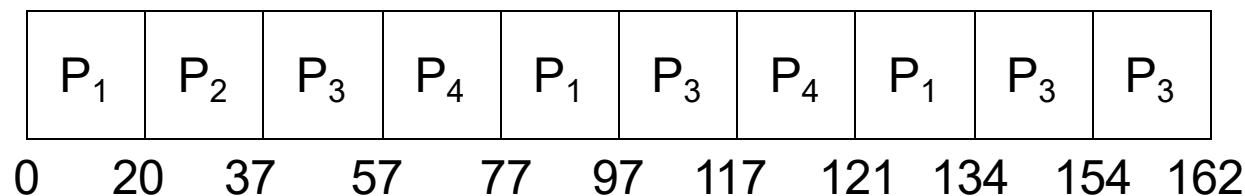
- **Fixed time quantum for scheduling (q):** A Process is allocated CPU for q time units, preempted thereafter and inserted at the end of the ready queue
 - Processes are **scheduled cyclically** based on q
 - Usually **q is small**, around 10-100 milliseconds
- **Performance:**
 - *n processes in ready queue implies* waiting time is no more than $(n-1)q$ time units
 - **Large q :** Degenerates to FCFS
 - **Small q :** *Many context switches; high overhead*

Example: RR with Time Quantum = 20

<u>Process</u>	<u>Burst Time</u>
P_1	53 \rightarrow 33
P_2	17 \rightarrow 0
P_3	68 \rightarrow 48
P_4	24 \rightarrow 4

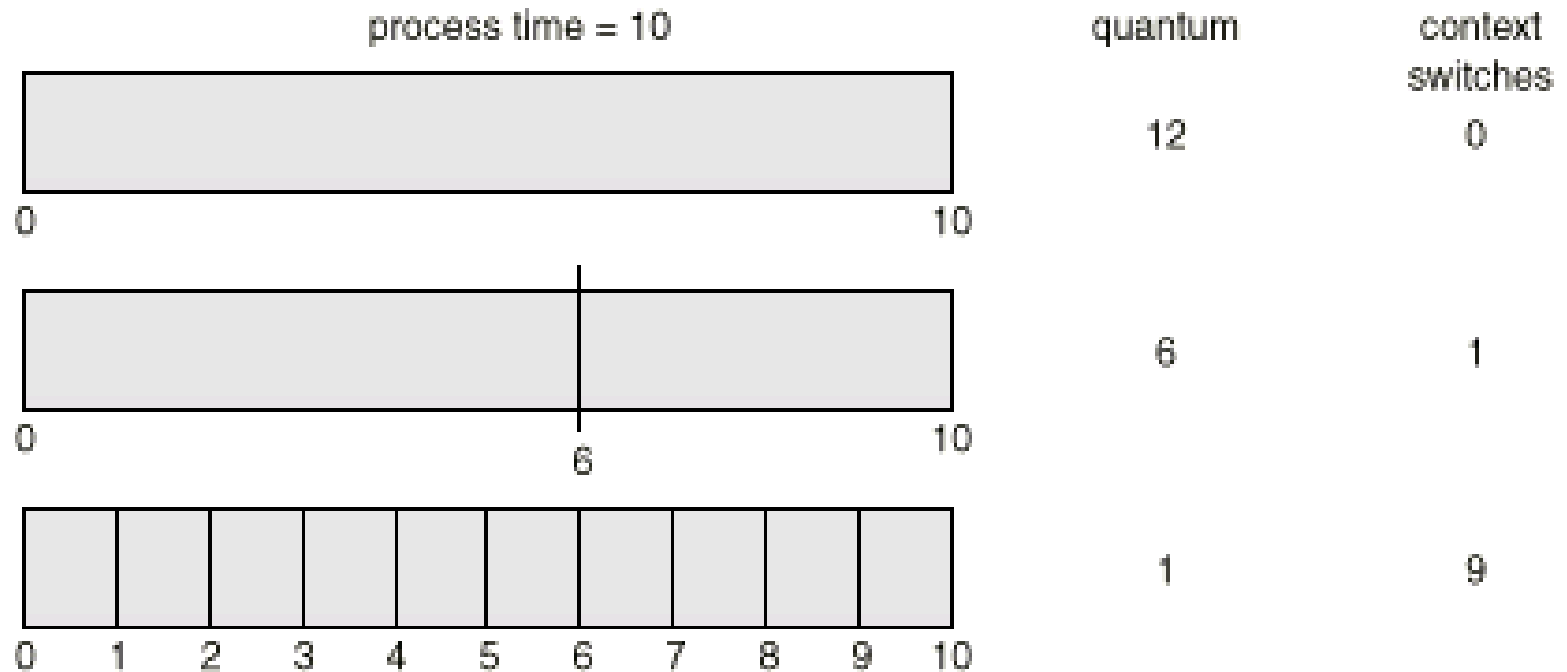
- All processes come at time 0 in the order of P_1 , P_2 , P_3 , P_4

- **RR scheduling Gantt Chart:**

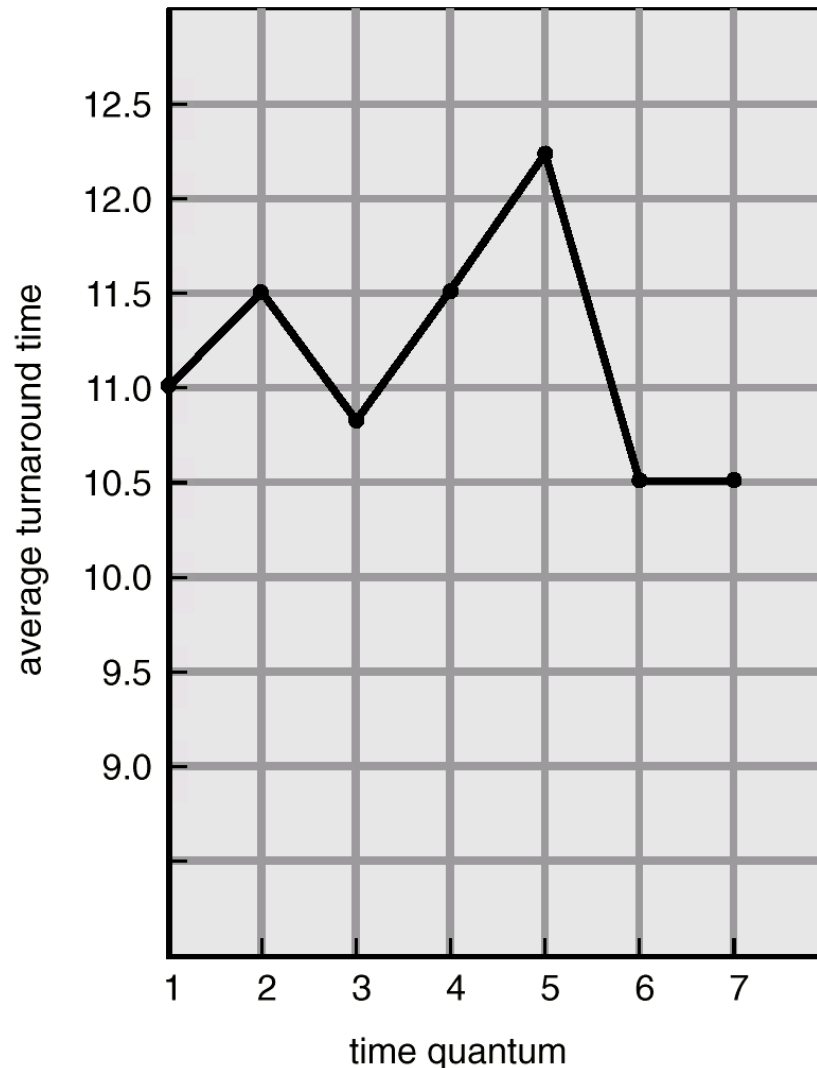


- Typically, higher average waiting/turnaround time than SJF, but better *response time*

Smaller Time Quantum Increases Context Switches



Turnaround Time Varies With Time Quantum



process	time
P_1	6
P_2	3
P_3	1
P_4	7

Assume arrival order is P_1 , P_2 , P_3 , P_4 all at time 0

- No well-defined relationship between average turnaround time and quantum size
- Average turnaround time remains fixed once quantum size is larger than maximum CPU burst length



Multilevel Queue Scheduling

- Different processes have different requirements
 - Foreground processes like those handling I/O need to be interactive (**RR is preferred**)
 - Background processes need NOT be interactive; scheduling overhead can be low (**FCFS**)
- **Solution: Multi-level Queue Scheduling**
 - Ready queue is partitioned into several queues
 - Each queue has its **own scheduling algorithm**
 - **How to schedule among the queues?**



Multilevel Queue Scheduling (Cont.)

- Two schemes for inter-queue scheduling
 - Fixed priority scheduling
 - Queues served in priority order (e.g., foreground before background)
 - Starvation for lower priority queues
 - Time-slice based scheduling
 - Each queue gets a fixed time quantum on the CPU (e.g., 80ms for foreground, 20ms for background, and then repeat)



Scheduling Algorithms: Multiprocessor System

1. Partitioned Scheduling (Asymmetric Multiprocessing - AMP)
2. Global Scheduling (Symmetric Multiprocessing - SMP)

We assume a multi-core CPU and that each process may only execute on one CPU core at any time instant



Partitioned Scheduling (AMP)

- Processes are partitioned apriori (at process creation time) among CPU cores
 - Each process is mapped to one core
 - Separate uniprocessor CPU scheduling for each core (**asymmetric scheduling**)
- Advantages
 - Core-specific scheduling strategy is feasible (FCFS, SJF, RR, multi-level, etc.)
 - Easy and simple extension of uniprocessor CPU scheduling to multiprocessor CPU scheduling



Partitioned Scheduling: Issues

- How to map cores to processes?
 - Poor mapping can lead to unequal loads: a core is idling while another is overloaded
 - May reduce system/process performance
 - **NP-Hard problem**: Similar to the well-known knapsack problem!
 - Heuristics such as best-fit could be used if CPU burst lengths are known



Global Scheduling (SMP)

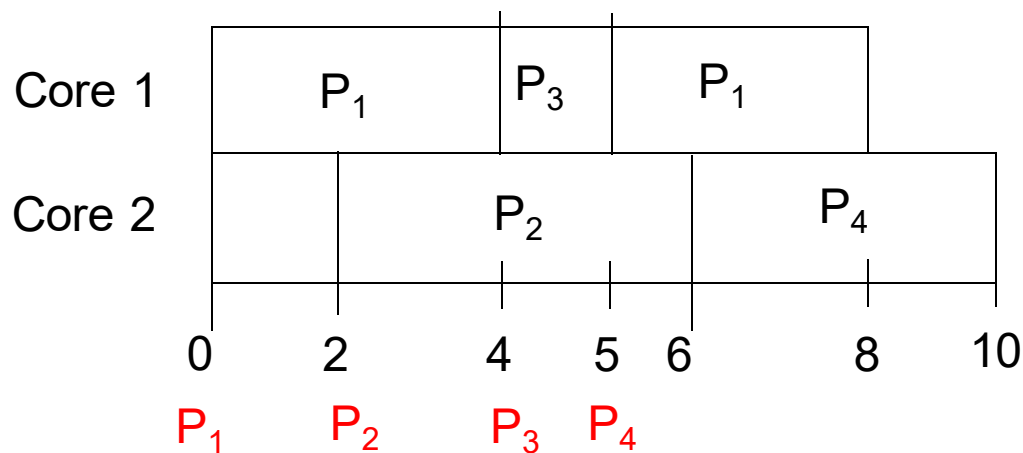
- One or more ready queues for the entire system (no mapping of queues to CPU cores)
 - When any core becomes idle, CPU scheduler runs and allocates the next process to execute
 - Process selection based on strategy applied globally or **symmetrically** across all cores (FCFS, SJF, etc.)
 - It is possible that the same process may execute on different cores at different times

No core-process mapping problem!

Example of SRTF (dual-core)

<u>Process</u>	<u>Arrival Time</u>	<u>Burst Time</u>
P_1	0.0	7 \rightarrow 3 \rightarrow 0
P_2	2.0	4 \rightarrow 0
P_3	4.0	1 \rightarrow 0
P_4	5.0	4 \rightarrow 0

- **SJF (Preemptive) on dual-core Gantt Chart:**



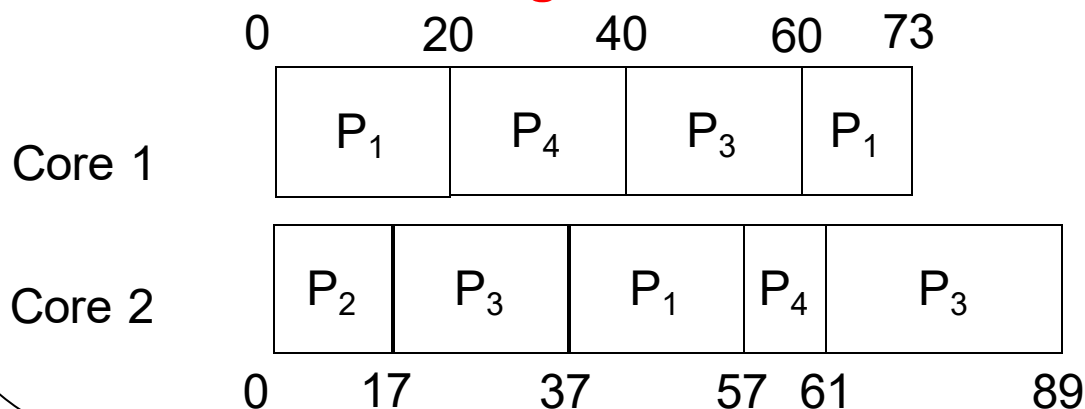
- Average waiting time = $(1 + 0 + 0 + 1)/4 = 0.5$

Example of RR with $q = 20$ (dual-core)

<u>Process</u>	<u>Burst Time</u>
P_1	53 \rightarrow 33 \rightarrow 13 \rightarrow 0
P_2	17 \rightarrow 0
P_3	68 \rightarrow 48 \rightarrow 28 \rightarrow 0
P_4	24 \rightarrow 4 \rightarrow 0

- All processes come at time 0 in the order of P_1 , P_2 , P_3 , P_4

• RR scheduling dual-core Gantt Chart:





Global Scheduling: Issues

- Implementation **complexity** is high when compared to partitioned scheduling
 - Need to synchronize clocks across cores
 - Global strategy for process selection combining all the cores
- Implementation **overhead** is high when compared to partitioned scheduling
 - Process could context switch from one core and be scheduled on another (private core-specific cache data needs to be migrated)