

FYS 4411/9411
Computational
Physics 2

F989411

Basics of MC (VMC) calculation

- need a trial wave function (wf)
- need a Hamiltonian.



$$\hat{H} = \hat{H}_0 + \hat{H}_I$$

onebody
operator
(non-interacting)
part

interacting
part
(two-body
three-body)

$$\hat{H}_0 = \sum_{i=1}^N \left(-\frac{\hbar^2}{2m} \vec{r}_i^2 + \hat{N}_{\text{ext}}(\vec{r}_i) \right)$$

number of particles

$$\hat{N}_{\text{ext}} = \frac{1}{2} m \omega^2 r_i^2$$

$$r_i^2 = (x_i^2 + y_i^2 + z_i^2)$$

For one single particle we have an analytical for the harmonic oscillator.

1-Dim ground state

$$\left(-\frac{\hbar^2}{2m} \frac{d^2}{dx^2} + \frac{1}{2} m \omega^2 x^2 \right) \psi(x) = \epsilon_0 \psi(x)$$

$$\epsilon_0 = \hbar \omega (n_x + 1)^{1/2}$$

$$n_x = 0 \Rightarrow \epsilon_0 = \frac{1}{2} \hbar \omega$$

$$\psi(x) \Rightarrow \psi_0(x) = d e^{-\frac{1}{2} w^2 x^2}$$

$$\psi_0(x) \sim e^{-\frac{1}{2} \beta x^2}$$

2 Dim $n_x = n_y = 0$

$$\epsilon_0 = \hbar \omega$$

$$\psi_0(x) \sim e^{-\frac{1}{2} \beta (x^2 + y^2)}$$

3 Dim $n_x = n_y = n_z = 0$

$$\epsilon_0 = \frac{3}{2} \hbar \omega$$

$$\psi_0(x) \sim e^{-\frac{1}{2} \beta (x^2 + y^2 + z^2)}$$

d-Dim

$$\epsilon_0 = \frac{d}{2} \hbar \omega$$

$$\psi_0(x) \sim e^{-\frac{1}{2} \beta r^2}$$

$$r^2 = \sum_{i=1}^d x_i^2$$

general
coordinate.

Ansatz for non-interacting
Bosons -

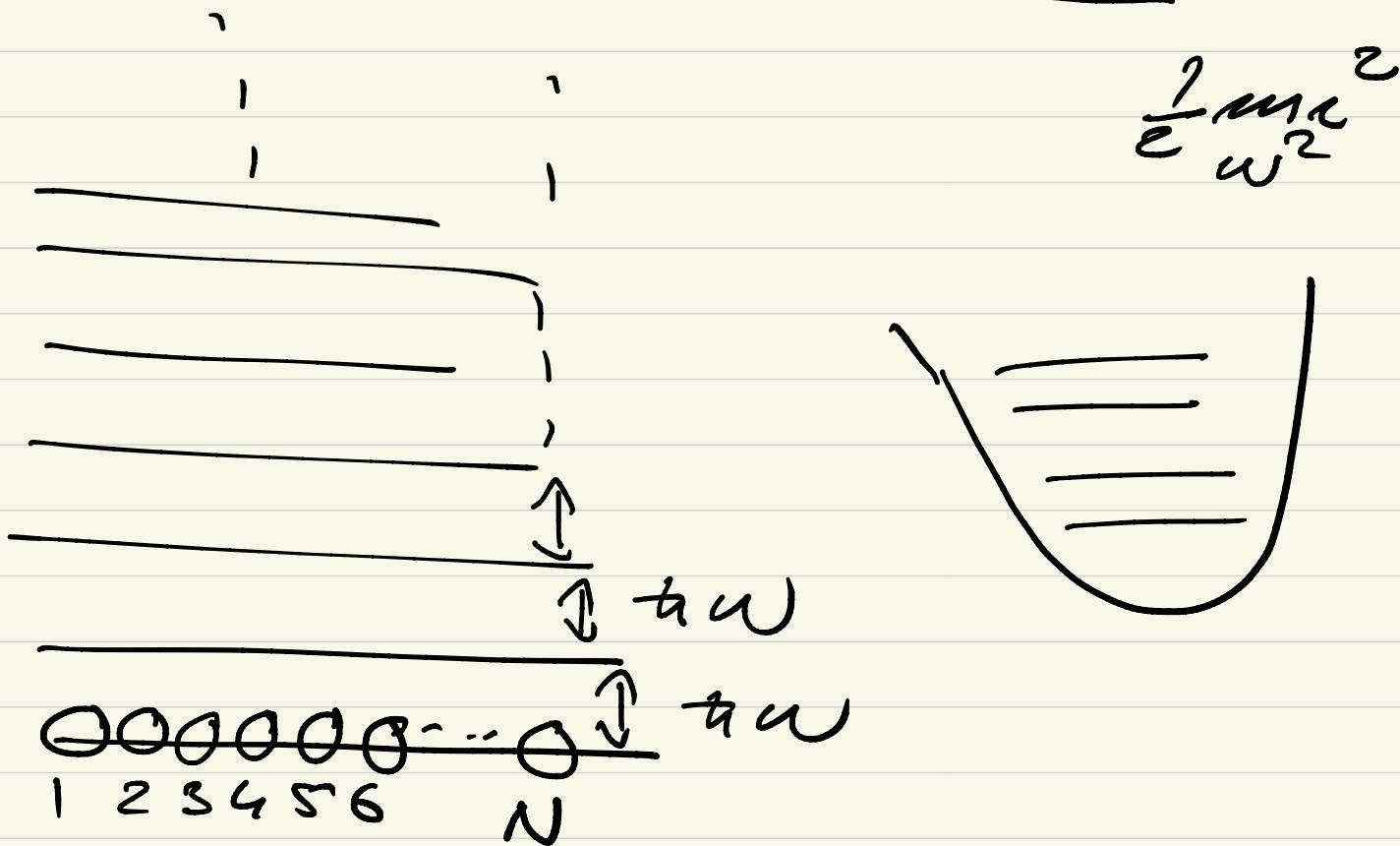
$$\Psi_0(\vec{r}_1, \vec{r}_2, \vec{r}_3, \dots, \vec{r}_N)$$

$$= \prod_{i=1}^N e^{-\frac{1}{2}B r_i^2}$$

analytical

$$\hat{H}_0 \Psi_0 = E_0 \Psi_0$$

$$= \boxed{N \cdot \frac{\hbar}{2} \tau \omega}$$



VMC approach:

Basic element we want
to evaluate

$$| E[H] = \frac{\int d\vec{r} \psi_T^* H \psi_T}{\int d\vec{r} \psi_T^* \psi_T}$$
$$d\vec{r} = d\vec{r}_1 d\vec{r}_2 d\vec{r}_3 \dots d\vec{r}_N$$

$$\psi_T = \psi_T(\vec{r}; \vec{\beta})$$

↑
quantum
numbers

↓
variational
parameters

$$\min_{\vec{\beta}} |E[H]|$$

How can we evaluate $E[H]$ as a function of $\vec{\beta}$?

We want to rewrite in terms of $\int d\vec{r} \gamma P_E$ PDF

$$E[A] = \int d\vec{r} \gamma P(\vec{r}; \vec{\beta}) A(\vec{r}, \dots)$$

Define $P(\vec{r}; \vec{\beta})$

$$= \frac{1}{\int d\vec{r} |4_T(\vec{r}; \vec{\beta})|^2}$$

Define the local energy

$$E_L(\vec{r}; \vec{\beta}) = \frac{1}{4_T} H \frac{1}{4_T} 4_T$$

$$E[H] = \frac{\int d\vec{r} \gamma 4_T^* H 4_T}{\int d\vec{r} \gamma |4_T|^2}$$

$$E[\bar{H}] = E[\bar{E}_L(\vec{\beta})] =$$

$$\int d\vec{r} \hat{P}(\vec{r}; \vec{\beta}) E_L(\vec{r}; \vec{\beta}) \\ \simeq \frac{1}{M} \sum_{i=1}^M E_L(\vec{r}_i; \vec{\beta})$$

↗

Monte Carlo sampling

= Randomly selected positions

$$\vec{r}_i = (r_1^{(i)}, r_2^{(i)} \\ \dots \quad r_N^{(i)})$$

Ingredients in VMC

$$\boxed{\bar{E}_L} = \frac{1}{4\pi} \boxed{H - 4\frac{1}{r}}$$

$$= \frac{1}{4\pi} \left[\sum_{i=1}^N \left(-\frac{e^2}{2m} \vec{D}_i^2 + \vec{V}_{ext}(\vec{r}_i) \right) + H_I \right] \times \frac{1}{4\pi}$$

1)

$$\frac{1}{4\pi} \left[\sum_{i=1}^N -\frac{\vec{t}_i^2}{2m} D_i^2 \right] \chi_{\vec{t}}$$

First one is $\chi_{\vec{t}} =$

$$\frac{N}{\pi} e^{-\frac{1}{2} \beta c_i^2}$$

c_i ,

2)

$$\frac{1}{4\pi} \left[\sum_{i=1}^N \frac{1}{2} m \omega_i^2 r_i^2 \right] \chi_{\vec{t}}$$

\checkmark Ext

$$= \sum_{i=1}^N \frac{1}{2} m \omega_i^2 r_i^2$$

3)

$$\frac{1}{4\pi} \hat{H}_1 \chi_{\vec{t}} = H_1$$

$$(H_1 = \sum_{i < j}^N \sigma(\vec{r}_i - \vec{r}_j))$$

END JAN 16 Lecture, 2020

Kinetic energy

$$\langle T \rangle \approx \frac{1}{M} \sum_{i=1}^N \frac{1}{4\pi} (\vec{r}_i) \left(\sum_{j=1}^N -\frac{\hbar^2}{2m} \right)$$

$$D_j^2 \psi_j(\vec{r}_i)$$

From a single particle j :

$$\frac{1}{4\pi} -\frac{\hbar^2}{2m} D_j^2 \psi_j(\vec{r}_1, \vec{r}_2, \dots, \vec{r}_j, \dots, \vec{r}_w)$$

- Numerically

$$\frac{d^2 u(x)}{dx^2} \approx \frac{u(x+\Delta x) + u(x-\Delta x) - 2u(x)}{(\Delta x)^2}$$

In three/two dims

$$\frac{d^2 u(x, y, z)}{dx^2} =$$

$$u(x, y, z) \rightarrow u(x_i, y_j, z_k)$$

$$= u_{ijk}$$

$$u(x+\Delta x, y, z) = u_{i+1jk}$$

$$1) \frac{\partial^2 u}{\partial x^2} = \frac{u_{i+1,j,k} + u_{i-1,j,k} - 2u_{i,j,k}}{h^2}$$

$$2) \frac{\partial^2 u}{\partial y^2} = \frac{u_{i,j+1,k} + u_{i,j-1,k} - 2u_{i,j,k}}{h^2}$$

reset $x_i + h \rightarrow x'_i$

$x_i - h \rightarrow x'_i$

$u_{i+1,j+1,k}$ instead

of $u_{i,j+1,k}$

- Numerical approach if it is useful to remain near the analytical result?

- Numerical approach if it is too complicated to set up analytical expression(s) with given off

3) For our case

$$\psi_T = \prod_{i=1}^N e^{-\alpha r_i^2} \times \prod_{i < j} \pi f(r_{ij})$$

single-particle part

$$r_{ij} = |\vec{r}_i - \vec{r}_j|$$

central force

correlated part /
correlation part /
Jastrow/Jastrow-Pade'

.....

Same + difficulty with
the analytical expression
for E_L .

VMC code

$$\langle E \rangle = \langle E [E_L] \rangle_{\vec{\alpha}} \approx \frac{1}{M} \sum_{i=1}^M E_L(\vec{r}_i; \vec{\alpha})$$

variance $\sigma_E^2 = \langle E^2 \rangle - \langle E \rangle^2$

need $\langle E^2 \rangle$

$$\sigma_E^2 = \textcircled{1}$$

$\langle E \rangle = \text{unknow}$
don't know the
exact value

if $\psi_T = \psi_{\text{Exact}}$

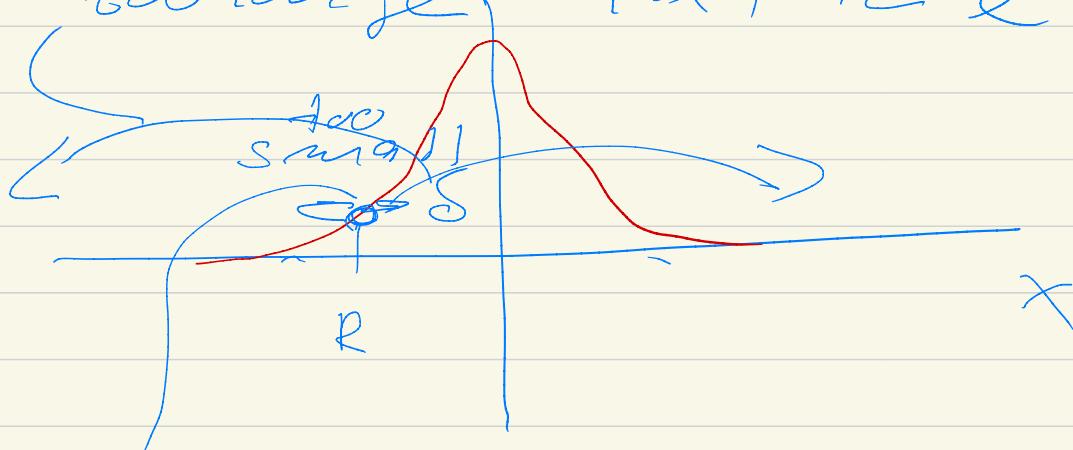
$$\sigma_E^2 = \frac{\int \psi_T^* H \psi_T d\vec{r}}{N} - \left[\frac{\int \psi_T^* H \psi_T d\vec{r}}{N} \right]^2$$

$$\langle E^2 \rangle - \langle E \rangle^2$$

$$H \psi_{\text{Exact}} = E_{\text{Exact}} \psi_{\text{Exact}}$$

We want $E[\bar{E}_L(4\tau)]$ which
as close as possible to the
Exact energy (unknown)
and $\bar{T}_E^2 \rightarrow 0$

Harmonic oscillator 1-dim
too large, $\psi(x) \approx e^{-\frac{1}{2}\alpha^2 x^2}$



when sampling in
space (picking different
configuration/samples)
we make a proposal

$$R' = R + n\delta$$

$$n \in [-0.5, +0.5]$$

$\delta \rightarrow$ has to be tuned
by you?

$$\text{Trial wf } \psi(x_1, x_2, \dots, x_N; \alpha) \\ = \frac{1}{\prod_{i=1}^N} e^{-\frac{1}{2} \alpha^2 x_i^2}$$

$$\begin{aligned} 1-\text{dim} \quad x_i^2 &= r_i^2 \\ 2-\text{dim} \quad r_i^2 &= x_i^2 + y_i^2 \\ 3-\text{dim} \quad r_i^2 &= x_i^2 + y_i^2 + z_i^2 \end{aligned}$$

Harmonic oscillator in 1-dim

$$u(x) = \boxed{x R(x)} \quad | u(x) = x R(x) \\ -\frac{\hbar^2}{2m} \frac{d^2 u}{dx^2} + \frac{1}{2} m \omega_x^2 x^2 u(x)$$

$$= E u(x) \quad u(x) \sim \underline{\frac{x}{\alpha x^2}}$$

Scale equations

$$x = \gamma f \quad [f] = \text{modine}$$

$$[f] = \text{length}$$

$$-\frac{\hbar^2}{2f^2 m} \frac{d^2 u}{df^2} + \frac{1}{2} m \omega_f^2 f^2 u$$

$$x \frac{\cancel{f^2 m}}{\hbar^2} = E u$$

$$-\frac{1}{2} \frac{d^2 u}{dx^2} + \frac{1}{2} \frac{m^2 \chi^4 \omega^2 u}{t^2} = \lambda u$$

$$\lambda = \frac{m^2 \chi^2}{t^2} E$$

$$\frac{m^2 \chi^4}{t^2} \omega^2 = 1 \Rightarrow$$

$$\chi = \sqrt{\frac{t^2 c^2}{m \omega t^2}}$$

Natural length scale
in terms of the physical constants

$$t = c = \ell = m = 1$$

$$\text{choose } \omega = 1$$

$$\chi = 1$$

Metropolis algorithm

Markov Chain PDF : P_i

Markov chain

$$P_i(t+\delta) = \sum_j W(j \rightarrow i) P_j(t)$$

$$P_i^{(n)} = \sum_j W(j \rightarrow i) P_j^{(n-1)}$$

II steps

Transition

probability

We have a model for

$$P_i^{(n)} = \frac{1}{\|x_i\|^2}$$

$$\rightarrow \int \|x_i\|^2 d\tau$$

multi-dimensional case

$$W(j \rightarrow i) = \text{unknown}$$

We can model w

$$w(j \rightarrow i) = \alpha(j \rightarrow i) \overline{T(j \rightarrow i)}$$

↑

acceptance

of proposed

move

The likelihood for a
specific transition

Modified Metropolis
algorithm \Rightarrow

Metropolis-Hastings

algo,

Metropolis (Brute
force)

$$\overline{T}(j \rightarrow i) = \overline{T}(i \rightarrow j)$$

Detailed balance

$$\frac{P_i}{P_j} = \frac{w(G \rightarrow i)}{w(i \rightarrow j)}$$

'known'

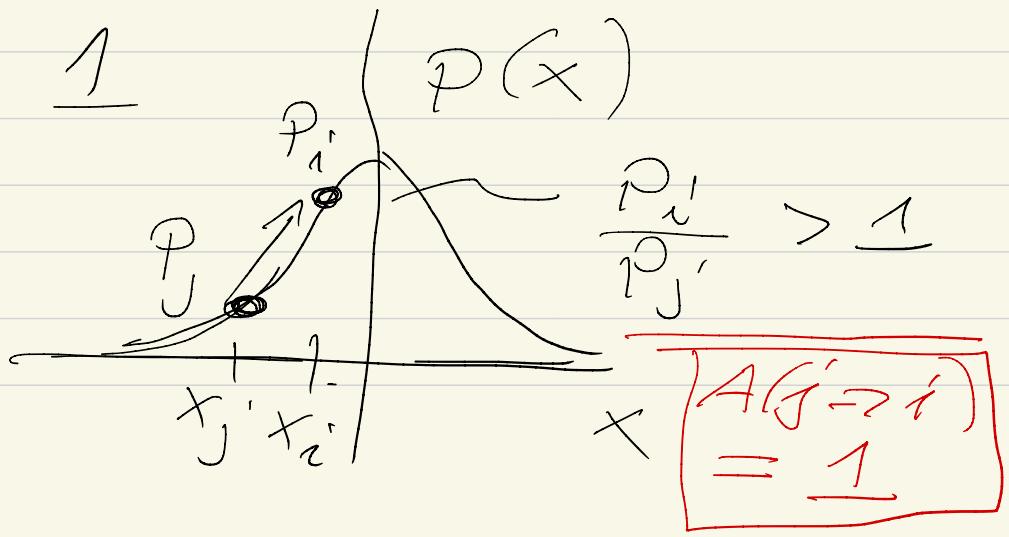
$$V = \frac{A(G \rightarrow i) \tau(j \rightarrow i)}{A(i \rightarrow j) \tau(i \rightarrow j)}$$

$$= \frac{A(G \rightarrow i)}{A(i \rightarrow j)}$$

'unknown'

$$0 \leq A(G \rightarrow i) \leq 1$$

$$\frac{P_i}{P_j} \geq 1$$

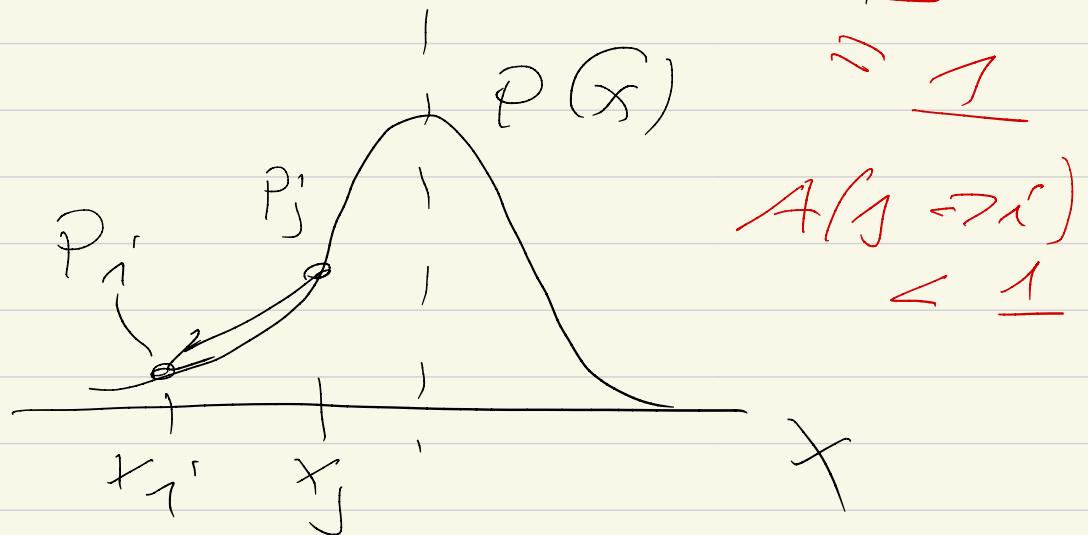


$$A(i \rightarrow j) < 1$$

$$\frac{A(j \rightarrow i)}{A(i \rightarrow j')} > 1$$

$$\frac{A(j \rightarrow i)}{A(i \rightarrow j')} = 1, \text{ stay at the same place}$$

$$\frac{P_i}{P_j} < 1 \Rightarrow \frac{A(j \rightarrow i)}{A(i \rightarrow j)} < 1$$



Metropolis algo

$$A(j \rightarrow i) = \min\left(1, \frac{p_i}{p_j}\right)$$

compute a random number $r \in [0, 1]$
(uniform PDF

accept move if

$$\boxed{r \leq \frac{p_i}{p_j}}$$

$$\bar{T}(j \rightarrow i) = T(i \rightarrow j)$$

$i \not\rightarrow j$ not

Need

$$A(j \rightarrow i) = \text{Model}$$

$$\min\left(1, \frac{p_i \bar{T}(i \rightarrow j)}{p_j T(j \rightarrow i)}\right)$$

How do we model

$\bar{T}(i \rightarrow j)$? \Rightarrow importance

sampling.

$$\bar{T}(i \rightarrow j) = \bar{T} \Rightarrow \bar{T}(\vec{x}, t)$$

use Fokker-Planck eq.

$$\boxed{\frac{\partial \bar{T}}{\partial t} = D \frac{\partial^2}{\partial x^2} \bar{T}(x, t)} -$$

standard dispersion

equations,

$$- D \frac{\partial}{\partial x} \underbrace{F T(x, t)}_{\text{Force}} \quad \begin{array}{l} \text{Drift} \\ \text{force} \end{array}$$

$$F = F(x)$$

$$\frac{\partial \bar{T}}{\partial t} = \sum_i D_i \frac{\partial}{\partial x_i} \left(\frac{\partial}{\partial x_i} \bar{T} - \vec{F}_i \cdot \vec{\nabla} \bar{T} \right)$$

The convergence towards
a stationary state
(equilibrium, rest state
state)

$$\frac{\partial \bar{T}}{\partial t} = 0 =$$

$$\sum_i D \vec{e}_i \cdot \frac{\partial}{\partial x_i} \left(\vec{F}_{i'} - \vec{F}_i \right) \bar{T}$$

zero if

$$\frac{\partial \bar{T}}{\partial x_{i'}^2} = \bar{T} \frac{\partial}{\partial x_{i'}} \vec{F}_{i'} +$$

$$\vec{F}_{i'} \frac{\partial}{\partial x_{i'}} \bar{T}$$

$$\underline{\vec{F}} = g(x) \frac{\partial \bar{T}}{\partial x}$$

$$\frac{\partial^2 \bar{T}}{\partial x_i^2} = \bar{T} \frac{\partial g}{\partial \bar{x}_i} \left(\frac{\partial \bar{T}}{\partial x_i} \right)^2$$

$$+ \bar{T} \cdot g \frac{\partial^2 \bar{T}}{\partial x_e^2} + \\ g \left(\frac{\partial \bar{T}}{\partial x_i} \right)^2$$

Terms containing first and second derivatives have to cancel each other. Only passive

$$\text{if } g = \frac{1}{\bar{T}}$$

$$\Rightarrow \vec{F} = 2 \underset{4\bar{T}}{\cancel{1}} \vec{v}$$

named quantum force.

The solution to the Fokker-Planck equation

$$\frac{\partial \bar{T}}{\partial t} = \sum_i D \frac{\partial^2}{\partial x_i^2} \left(\frac{\partial \bar{T}}{\partial x_i} - F_i \bar{T} \right) T_{G,i}$$

$$\bar{T}(y, x, t) =$$

STATE \xrightarrow{dt} STATE

$$\left(\frac{1}{4\pi D \delta t} \right)^{\frac{1}{2}} \exp \left(- \frac{(y - x - D \delta t F(x))^2}{4 D \delta t} \right)$$

Parameter

Metropolis-Hastings

$$A(x \rightarrow y) =$$

$$\frac{\tau(x \rightarrow y) |\psi_T(y)|^2}{\tau(y \rightarrow x) |\psi_T(x)|^2}$$

$$\frac{\tau(y \rightarrow x) |\psi_T(x)|^2}{\tau(x \rightarrow y) |\psi_T(y)|^2}$$

- Computer simulation aspects

$$\psi_T = \psi_{OB} \psi_C$$



one-body



corelated
part

$$\prod_{i=1}^N e^{-\alpha^2 r_i^2}$$



$$\prod_{i' < j'} g(r_{ij'})$$

$$r_i = \sqrt{x_i^2 + y_i^2 + z_i^2}$$

$i' < j'$

$$r_{ij} = |\vec{r}_i - \vec{r}_j|$$

$$\exp \left\{ \sum_{i < j} f(r_{ij}) \right\}$$

Two particles interacting
via a Coulomb force

$$\prod_{i < j} g(r_{ij}) = \exp \left\{ \pm \frac{r_{12}}{1 + \beta r_{12}} \right\}$$

$$r_{12}$$

Ratio in Metropolis Test
(without Importance
Sampling)

$$\textcircled{1} \quad \frac{|\psi_T^{\text{new}}|^2}{|\psi_T^{\text{old}}|^2} = \frac{|\psi_{OB}^{\text{new}}|^2 |\psi_C^{\text{new}}|^2}{|\psi_{OB}^{\text{old}}|^2 |\psi_C^{\text{old}}|^2}$$

\textcircled{2} quantum force

$$\frac{\nabla \psi_T}{\psi_T} = \frac{\nabla (\psi_{OB} \psi_C)}{\psi_{OB} \psi_C}$$

$$= \frac{D \psi_{OB}}{\psi_{OB}} + \frac{D \psi_C}{\psi_C}$$

two particles

$$\frac{1}{\psi_{OB}} \sum_{i=1}^2 D_i \psi_{OB}$$

$$\psi_{OB} = e^{-\alpha^2(r_1^2 + r_2^2)}$$

$$= e^{-\alpha^2(x_1^2 + x_2^2)}$$

$$e^{-\alpha^2(x_1^2 + x_2^2)} \left[-\alpha^2 z x_1 - \alpha^2 z x_2 \right]$$

$$e^{-\alpha^2(x_1^2 + x_2^2)} \quad \text{gradient}$$

$$\boxed{= -\alpha^2 z x_1 - \alpha^2 z x_2}$$

③ $\langle k_i \rangle = -\frac{1}{2} \frac{\langle \psi_i | D_i^2 | \psi_i \rangle}{\langle \psi_i | \psi_i \rangle}$

in the local energy
we need

$$\hat{k}_x = -\frac{1}{z} \frac{1}{\psi_1} \nabla_z^2 \psi_T$$

$$\frac{\nabla_z^2 \psi_T}{\psi_T} = \frac{\nabla^2 \psi_{0B}}{\psi_{0B}} + \frac{\nabla^2 \psi_C}{\psi_C} + 2 \frac{\nabla \psi_{0B} \cdot \nabla \psi_C}{\psi_{0B} \psi_C}$$

product of
two gradients