RNN Model to Detect Fire in Videos

BITS F312 Neural Networks and Fuzzy Logic - Assignment 2

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Dataset and Data Pre-processing

Observations about Dataset:

- 60 fire and 60 not-fire RGB videos
 - Each video of different length, framerate, resolution
- Min #frames = 45, Max #frames = 6103

Pre-processing applied:

- Each video should have equal number of frames, (so as to train on a many to one neural network)
- Selected a smaller number of frames, **45 frames** (= min #frames), from each video
- Frames selected uniformly
- The video was downscaled to **128x128** resolution, and then normalized
- Each video can be represented as a numpy array of shape (45, 128, 128, 3)

Model Architecture

- Convolutional Layers: to extract features from video frames
- LSTM Layer: for classifying and predicting based on time series data

Snapshot of Architecture code snippet for details:

Density of layers, Activation functions, Strides in MaxPool layers, Regulariser term, Dropout value

```
inp = Input(x_train[0].shape)
# conv layers
convOut = Conv2D(16, (3, 3), padding='valid', activation='relu', data_format="channels_last")(inp)
convOut = MaxPool3D((1, 2, 2))(convOut)
convOut = Conv2D(8, (3, 3), padding='valid', activation='relu', data_format="channels_last")(convOut)
convOut = MaxPool3D((1, 2, 2))(convOut)
# flatten
flatOut = Reshape((seq_len, -1))(convOut)
# RNN
rnnOut = LSTM(512, return_sequences = False)(flatOut)
# dense layers
denseOut = Dense(256, activation='tanh', kernel_regularizer=tf.keras.regularizers.L2(0.01))(rnnOut)
denseOut = Dropout(0.2)(denseOut)
denseOut = Dense(32, activation='tanh', kernel_regularizer=tf.keras.regularizers.L2(0.01))(denseOut)
out = Dense(1, activation='sigmoid')(denseOut)
model = Model(inputs = inp. outputs = out)
model.compile(optimizer = tf.keras.optimizers.Adam(learning_rate=0.001), loss = 'binary_crossentropy', metrics = ['accuracy'])
print(model.summarv())
```

Model: "model_19"		
Layer (type)		Param #
input_20 (InputLayer)	Alberta Communication Communic	
conv2d_30 (Conv2D)	(None, 45, 126, 126, 16)	448
max_pooling3d_30 (MaxPooling	(None, 45, 63, 63, 16)	0
conv2d_31 (Conv2D)	(None, 45, 61, 61, 8)	1160
max_pooling3d_31 (MaxPooling	(None, 45, 30, 30, 8)	0
reshape_19 (Reshape)	(None, 45, 7200)	8
lstm_19 (LSTM)	(None, 512)	15796224
dense_47 (Dense)	(None, 256)	131328
dropout_19 (Dropout)	(None, 256)	0
dense_48 (Dense)	(None, 32)	8224
dense_49 (Dense)	(None, 1)	33
Total params: 15,937,417 Trainable params: 15,937,417 Non-trainable params: 0		

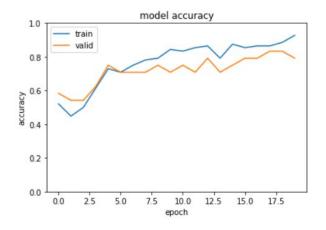
Training of the Model and Results

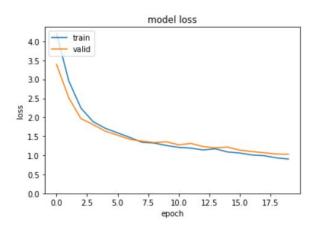
Optimiser: Adam optimiser

Callbacks: Reduce_Ir_on_plateau and Early_stopping

history = model.fit(x_{rain} , y_{train} , validation_data=(x_{valid} , y_{valid}), epochs=20, batch_size=2, callbacks=callbacks)

Plot of Accuracy and Loss curves:





Extra highlights

- Designed a CNN model similar to the one in the previous assignment
- Trained the model on individual frames as independent images
- Calculated the prediction over a few frames per video and classified the video according to the average over all predictions
- Performed very well with greater than 90% training, validation accuracy
- But, does not incorporate sequential analysis

Thank You!

Link to the NB: https://www.kaggle.com/code/arvangupta8501/grp-9-assign-2-lstm?scriptVersionId=81622678