

include/turtlebot/turtlebot.h



```
graph TD; A[include/turtlebot/turtlebot.h] --> B[ros/ros.h]; A --> C[geometry_msgs/Twist.h];
```

The diagram illustrates a C++ header file's dependencies. At the top, a grey box labeled 'include/turtlebot/turtlebot.h' has two blue arrows pointing downwards to two white boxes. The left box is labeled 'ros/ros.h' and the right box is labeled 'geometry\_msgs/Twist.h'.

ros/ros.h

geometry\_msgs/Twist.h