

Measurement Error Models on Spatial Network Lattices: Car Crashes in Leeds

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Introduction

- During the last decade, several authors developed car crashes models to support local authorities. They mainly focused on **areal level lattice models**.
- Recently, we observed a surge of interest in statistical analyses developed on a **network lattice**.

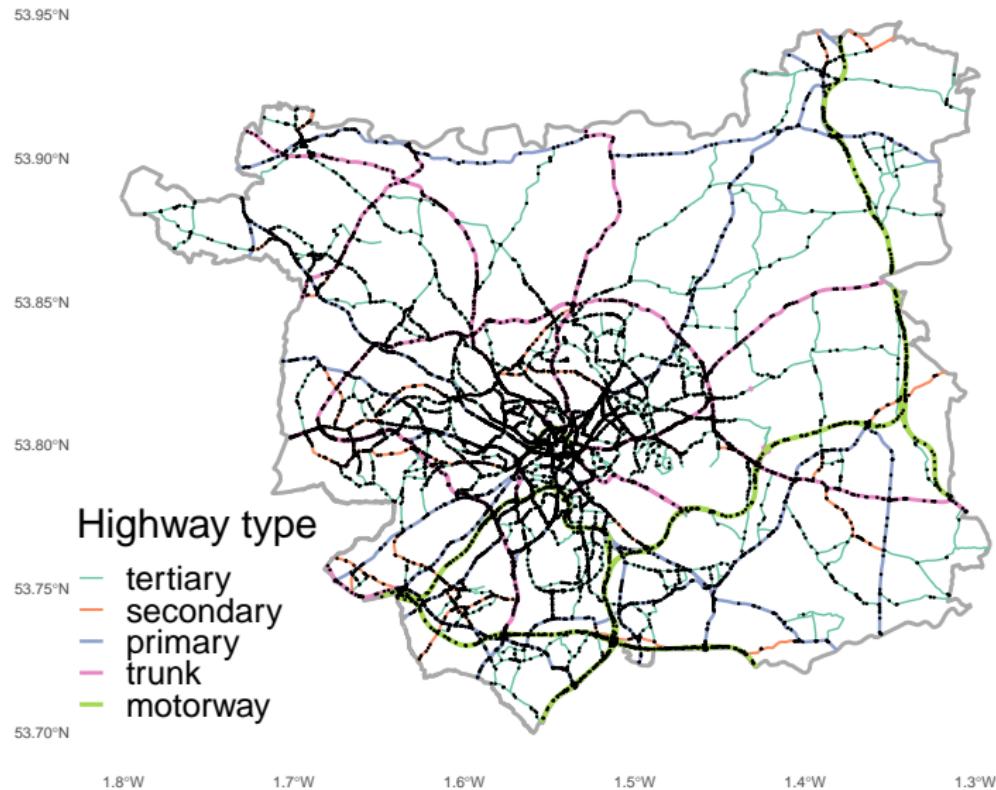
Introduction (cont)

- Several studies suggested that **traffic volumes** represent a key component for estimating road risk indices. Nevertheless, it's difficult to calculate these quantities at the network level.
- Hence, the objective of this paper is to propose a statistical model to estimate **car crashes rates** at the road network level using a **suitable proxy** for the traffic volumes.

Car crashes in Leeds

- We analysed all car crashes that occurred in the major roads of the street network of **Leeds** (UK) from 2011 to 2018. The sample included 13863 events.
- The street network was built using data downloaded from **Open Street Map** (OSM), an open-source online database of vector and raster spatial data.
- First, we filtered only the road segments classified as *motorways, trunks, primary roads, secondary roads, or tertiary roads*. Then, we applied several preprocessing steps to remove isolated clusters of road segments. The final sample included 4176 segments.

Car crashes in Leeds (cont)



Weighted edge betweenness centrality measure

The **weighted edge betweenness centrality measure** (WEBCM) is defined as:

$$C_B(e) = \sum_{s,t \in V} \frac{\varsigma(\pi_{s,t}|e)}{\varsigma(\pi_{s,t})},$$

where:

- e is an edge (i.e. a segment of the street network); s, t are two nodes and V is the set of all vertices.
- $\pi_{s,t}$ represents the shortest path between s and t ;
- $\varsigma(\cdot)$ computes the sum of the weights for a given path;
- $\pi_{s,t}|e$ means that the e th edge belongs to the shortest path between s and t .

Weighted edge betweenness centrality measure (cont)

- Hence, the WEBCM assigns to each edge a value that is proportional to the sum of the weights of the shortest paths going through that edge.
- The weights are given by the geographical length (in metres) of the segments times a **discount factor** proportional to the road types (to penalise local roads).
- Furthermore, the WEBCM suffers an **edge effect bias** due to the exclusion of some road segments located just outside the city boundary.

Weighted edge betweenness centrality measure (cont)

For these reasons, we estimated the edge betweenness centrality considering a buffer of 20 km.

Bayesian Hierarchical Model

- The car crashes counts were modelled using a **full Bayesian hierarchical model** estimated via INLA methodology.
- Let y_i denote the number of car crashes that occurred on the i th road segment. We assumed that

$$y_i | \lambda_i \sim \text{Poisson}(e_i \lambda_i), i = 1, \dots, 4176,$$

where λ_i represents the car crashes rate and e_i is an exposure parameter equal to the geographical length of the segments.

Bayesian Hierarchical Model (cont)

- We specified the following **log-linear model**:

$$\log \lambda_i = \beta_0 + \beta_x x_i + \beta_z z_i + \nu_i, i = 1, \dots, 4176.$$

β_0 denotes the intercept, x_i is the road traffic volumes (i.e. the unobserved covariate), z_i is a set of socio-demographic regressors, and ν_i are spatially structured error terms modelled via a Conditional AutoRegressive (CAR) model.

- More precisely, we assumed that

$$\nu_i | \{\nu_{i'}, i' \in \partial_i\}; \tau_\nu \sim N \left(m_i^{-1} \sum_{i' \in \partial_i} \nu_{i'}, \frac{1}{m_i \tau_\nu} \right)$$

where τ_ν is the marginal precision of the RE while ∂_i and m_i denote, respectively, the indices and the cardinality of the set of neighbours for road segment i .

Bayesian Hierarchical Model (cont)

- The WEBCM represents a proxy for the road traffic and it has an intrinsic spatial error. Hence, we also defined a **measurement error model** connecting the WEBCM and the traffic values:

$$w_i = x_i + \xi_i + u_i, i = 1, \dots, 4176.$$

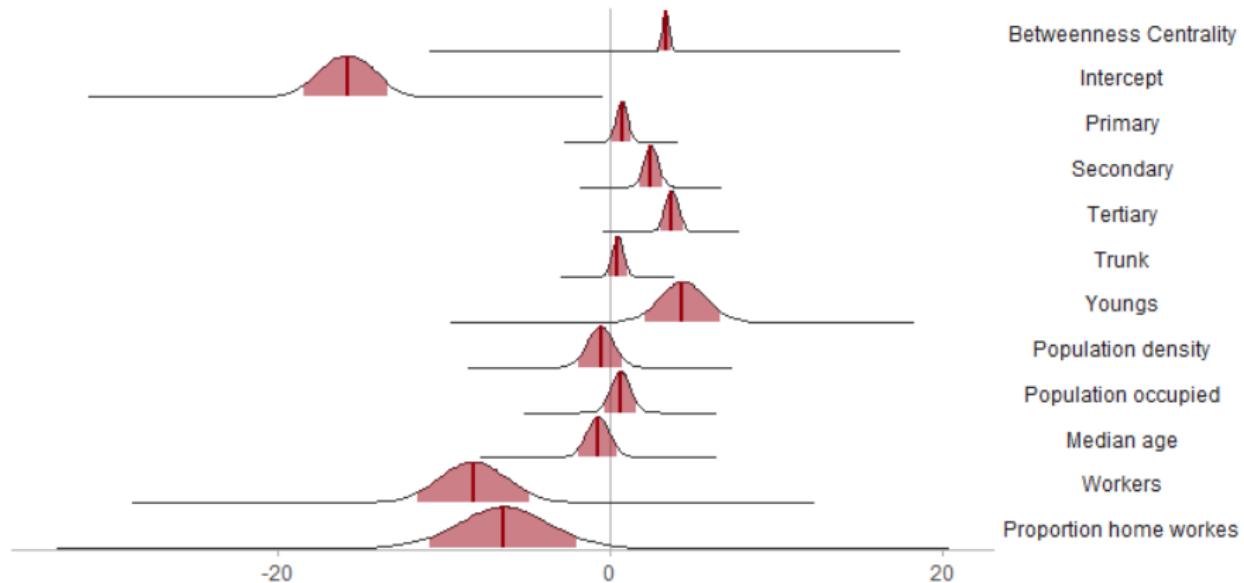
w_i are the estimates of WEBC, ξ_i are unstructured error terms, i.e. $\xi_i \sim N(0, \tau_\xi^{-1})$, and u_i are spatial random errors, i.e. $u_i | \{u_{i'}, i' \in \partial_i\} \sim \text{CAR}$.

- Finally, we included a third model, usually named **exposure model**, including a relationship between the unobserved covariate and the socio-economic regressors:

$$x_i = \alpha_0 + \boldsymbol{\alpha}_z \mathbf{z}_i + \varepsilon_i, i = 1, \dots, 4176$$

The term $\varepsilon_i \sim N(0, \tau_\varepsilon^{-1})$ represents an unstructured error

Results



Results (cont)

The following table summarises the estimates of β_x , i.e. the coefficient of the error-prone covariate.

	β_x	σ_{β_x}	$\beta_x(2.5\%)$	$\beta_x(97.5\%)$
No ME	0.066	0.018	0.032	0.101
ME + no buffer	2.564	0.101	2.364	2.761
ME + buffer	3.367	0.201	2.905	3.850

Conclusions

- It seems that the ME model applied to WEBCM can successfully approximate the unknown road traffic values and represent a relevant determinant for the road risk index.
- The suggested methodology could be extended to a spatio-temporal or multivariate framework. Nevertheless, these extensions are not straightforward due to the increasingly burdensome computational costs.
- In the future, we plan to explore different specifications for the measurement error model.

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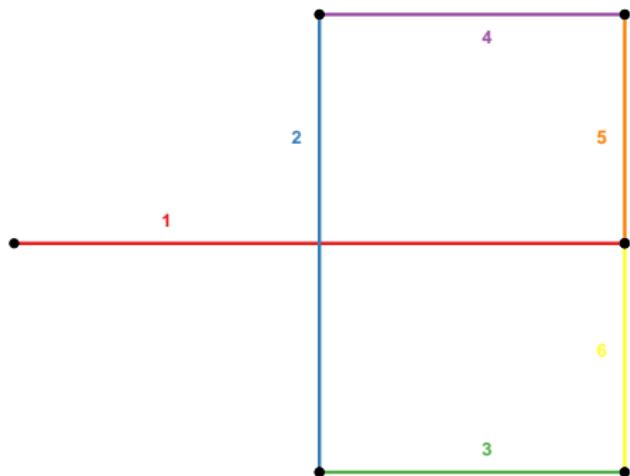
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Supplementary Materials

Spatial network lattice

A street network can be represented at the same time as a spatial object with segments and junctions (left) and a graph object with nodes and vertices (right is the corresponding adjacency matrix).



$$\begin{matrix} & \textcolor{red}{1} & \textcolor{blue}{2} & \textcolor{green}{3} & \textcolor{purple}{4} & \textcolor{orange}{5} & \textcolor{yellow}{6} \\ \textcolor{red}{1} & \cdot & \cdot & \cdot & \cdot & 1 & 1 \\ \textcolor{blue}{2} & \cdot & \cdot & 1 & 1 & \cdot & \cdot \\ \textcolor{green}{3} & \cdot & 1 & \cdot & \cdot & \cdot & 1 \\ \textcolor{purple}{4} & \cdot & 1 & \cdot & \cdot & 1 & \cdot \\ \textcolor{orange}{5} & 1 & \cdot & \cdot & 1 & \cdot & 1 \\ \textcolor{yellow}{6} & 1 & 1 & 1 & \cdot & 1 & \cdot \end{matrix}$$