

CAN脚本使用方法

Open terminal

udevadm info -a -n /dev/ttyACM* | grep serial

```
arx3070t@arx4070t:~$ udevadm info -a -n /dev/ttyACM* | grep serial
ATTRS{serial}=="209738784D4D"
ATTRS{serial}=="0000:00:14.0"
```

Replace serial value

Open arx_can.rules

```
SUBSYSTEM=="tty", ATTRS{idVendor}=="16d0", ATTRS{idProduct}=="117e",
ATTRS{serial}=="2097388F4D4D", SYMLINK+="arxcan0"
```

run set.sh to change rule

And then run can.sh to start can

Finally run X5.sh to run the arm code.