

# **Convergence Analysis of Evolution Strategies with Covariance Matrix Adaptation (CMA-ES) via Markov Chain Stability Analysis**

Blackbox Optimization and Derivative-Free Algorithms

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Armand Gissler

Friday 2<sup>nd</sup> June, 2023

CMAP, École polytechnique & Inria  
(with Anne Auger & Nikolaus Hansen)



# Black-box optimisation and Evolution strategies

Consider the optimisation problem

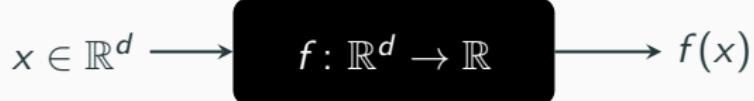
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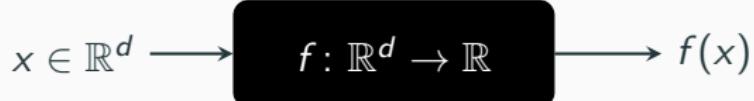


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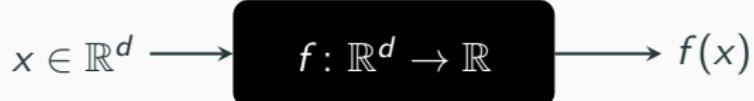
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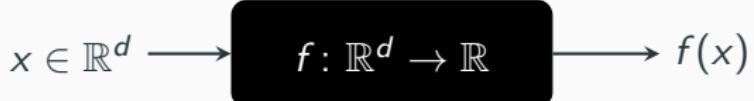
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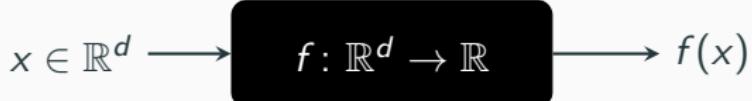
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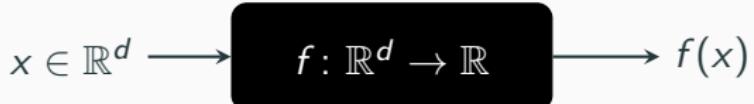
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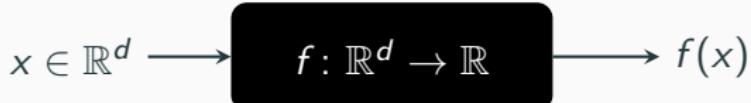
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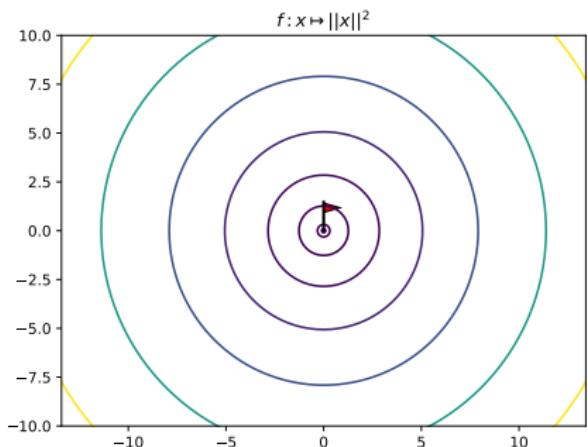
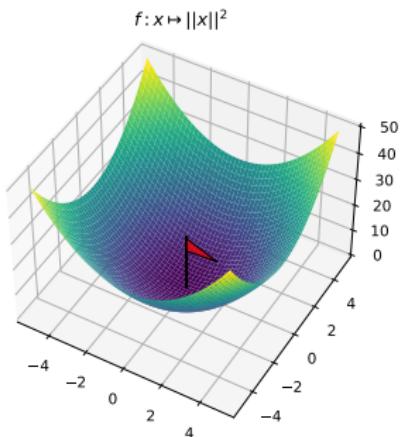
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- **proofs of convergence require additional assumptions so far**

- Without covariance matrix adaptation: Touré et al, *Global linear convergence of Evolution Strategies with recombination on scaling-invariant functions* (2021)
- With a sufficient decrease condition: Diouane et al, *Globally convergent evolution strategies* (2015)
- Assuming that the covariance matrix is bounded: Akimoto et al, *Global linear convergence of evolution strategies on more than smooth strongly convex functions* (2022)
- Using a different update for the covariance matrix: Glasmachers et al, *Convergence analysis of the Hessian estimation evolution strategy* (2022)

## CMA-ES: algorithm presentation

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# Level sets representation



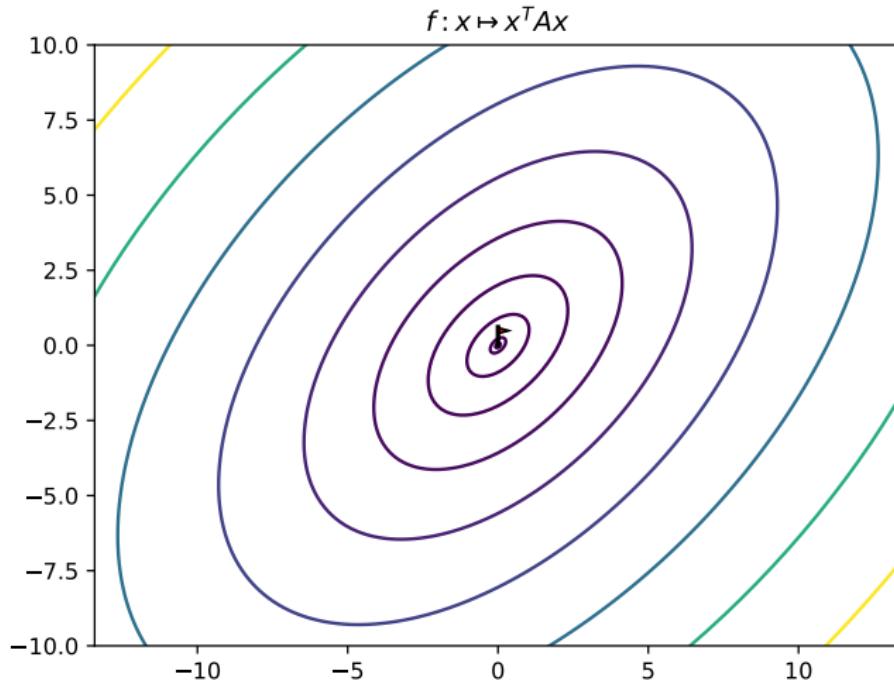
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Principle of Evolution Strategies (ES) : approximate the minimum of the function by a distribution  $\mathcal{N}(m, \sigma^2 C)$ .

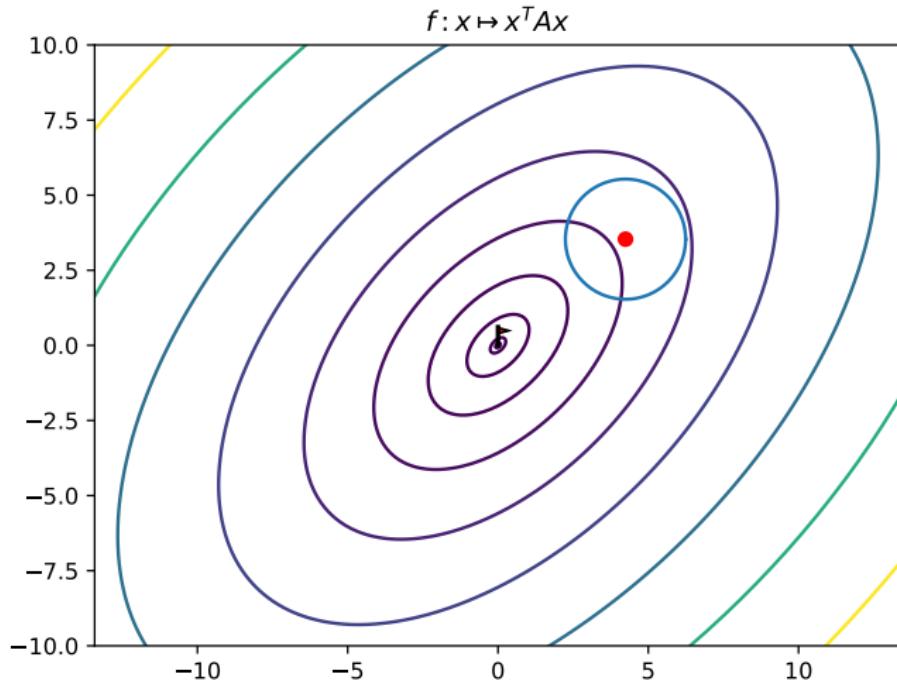
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At each iteration  $t \in \mathbb{N}$ , given a **mean**  $m_t$ , a **stepsize**  $\sigma_t$  and a **covariance matrix**  $C_t$  :

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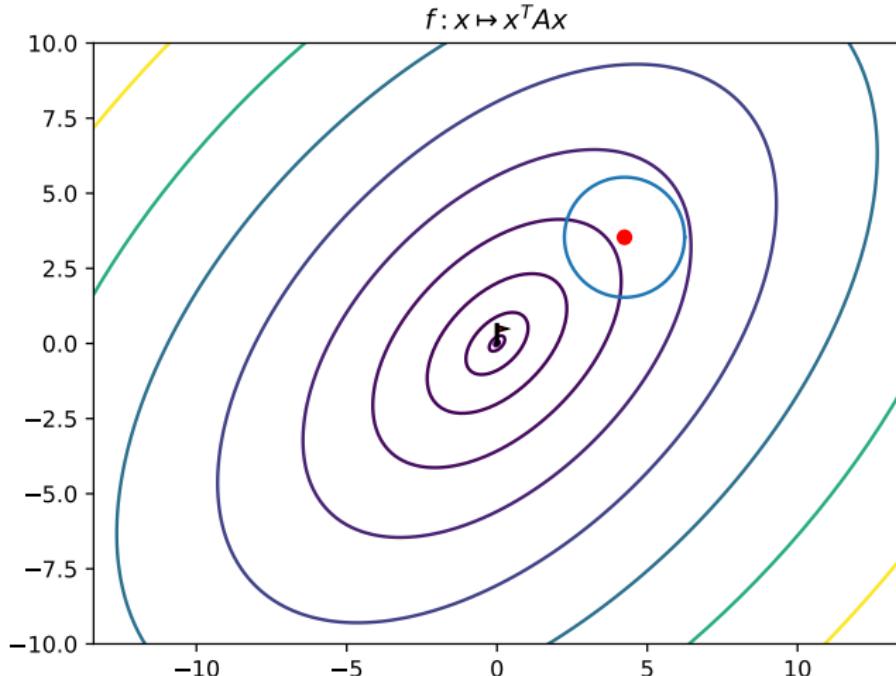
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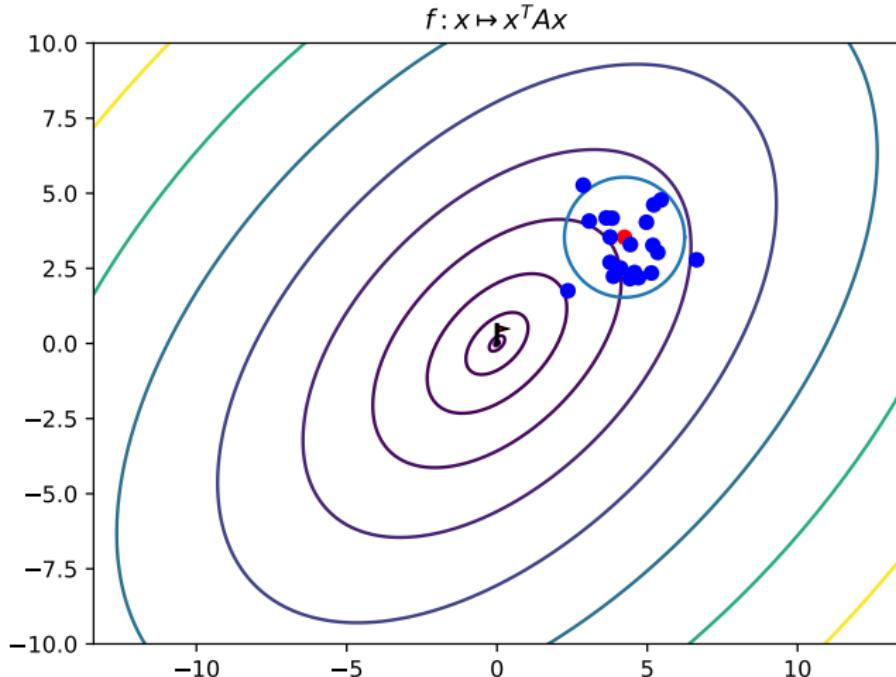
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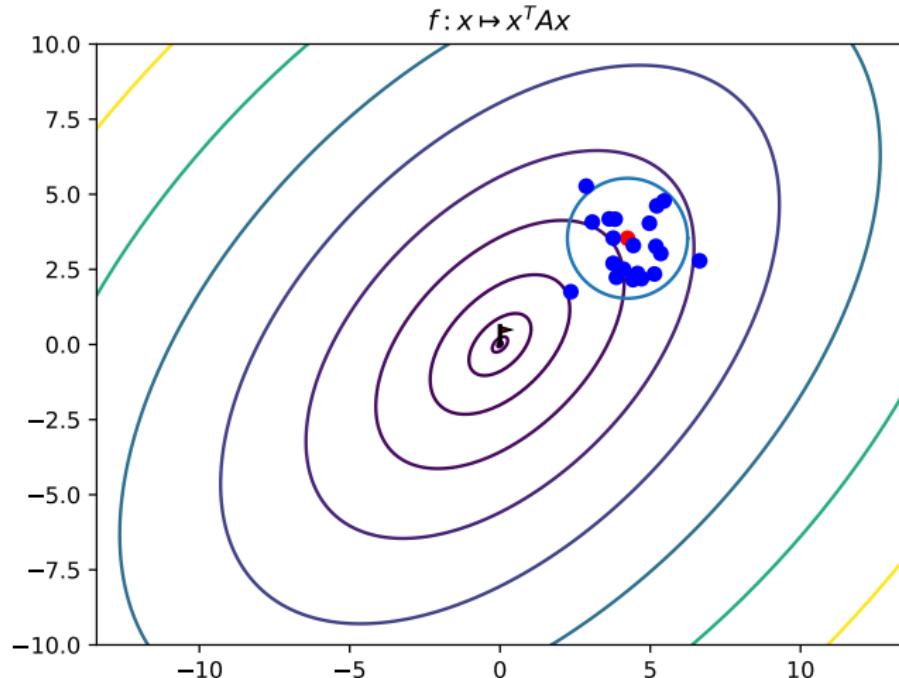
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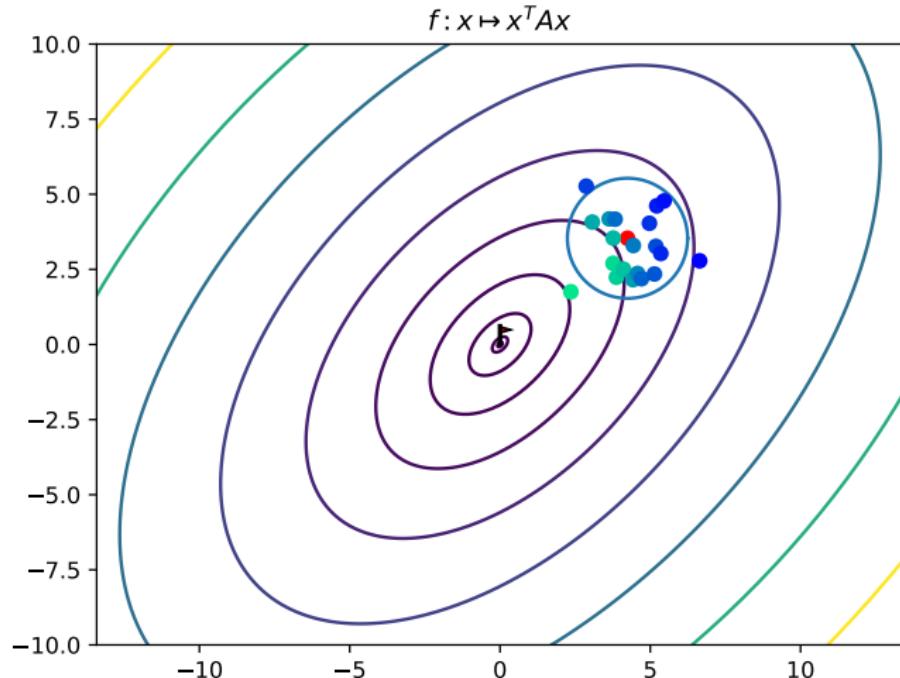
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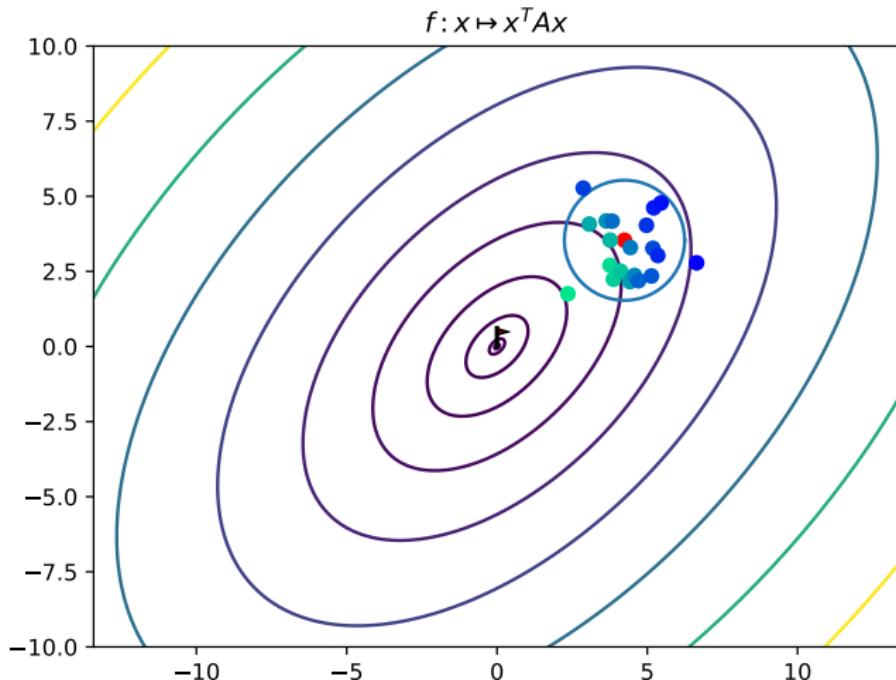
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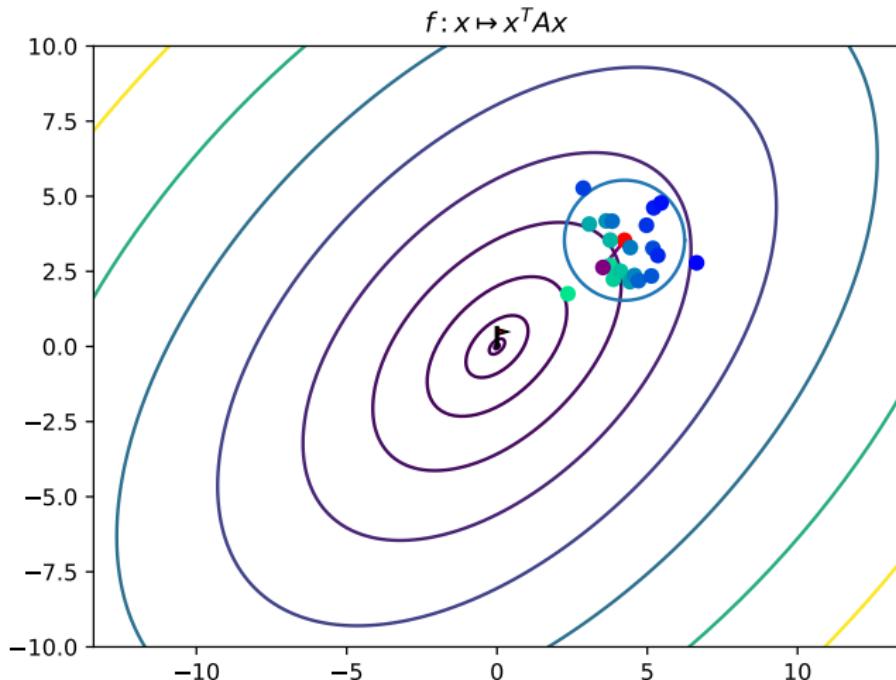
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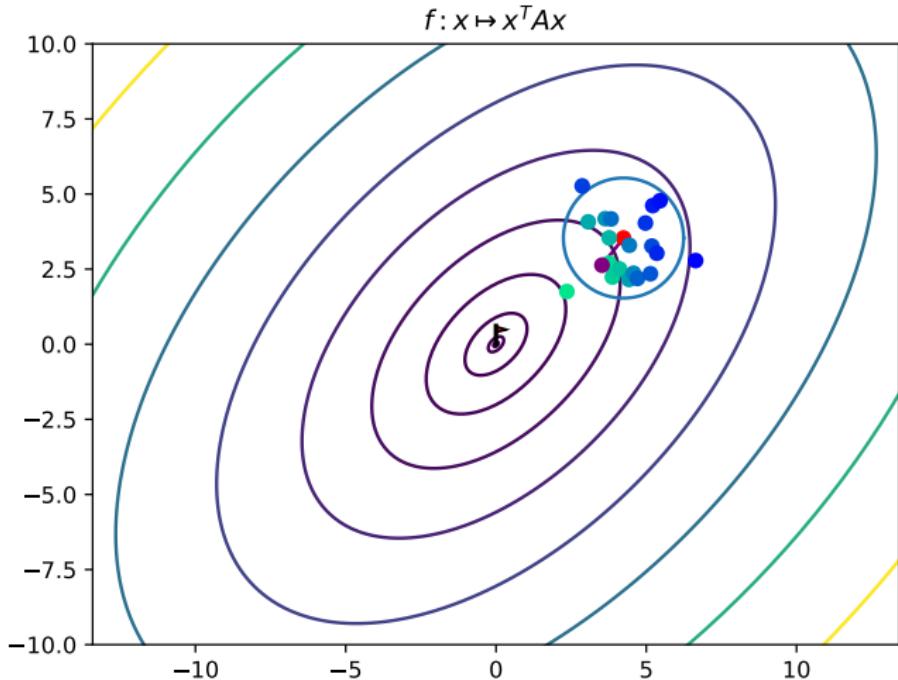
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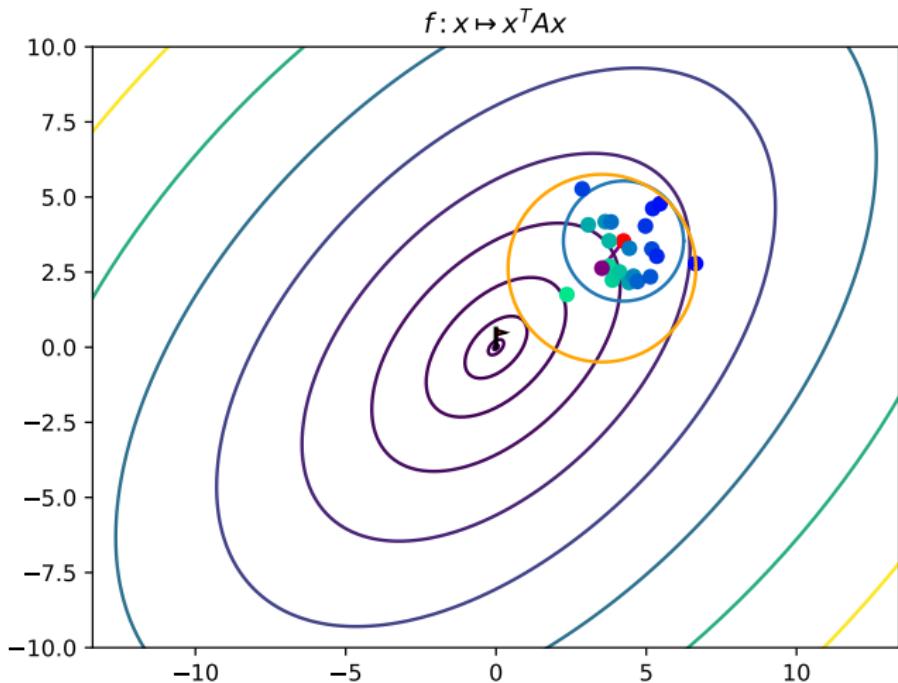
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**Increase** the stepsize if the path taken by the mean is **larger than expected** (assuming no selection)

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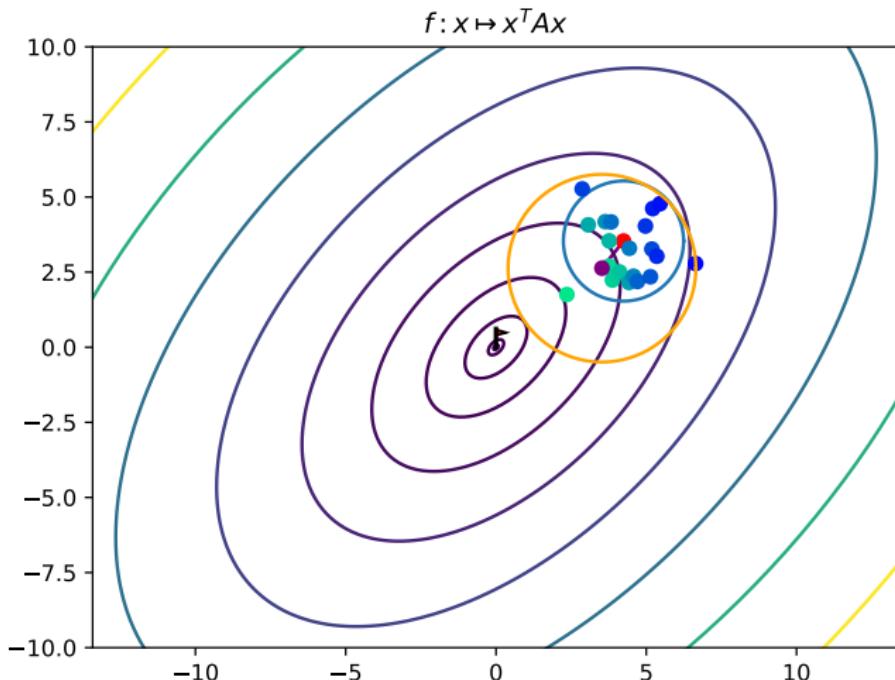
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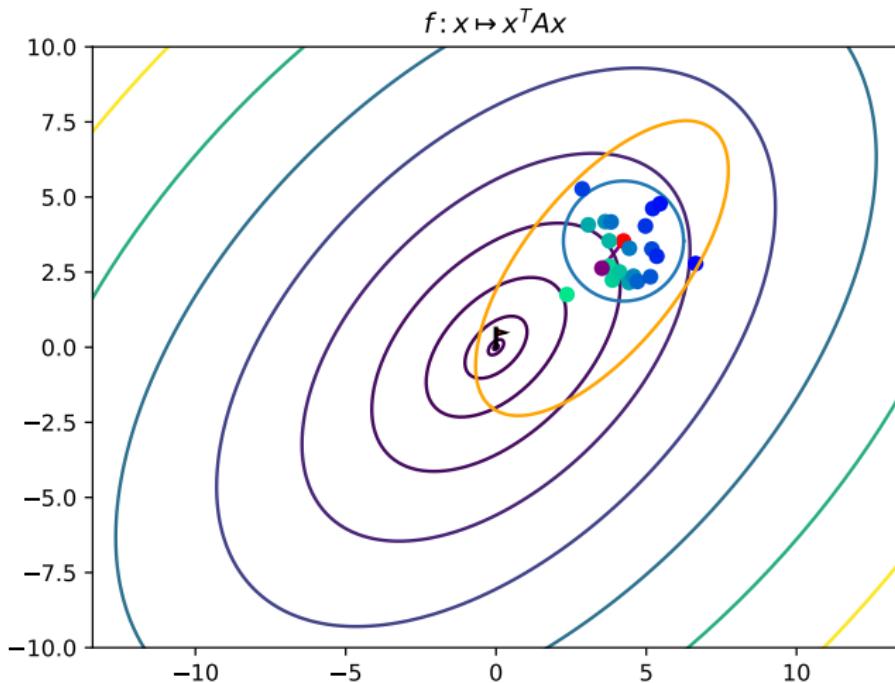
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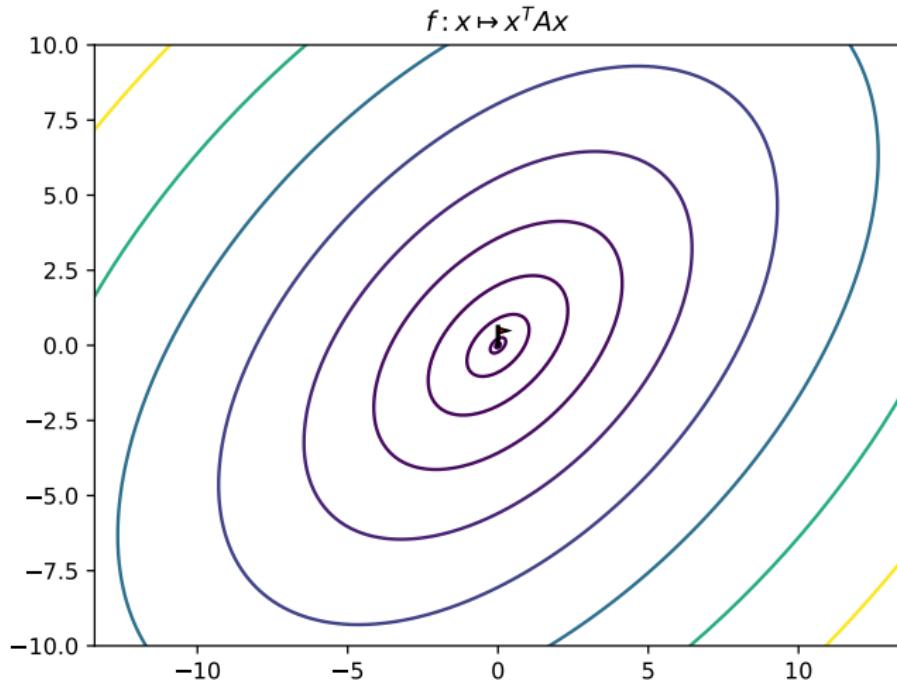
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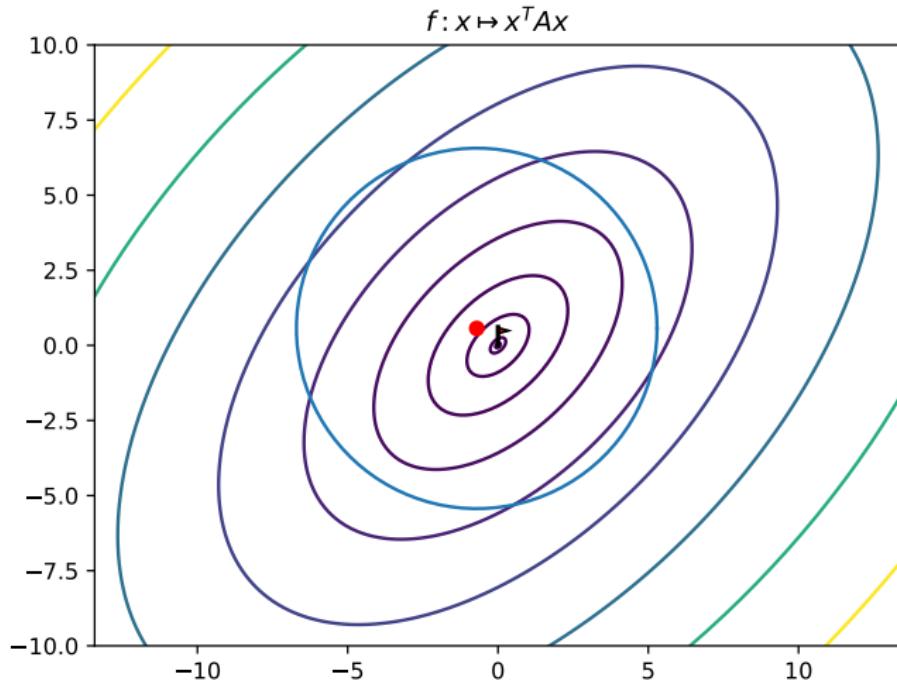
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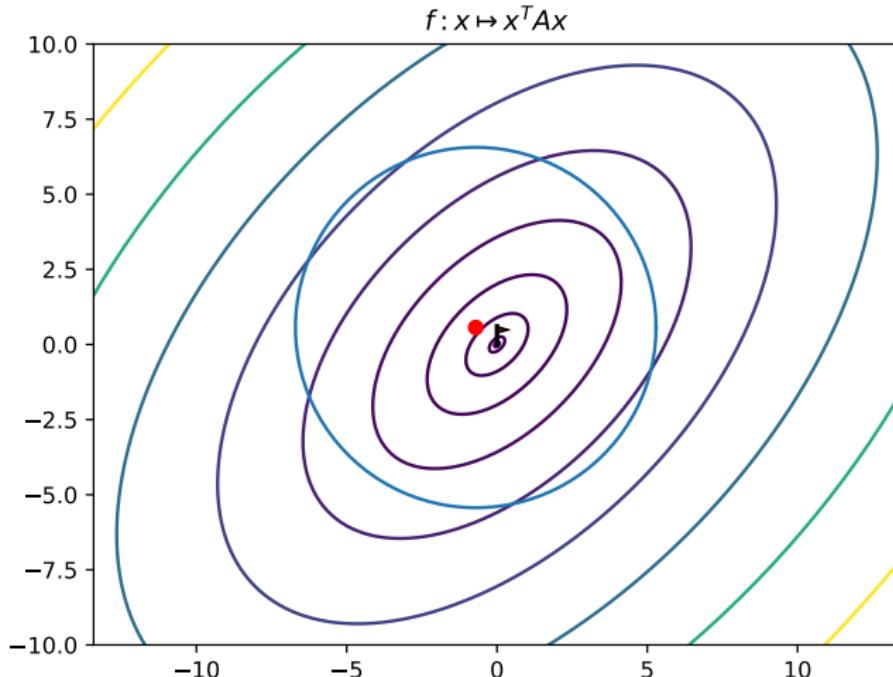
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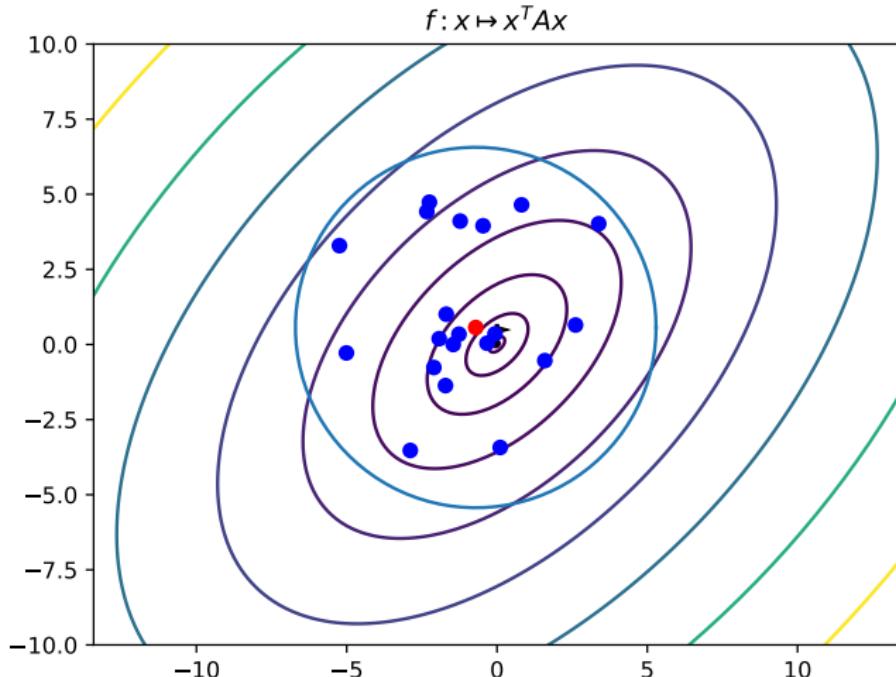
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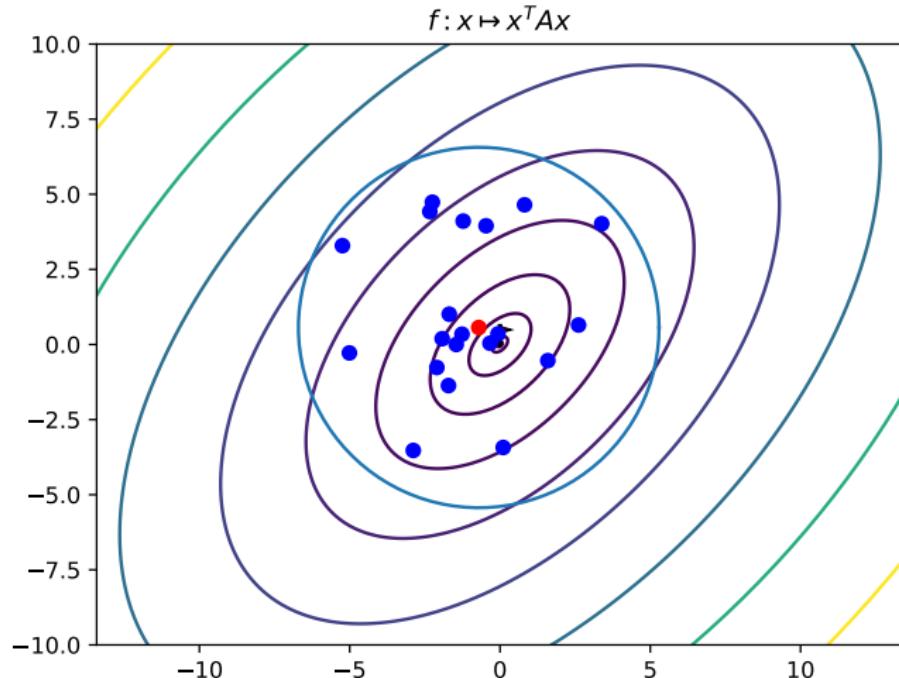
Generate  $\lambda$  offspring  $x_{t+1}^i \sim \mathcal{N}(m_t, \sigma_t^2 C_t)$  independently



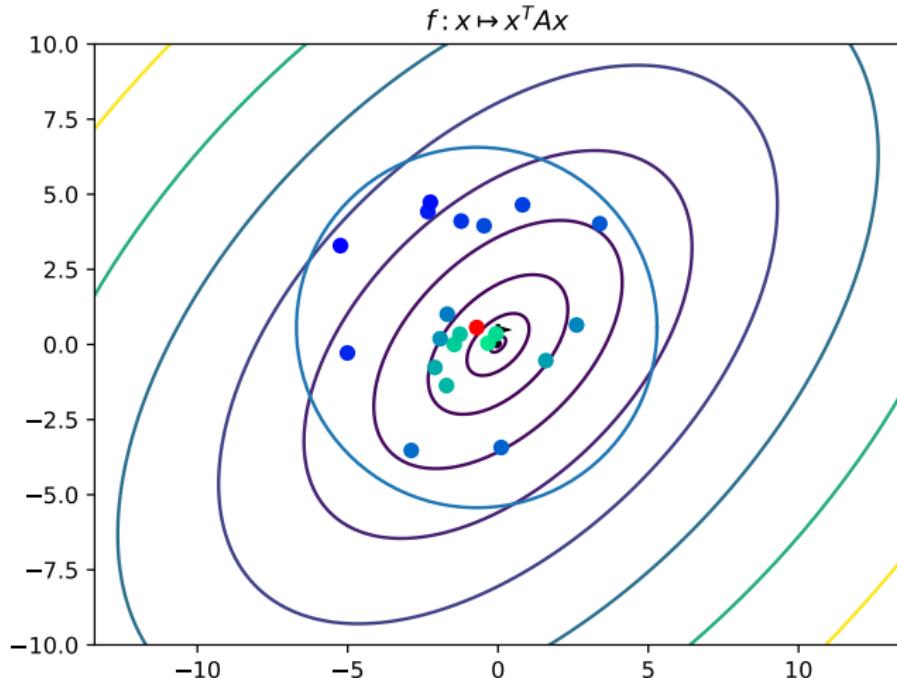
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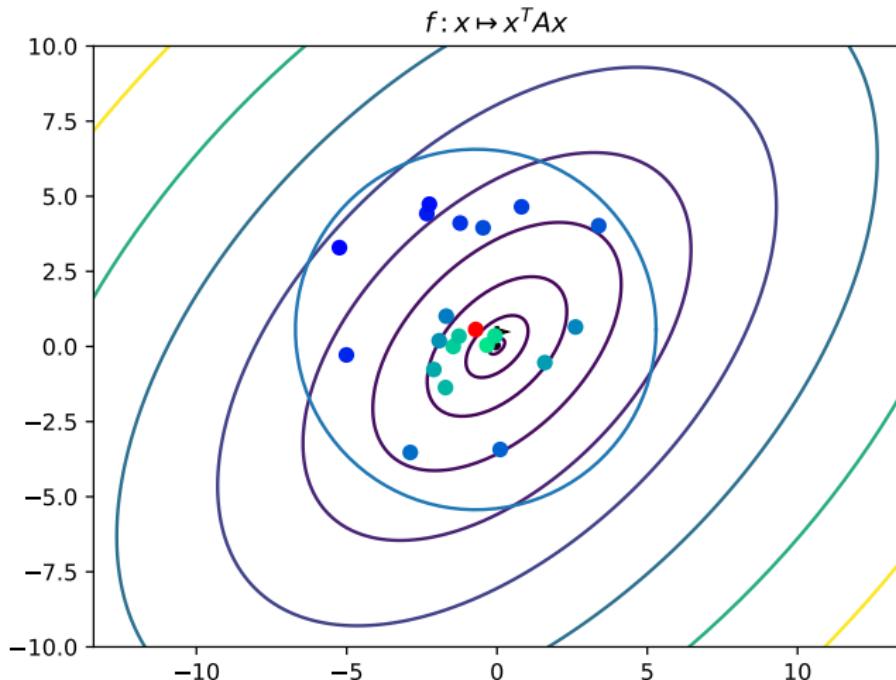
Rank the  $x_{t+1}^i$  w.r.t. their  $f$ -values  $f(x_{t+1}^{1:\lambda}) \leq \dots \leq f(x_{t+1}^{\lambda:\lambda})$



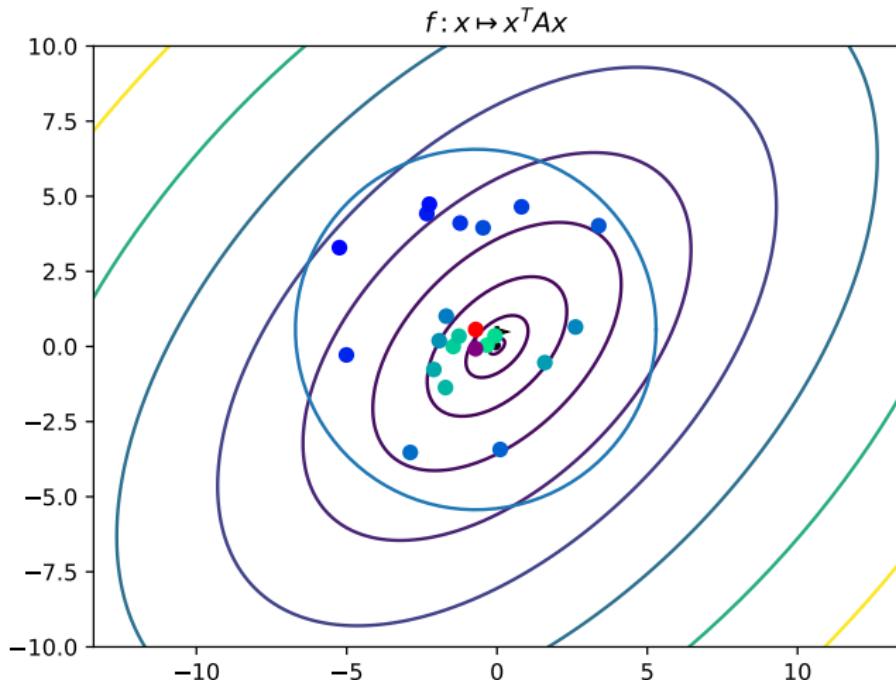
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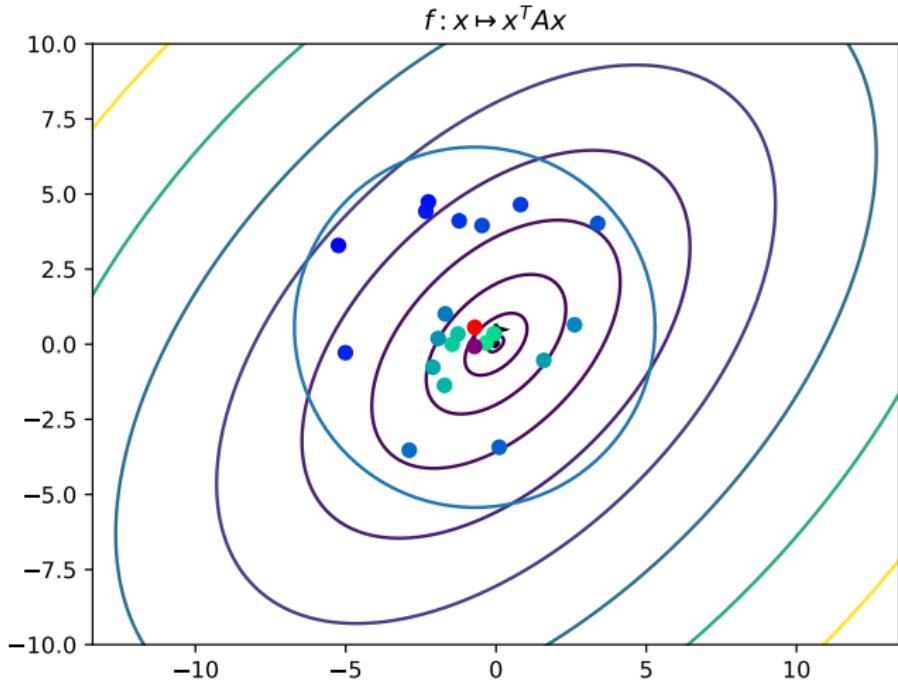
Update the mean  $m_{t+1} = \sum w_i x_{t+1}^{i: \lambda}$



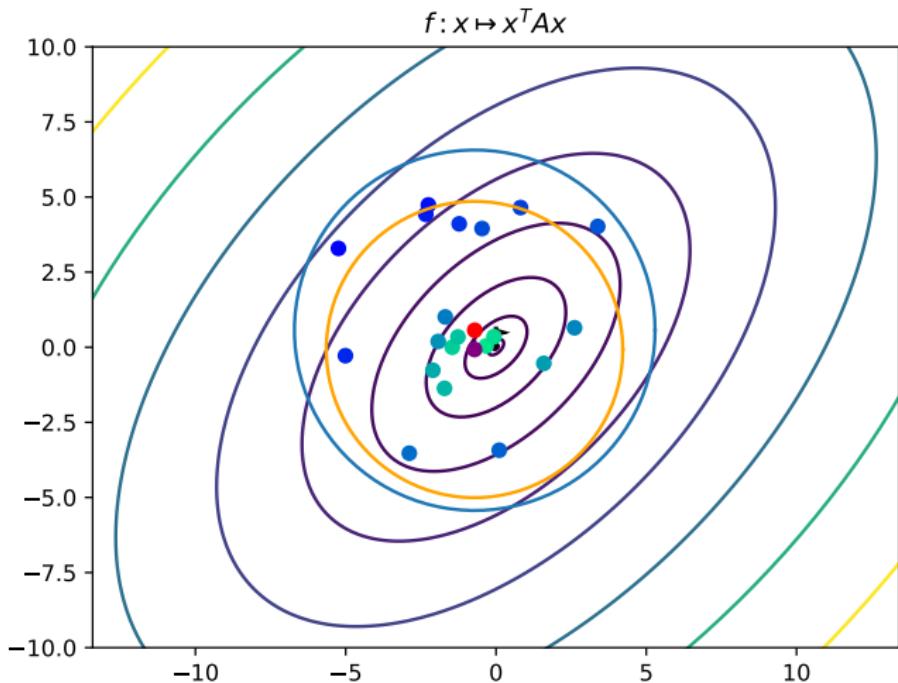
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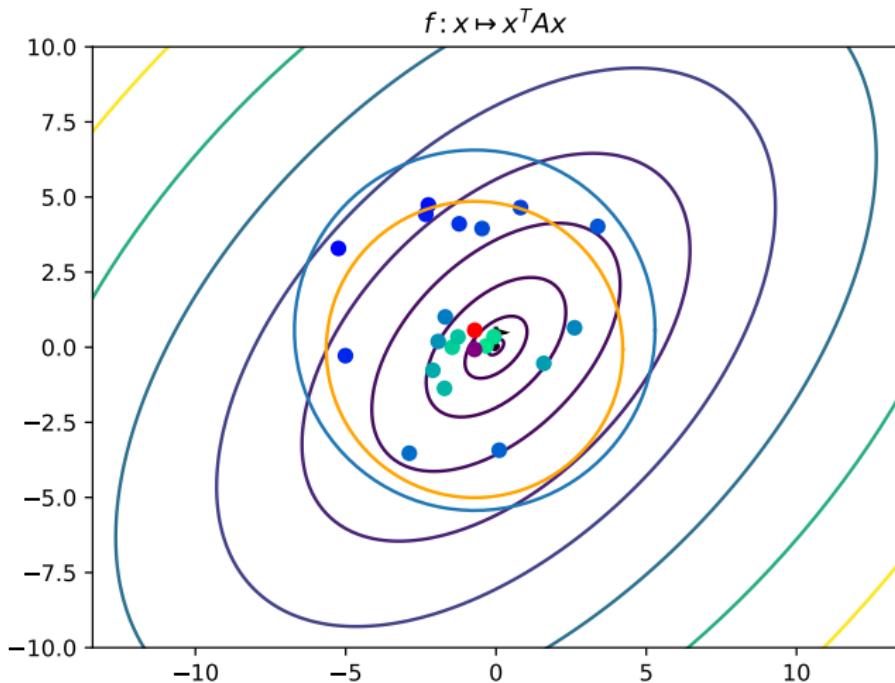
## Adapt the stepsize



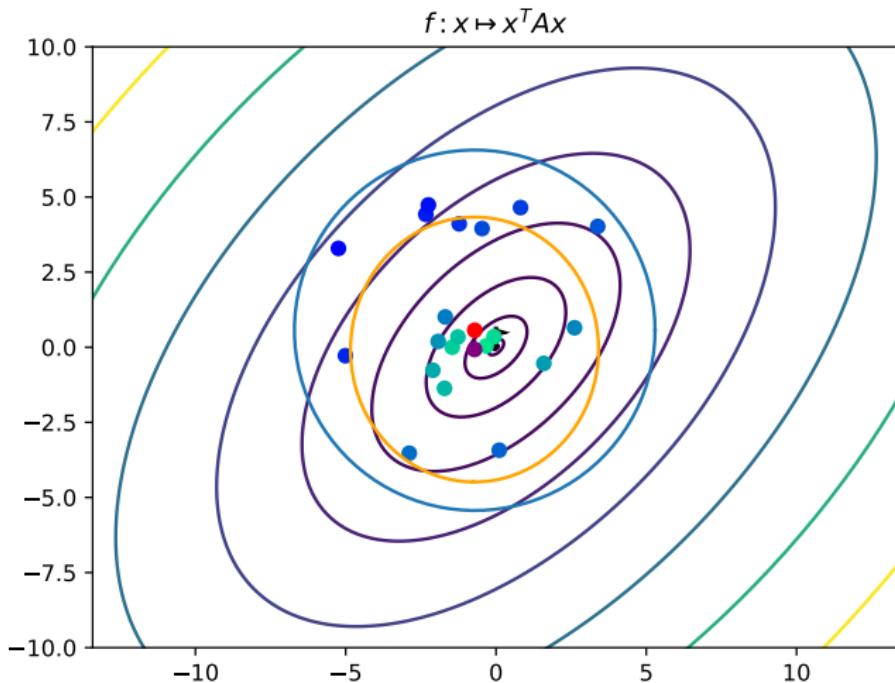
## Adapt the stepsize



## Adapt the covariance matrix



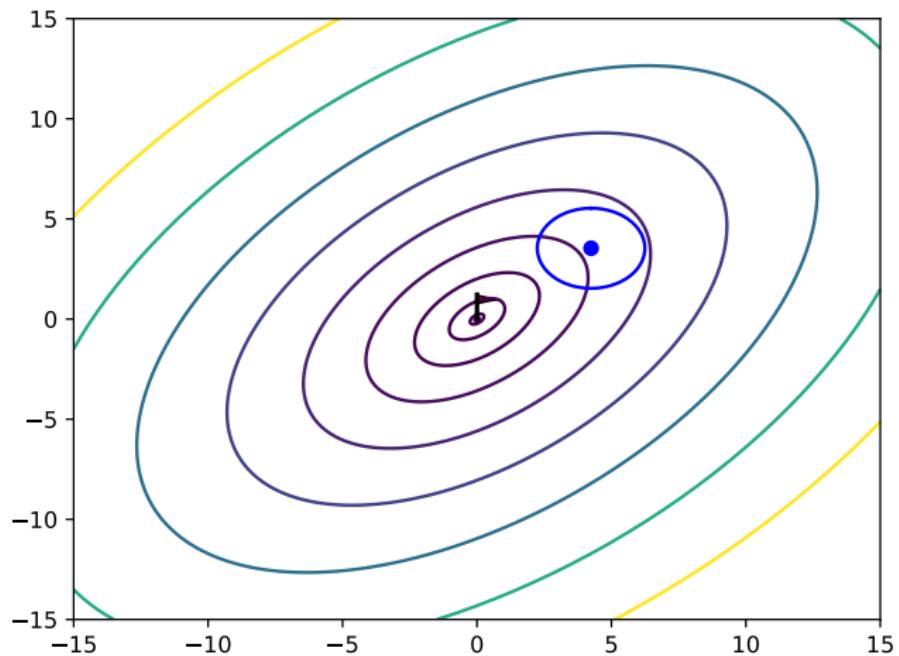
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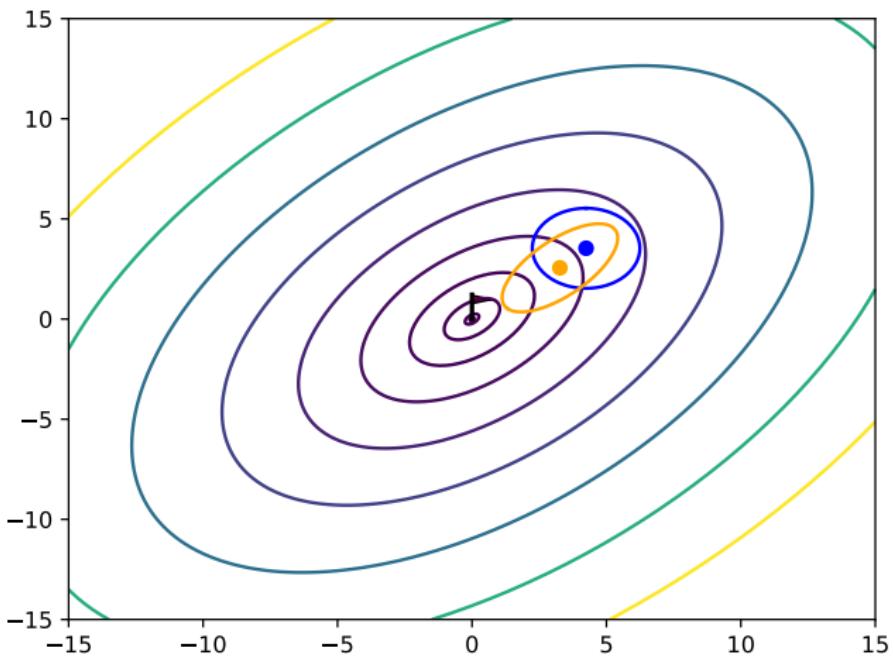
## Linear convergence

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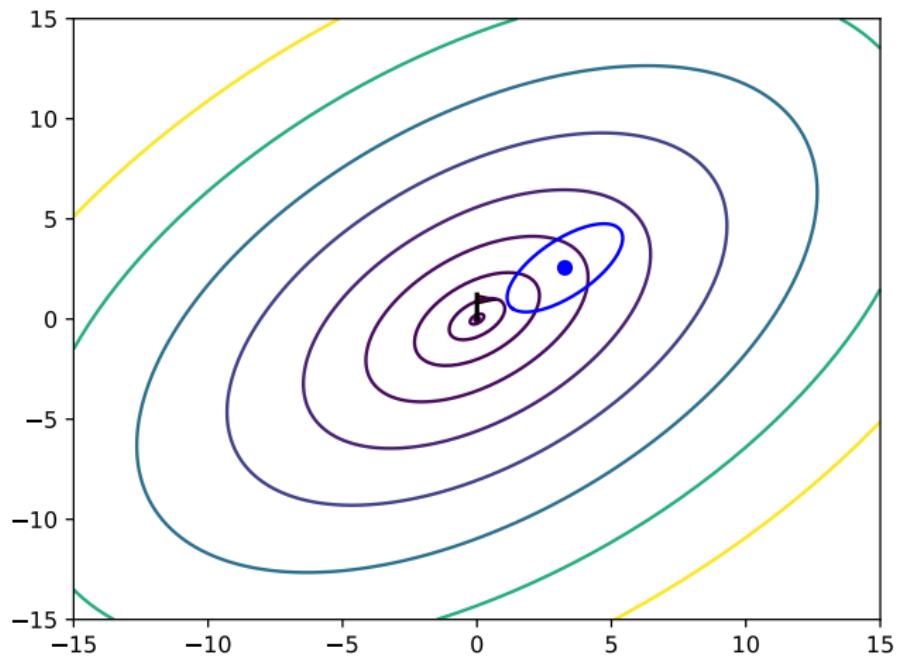
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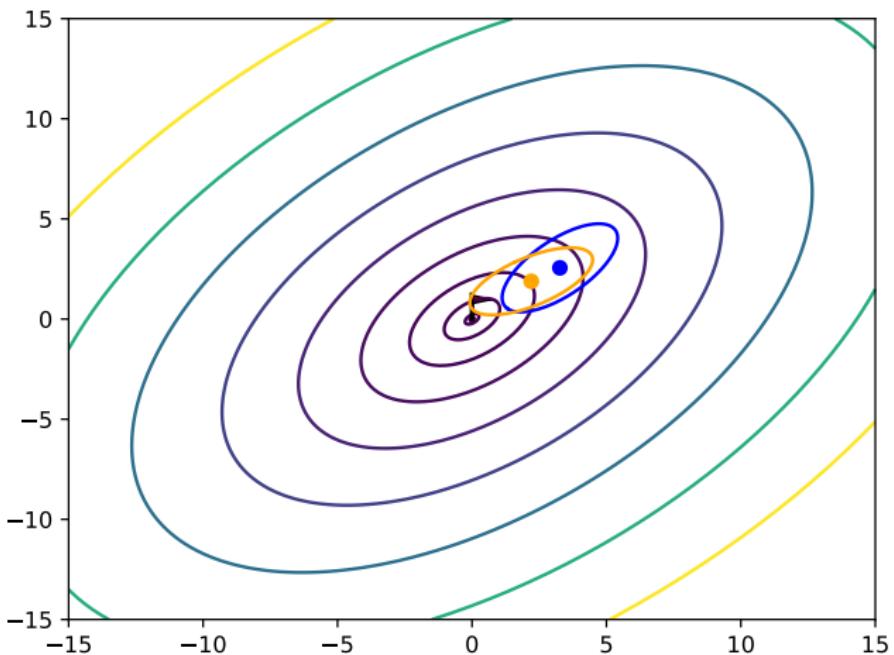
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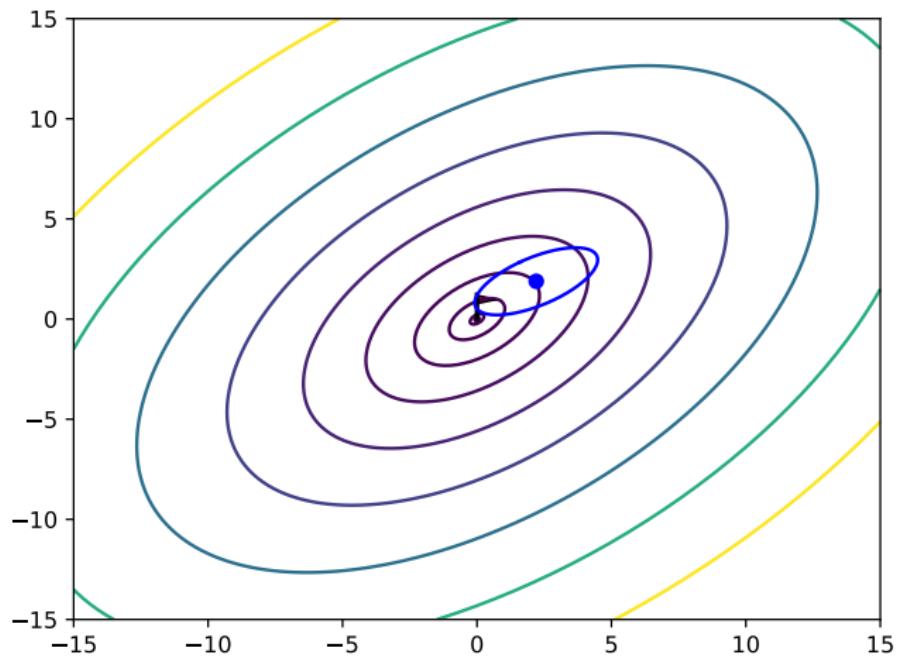
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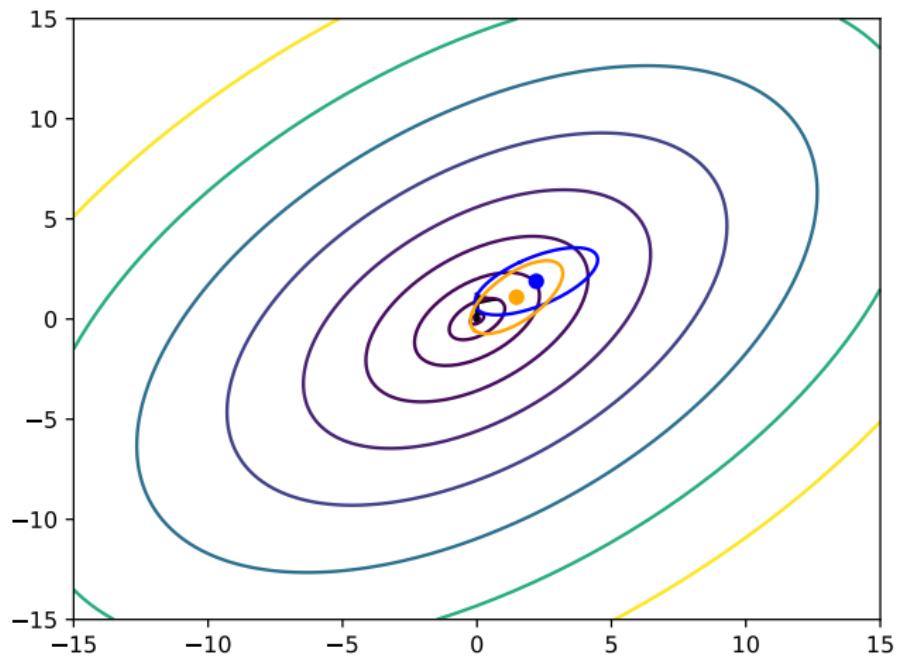
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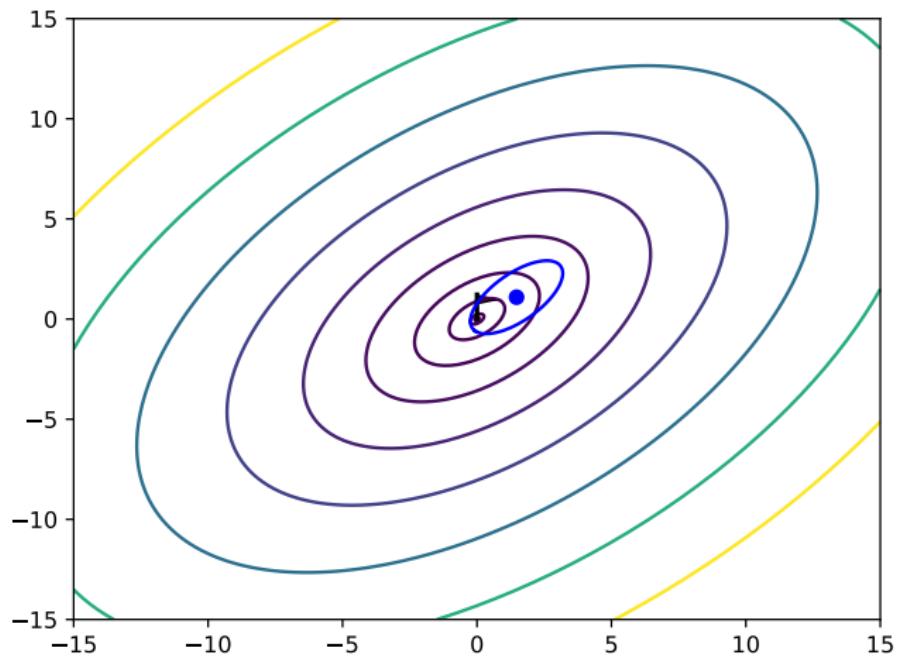
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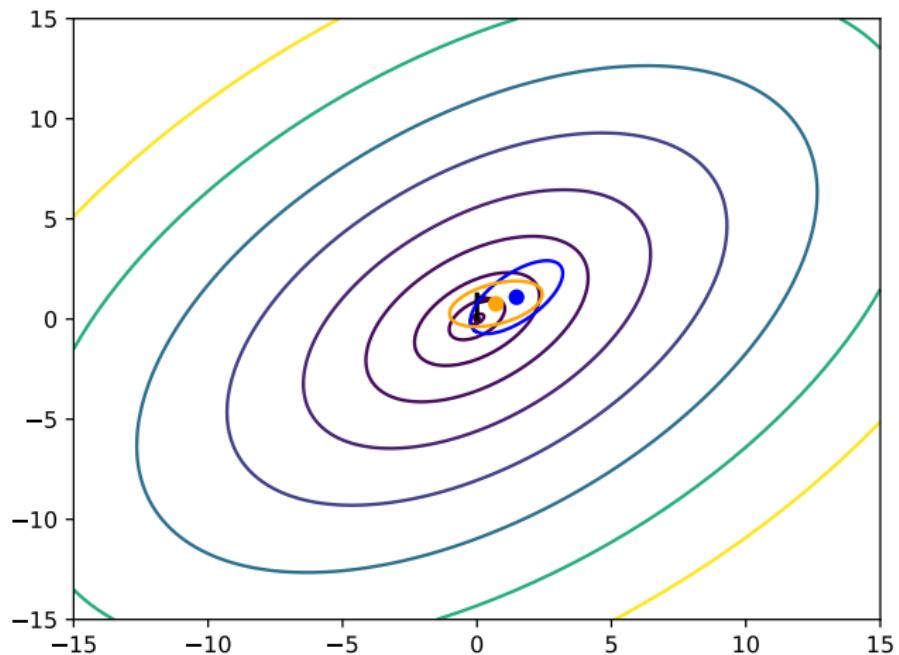
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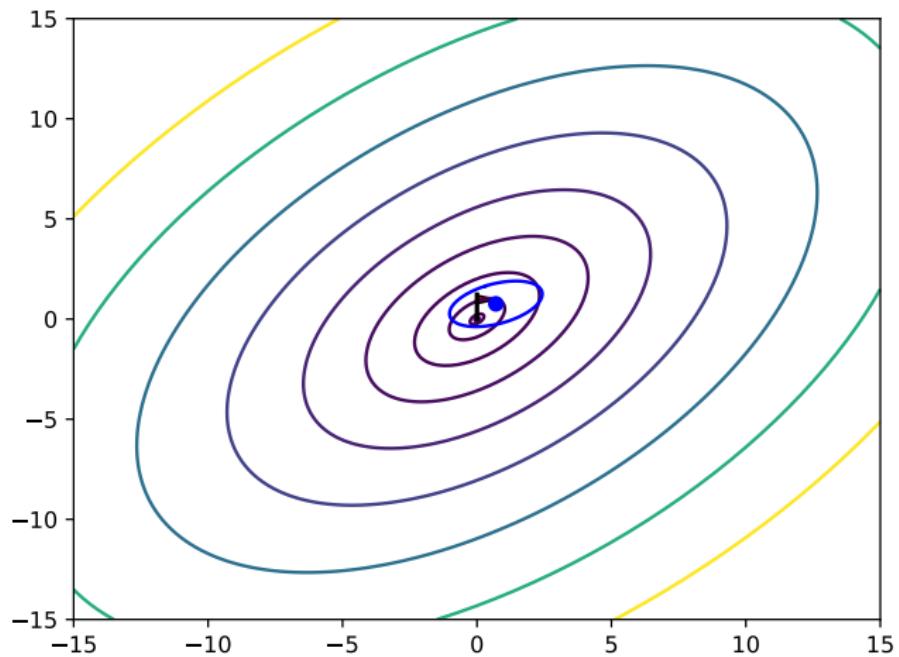
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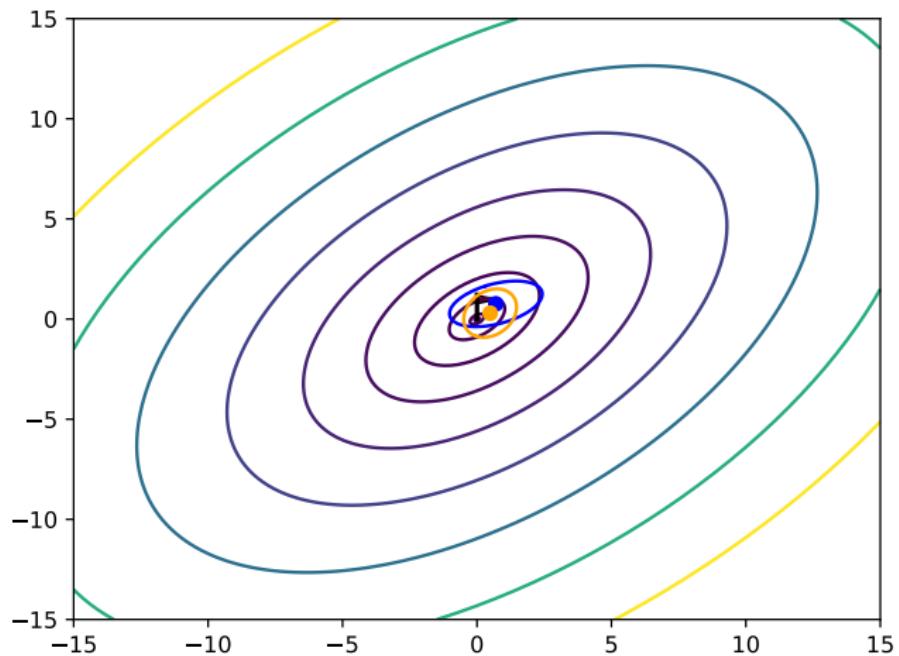
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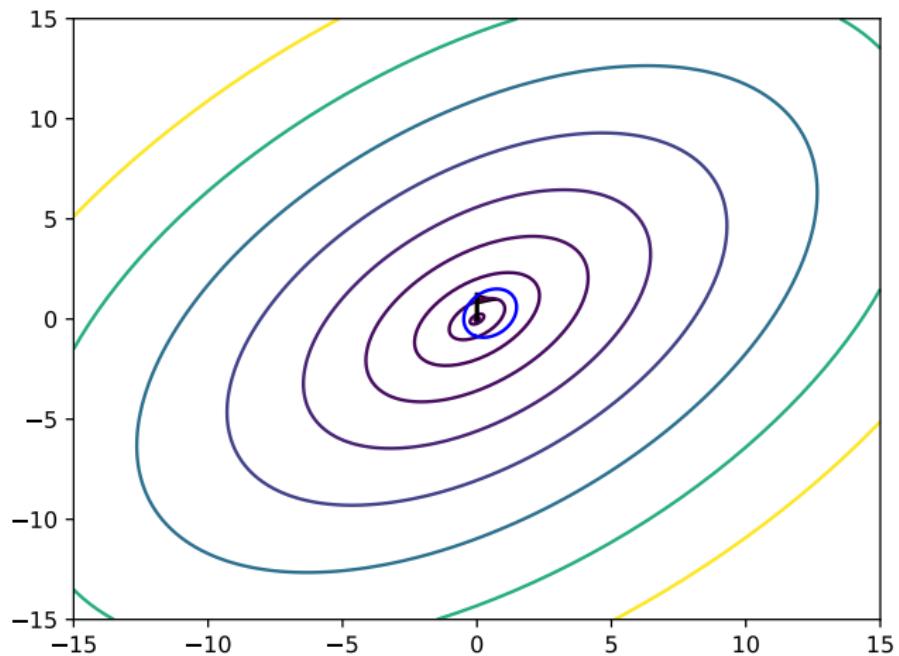
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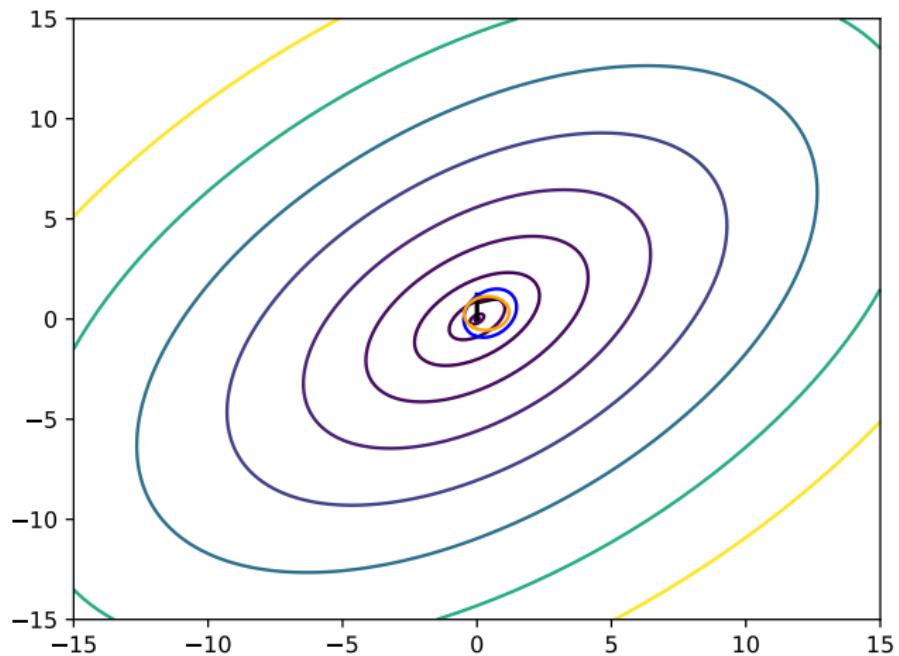
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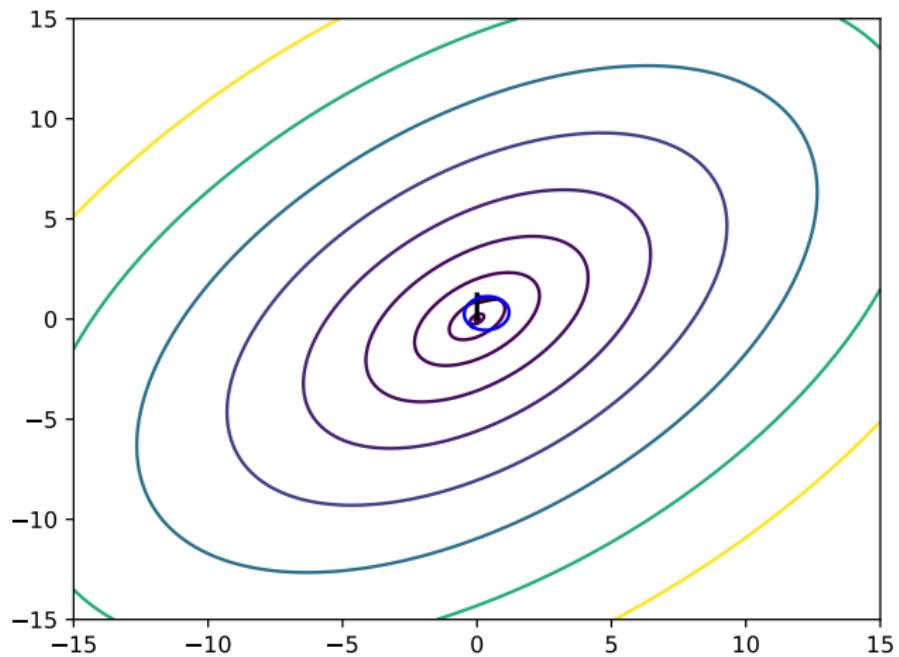
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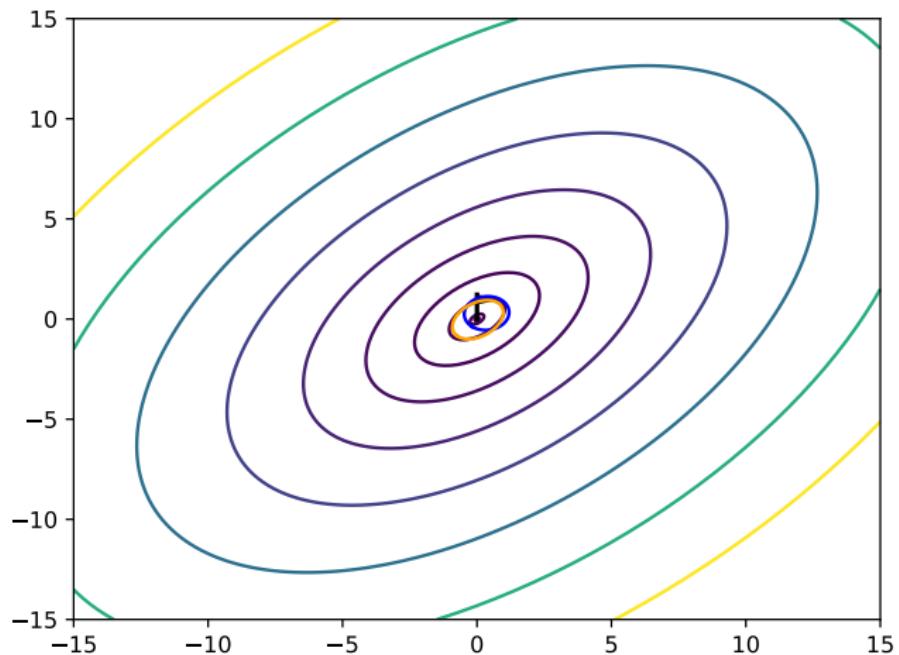
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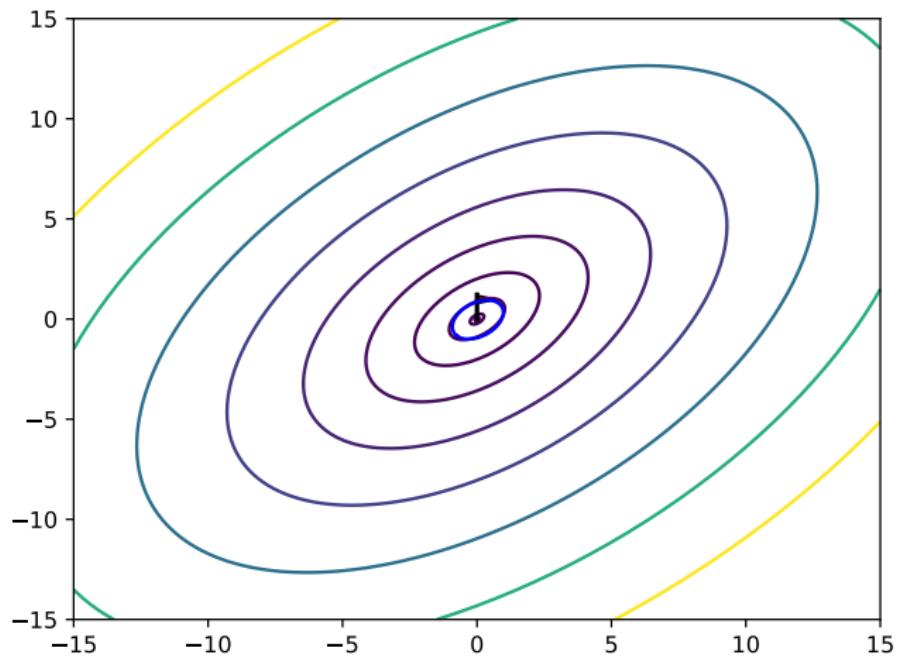
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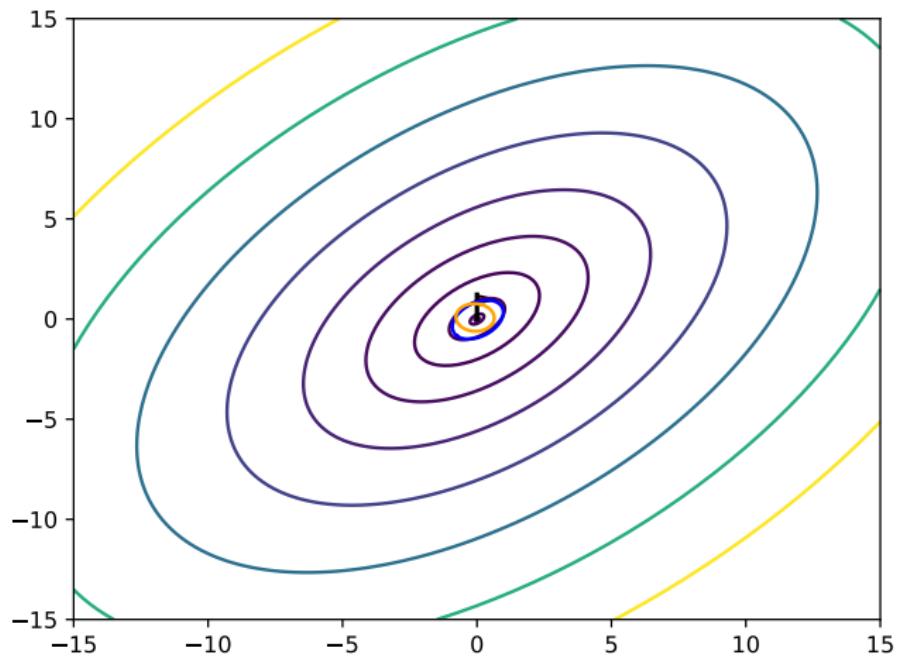
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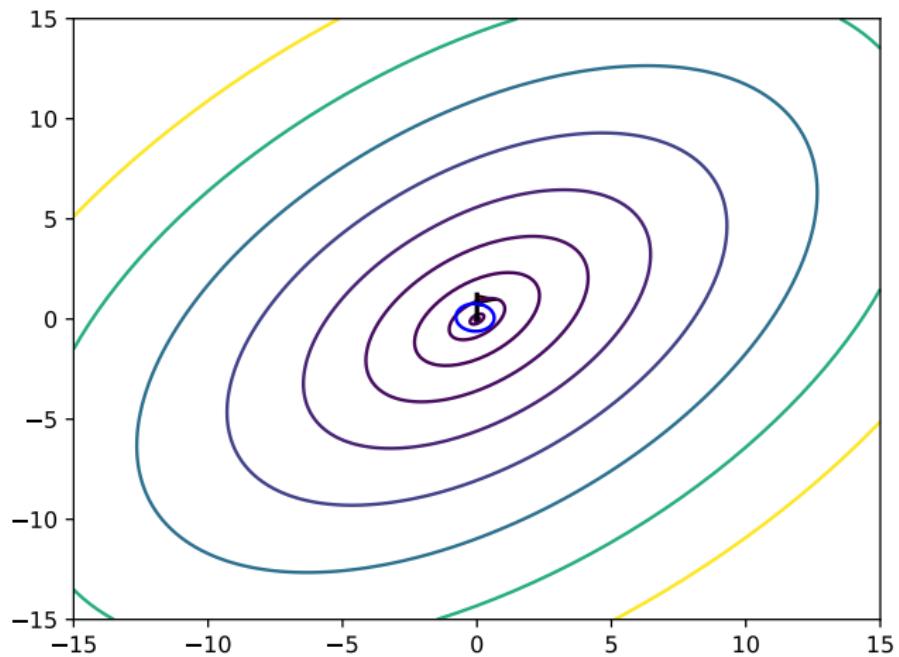
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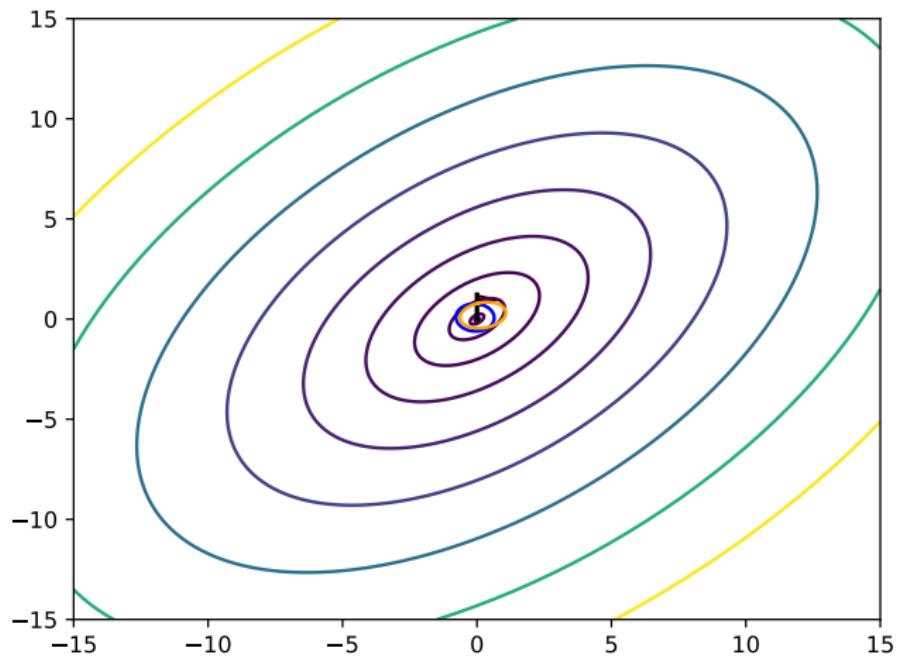
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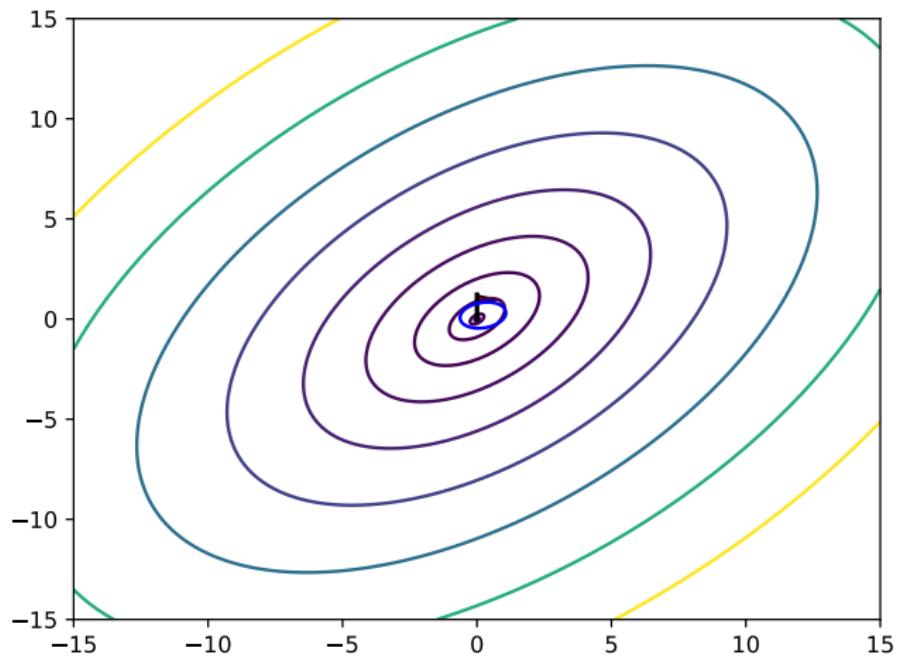
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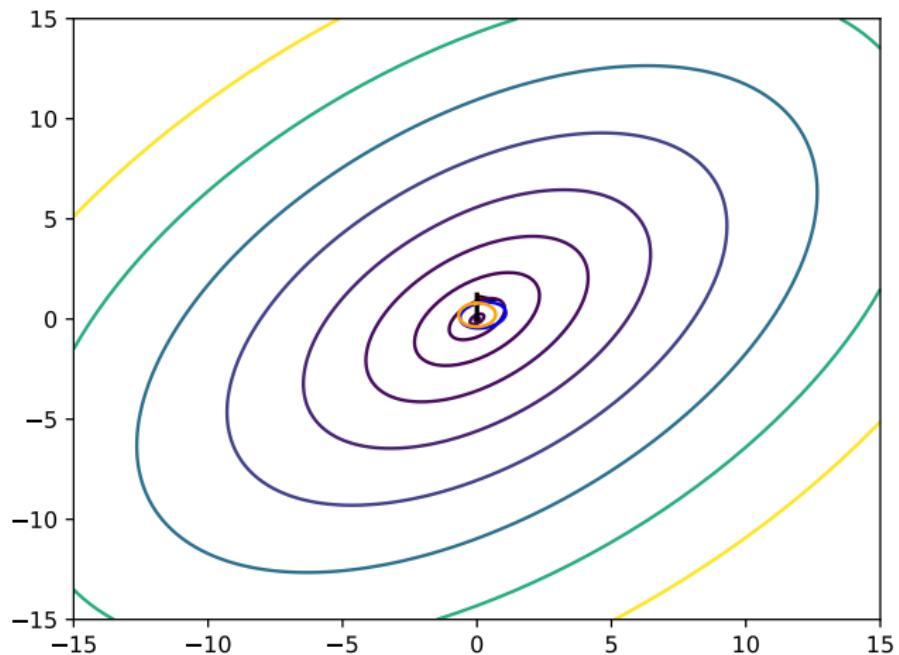
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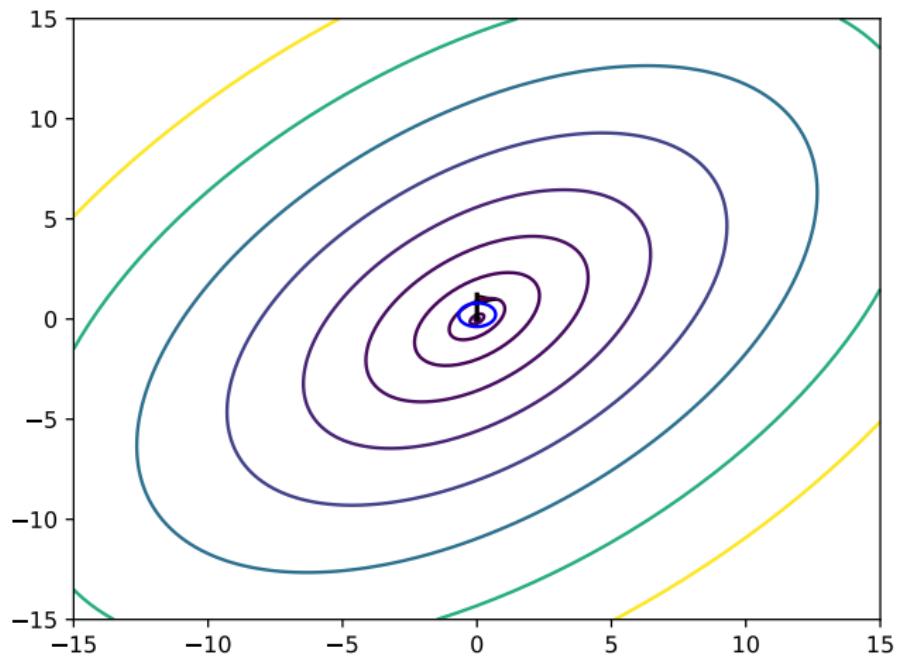
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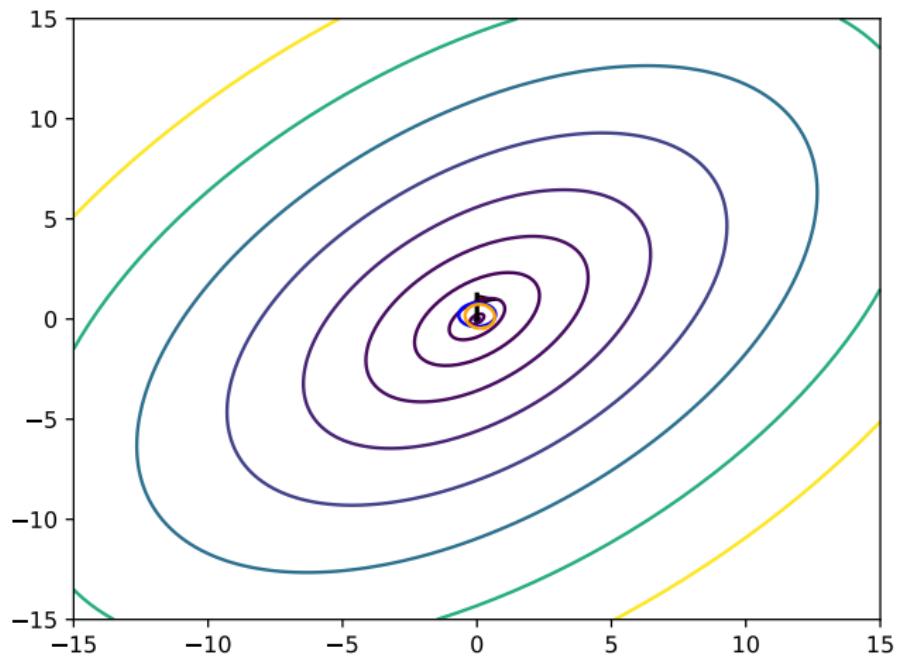
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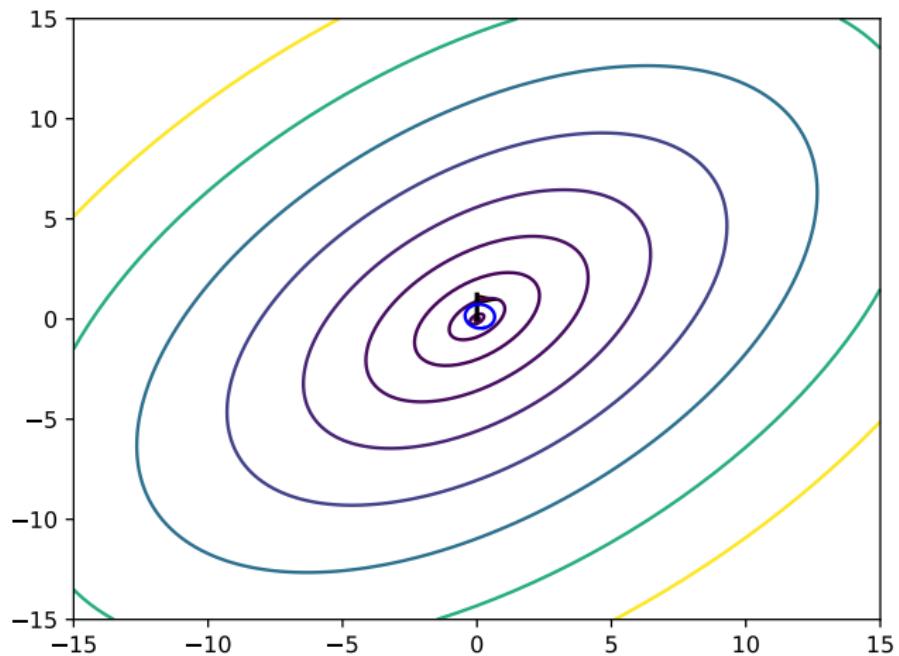
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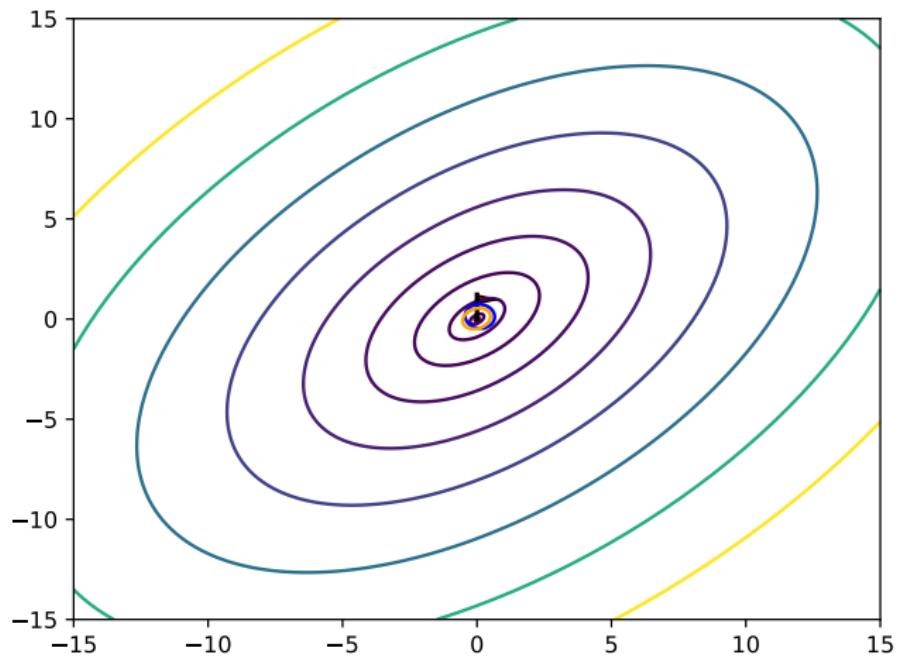
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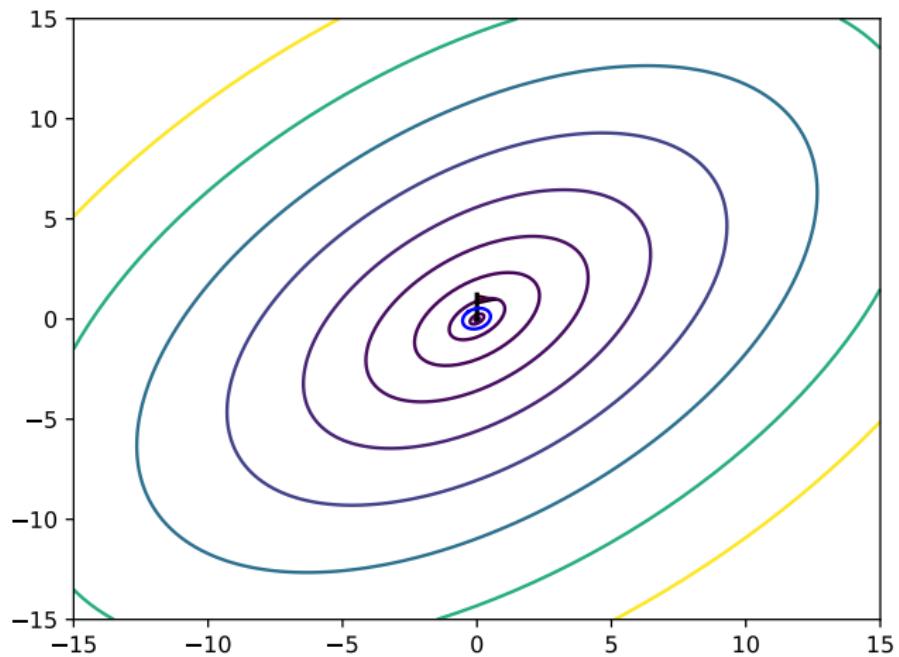
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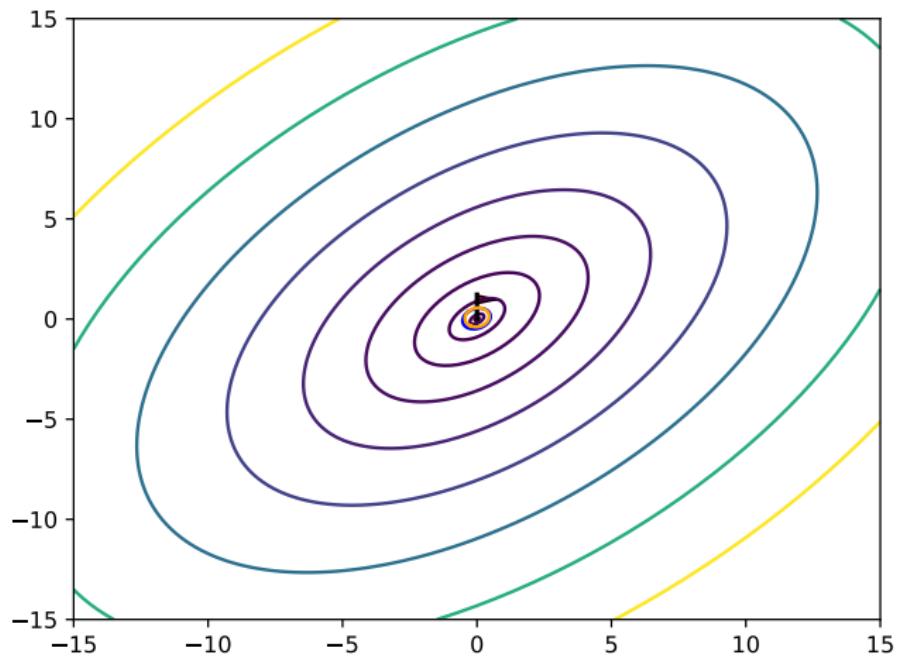
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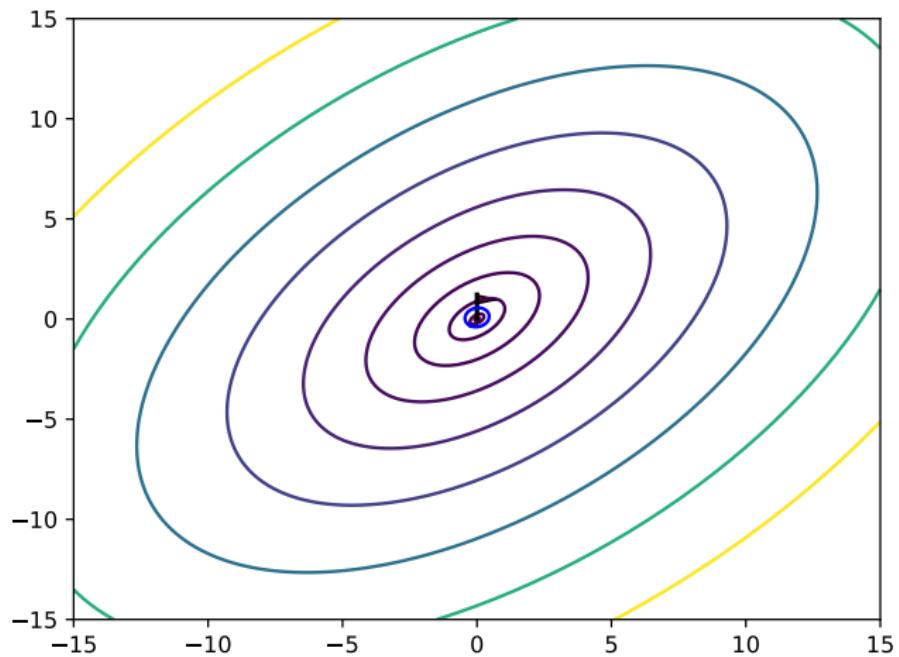
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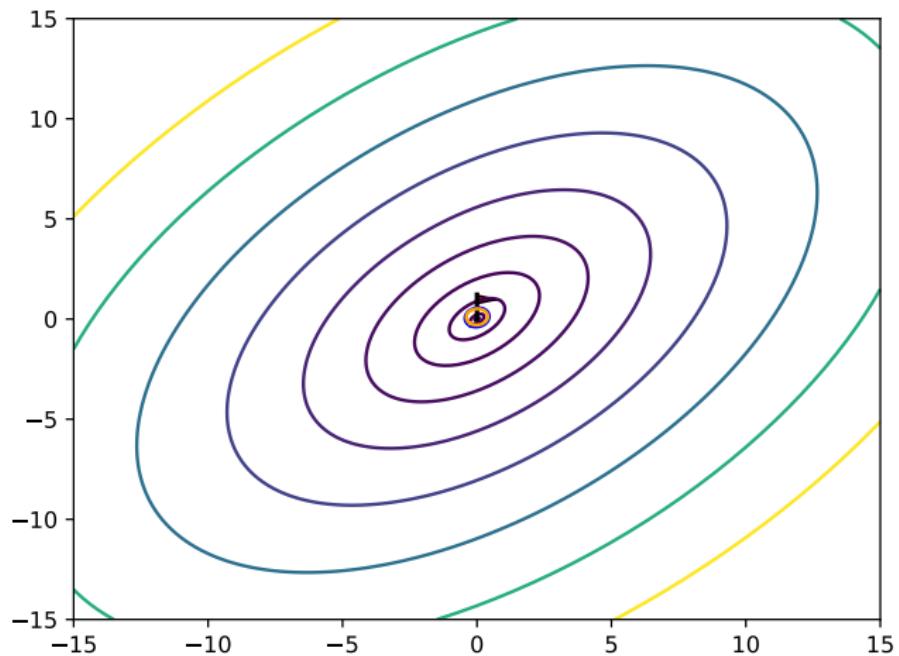
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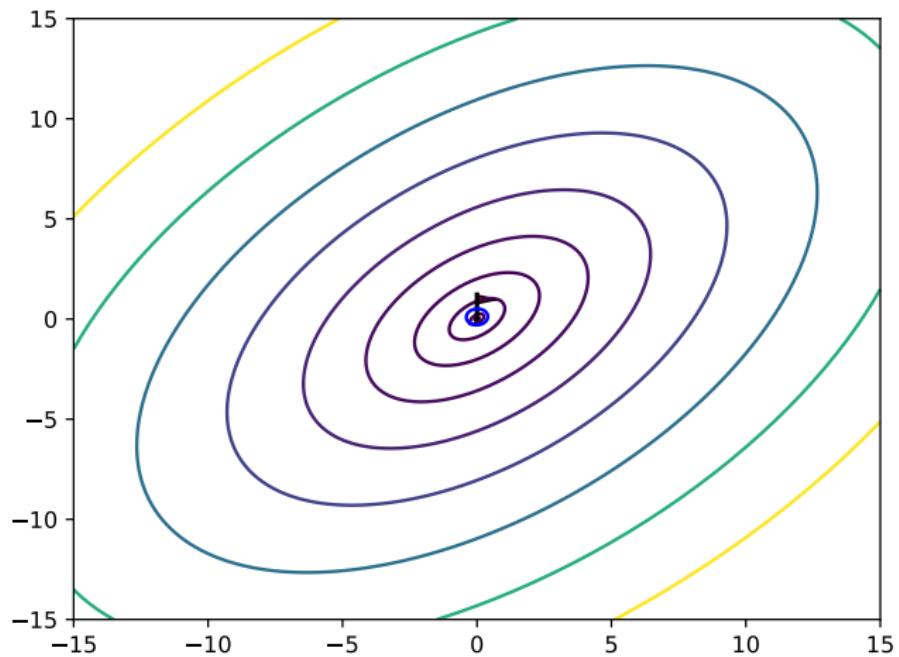
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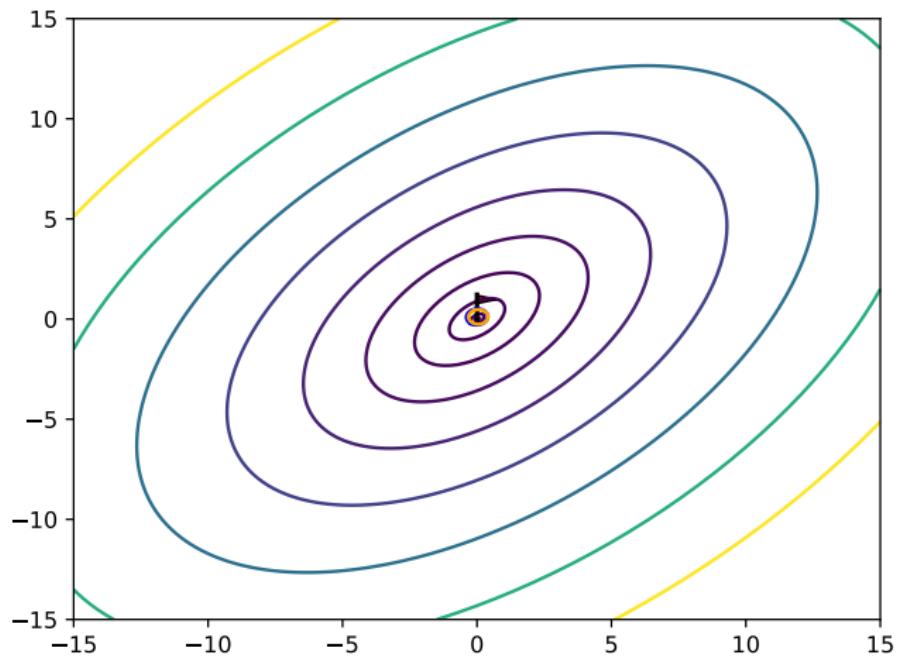
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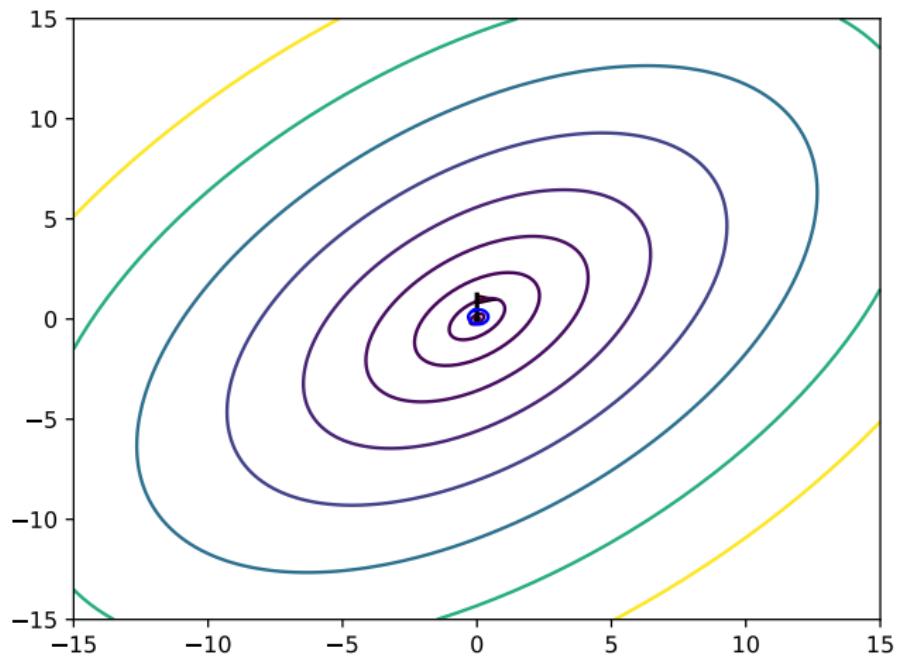
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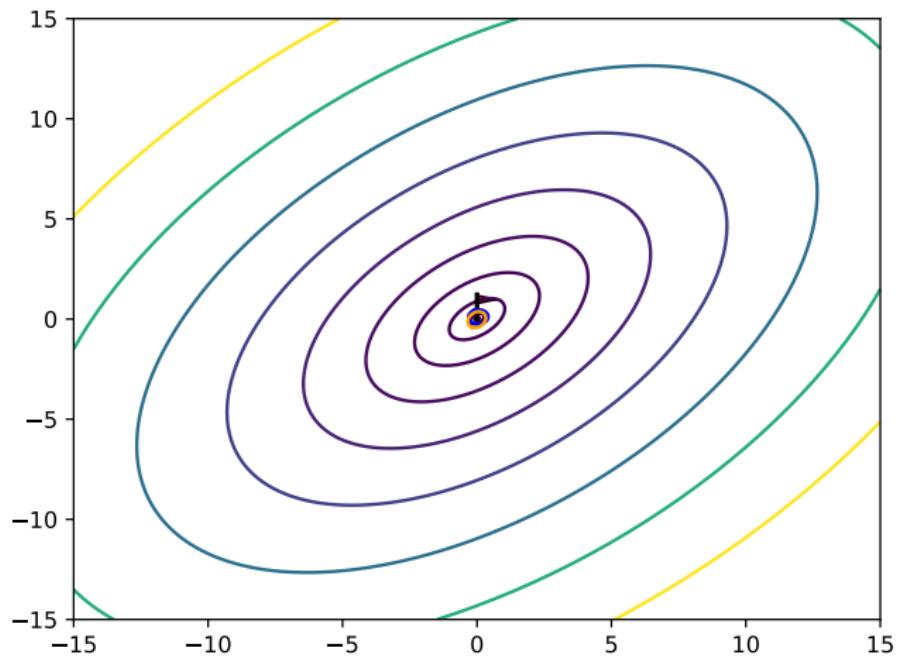
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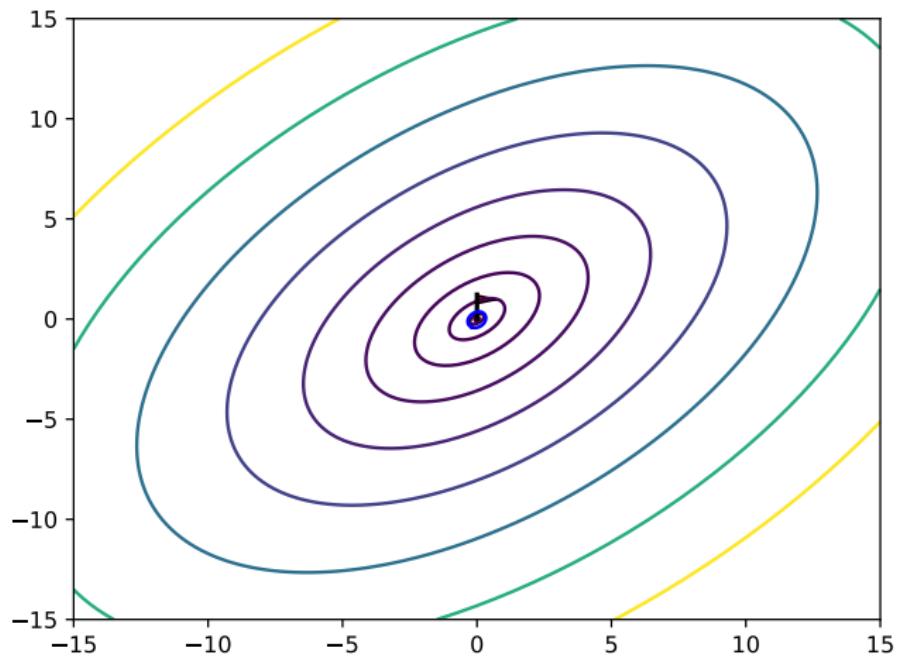
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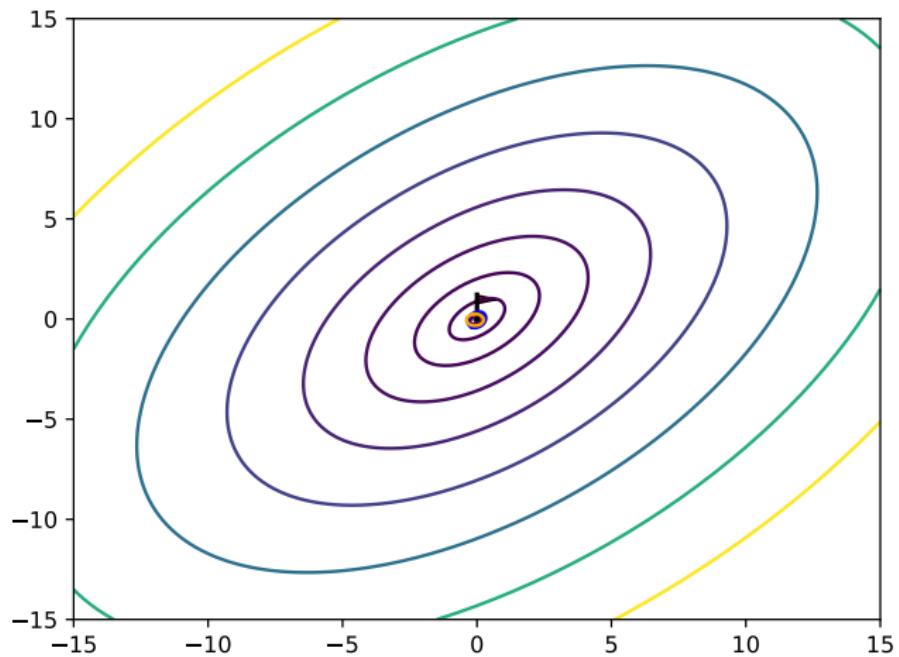
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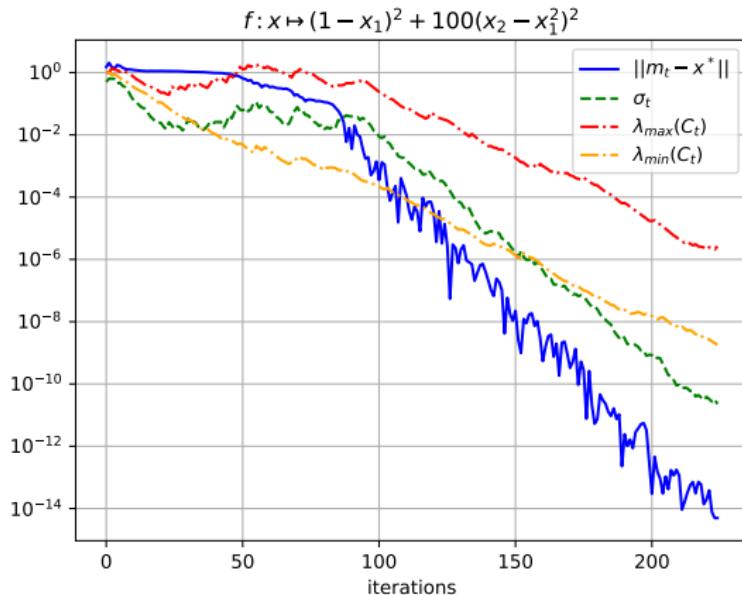
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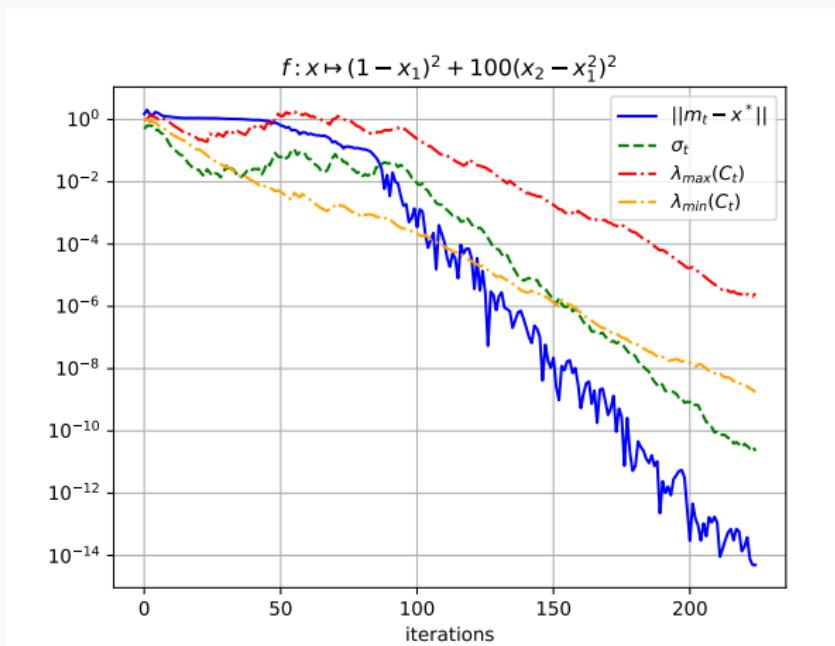


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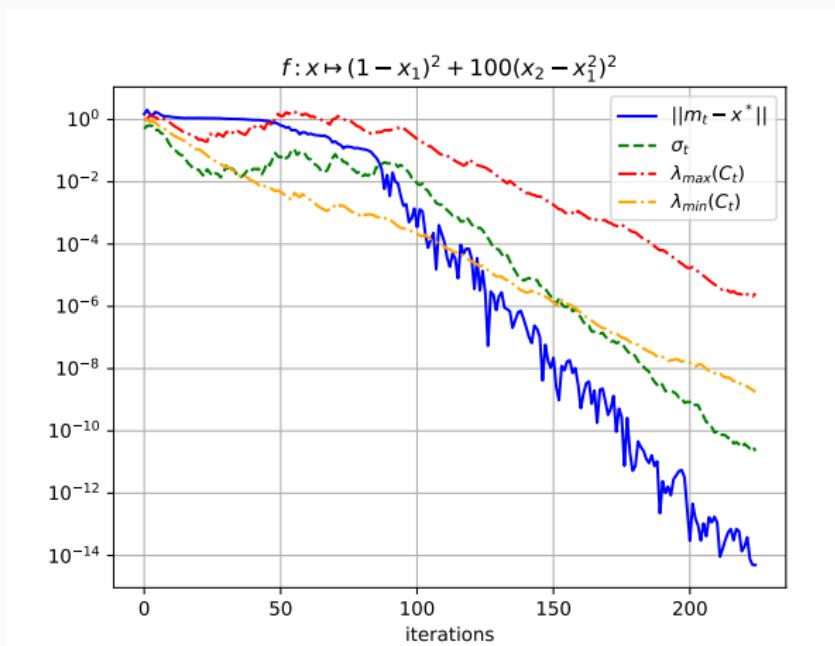
$$\frac{\|m_t - x^*\|}{\|m_0 - x^*\|}$$

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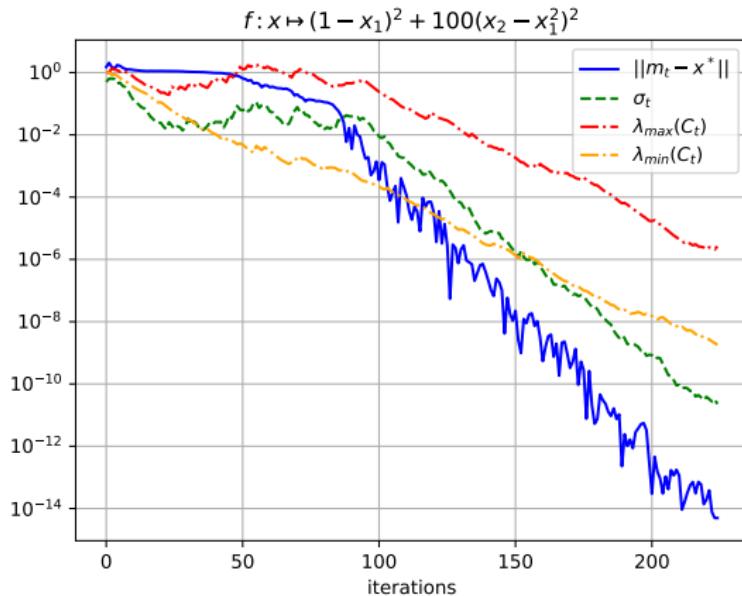
$$\log \frac{\|m_t - x^*\|}{\|m_0 - x^*\|}$$

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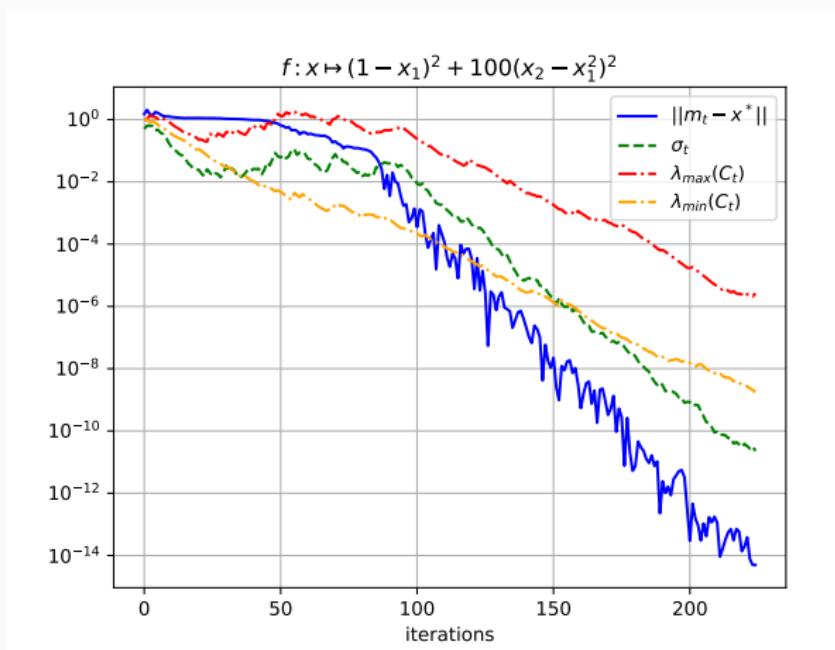
$$\log \frac{\|m_t - x^*\|}{\|m_0 - x^*\|} = -\text{CR} \times t$$

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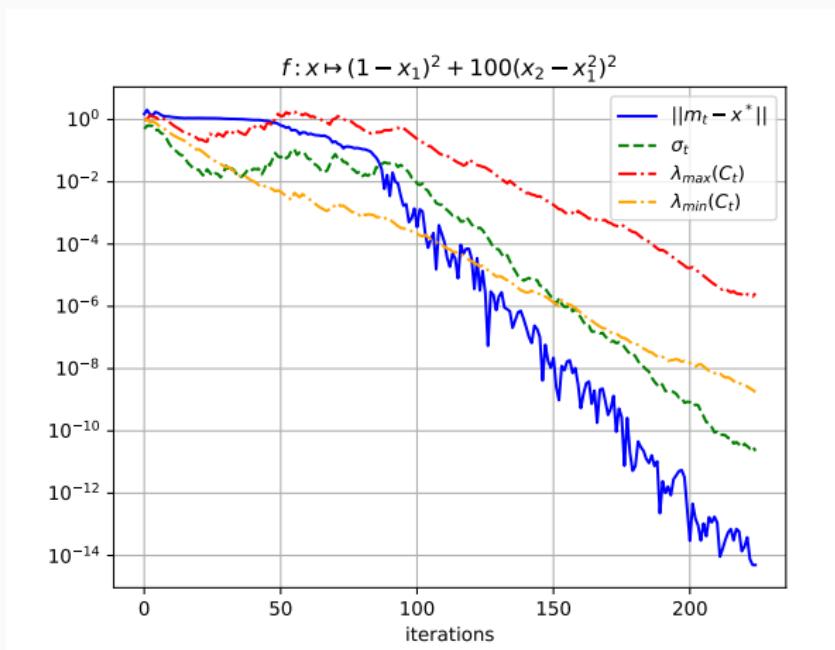
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## CMA-ES : presentation

At each iteration  $t \in \mathbb{N}$ , given a **mean**  $m_t$ , a **stepsize**  $\sigma_t$  and a **covariance matrix**  $C_t$  :

1. Generate  $\lambda$  offspring  $x_{t+1}^i \sim \mathcal{N}(m_t, \sigma_t^2 C_t)$  *independently*
2. Rank the  $x_{t+1}^i$  w.r.t. their  $f$ -values:  $f(x_{t+1}^{1:\lambda}) \leq \dots \leq f(x_{t+1}^{\lambda:\lambda})$
3. Update the mean:  $m_{t+1} = \sum w_i x_{t+1}^{i:\lambda}$

The best offspring have the largest weights:  $w_1 \geq w_2 \dots$

4. Update the stepsize:  
Increase the stepsize if the path taken by the mean is larger than expected (assuming no selection)
5. Update the covariance matrix

$$C_{t+1} = (1 - c)C_t + c \sum w_i \frac{(x_{t+1}^{i:\lambda} - m_t)(x_{t+1}^{i:\lambda} - m_t)^T}{\sigma_t^2}$$

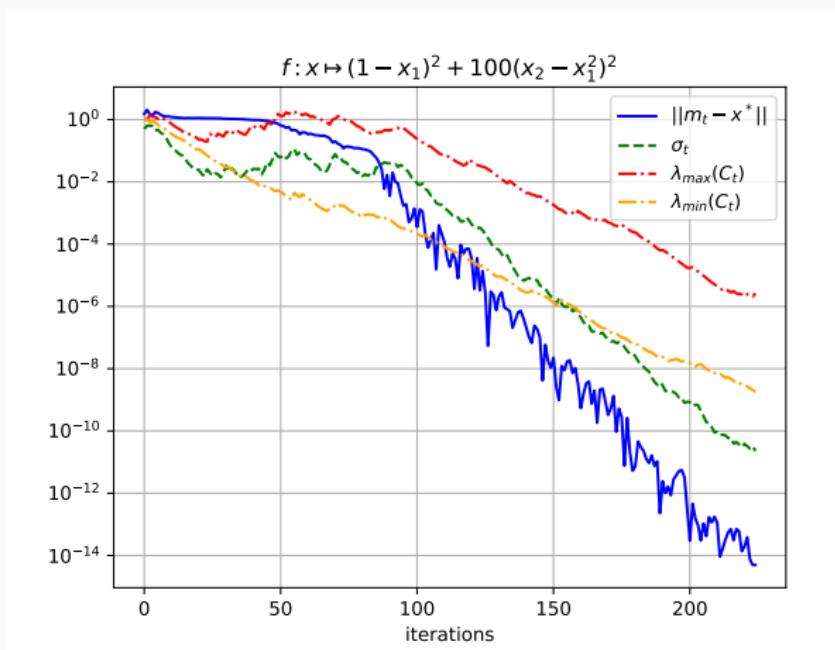
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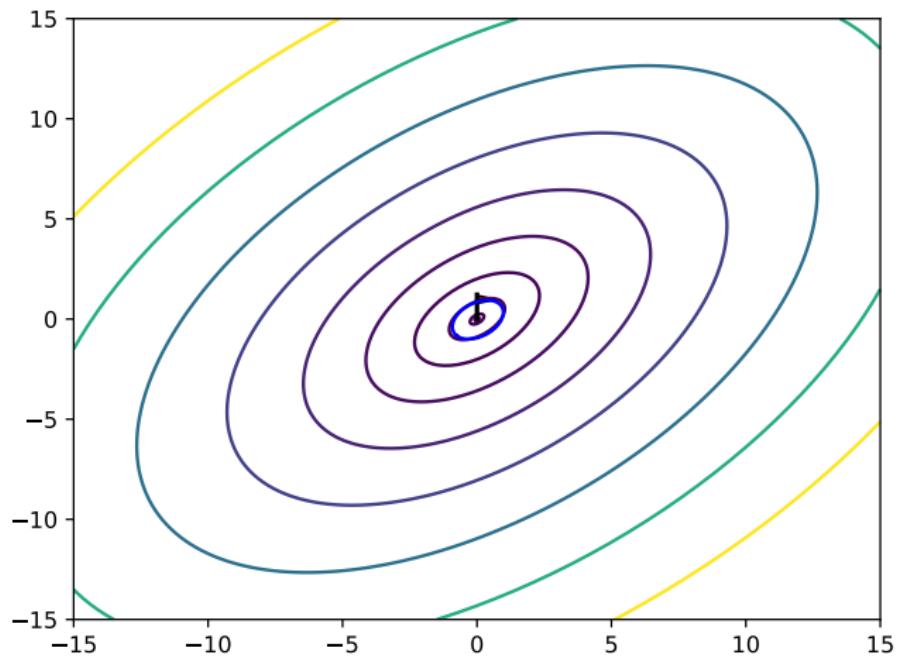
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Goal: proof of linear convergence and of the learning of the inverse Hessian

## Analysis via Markov chains

---

## Markov chains

A **Markov chain** is a random sequence  $(\phi_t)_{t \in \mathbb{N}}$  such that

$$\text{Distribution}(\phi_{t+1} \mid \phi_0, \dots, \phi_t) = \text{Distribution}(\phi_{t+1} \mid \phi_t)$$

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- The Markov chain is **ergodic** when it satisfies the following LLN

$$\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=0}^{T-1} f(\phi_t) = \int f(x) \pi(dx).$$

---

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# CMA-ES as a Markov chain

Consider the random sequence

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Question: Could we use the LLN for Markov chains to prove linear convergence for CMA-ES?

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Suppose that  $(m_t, \sigma_t, C_t)_{t \in \mathbb{N}}$  has an invariant measure  $\pi$ .

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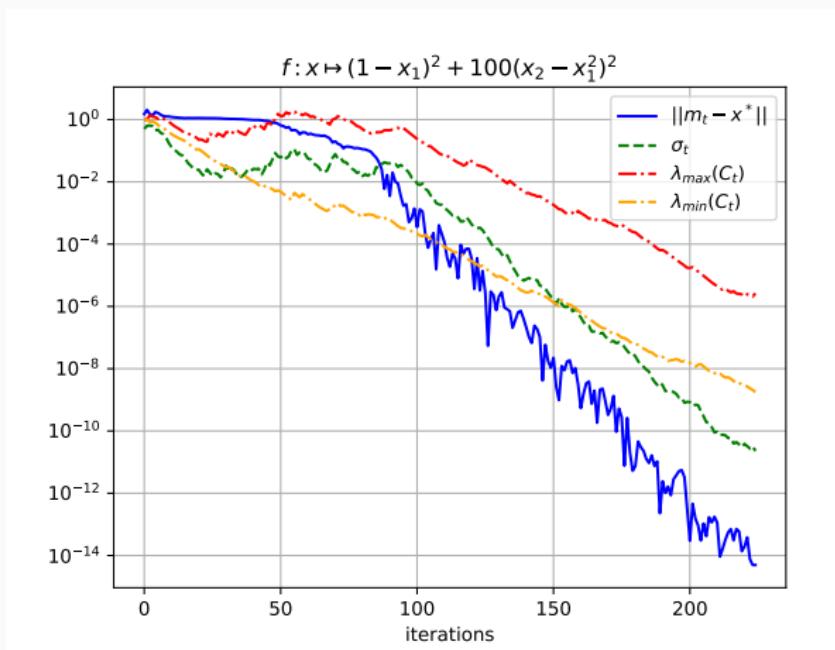
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We do not progress towards the optimum anymore! The **existence of an invariant measure** seems to be **incompatible** with the **convergence** to the optimum.

# Linear convergence



$$\lim_{t \rightarrow \infty} \frac{1}{t} \log \frac{\|m_t - x^*\|}{\|m_0 - x^*\|} = -\text{CR}$$

## Normalization

$$\|m_t - x^*\|, \sigma_t \text{ and } \lambda_{\min}(C_t) \rightarrow 0$$

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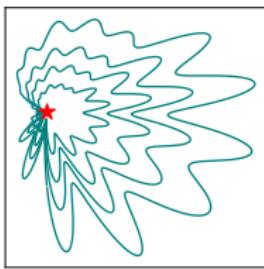
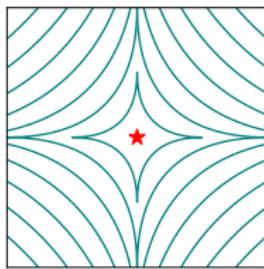
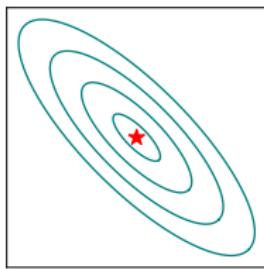
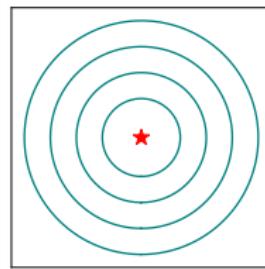
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# Scaling-invariant functions

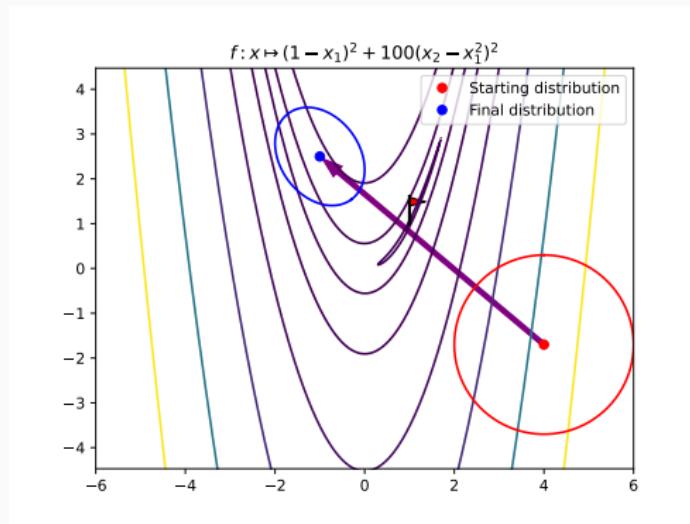


## Irreducibility of CMA-ES

A Markov chain  $(\phi_t)_{t \in \mathbb{N}}$  is **irreducible** if all states are reachable in finite time with positive probability.

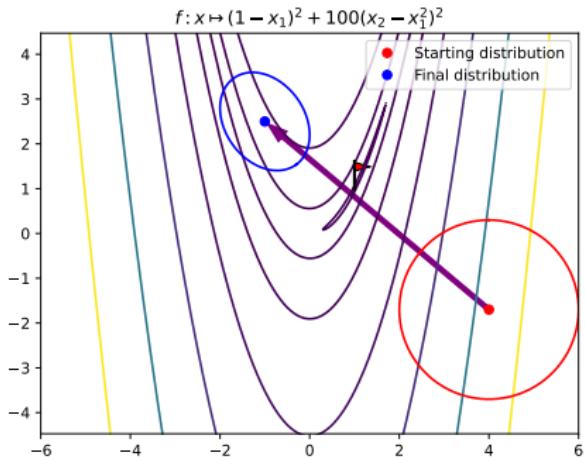
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Given a starting and a final distributions, **can we reach the final distribution in finite time with positive probability?**

## Theorem (Irreducibility of the normalized chain)

*When minimizing a scaling-invariant function  $f$  with Lebesgue-negligible level sets, the sequence*

$$\left( Z_t, \frac{C_t}{\lambda_{\min}(C_t)} \right)_{t \in \mathbb{N}}$$

*defines a irreducible, aperiodic Markov chain, and compact sets are small sets.*

## Ergodicity of the normalized chain<sup>2</sup>

$$\left( Z_t, \frac{C_t}{\lambda_{\min}(C_t)} \right)_{t \in \mathbb{N}}$$

is **ergodic** if

---

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ISBN: 978-1-4471-3267-7.

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- it satisfies the following **drift** condition:  $\exists V: X \rightarrow [0, +\infty]$

$$\mathbb{E}_t \left[ V \left( Z_{t+1}, \frac{C_{t+1}}{\lambda_{\min}(C_{t+1})} \right) \right] \leq (1 - \varepsilon) V \left( Z_t, \frac{C_t}{\lambda_{\min}(C_t)} \right)$$

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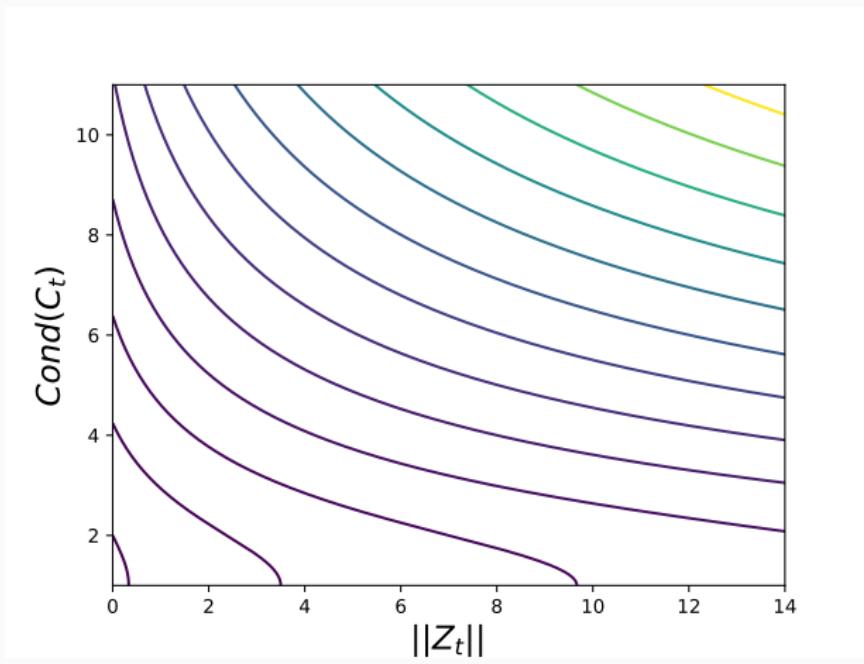
The function  $V$  is called the **potential function** or the **drift function** or the **Lyapunov function**.

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## Drift condition

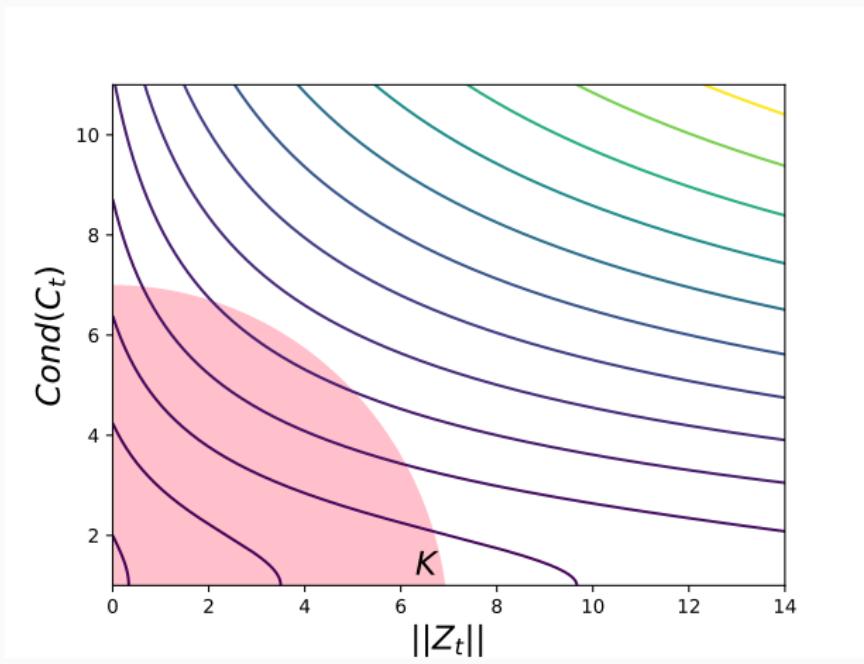
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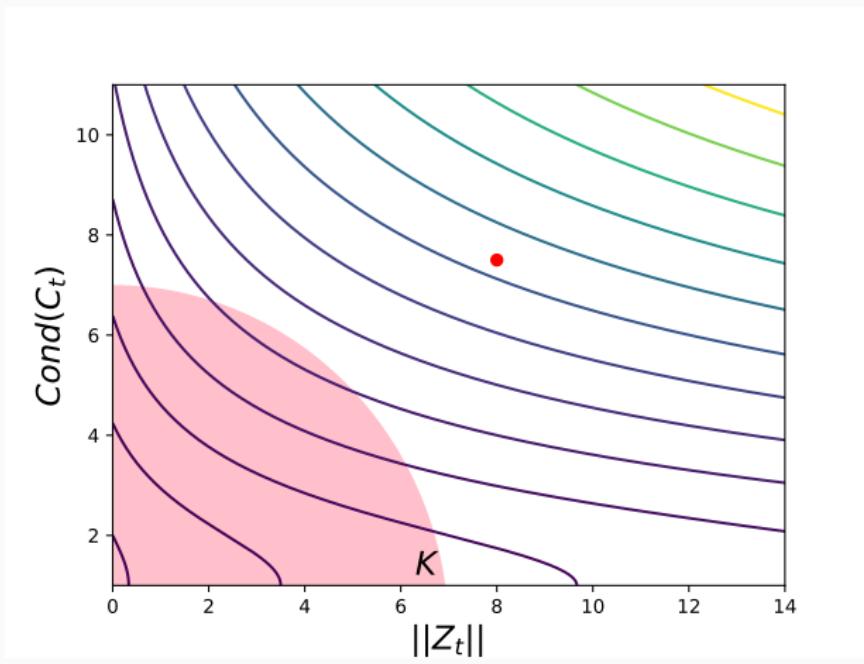
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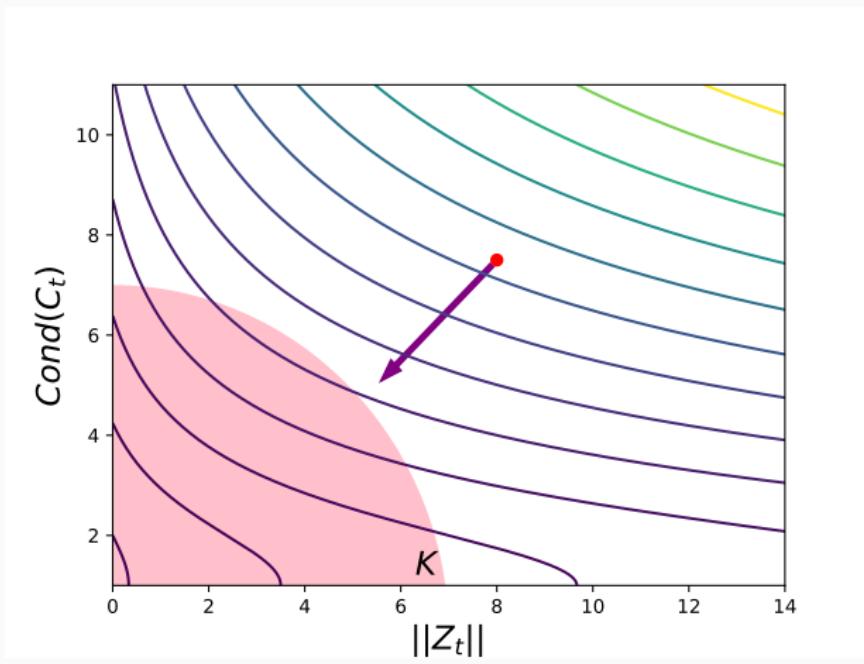
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## Theorem (Drift condition for the normalized chain)

When minimizing a spherical function  $f: x \mapsto g(x^T x)$  ( $g: \mathbb{R} \rightarrow \mathbb{R}$  increasing), then the irreducible, aperiodic Markov chain  $(Z_t, C_t/\lambda_{\min}(C_t))_{t \in \mathbb{N}}$  satisfies a Foster-Lyapunov condition with the potential defined by

$$V(Z, C) = \sum_{k=1}^d \left\{ \frac{\lambda_k(C)}{\lambda_1(C)} |\langle v_k(C), Z \rangle|^2 \right\} + \beta \times \text{Cond}(C)$$

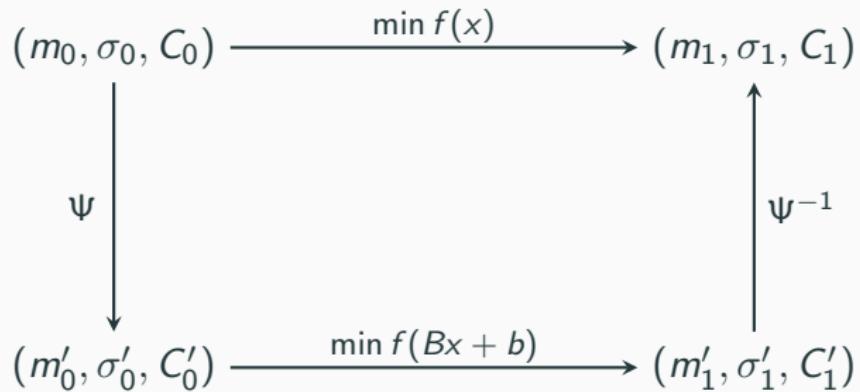
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This can be generalized to when minimizing ellipsoid functions  $f(x) = g(x^T H x)$  using the **affine-invariance** of CMA-ES.

# Affine-Invariance



## Proof of linear convergence

$$\frac{1}{T} \log \frac{\|m_T - x^*\|}{\|m_0 - x^*\|} \rightarrow -\text{CR}?$$

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- **When minimizing a convex-quadratic function**

$$\mathbb{E} \left[ \frac{C_t}{\text{normalization}} \right] \xrightarrow{t \rightarrow \infty} \text{constant} \times H^{-1}$$

---

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*Thank you!*