FLORIDA STATE UNIVERSITY FAMU-FSU COLLEGE OF ENGINEERING

TRI-MODAL MODELS OF LOCOMOTION APPLICATIONS TO ROBOT DESIGN AND CONTROL

By

MAX AUSTIN

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	Jonathan Clark
	Professor Directing Dissertation
	Rodney Roberts
	University Representative
	Christian Hubiki
	Committee Member
	Kuroush Shoele
	Committee Member
The Graduate School has verified and apdissertation has been approved in according	pproved the above-named committee members, and certifies that the dance with university requirements.