

NeXus Recapitulation and Developments

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October 1, 2012

- Brief Introduction to NeXus
- Decisions from NIAC 2010
- Developments since NIAC 2010
- Topics for this NIAC Meeting

- Definition of a standard data format
 - Rules
 - Validation tools
- Promotion of NeXus
 - Documentation
 - NeXus API
 - Outreach to the scientific community

- Complete data for typical use
- Extendable, add additional data as you please
- Self describing
- Easy automatic plotting
- Store a full beamline description (FBD)
- Platform independent, public domain, efficient
- Suitable for a wild variety of applications

- 1 Physical file format and API for accessing files
- 2 Rules for storing data in files
- 3 Component and application definitions
- 4 NeXus Utilities

- NXsubentry
- NXcollection
- Support for CIF style coordinate systems
- Non C-storage order arrays: offset, stride attributes
- Python tree API becomes part of NAPI
- Look into NAPI thread safety and PHDF

```
entry:NXentry
  sample:NXsample
  instrument:NXinstrument
  ....
  sas:NXsubentry
    sample:NXsample

    instrument:NXinstrument
      source:NXsource
      velocity_selector:NXvelocity_selector
      detector:NXdetector
        data[xsize,ysize], signal=1 (1)
    control:NXmonitor
      data
    data:NXdata
      link to (1)
```

```
entry, NXentry
  measurement: NXcollection
    positions: NXcollection
      om
      two_theta
    scalars: NXcollection
      title
      wavelength
  data: NXdata
    detector1
    mca5
```


- HDRI Meeting Hamburg
- PanData floundered
- Code Camp 2011
- Collaboration with DECTRIS
- Code Camp 2012
- NAPI release 4.3, NXDL 3.2 == 1.0

- German synchrotron and neutron sources
- Collaboration with little money
- Invented something NeXus alike
- Later convinced to go NeXus
- Additional and revised synchrotron base classes
 - NXcapillary
 - NXbending_magnet
 - NXinsertion_device
 - NXxray_lens
- Current state: Eugen?

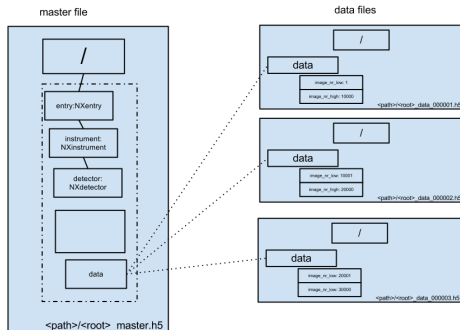
- European project to standardize logins, data catalogs and data
- NeXus at first well received
- Then plans to develop method specific formats between facilities
- Dormant ever since

- At APS
- NX_UNLIMITED for all dimensions
- 64 bit dimensions
- HDF-5 1.8
- Documentation updates
- WWW-site from manual
- NXimpatient document: NeXus in 8 pages
- Test for python-API 30% complete
- Python Tree API cleaned up
- PHDF not useful
- New C++ Tree API (Eugen)

- Manufacturer of Pilatus and Eiger detectors
- Going for NeXus/HDF-5 for Eiger
- Detector Software writes NXdetector group
- More fields added to NXdetector to accomodate pixel detectors
- This is well on its way

DECTRIS File Structure

File Format (Dectris)



- DECTRIS has a problem:
 - Detector outputs 5-10 GB/sec
 - They deliver the detector and the computer going with it
 - They cannot ask their customers to provide the appropriate hardware for such a detector: parallel file system etc.
 - Must compress and write the file on one computer
 - Compression has to be parallel as CPU intensive
- File structure a workaround for HDF-5 not allowing sections of datasets in different files
- Sidenote: LZ4 or snappy compression; up to 450MB/sec on write

Upcoming DECTRIS Meeting with Community

- DECTRIS aims at meeting customers in october
- How far can we compromise?
- Anyone from the NeXus community who wishes to join?
- Comment from code camp: ask for tool to convert to HDF-5 standard compression

- May 2012
- Organised with DECTRIS to address performance issues
- HDF people gave overview of new developments in HDF-5
- DECTRIS (and DESY) pays for:
 - Writing pre compressed chunks
 - Dynamically loadable filters

- Asynchronous I/O
- Journaling
- Single Writer, Multiple Reader semantics
- Better fault tolerance
- In memory HDF-5 files
- Shared object headers

Other Things the HDF people work on

- Better multi threading support
- Virtual Object Layer, completely replace storage layer
 - Use HDF-5 data model but not file format
 - Opens path to more storage models
 - Metadata server for better parallel support
 - Mirroring, stacking
- Better parallel processing support: meta data server

- 64 bit dimensions
- HDF-1.8
- NX_UNLIMITED everywhere
- Alpha python tree API included
- First release of application definitions
- Updated manual

- Moved documentation to sphinx
 - Wiki like syntax allows for easier editing then docbook
 - URL:
- Cleaned up trac tickets
- Decided to drop autoconf in favour of CMake
- Resolved CIF coordinate issue
- Devised a good suggestion for handling axes at multidimensional datasets
- Cleanup of NeXus applications: nx2dtd, NXDump, nxtraverse, NXformat_dfn dropped
- Got NAPI 4.3 release ready

- Review of NeXus: where are we headed?
- Roadmap OO-NeXus
- CIF coordinates
- Process for changing base classes
- Review synchrotron beamline classes
- Review additions to NXdetector
- Materials definition
- Multi dimensional array axes encoding
- What to do about expired NIAC members?
- Electing new officers

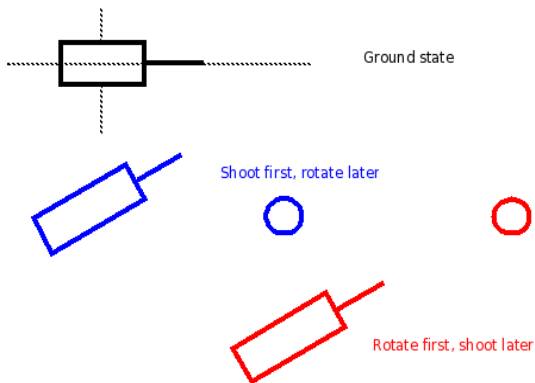
- Is anyone using NXcharacterization? Remove?
- Who is using F77 NAPI? How much effort to put into this?
- Do we go into timed data?

- Finalize
- Hope for endorsement of CIF community
- AIM: provide data necessary to derive positions of components from transformation matrices

$$T = \begin{pmatrix} 1 & 0 & 0 & x \\ 0 & 1 & 0 & y \\ 0 & 0 & 1 & z \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

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$$R = \begin{pmatrix} r_{11} & r_{12} & r_{13} & 0 \\ r_{21} & r_{22} & r_{23} & 0 \\ r_{31} & r_{32} & r_{33} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Combining Transformations



- Transformations can be combined by matrix multiplications
- Individual matrices can be derived by looking at the situation when everything else is 0
- Absolute positions can be obtained by multiplying the resulting matrix with its transpose
- Defines new coordinate systems at components
- CIF contains a duplication: vector, offset scheme

- Allows to calculate absolute positions of components in the laboratory coordinate systems
- Can directly convert from a detector coordinate system to vectors in Lab coordinate system
- Calculate things like impact of primary beam on detector, SAS
- Allows arbitray axis to be expressed
- Intuitively describe an instrument with angles and translations and still be able to recover absolute coordinates

- rotation_angle, polar_angle, rotate 0 1 0
- azimuthal_angle, rotate 0 0 1
- distance, translate 0 0 1
- chi, rotate 0 0 1
- phi rotate, 0 1 0
- NeXus polar coordinate system: rotate azimuthal_angle, rotate polar_angle, translate by distance

CIF Dependency Table

axis-id	type	equipment	dependson	vector	offset
gonio_phi	rotation	goniometer	.	1,0,0,	...
det_z	translation	detector	.	0,0,-1	0 0 0
det_y	translation	detector	det_z	0,1,0	0,0,0
det_x	translation	detector	det_y	1,0,0	0,0,0

- Implied: use existing NeXus coordinate system
- dependson attribute pointing to depending axis
- transform field in base classes which becomes a comma separated list of the path to the transformations required to position this component
- Create a special container to hold axis dependencies, NXdependency, to collect the dependencies in one place for easy access. This is what CIF does


```
sample, NXsample  
  rotation_angle  
  chi (dependson rotation_angle)  
  phi (dependson phi)
```

```
sample, NXsample  
    rotation_angle  
    chi  
    phi  
    transform = rotation_angle,chi,phi
```

```
sample, NXsample
  rotation_angle
  chi
  phi
dependency, NXdependency
  sample/chi =
    sample/rotation_angle
  sample/phi =
    sample/chi
  instrument/detector/x_translation =
    instrument/detector/distance
  instrument/detector/distance =
    instrument/detector/polar_angle
```

sample, NXsample

rotation_angle (vector 0,1,0)

chi (depends_on rotation_angle, vector 0,0,1)

phi (depends_on chi, vector 0,1,0)

depends_on

phi

- Add offset attribute to fully cover CIF. This is an extra translation
- offset_unit to give units for offset
- The vector attribute becomes mandatory
- This gives us CIF endorsement!

- Passing them through NIAC is slow (2 years!)
- Must be documented well enough, no duplicates
- Suggestion: leave to technical group
- Suggestion2: technical group publishes changes to NIAC for intervention

Review of Synchrotron Beamline Components

- NXcapillary
- NXbending_magnet
- NXinsertion_device
- NXxraylens

```
acquisition_mode:NX_CHAR  
angular_calibration:NX_FLOAT[i,j]  
angular_calibration_applied:NX_BOOLEAN  
bit_depth_readout:NX_INT  
countrate_correction__applied:NX_BOOLEAN  
countrate_correction:NX_FLOAT[i,j]  
detector_readout_time:NX_FLOAT  
exposure_time_time:NX_FLOAT  
flatfield:NX_FLOAT[i,j]  
flatfield_applied:NX_BOOLEAN  
flatfield_error:NX_FLOAT[i,j]  
frame_start_number:NX_INT  
frame_time:NX_FLOAT[NP]
```



```
gain_setting:NX_CHAR  
pixel_mask:NX_FLOAT[i,j]  
pixel_mask_applied:NX_BOOLEAN  
saturation_value:NX_INT  
sensor_material:NX_CHAR  
sensor_thickness:NX_FLOAT  
threshold_energy:NX_FLOAT  
trigger_dead_time:NX_FLOAT  
trigger_delay_time:NX_FLOAT
```

- This is about defining materials: samples, filters, multi layers etc.
- Bag of worms
- Recommendation
 - Use textual description
 - When decisive for DA: community should suggest enums

- Neutron event data to be correlated with other time based data
- Dynamic scans collecting detector frames and other data with possibly different sampling rates
- FELS will collect data only dynamically
- We have NXlog
- Questions to the NIAC:
 - Shall NeXus expand into this market?
 - Is the tech committee to be tasked to develop a recommendation how to store this better?