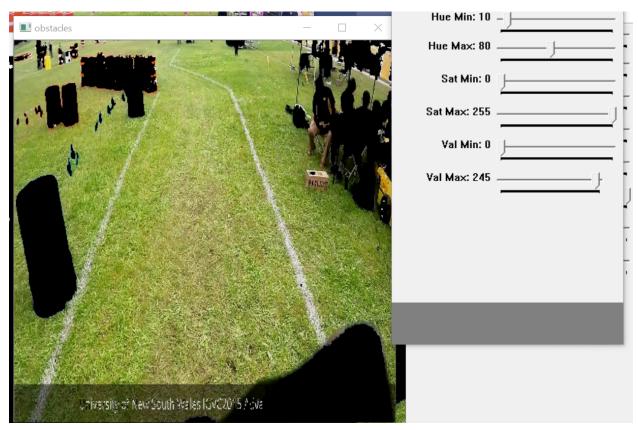
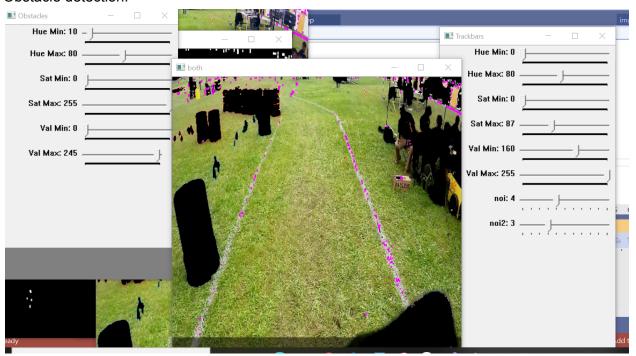


Lane detection



Obstacle detection.



Both implemented together.