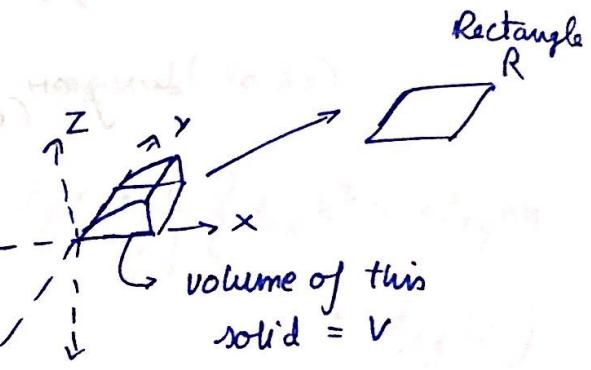


Carry & calculate

MA III

Integrating functions on two variables:



$$V = \iint_R f(x, y) dx dy$$

Here also there is Darboux Sum & Riemann Sum, but everything in two dimensions.

norm of a partition P :

$$\text{norm of } P = \max \left\{ (x_{i+1} - x_i), (y_{j+1} - y_j) \mid \begin{array}{l} i = 0 \dots m-1 \\ j = 0 \dots n-1 \end{array} \right\}$$

Divisions for interval $x_{i+1} = x$

partition test for interior of square

$$f_{\min} * A \leq L(f, P) \leq R(f, P, +) \leq U(f, P) \leq f_{\max} * A$$

compute the sum as follows

$$A = (b-a)(c-d)$$

$$R = [a, b] \times [c, d]$$

Area under the product function

Theorem (Riemann condition):

Let $f: R \rightarrow \mathbb{R}$ be a bounded fn. Then f is integrable if & only if
for every $\epsilon > 0$ there is a partition P_ϵ of R such that:

$$|U(f, P_\epsilon) - L(f, P_\epsilon)| < \epsilon$$

* Regular partitions: equally spaced along each axis.

to check integrability of a fn, it is enough to use regular partitions.

* Domain additivity property: Integral over a rectangle $R =$ sum of areas over sub-rectangles which make up R .

* $| \iint_R f | \leq \iint_R |f|$

Fubini Theorem & the Iterated Integrals:

let $R = [a, b] \times [c, d]$ and $f: R \rightarrow \mathbb{R}$ be integrable. Let I denote the integral of f on R .

1. if for each $x \in [a, b]$, the Riemann integral $\int_c^d f(x, y) dy$ exists,

then the iterated integral $\int_a^b \int_c^d f(x, y) dy dx$ exists & is equal to I .

2. if for each $y \in [c, d]$, the Riemann integral $\int_a^b f(x, y) dx$ exists,

then the iterated integral $\int_c^d \int_a^b f(x, y) dx dy$ exists & is equal to I .

\therefore if f is integrable on R

both \int exists

ONLY THEN $I = I_1 = I_2$



*** :

- * Both iterated integrals may exist but the function may not be integrable.

e.g. $R = [0, 1] \times [0, 1]$

$$f(x, y) = \begin{cases} \frac{xy(x^2-y^2)}{(x^2+y^2)^3}, & (x, y) \neq (0, 0) \\ 0, & (x, y) = (0, 0) \end{cases}$$

- * The function f may be double integrable, but one of the iterated integrals may not exist.
- * If f is a cont. fn. on its domain, then for sure 100% both iterated integrals will exist & the fn. will be double integrable.
- * If f is bounded & monotone in both x, y then f is double integrable.
- * If a fn. is bounded & continuous on R except possibly 2 finitely many points in R , then f is double integrable.

alternate version:

If f is bounded + cont. except possibly along a finite no. of graphs of continuous fns., then f is integrable on \mathbb{R} .

fancy way: f is integrable if pts. of discontinuity of f is a set of "content zero".

BUT

There are fns. who have discontin. which isn't content zero.

but they are still integrable!

- * When we have fns. defined over areas which aren't rectangles, we make a rectangle containing that fn. & then do $\iint f dxdy$.
- choice of rectangle does not matter as only 0 is getting added outside.
- * The boundary of area $D \in \mathbb{R}^2$ is given by ∂D

∂D is of content zero $\rightarrow f$ is int

f is int $\not\rightarrow \partial D$ is of content zero.

Elementary Region : Type 1:

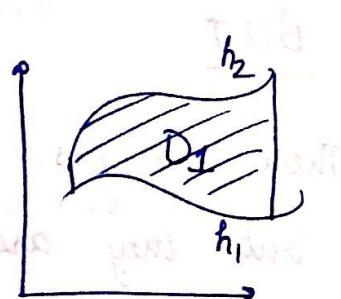
let $h_1, h_2 : [a, b] \rightarrow \mathbb{R}$ be two cont. fns

such that $h_1(x) \leq h_2(x) \quad \forall x \in [a, b]$

Consider the region D ,

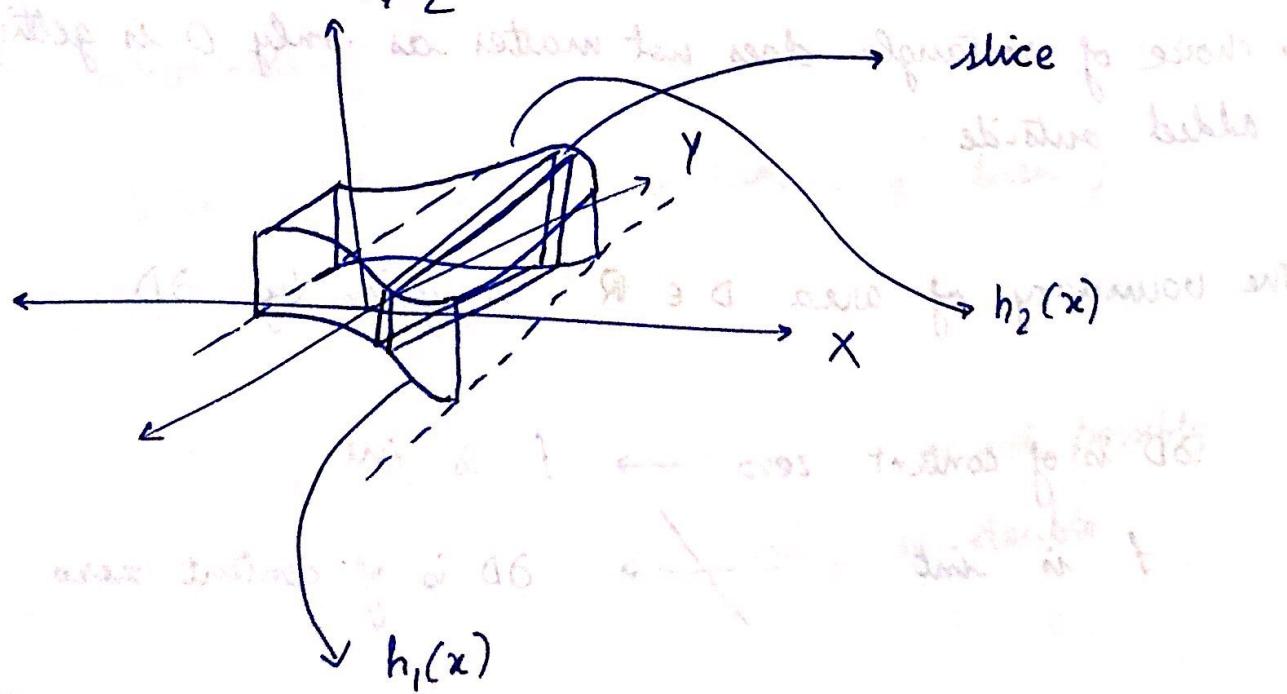
$$D_1 = \left\{ (x, y) \mid a \leq x \leq b \quad \text{and} \quad h_1(x) \leq y \leq h_2(x) \right\}$$

$D_1 \rightarrow$ Type 1 region



∴ Double integrals on this region :

~~for each slice with width Δx and height Δy, volume element ΔV = f(x,y)ΔxΔy~~



$$\text{volume} = \int \text{slice } dx$$

as sqrt of height of slice

$$\text{slice} = \int f(x, y) dy$$

as area of cross section perpendicular to axis of integration

→ limits of slice integral?

$$\rightarrow h_1(x) \text{ & } h_2(x) \text{ at that } x$$

$$\therefore \text{slice} = \int_{h_1(x)}^{h_2(x)} f(x, y) dy$$

→ limits of volume?

* coordinate boundaries of D ,

* projected boundaries $x = h_1(y), h_2(y)$

$$\text{volume} = \int \text{slice}(x) dx$$

$$\int_{a}^{b} 1 - y^2 dy = \frac{2}{3}$$

$$\sqrt{1-y^2} = (y, \sqrt{1-y^2}) \quad \int_{h_1(x)}^{h_2(x)} (1-y^2)^{1/2} dy \Big|_{(b, x)} = 0 \quad \text{for}$$

$$\therefore V = \int_a^b \int_{h_1(x)}^{h_2(x)} f(x, y) dy dx$$

* figure 1 + 2 above → Type I (thin shaped or annulus)

rings \pm sqrt

$$1 \geq x \geq 0$$

$$x - 1 \geq y \geq 0$$

Elementary region : Type 2:

Basically, everything interchanges axes.

now, region is sandwiched b/w two curves of y.

and we take slices along the other axis.

$$V = \int_{c}^{d} \int_{k_1(y)}^{k_2(y)} f(x,y) dx dy$$

c, d → y boundaries of fn.

$k_1(y)$, $k_2(y)$ → cont. curves bounding the region.

e.g. Let $D = \{(x,y) \mid x^2 + y^2 \leq 1, x \geq 0, y \geq 0\}$ $f(x,y) = \sqrt{1-y^2}$

calculate $\iint_D \sqrt{1-y^2} dx dy$

M-I :

Type - 1 region

$$0 \leq x \leq 1$$

$$0 \leq y \leq \sqrt{1-x^2}$$

$$\therefore V = \int_0^1 \int_0^{\sqrt{1-x^2}} \sqrt{1-y^2} dy dx$$

↳ annoying integral.

let's try M-II:

Type - 2 region

$$0 \leq y \leq 1$$

$$0 \leq x \leq \sqrt{1-y^2}$$

$$V = \int_0^1 \int_0^{\sqrt{1-y^2}} \sqrt{1-y^2} dx dy$$

$$= \int_0^1 \int_0^{\sqrt{1-y^2}} (x\sqrt{1-y^2}) dy$$

$$= \int_0^1 1-y^2 dy = \frac{2}{3}$$

... easy!

* Type 1 & 2 unions \rightarrow Type 3+5 (star shaped or annulus)

ob ab a ~

Polar coordinates:

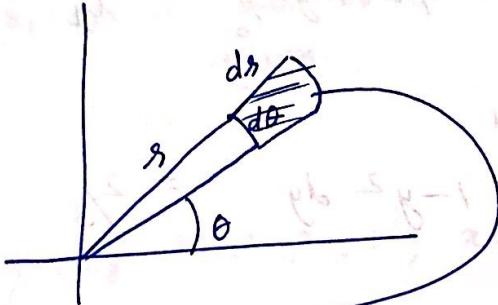
$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$D = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 \leq a^2\}$$

$$D^+ = \{(r, \theta) \mid r \in [0, a], \theta \in [0, 2\pi]\}$$

Rectangles in polar coordinates?



$$A = \frac{1}{2} [(r+dr)^2 d\theta - r^2 d\theta]$$

$$\sim r dr d\theta$$

$$\iint_D f(x, y) dA$$

$$= \iint_D f(x, y) dx dy = \iint_{D^*} f(r\cos\theta, r\sin\theta) r dr d\theta$$

Eg: $\iint_D f(x, y) dx dy$; $f(x, y) = x^2 + y^2$

$$D = \{(x, y) \mid x^2 + y^2 \leq 1\}$$

Transform to polar coords.

$$D^* = \{(r, \theta) \mid r \in [0, 1], \theta \in [0, 2\pi]\}$$

$$f = x^2 + y^2 = r^2$$

$$V = \int_0^{2\pi} \int_0^1 r^2 \cdot r dr d\theta = \int_0^{2\pi} \frac{r^4}{4} \Big|_0^1 d\theta$$

$$= \int_0^{2\pi} \frac{1}{4} d\theta = \frac{\pi}{2}$$

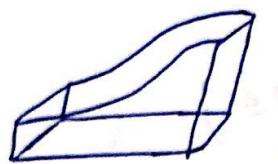
$$\iint_D f(x, y) dx dy = \iint_{D^*} f(r\cos\theta, r\sin\theta) r dr d\theta$$

line of the circle

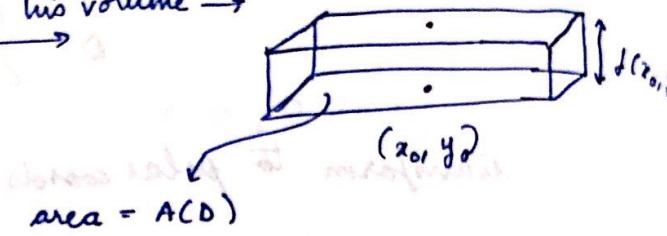
Mean value theorem for double integrals:

If D is an elementary region in \mathbb{R}^2 and $f: D \rightarrow \mathbb{R}$ is continuous, then exists (x_0, y_0) in D such that:

$$f(x_0, y_0) \times A(D) = \iint_D f(x, y) dx dy$$



← his volume
is equal to his volume →



* now we going to do triple integration.
visualising bt ko skta hai.

→ Riemann sum again: $S(f, P_n, t) = \sum_i \sum_j \sum_k f(t_{ijk}) \Delta B_{ijk}$

$f(t_{ijk})$ volume
of element

if $S(f, P_n, t)$ converges to S , then f is integrable.

$$\rightarrow \iiint_B f dV$$

* Integrating over bound regions B in \mathbb{R}^3 .

- if $f: B \subset \mathbb{R}^3 \rightarrow \mathbb{R}$ is bounded and continuous, except at a finite union of graphs of cont. fns of the form:

$$z = f_1(x, y)$$

$$z = f_2(y, z)$$

$$y = f_3(x, z)$$

then it is integrable.

- if $\iiint_B f$ exists then it is equal to $\iint_B f$ — original fn.
 \downarrow
Rectangular
cuboid
- \downarrow
 $f_n + \text{extra zeroes}$
- \downarrow
edgy
volume

* Fubini's theorem:

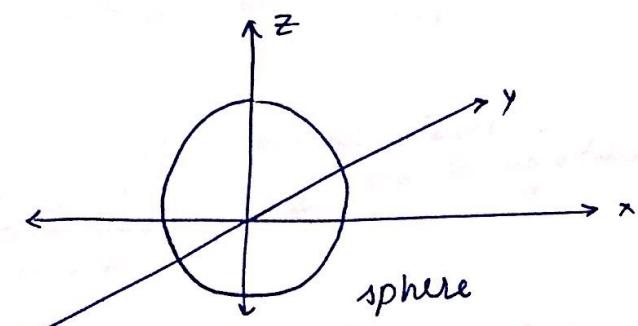
- if f is integrable, any iterated integral that exists HAS TO BE EQUAL TO THE TRIPLE INTEGRAL!

$$\iiint_B f \, dV = \int_{x_1}^{x_2} \int_{y_1}^{y_2} \int_{z_1}^{z_2} f \, dz \, dy \, dx$$

↳ if \exists he exists

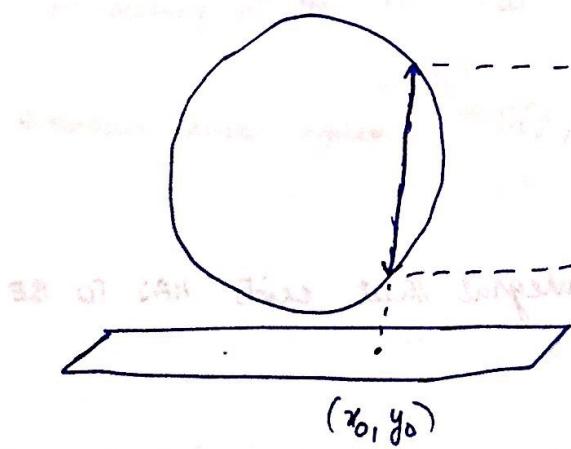
- * if f is cont. on B , then f is integrable on B and all iterated integrals exist & their values are equal to B .

*



in the two ways (1) & ways in 3D with lines

First, let's make a line segment at every (x, y) in the domain of this fn.



$$l = \int_{z_1}^{z_2} dz$$

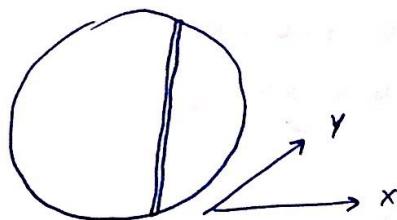
z_1, z_2 are functions of (x, y)

values of z_1 & z_2

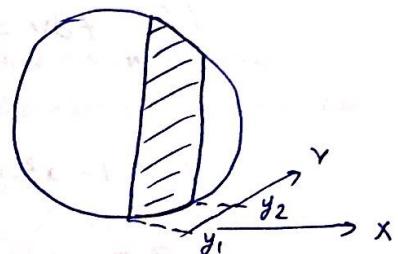
(x, y)

now lets make an area segment

$$A = \int_{y_1}^{y_2} l \, dy$$



on integrating



$y_1, y_2 \rightarrow$ functions of x

bc it changes
for every x

Finally, volume = $\int_{x_1}^{x_2} A \, dx$; $x_1, x_2 \rightarrow$ bounds of x

$$V = \iiint dxdydx$$

+ $\phi_1(x) r_1(x, y)$

if function value changes for different places, incorporate that in the integral,

$$v = \iiint f \, dz \, dy \, dx$$

$$\frac{\pi}{4} = \pi \cdot \frac{1}{4} \cdot \frac{1}{2} = \frac{\pi}{8}$$

eg. $f(x, y, z) = 1$

$$W = \{(x, y, z) \mid x^2 + y^2 + z^2 = 1\}$$

$$\iiint_W f dV = ?$$

$$z^2 = 1 - x^2 - y^2$$

$$\therefore z = \pm \sqrt{1 - x^2 - y^2} \rightarrow z \text{ bounds at } (x, y)$$

$$\text{for volume} = \text{area} \times \text{height}$$

$$\text{equation for area: } l = \int_{-\sqrt{1-x^2-y^2}}^{\sqrt{1-x^2-y^2}} 1 \times dz = l(x, y)$$

$$A = \int_{-\sqrt{1-x^2}}^{\sqrt{1-x^2}} l dy = A(x)$$

To find y bounds,
project the curve
onto x-y plane ($z=0$)

$$V = \int_a^b A dx$$

$$a = -1$$

$$b = 1$$

$$\therefore V = \int_{-1}^1 \int_{-\sqrt{1-x^2}}^{\sqrt{1-x^2}} \int_{-\sqrt{1-x^2-y^2}}^{\sqrt{1-x^2-y^2}} dz dy dx = \frac{4\pi}{3}$$

Change of variables :

consider a $U-V$ plane (a different sort of $X-Y$ plane)

$$x = au + bv + t_1 \quad \dots \text{affine linear functions}$$

$$y = cu + dv + t_2 \quad \dots \text{describes the transformation}$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} + \begin{pmatrix} t_1 \\ t_2 \end{pmatrix}$$

* A square in UV plane gets transformed to a $\parallel gm$ in XY plane.



$$\text{Area of this new } \parallel gm = \left| \begin{matrix} a & b \\ c & d \end{matrix} \right| \cdot \text{area of original square}$$

$$x = h_1(u, v) = au + bv + t_1 ; \quad y = h_2(u, v)$$

$$= cu + dv + t_2$$

$$\therefore \Delta x \sim \frac{\partial h_1}{\partial u} \Delta u + \frac{\partial h_1}{\partial v} \Delta v$$

$$\Delta y \sim \frac{\partial h_2}{\partial u} \Delta u + \frac{\partial h_2}{\partial v} \Delta v$$

OR

$$\begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix} = \begin{pmatrix} \frac{\partial h_1}{\partial u} & \frac{\partial h_1}{\partial v} \\ \frac{\partial h_2}{\partial u} & \frac{\partial h_2}{\partial v} \end{pmatrix} \begin{pmatrix} \Delta u \\ \Delta v \end{pmatrix}$$

$$J(h) = \begin{pmatrix} \frac{\partial h_1}{\partial u} & \frac{\partial h_1}{\partial v} \\ \frac{\partial h_2}{\partial u} & \frac{\partial h_2}{\partial v} \end{pmatrix} = \text{The Jacobian}$$

$$\begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix} + \begin{pmatrix} u \\ v \end{pmatrix} \begin{pmatrix} \frac{\partial h_1}{\partial u} & \frac{\partial h_1}{\partial v} \\ \frac{\partial h_2}{\partial u} & \frac{\partial h_2}{\partial v} \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$$



$|J|$ = scaling factor of area from
U-V plane to X-Y plane



always having area $\begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$ To find jacobian project the curve

(u,v) \rightarrow $x = u + v$ $y = u - v$ \rightarrow (x,y) \in X-Y plane \Rightarrow $\Delta A = \Delta u \Delta v$

$\int \int f(x,y) dx dy$

$$= \int \int f(u+v, u-v) \frac{\partial(x,y)}{\partial(u,v)} du dv$$

$\frac{\partial(x,y)}{\partial(u,v)}$

$$= \int \int f(u+v, u-v) \frac{\partial(u+v, u-v)}{\partial(u,v)} du dv$$

$$= \int \int f(u+v, u-v) \frac{1}{\sqrt{2}} du dv$$

Theorem (Change of variables formula)

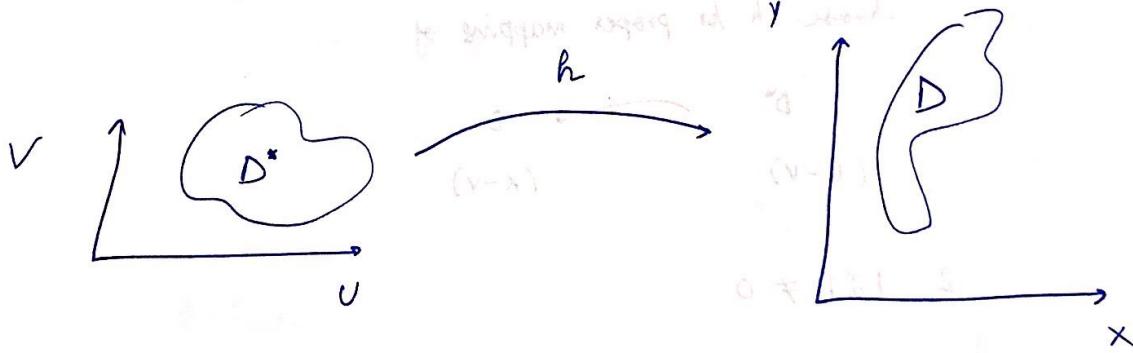
- Let D be a closed & bounded subset of \mathbb{R}^2 such that ∂D has content zero. Let $f: D \rightarrow \mathbb{R}$ be continuous.
- Suppose \mathcal{R} is an open subset of \mathbb{R}^2 and $h: \mathcal{R} \rightarrow \mathbb{R}^2$ is a one-one differentiable function ($h \rightarrow$ transformation matrix)

$$h = \begin{pmatrix} h_1 & h_2 \\ \downarrow & \downarrow \end{pmatrix} \xrightarrow{\text{transform}} X \text{ transform}$$

where h_1 & h_2 have continuous partial derivatives in \mathcal{R}

& $\det J(h) \neq 0 \Rightarrow$ would transform $U-V$ plane into one dimension

- Let $D^* \subset \mathcal{R}$ such that $h(D^*) = D$



then

$$\iint_D f(x,y) dx dy = \iint_{D^*} (f \circ h)(u,v) |J(h)(u,v)| du dv$$

L \rightarrow scaling factor of dA

Integral in XY plane = Integral in $U-V$ plane on transformed area
on original area

* For $|J|$ we write $\frac{\partial(x,y)}{\partial(u,v)} = \frac{dA_{xy}}{dA_{uv}}$

* $UV \xrightarrow{J} XY$

$\therefore dA_{xy} = |J| dA_{uv}$

$|J| = \frac{dA_{xy}}{dA_{uv}}$

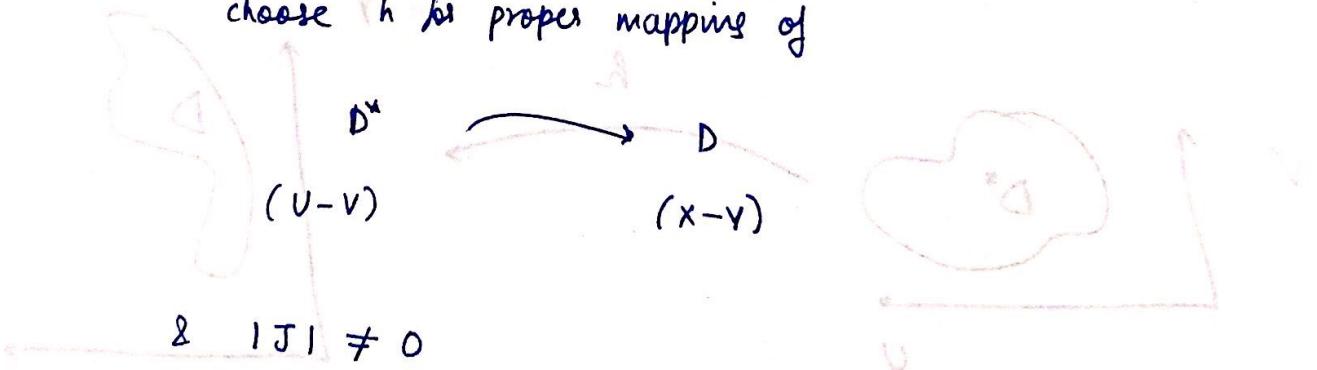
$$\therefore \iint_D f dx dy = \iint_{D^*} f(x(u,v), y(u,v)) |J| du dv$$

* For polar coordinates:

$$\frac{\partial(x,y)}{\partial(r,\theta)} = \begin{vmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{vmatrix} = \frac{r}{r} = 1$$

* For change of variables: $\phi = (x, y)$

choose ϕ for proper mapping of



Boundary
of D^* in $UV \approx$ Boundary of
 D in XY

As per sketch given.

Sketch shows that UV is deeper than XY in depth \Rightarrow area UV is larger

* in 3D:

$$\iiint_P f dV = \iiint_{P_u} |J| J_I dV$$

$$|J| = \frac{\partial(x, y, z)}{\partial(u, v, w)} = \frac{dV_{xyz}}{dV_{uvw}}$$

$$= \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

* Spherical jacobian in 3D:

$$|J| = r^2 \sin \phi$$

of volume factor

$$dV_{xyz} = dV_{r, \theta, \phi} \times |J|$$

Curves & paths

$$\therefore V \text{ of sphere} = \int_0^{2\pi} \int_0^\pi \int_0^R p^2 \sin \phi \cdot r^2 \sin \theta \cdot dr \cdot d\theta \cdot d\phi$$

$$= \frac{4\pi}{3}$$

area of hemisphere divided

* in cylindrical:

$$x = r \cos \theta$$

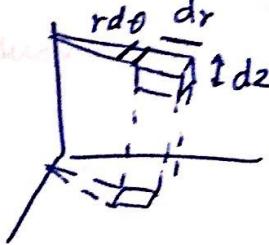
$$y = r \sin \theta$$

$$z = z$$

$$|J| = r \quad (\text{on computing})$$

$$\text{and } dV_{xyz} = dx \cdot dy \cdot dz$$

$$dV_{r,\theta,z} = dr \cdot d\theta \cdot dz \cdot r$$



$$\therefore \text{clearly, ratio} = r$$

* For convert to diff systems to make it easier

↳ cartesian

↳ spherical

↳ cylindrical

↳ polar

$$\text{from } \Phi \rightarrow \phi b \theta b \psi b$$

$$sb \psi b \theta b$$

some values of jacobians:

* spherical:

$$dx dy dz = \underline{r^2 \sin \phi} dr d\phi d\theta$$

* polar:

$$dx dy = \underline{r ds d\theta}$$

* cylindrical:

$$dx dy dz = \underline{r dr d\theta dz}$$

Vector & scalar fields:

- * A vector field \bar{F} is a conservative vector field if it is a gradient of some scalar function i.e. there exists a diff. scalar fn. f such that $\bar{F} = \nabla f$

Curves & paths:

- they are continuous maps from $[a, b] \rightarrow \mathbb{R}^n$



a path where each point corresponds to some n dimensional output

→ cont. if all its one dimensional mappings are individually
cont.

→ closed path $\Rightarrow c(a) = c(b)$

→ simple path $\Rightarrow c(t_1) \neq c(t_2)$

↳ parameter

for any t_1, t_2

Line integrals of vector fields:

$$\int_C \mathbf{F} \cdot d\mathbf{s} = \int_a^b \overline{\mathbf{F}}(c(t)) \cdot \overline{c}'(t) dt$$

dot product of vector at that pt.

w/ tangent vector of path

t is the parameter to traverse $[a, b]$

- convert everything to t and then \int

$$\int_C \mathbf{F} \cdot d\mathbf{s} = \int_a^b F_x dx + \int_a^b F_y dy + \int_a^b F_z dz$$

... cos of
dot product

does nothing
if opposite direction

cancel with a minus

eg. $\int_C x^2 dx + xy dy + dz$

where C is the path from $(0,0,0)$ to $(1,1,1)$.

$$C: [0,1] \rightarrow \mathbb{R}^3, \quad c(t) = \langle t, t^2, 1 \rangle$$

$F = \langle x^2, xy, 1 \rangle$

$$F(c(t)) = \langle t^2, t^3, 1 \rangle$$

$$c'(t) = \langle 1, 2t, 0 \rangle$$

$$\therefore \int_C F \cdot ds = (x^2)dx + (xy)dy + dz$$

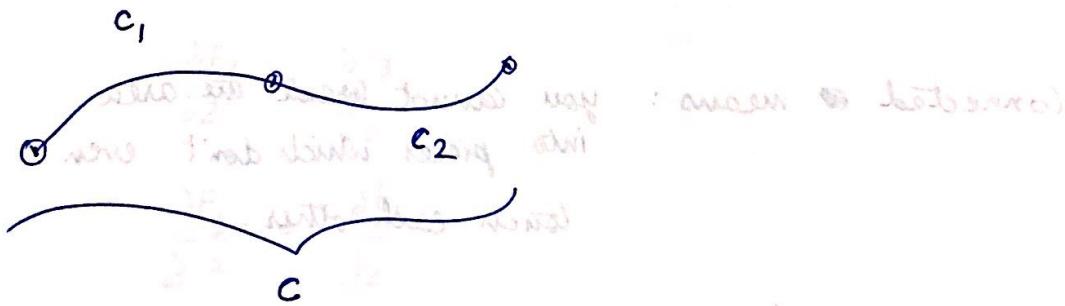
condition for independence (relevant for $\int_C F \cdot ds$)

$$= \int_0^1 t^2 + 2t^4 dt = 11/15$$

\Rightarrow $\int_C F \cdot ds$ independent of path

\Rightarrow $\int_C F \cdot ds$ is well defined

*



gives a new way and may be better than old

old way - the out flow with respect

$$\int_C F \cdot ds = \int_{C_1} F \cdot ds + \int_{C_2} F \cdot ds$$

better way is to write

- * you can reparameterise a path in many ways, but if you start navigating it ~~is~~ in reverse, please put a minus sign!
- * Reparameterisation fn. must be bijective & its inverse also!

FTC:

$$\int_C \nabla f \cdot d\bar{s} = f(c(b)) - f(c(a))$$

$$\int_C \nabla f \cdot d\bar{s} = 0 \quad (\text{closed curve})$$

- independent of path
→ only depend on endpts.

(connected ~~is~~ means: you cannot break the area into pieces which don't even touch each other.)

Path connected: if you can draw even a single path b/w any two pts. such that the entire path lies inside the domain, then it is path connected.

Path connected \Rightarrow connected and between points
 connected $\not\Rightarrow$ path connected

* For a given continuous vector field \bar{F} in \mathbb{R}^n defined on D , an open, path connected subset of \mathbb{R}^n , the vector field \bar{F} is a conservative field if and only if

$\int_C \bar{F} \cdot d\bar{s}$ is independent of path in D .

* conditions for cons. fields: (Necessary but not sufficient)

if $\bar{F} = ab \langle F_1, F_2, F_3 \rangle$ & is a conservative vector field then, in D where $F_1, F_2, F_3 \in C^1$

$$\frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x}, \quad D = \text{open}$$

$$\text{and } \frac{\partial F_2}{\partial z} = \frac{\partial F_3}{\partial y}$$

$$\frac{\partial F_3}{\partial x} = \frac{\partial F_1}{\partial z}$$

* converse is partially true under some additional hypothesis on D .

Simply connected: area w/ no holes & can't consist of 2 or more pieces

* sufficient condition for cons fields:

$D = \text{open} + \text{simply connected}$

same cond. as b⁴.

Summary:

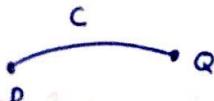
for a given vector field $\bar{F} : D \subset \mathbb{R}^n ; n=2,3$

1. if F is a cont, conservative v.f. i.e. $\bar{F} = \nabla f \rightarrow$ some scalar f , fn.

then

$$\int_C \bar{F} \cdot ds = f(P) - f(Q)$$

... independent of path,
only depends on
endpt.



2. let F be a cont. field & D be an open connected set in \mathbb{R}^n .

Then F is a conservative field if and only if the line integral of F is path independent in D .

3. If $F = \text{cons.}$

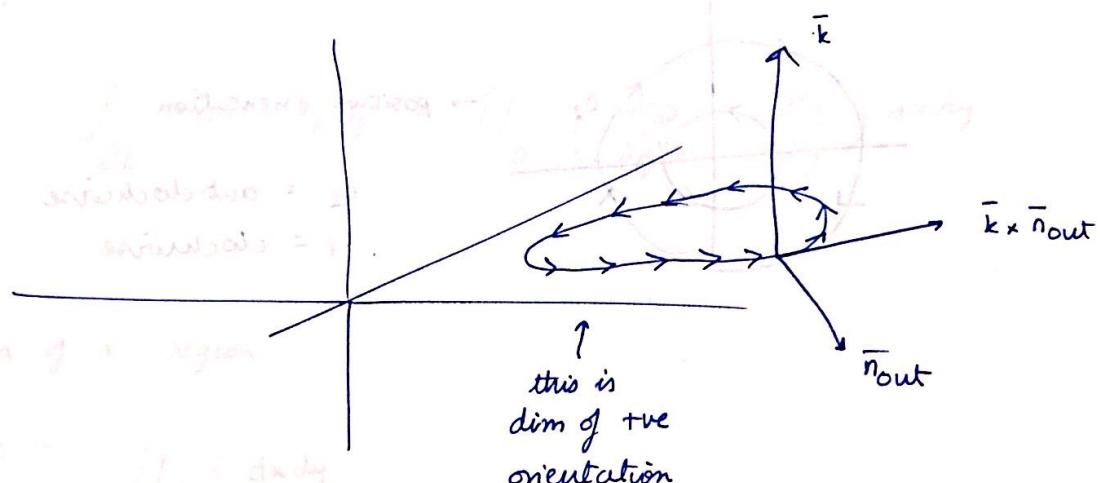
$$\frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x}$$

4. let D be an open, simply connected region in \mathbb{R}^2

F is cons. if & only if

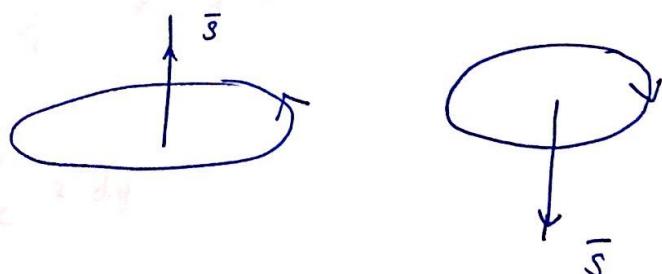
$$\frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x}$$

* direction of positive orientation: $\vec{d} = \vec{k} \times \vec{n}_{\text{out}}$



(while traversing the curve,
the enclosed area is always
on your left
→ anticlockwise)

∴ orientation of boundary induces orientation of area.

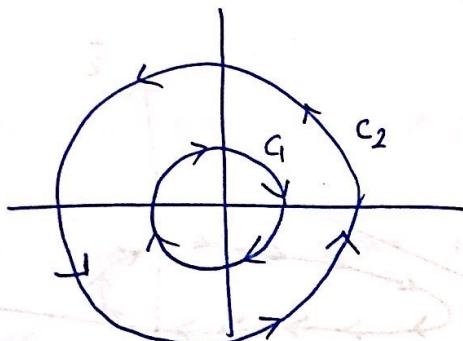


* compare $c'(t)$ with $\bar{k} \times \bar{n}_{\text{out}}$ to see if you are traversing +ve ly or -ve ly.

$$c'(t) = \bar{k} \times \bar{n}_{\text{out}} = +ve$$

$$c'(t) = -\bar{k} \times \bar{n}_{\text{out}} = -ve$$

eg.



→ positive orientation

C_2 = anticlockwise

C_1 = clockwise

→ independent of path,
only depends on
endpt.

(was all previous slides)

* If two regions are separated by open connected set in \mathbb{R}^2

then ∂ is connected iff and only if the two

regions are disjoint

ex. if boundary is made of interiorwise



Green's Theorem:

- Let D be a bounded region in \mathbb{R}^2 with a positively oriented boundary ∂D consisting of a finite no. of non intersecting simple closed curves piecewise c_i curves.
- Let Ω be an open set in \mathbb{R}^2 such that $(D \cup \partial D) \subset \Omega$ and let $F_1 : \Omega \rightarrow \mathbb{R}$ & $F_2 : \Omega \rightarrow \mathbb{R}$ be C_1 fns.

then,

$$\int_{\partial D} F_1 dx + F_2 dy = \iint_D \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy$$

* Area of a region:

$$A = \iint_D 1 dx dy$$

→ choose F_1 & F_2 such that

$$\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} = 1$$

$$\therefore A = \frac{1}{2} \int_C x dy - y dx$$

$$= \int_C x dy$$

$$= - \int_C y dx$$

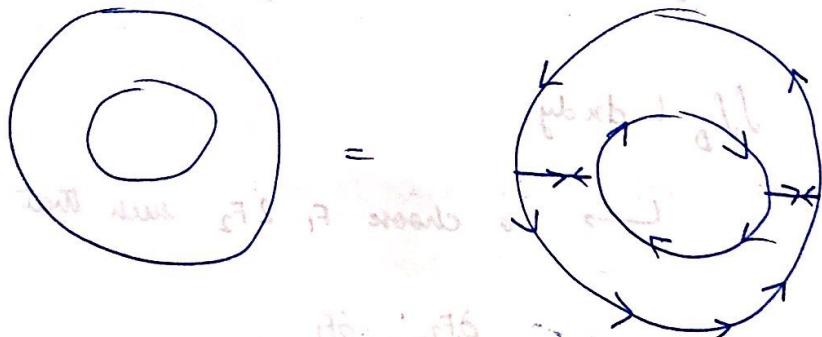
* in polar coords:

$$\begin{aligned} A &= \iint 1 \, dx \, dy \\ &= \frac{1}{2} \int_C x \, dy - y \, dx \\ &= \frac{1}{2} \int_C \left(x(t) \frac{dy}{dt} - y(t) \frac{dx}{dt} \right) dt \end{aligned}$$

$x = a \cos t$
 $y = a \sin t$

\Rightarrow simplifies to $\int_C \frac{1}{2} r^2 d\theta$ = area of v small segment at (r, θ) summed up.

* for edgey areas, break them up:



induced line integrals along boundaries cancel

$$x \, dy - y \, dx \quad \frac{1}{2} \pi a^2$$

$$x \, dy - y \, dx =$$

$$x \, dy - y \, dx =$$

Del operator:

$$\nabla = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}$$

$$\text{curl } \mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

$$\mathbf{F} = \langle F_1, F_2, F_3 \rangle$$

- * For an object in a velocity vector field in XY plane

$$\nabla \times \mathbf{v} = 2 \mathbf{w}$$

curl = $2 \times$ angular velocity about \hat{z} axis

- * $\nabla \times \mathbf{F} = 0 \Rightarrow$ fluid has no rigid rotations
= curl free
= irrotational

let $\mathbf{F} = \nabla f$

$$\therefore \nabla \times \mathbf{F} = \nabla \times \nabla f = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{vmatrix}$$

$$= i \left(\frac{\partial^2 f}{\partial y \partial z} - \frac{\partial^2 f}{\partial z \partial y} \right) = 0$$

$$+ j \left(\frac{\partial^2 f}{\partial z \partial x} - \frac{\partial^2 f}{\partial x \partial z} \right) = 0$$

$$+ k \left(\frac{\partial^2 f}{\partial x \partial y} - \frac{\partial^2 f}{\partial y \partial x} \right) = 0$$

because f is C^2

$$\therefore \bar{\nabla} \times \bar{\mathbf{F}} = 0 \text{ for gradient field}$$

$$\text{curl } \mathbf{F} = 0$$

Green's theorem - curl edition!

$$\oint_{\partial D} \bar{F} \cdot d\bar{s} = \iint_D (\operatorname{curl} \bar{F} \cdot \hat{k}) dx dy$$

$$F(x, y) = F_1(x, y) \hat{i} + F_2(x, y) \hat{j} \quad \bar{F} = \langle F_1, F_2 \rangle$$

D - open + connected

∂D - partial derivative w.r.t. x & y is continuous & ∂D - positively oriented

Conservative field & its curl:

Theorem:

1. let \mathcal{R} be an open, simply connected region in \mathbb{R}^2
2. if $\bar{F} = F_1 \hat{i} + F_2 \hat{j}$ is such that F_1 & F_2 have continuous first order partial derivatives on \mathcal{R} .

then \bar{F} is a cons. field in \mathcal{R} if and only if

Intuitively - $(\frac{\partial F_2}{\partial x}) = (\frac{\partial F_1}{\partial y})$

Also true $\boxed{\nabla \times \bar{F} = 0}$ in \mathcal{R}

Lemma - $\vec{T} \times \vec{T} = \vec{0}$
 Only if the tangent along a line
 must lie in the tangent plane.

$\operatorname{curl} \bar{F} = 0 \not\Rightarrow$ gradient field

gradient field $\Rightarrow \operatorname{curl} \bar{F} = 0$

\vec{F} - tangent plane $\Rightarrow \operatorname{curl} \vec{F} = 0$

Divergence of a vector field:

$$\operatorname{div} \mathbf{F} = \nabla \cdot \bar{\mathbf{F}} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} ; \quad \mathbf{F} = \langle F_1, F_2, F_3 \rangle$$

* divergence of any curl is 0

$$\nabla \cdot (\nabla \times \bar{\mathbf{G}}) = 0 \quad \text{if } \mathbf{G} \text{ is a } C^2 \text{ vector field}$$

Green's theorem - Divergence edition!

Intuitively, since \mathbf{F} is C^2 , we have $\nabla \cdot \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y}$.

$$\int_{\partial D} \bar{\mathbf{F}} \cdot \bar{n} \, ds = \iint_D \nabla \cdot \mathbf{F} \, dx \, dy$$

$$T(t) = \frac{c'(t)}{\|c'(t)\|} \quad \begin{array}{l} \text{- tangent} \\ \text{unit vector} \end{array}$$

$$\bar{n} = \bar{T} \times \bar{k} \quad \begin{array}{l} \text{- normal} \\ \text{unit vector} \end{array}$$

Left Turn $\leftarrow \theta = 7200^\circ$

$\theta = 7200^\circ \leftarrow$ Left Turn

Surfaces:

Let D be a path connected subset in \mathbb{R}^2 . A parameterised surface is a continuous function $\phi: D \rightarrow \mathbb{R}^3$

$$\phi(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$$

$\nabla \bar{\phi}_u$ = partial derivative along u axis (for fixed v_0)

$$\nabla \bar{\phi} \cdot (1, 0)$$

$$\text{Surface tangent} = \frac{\partial \phi}{\partial u} = \left\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right\rangle$$

$\nabla \bar{\phi}_{v_0}$ = partial derivative along v axis (for fixed u_0)

domain of ϕ contains the region non-parameterised surface $\phi(v_0 - \delta, v_0 + \delta)$, then the surface integral of f over this region is $\int_{v_0-\delta}^{v_0+\delta} \int_{u_0-\delta}^{u_0+\delta} f(\phi(u, v)) du dv$

$$= \frac{\partial \phi}{\partial v} = \left\langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \right\rangle$$

these are the tangents along 2 dir.

\therefore they lie in tangent plane

$$\therefore \bar{n}_t = \frac{\nabla \bar{\phi}_u \times \nabla \bar{\phi}_v}{\|\nabla \bar{\phi}_u \times \nabla \bar{\phi}_v\|}$$

$$\& \pi: \text{tangent plane} = (x, y, z) :$$

$$\bar{n}_{(u_0, v_0)} \cdot \langle (x - x_0), (y - y_0), (z - z_0) \rangle = 0$$

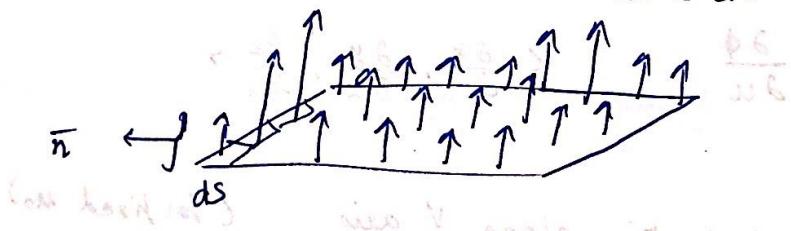
* Non-singular surface: non-zero \bar{n}

singular surface: $\bar{n} = \text{null vector}$

* $\text{Area}(\phi) = \iint_E \|\bar{\phi_u} \times \bar{\phi_v}(u, v)\| du dv$

* ϕ : function from E in \mathbb{R}^2 to \mathbb{R}^3

$\|\bar{\phi_u} \times \bar{\phi_v}\| = \cancel{\text{normal vector magnitude}}$ for area $dS = du dv$



since:

(i) ∂E is of content zero

(ii) $\bar{\phi_u} \times \bar{\phi_v} \rightarrow$ cont. on E \Rightarrow tangent plane $\frac{\partial \phi}{\partial u}, \frac{\partial \phi}{\partial v}$ - null vector

↪ integral is well defined

$dS = \|\bar{\phi_u} \times \bar{\phi_v}\| du dv$ \rightarrow surface integral with the unit vector

$$\therefore \text{Area} = \iint dS = \sqrt{\det(g_{ij})} du dv$$

smooth function ϕ : π

$$d\bar{s} = \bar{\phi}_u \times \bar{\phi}_v$$

~~Surface area element~~ \Rightarrow surface area

$$= \begin{vmatrix} i & j & k \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{vmatrix}$$

$$|ds| = \sqrt{x_{ds}^2 + y_{ds}^2 + z_{ds}^2}$$

Surface integral of a vector field:

~~using the parameterisation~~ \bar{F} : bounded vector field on \mathbb{R}^3 ~~over the surface~~

domain of F contains the singular non parameterised surface $\phi: E \rightarrow \mathbb{R}^3$, then the surface integral of F over S is

$$\iint_S \bar{F} \cdot d\bar{s} = \iint_E \bar{F}(\phi(u, v)) \cdot (\bar{\phi}_u \times \bar{\phi}_v) du dv$$

$$\text{which } \bar{\phi}_u \times \bar{\phi}_v \Rightarrow = \hat{n} \text{, } \iint_E \bar{F} \cdot \hat{n} ds \text{, } ds = dx$$

* How to solve q's:

write surface as $\langle x, y, z \rangle = \langle f_1, f_2, f_3 \rangle$

∇P_x = change vector along x

$$= \left\langle \frac{\partial f_1}{\partial x}, \frac{\partial f_2}{\partial x}, \frac{\partial f_3}{\partial x} \right\rangle$$

$$\nabla P_y = " \quad \text{[magnitude of } \sqrt{\left(\frac{\partial f_1}{\partial y}\right)^2 + \left(\frac{\partial f_2}{\partial y}\right)^2 + \left(\frac{\partial f_3}{\partial y}\right)^2} \text{]} = \| \mathbf{k}_y \|$$

$$= \left\langle \frac{\partial f_1}{\partial y}, \frac{\partial f_2}{\partial y}, \frac{\partial f_3}{\partial y} \right\rangle \text{ [magnitude of } \sqrt{\left(\frac{\partial f_1}{\partial y}\right)^2 + \left(\frac{\partial f_2}{\partial y}\right)^2 + \left(\frac{\partial f_3}{\partial y}\right)^2} \text{]}$$

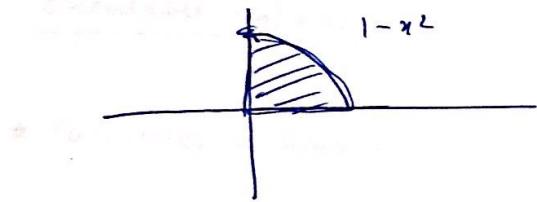
$$\bar{n} = \nabla P_x \times \nabla P_y$$

since $\bar{F} = \langle F_1, F_2, F_3 \rangle$ has direction & p means
that \bar{F} is perpendicular to surface

• F_1 = function of $\langle x, y, z \rangle$ in 2 ways

• F_2 = function of $\langle x, y, z \rangle$
• F_3 = function of $\langle x, y, z \rangle$

$$\iint_{\text{surface}} \bar{F} \cdot d\bar{s} = \iint_{\text{xy-plane}} \langle F_1, F_2, F_3 \rangle \cdot (\nabla P_x \times \nabla P_y) dx dy$$



* Reparameterising surfaces:

- magnitude will stay same
- sign may change

Let $\phi: E \rightarrow \mathbb{R}^3$ be a smooth parameterised surface.

Suppose $\tilde{\phi} = \phi \circ h$ is a repara. of ϕ .

How do the normal vectors (and the area they denote) transform?

$$(\tilde{\phi}_{\tilde{u}} \times \tilde{\phi}_{\tilde{v}})(\tilde{u}, \tilde{v}) = (\phi_u \times \phi_v)(u, v) \times \text{scaling factor}$$

\downarrow

Area in $\tilde{u}-\tilde{v}$ space

* If the exists a function h we can get out a normal vector at every pt on ~~the surface~~ that $\tilde{\phi}(u, v) = h(u, v)$

~~function~~ say that the surface is ~~orientable~~

If a param. of the surface has the same Area in $u-v$ space

$$u, v \xrightarrow{J\tilde{h}} \tilde{u}, \tilde{v}$$

$$A_{uv} = \frac{A_{\tilde{u}\tilde{v}}}{|J|}$$

if $J > 0$:

$$\iint_{\tilde{\phi}} \bar{F} \cdot d\bar{s} = \iint_{\phi} F \cdot ds$$

if $J < 0$:

$$\iint_{\tilde{\phi}} \bar{F} \cdot d\bar{s} = - \iint_{\phi} \bar{F} \cdot ds$$

* if $\tilde{\phi}(\tilde{u}, \tilde{v}) = \phi(\tilde{v}, \tilde{u})$ (variable exchange)

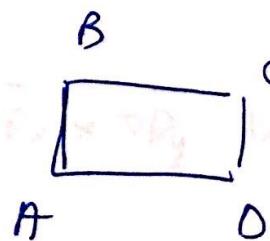
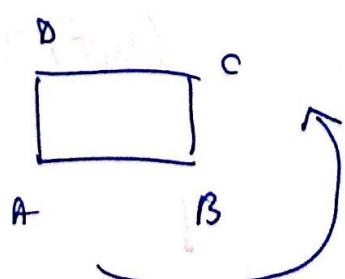
the new surface is called

'opposite' of the old one

$$\iint_{\text{opp}} \bar{F} \cdot d\bar{s} = - \iint_{\phi} \bar{F} \cdot ds$$

$$(\phi \#)^{\text{opp}} = \phi$$

opposite



ACW: ABCDA

ACW: ADCBA

Orientable surfaces:

* Parameterised surface:

$$\hat{n}(u, v) = \frac{\phi_u \times \phi_v}{\|\phi_u \times \phi_v\|}$$

↓

normal unit vector at a pt. (u, v)

$$\phi_u = \frac{\partial f_x}{\partial u}, \frac{\partial f_y}{\partial u}, \frac{\partial f_z}{\partial u}$$

$$\phi_v = \frac{\partial f_x}{\partial v}, \frac{\partial f_y}{\partial v}, \frac{\partial f_z}{\partial v}$$

* implicit surface:

$$F(x, y, z) = 0$$

normal unit vector $\hat{n} = \frac{\nabla F(P)}{\|\nabla F(P)\|}$

P is a pt. where we are finding \hat{n}

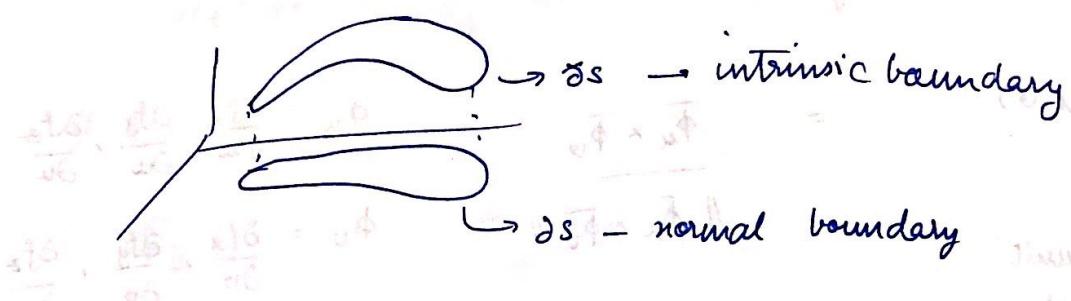
* if there exists a cont. fn. which can spit out a normal vector at every pt. on inputting that point

then we say that the surface is orientable

if a param. of S ~~not~~ yields same \hat{n} = ori-preserved

" " opposite \hat{n} = ori-reversed

Intrinsic boundary



Stokes Theorem:

Let S be piecewise C^2
bounded

oriented (imp.) surface in \mathbb{R}^3 , $\sigma = (s, \theta, z)$

where piecewise smooth intrinsic boundary ∂S
consists of a finite no. of non-intersecting simple closed
curves along w/ induced orientation

F = smooth vector field

$$\int_{\partial S} \bar{F} \cdot d\bar{r} = \iint_S \text{curl } F \cdot \hat{d}S$$

* To find area:

$$\iint_S \sqrt{1+z_x^2+z_y^2} dx dy$$

$$z_x = \frac{\partial z}{\partial x} \quad z_y = \frac{\partial z}{\partial y}$$

$$z = f(x, y)$$

$$\text{OR } \iint_S \sqrt{1+y_x^2+y_z^2} dx dz$$

$$y = f(x, z)$$

Surface integrals of \bar{F} are independent if

$$\iint_{\phi} \bar{F} \cdot d\bar{S} = \iint_{\tilde{\phi}} \bar{F} \cdot d\bar{S} \quad \phi - \tilde{\phi} = \text{ct}$$

ie if $\phi, \tilde{\phi}$ define

$\phi, \tilde{\phi}$ lie in D

& have same intrinsic boundary & same orientation

* How to check if F is a curl field?

not necessary

BUT NOT : $\operatorname{div} F = 0$

sufficient
condition

↳ simply connected domain

Consequences of Stokes Theorem:

F - smooth vector field on an open subset D of \mathbb{R}^3
such that $\operatorname{curl} F = 0$ on D

(i) Suppose S is a bounded oriented piecewise C^2 surface
in D , ∂S - intrinsic boundary

$$\int_{\partial S} \bar{F} \cdot d\bar{\gamma} = 0$$

$$\text{if } \partial S = C_1 - C_2, \quad \partial S = C_1 \cup C_2$$

$$C_1 = -C_2$$

$$\int_{C_1} \bar{F} \cdot d\bar{\gamma} = \int_{C_2} \bar{F} \cdot d\bar{\gamma}$$

(ii) if D is simply connected, $F = \nabla f$

* if $\partial S = \emptyset$ (null)

∂S - i.b of surface S

$$\Rightarrow \iint_S \operatorname{curl} F \cdot dS = 0$$

Gauss Divergence Theorem:

Let D be a closed & bounded subset of \mathbb{R}^3 whose boundary ∂D consists of a finite no. of non intersecting piecewise smooth surfaces w/o any edges & is tve by oriented .

Let F be a smooth vector field in D .

$$\iint_{\partial D} \bar{F} \cdot d\bar{S} = \iiint_D (\operatorname{div} F) dx dy dz$$

To find volume:

choose F so that $\operatorname{div} F = 1$

$$F = \left\langle \frac{x}{3}, \frac{y}{3}, \frac{z}{3} \right\rangle$$

$$\therefore V = \iint_{\partial D} \bar{F} \cdot d\bar{S}$$

$$= \iint \left(\frac{x}{3} \|\phi_y \times \phi_z\| dy dz + \frac{y}{3} \|\phi_x \times \phi_z\| dx dz + \frac{z}{3} \|\phi_x \times \phi_y\| dx dy \right)$$

$$\hookrightarrow \det \begin{bmatrix} x & y & z \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{bmatrix} \neq d(u, v)$$

that is called the Wronskian

$$\text{vol} = \frac{1}{3} \iint_E W(x, y, z) (u, v) \cdot d(u, v)$$

- * if $\iint F \cdot dS$ is a lengthy calc, maybe $\iiint \text{div } F \cdot dv$ can be shorter

$$[\text{by part 3 int)} \text{ vol} = \frac{1}{3} b \cdot \bar{A} \text{ vol}$$

- * F is smooth vector field on an open subset containing a closed and bounded subset D of \mathbb{R}^2 such that $\text{div } F = 0$ on D & if ∂D consists of finite nonintersecting closed piecewise smooth surfaces, oriented by outward normals

$$\iint F \cdot dS = 0$$

∂D

$$\frac{1}{3} b \cdot \bar{A} \text{ vol} = 0$$

* if $\text{div } F = 0$ & $\text{curl } F \neq 0$ then $\iint F \cdot dS \neq 0$ on ∂D surface

$$\iint \text{curl } F \cdot dS \neq 0$$

$$\text{curl } F \cdot dS \neq 0$$

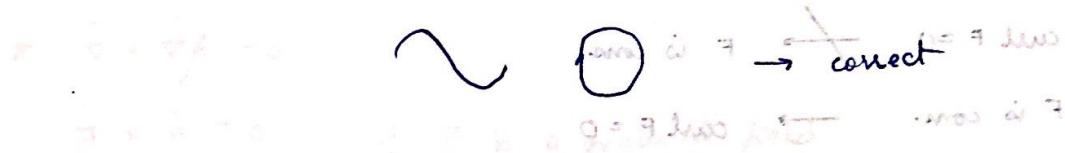
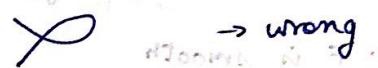
MA 111 formula sheet:

* closed path: start pt. = end pt. has no self intersections *

$$c(a) = c(b) \quad a = b \text{ does}$$

After 1st lesson: where parameter $\in [a, b]$, $a < b$.

* simple path: path does not intersect itself
between points *



* connected area: you cannot break the area into pieces which don't even touch each other *

* path connected: for any two pts. in that domain (all possible pairs), if you can draw

at least one path connecting them
which lies entirely in the domain,
then its path connected

path connected \rightarrow connected

connected \nrightarrow path connected

* simply connected: area w/ no holes & cannot consist of two or more pieces

simply connected \rightarrow path connected + connected

path connected \nrightarrow simply connected

connected \nrightarrow simply connected

- * condition for cons. field $\text{curl } F = 0$: entire domain is open & simply connected
- * $\text{curl } F = 0$
- * D - area on which F is defined must be
- * $\text{curl } F = 0 \rightarrow F$ is smooth

$$\text{curl } F = 0 \rightarrow F \text{ is cons.}$$

$$F \text{ is cons.} \rightarrow \text{curl } F = 0$$

- * dim of the orientation of $\bar{d}s = \bar{k} \times \bar{n}$ units

(area will be

(a) right) πr^2 and for (b) πr^2
area is πr^2 . (area division)

- * Green's Theorem / Stokes Theorem: $\int_C \bar{F} \cdot d\bar{r} = \iint_S \text{curl } F \cdot \bar{n} dS$; $C = \partial S$

conditions:

on S : \rightarrow bounded region in \mathbb{R}^2

\rightarrow positively oriented boundary (very very imp!!!)
using arrows no out flow

C : - consists of finite

non intersecting
simple

closed \leftrightarrow ∂S
piecewise C_1 curves

$$\mathbf{F} = \langle F_1, F_2 \rangle$$

$F_1, F_2 \rightarrow C_1$ fns.

Area = $\frac{1}{2} \int_C x dy - y dx$ if otherwise it is surface *
surface outwards orientation. Then it

$$= \int_C x dy = - \int_C y dx$$

: this is a p. of stokes at surfaces transposed *

* $\bar{\nabla} \times \bar{\nabla} f = 0$

$\bar{\nabla} \times \bar{F} = 0$ if F is a gradient field

* $\bar{\nabla} \cdot (\bar{\nabla} \times \bar{G}) = 0$ if G is a C^2 vector field

div. of any curl is 0

* Green's theorem - Divergence form:

(for Γ being a closed boundary) holds : 0 ms

$$\int_{\partial D} \bar{F} \cdot \bar{n} ds = \iint_D (\bar{\nabla} \cdot \bar{F}) dx dy$$

* Surface parameterised by $\langle u, v \rangle$:

$$\bar{dS}_{uv} = \overline{\phi_u \times \phi_v} \cdot du dv$$

where ϕ is the surface mapping

$$\text{Area} = \iint_E \|\bar{dS}\| \rightarrow \text{when } \partial E \text{ is of content zero}$$

$$\phi \text{ is } \bar{\phi}_u \times \bar{\phi}_v \rightarrow \text{cont. on } E$$

$$\hat{n} = \frac{\nabla F(P)}{\|\nabla F(P)\|}$$

- * surface is orientable if assignment of normals for every ds is cont. throughout the surface.

$$dS = b \times d$$

- * Sufficient condition to check if F is a curl field:

$$\cdot \operatorname{div} F = 0$$

- domain is simply connected

$$o = \bar{F} \times \bar{v}$$

$$o = \bar{v} \times \bar{F}$$

- * Gauss Divergence Theorem:

$$\iint_{\partial D} \bar{F} \cdot d\bar{S} = \iiint_D \operatorname{div} F \, dv$$

$$\iint_{\partial D} \bar{F} \cdot d\bar{S} = \iiint_D \operatorname{div} F \, dv \quad o \text{ is low func for sub}$$

conditions:

on D : closed (boundary pts. are part of set)

bounded (subset of \mathbb{R}^3)

on ∂D : POSITIVELY ORIENTED

consists of finite

non intersecting

piecewise smooth surfaces w/o any edges

on F : smooth vector field on D .

$$V = \frac{1}{3} \iint_E \text{Paraboloid } y = \frac{x^2 + z^2}{2} \text{ von oben } A$$

and die Integration

$$\left| \begin{array}{ccc} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \cancel{\frac{\partial x}{\partial v}} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{array} \right| du dv$$

: Determinant
zu schreiben

$x = u$, $y = v$ \rightarrow $\text{Basis des Paraboloids}$
Länge & Breite des $(0,0)$ zu (∞, ∞)

$$A \in \mathbb{R}^{n \times n} \rightarrow \mathbb{R}^m \text{ Range } J_{AB} = T(A)$$

antidifferenzierung nach
gewünschtes $A \circ B \Leftrightarrow$ Verteilung der Abstörungen $\rightarrow \delta A$

$$J_B^{-1} A \text{ (Antwort - Ant)} \\ \text{b. und ant}$$

Scaling matrix: (Bauborg selbst/Bauborg sonst) : Bauborg

of skin back to native units out of benefit:
 $\delta A \rightarrow$
 $\delta A \text{ in scaling message} \rightarrow$

Other options & matrices:

$\left[\begin{array}{c} w \\ g_w \end{array} \right] = w$	$\left[\begin{array}{c} w \\ g_w \\ h \end{array} \right] = w$
no scaling given in $\left[\begin{array}{c} w \\ g_w \end{array} \right]$ preferable	$\left[\begin{array}{c} w \\ g_w \\ h \end{array} \right]$