

Newtonian mechanics & electrodynamics were established nicely but some problems came:

(1) $\bar{E} \perp \bar{B}$ depending on frame (if \vec{v}_{rel} is diff.,
 \bar{B} is diff.)

(2) $\bar{F} = q(\bar{E} + \vec{v} \times \bar{B})$ is not consistent in diff frames.

(3) speed of light $c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$ comes out to be constant (independent of frame?!)

so lot, newtonian relativity & galilean transformations do not apply to electrodynamics

→ it is not right, so we had to find a new theory.

* ether was the ref. frame where v_{light} came out to be $= c$

• so, what was wrong? EM? NM? PR? GT?

Einstein correctly showed that it was

NM + GT

Einstein's postulates:

- ① Principle of relativity (all frames are ~~equally~~ equivalent)
- ② Speed of light in free space is same in all ref. frames

→ instead of proving this, he chose this as a postulate

step 1: make new transformation laws

& bkt Newton

→ (Lorentz transformation)

* Read up some more about inertial ref. frames.

- An implicit assumption in Einstein's postulates is that space & time are homogeneous

(space (length) intervals & time intervals are same always & anywhere (not frame to frame, anywhere within space of their frame))

let's derive the Lorentz transformations:

relate (x, y, z, t)

(x', y', z', t')

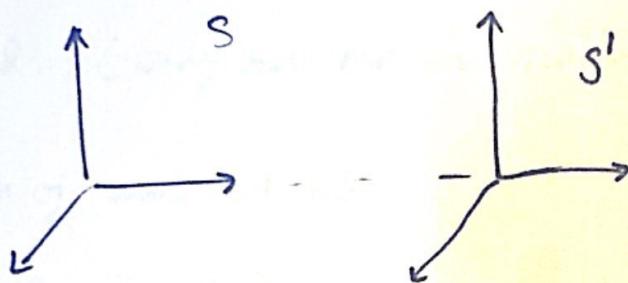
using the fact that space & time are homogeneous we can deduce that the Ans. must be linear.

$$x' = a_{11}x + a_{12}y + a_{13}z + a_{14}t$$

$$y' = a_{21}x + a_{22}y + a_{23}z + a_{24}t$$

$$z' = a_{31}x + a_{32}y + a_{33}z + a_{34}t$$

$$t' = a_{41}x + a_{42}y + a_{43}z + a_{44}t$$



x axis coincides w/ x' axis

if $y \perp z = 0$

$$\Rightarrow y' \perp z' = 0$$

$\Rightarrow y' \perp z'$ depend on $y \perp z$ only

(because n & t are independent vars which cant make $y' \perp z' = 0$)

w/ similar logic about xy & $x'y'$ plane

we simplify further:

now,

$$x' = a_{11}x + a_{12}y + a_{13}z + a_{14}t$$

$$y' = a_{22}y$$

$$z' = a_{33}z$$

$$t' = a_{41}x + a_{42}y + a_{43}z + a_{44}t$$

* Using PR. (only rel. motion matters)

(i) length of unit rod in S' (look part i)

is a_{22} in S'

(ii) length of unit rod in S

is $\frac{1}{a_{22}}$ in S

but these must be same cos all frames
are equivalent

$$\Rightarrow \frac{1}{a_{22}} = a_{22}$$

$$\Rightarrow a_{22} = 1$$

a_{22} can't be -1 because it flips orientation

but all frames are equivalent & orientation
must also be invariant on changing
frames.

now, $x' = a_{11}x + a_{12}y + a_{13}z + a_{14}t$

$$y' = a_{21}x + a_{22}y + a_{23}z + a_{24}t$$

$$z' = a_{31}x + a_{32}y + a_{33}z + a_{34}t$$

$$t' = a_{41}x + a_{42}y + a_{43}z + a_{44}t$$

* t is independent of y & z

+ y & $-y$ both give same t so y & $-y$

+ z & $-z$ both give same t so z & $-z$

∴ they don't affect t (neglect)

same for x

∴ x is independent of y & z (neglect)

∴

$$x' = a_{11}x + a_{14}t \quad z \text{ is } \frac{1}{ssD}$$

$$y' = y$$

∴ y is independent of x & t (neglect)

$z' = z$ is independent of x & t (neglect)

$$t' = a_{41}x + a_{44}t$$

$$\frac{1}{ssD} = \frac{1}{ssD}$$

General Method

$$1 = \frac{1}{ssD}$$

if x has

velocity with it constant (neglect) ssD

* $x' = a_{11}(x - vt)$ common to all

because v is direction of only depth

because $x' = 0$

always means

$x = vt$ at same

when the frames start moving :

let a light bulb flash from the origin
& an EM pulse is emitted

• write their eqns :

$$x^2 + y^2 + z^2 = c^2 t^2$$

$$x'^2 + y'^2 + z'^2 = c^2 t'^2$$



$$a_{11}^2(x-vt)^2 + y^2 + z^2 = c^2(a_{41}x + a_{44}t)^2$$

$$a_{11}^2(x^2 + v^2 t^2 - 2xt) + y^2 + z^2 = c^2(a_{41}^2 x^2 + a_{44}^2 t^2 + 2a_{41}a_{44}xt)$$

$$a_{11}^2 - c^2 a_{41}^2 = 1 \quad - \quad (x^2 \text{ coeff})$$

$$c^2 a_{44}^2 - a_{11}^2 v^2 = c^2 \quad - \quad (t^2 \text{ coeff})$$

$$-a_{11}^2 2v = c^2 2a_{41}a_{44} \quad - \quad (xt \text{ coeff})$$

$$a_{11}^2 = 1 + c^2 a_{41}^2$$

$$a_{11}^2 = \frac{c^2(a_{44}^2 - 1)}{v^2}$$

$$a_{11}^2 = -\frac{c^2 a_{41} a_{44}}{v}$$

on solving : ~~positions in velocity~~
~~length contraction~~

$$a_{44} = \frac{1}{\sqrt{1-v^2/c^2}}$$

$$a_{11} = \frac{1}{\sqrt{1-v^2/c^2}} = \gamma$$

$$a_{41} = -\frac{v}{c} \frac{1}{\sqrt{1-v^2/c^2}} = \gamma v$$

\therefore Lorentz transformation comes as:

$$(dx', dy', dz') = \frac{x - vt}{\sqrt{1-v^2/c^2}} \hat{i}$$

$$y' = y$$

$$z' = z$$

$$t' = \frac{t - \frac{vx}{c^2}}{\sqrt{1-v^2/c^2}}$$

* we use some notations:

$$\frac{v^2}{c^2} = \beta^2$$

where β is between 0 & 1
in fact $\beta = v/c$ (from theory)

$$\frac{1}{\sqrt{1-v^2/c^2}} = \gamma \quad (\text{as } \sqrt{1-\beta^2} = \sin \theta)$$

Some consequences of this:

① Time dilation

② Length contraction

③ Synchronization & simultaneity

Let's examine ②:

A rod has rest length $x_2' - x_1'$ in s' frame (moving)

$$x_2' = \frac{x_2 - vt_2}{\sqrt{1-\beta^2}}$$

$$x_1' = \frac{x_1 - vt_1}{\sqrt{1-\beta^2}}$$

$$x_2' - x_1' = \frac{(x_2 - x_1) - v(t_2 - t_1)}{\sqrt{1-\beta^2}}$$

* t_2 has to be $= t_1$ for length to be measured in a moving frame (simultaneity) $\Rightarrow x'_2 - x'_1 = \frac{x_2 - x_1}{\sqrt{1-\beta^2}}$

$$\Rightarrow \Delta l = \sqrt{1-\beta^2} \Delta l'$$



less than 1

so we observe a contracted length.

* any length L to the motion is unaffected.

* now lets see time dilation:

$$t = t' + \frac{v}{c^2} x' \quad - \text{why?}$$

(given) and $\frac{v}{c^2} = \frac{v}{\sqrt{1-v^2/c^2}}$

bec. $v_{rel} = -ve$
on switching frames

$$t_2 - t_1 = \frac{t'_2 - t'_1 + \frac{v}{c^2} (x'_2 - x'_1)}{\sqrt{1-v^2/c^2}} \quad - \text{why?}$$

$$\Delta t = \frac{\Delta t'}{\sqrt{1-v^2/c^2}}$$

③ simultaneity & synchronization

$$S' \quad \text{---} \quad \oplus \quad \textcircled{1} \quad \textcircled{1} \quad \textcircled{1} \quad \textcircled{1} \quad \textcircled{1} \quad \oplus \quad \text{---}$$

$x' = -$ \longleftrightarrow $x' = +$ $\rightarrow v$

$$S \quad \text{---} \quad \textcircled{1} \quad \textcircled{1} \quad \textcircled{1} \quad \textcircled{1} \quad \textcircled{1} \quad \text{---}$$

when $x' = +ve$ because $t = \text{const.}$

$$t' = -ve$$

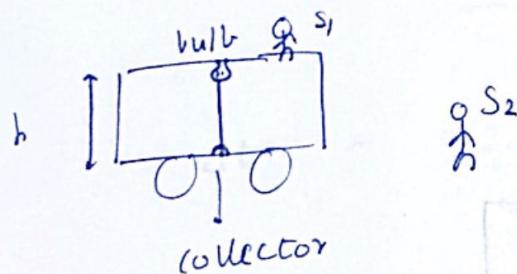
(synchronised
clocks in S)

$$x' = -ve$$

$$t' = +ve$$

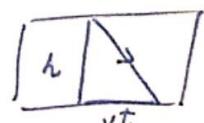
so stuff changes in S'

Time dilation expl.



$$t_1 = \frac{h}{c}$$

for t_2 : path of light is



$$t_2 = \frac{\sqrt{h^2 + v^2 t_1^2}}{c}$$

$\hookrightarrow \text{not } \sqrt{c^2 + v^2} //$
(acc. to Galileo)

$$\Rightarrow t_2 = \frac{\sqrt{h^2 + v^2 t_2^2}}{c}$$

$$c^2 t_2^2 = h^2 + v^2 t_2^2$$

$$t_2^2 (c^2 - v^2) = h^2$$

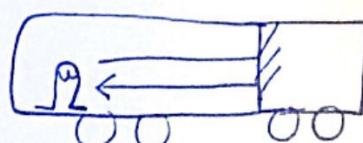
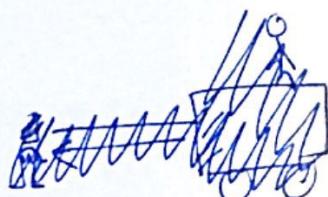
$$t_2 = \frac{h}{\sqrt{c^2 - v^2}}$$

$$= \frac{h}{c} \cdot \frac{1}{\sqrt{1 - v^2/c^2}}$$

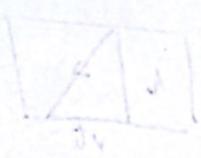
homework problem

$$(L_{\text{at rest}}) = t_1 \cdot \frac{1}{\sqrt{1 - v^2/c^2}}$$

length contraction cpt:

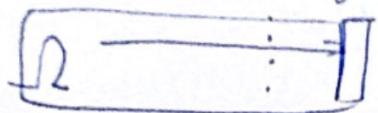


$$\Delta t' = \frac{2 \Delta x'}{c}$$



in relativity

while going, the front moved ahead by $v \Delta t$,



while coming back, the

back moved ahead by $v \Delta t_2$

$$\Delta t_1 = \frac{\Delta x + v \Delta t}{c} \quad (\text{time taken to hit cart})$$

$$\Delta t_2 = \frac{\Delta x - v \Delta t_2}{c}$$

$$\Rightarrow \Delta t_1 \left(1 - \frac{v}{c}\right) = \frac{\Delta x}{c}$$

$$\Delta t_1 = \frac{\Delta x/c}{1 - v/c}$$

$$\rightarrow \Delta t_2 = \frac{\Delta x/c}{1 + v/c}$$

$$\Delta t = \Delta t_1 + \Delta t_2$$

$$= \frac{\Delta x}{c} \left(\frac{2}{1 - v^2/c^2} \right)$$

$$\Delta t = \frac{2 \Delta x}{c} \cdot \frac{1}{1 - v^2/c^2}$$

~~Δt = time taken~~

convert to rel. s & v

$$\frac{\Delta t'}{\sqrt{1 - v^2/c^2}} = \frac{2 \Delta x}{c} \cdot \frac{1}{1 - v^2/c^2}$$

then $\sqrt{1 - v^2/c^2}$

$$\frac{2 \Delta x/c}{\sqrt{1 - v^2/c^2}} = \frac{2 \Delta x}{c} \cdot \frac{1}{1 - v^2/c^2}$$

$$\Delta x' = \frac{\Delta x}{\sqrt{1 - v^2/c^2}}$$

Finding out velocity:

$$x' = \frac{x - vt}{\sqrt{1 - v^2/c^2}}$$

$$t' = t - \frac{vx}{c^2}$$

$$x_0 = (\gamma - 1) x_0'$$

$$\Delta x' = \frac{\Delta x - v \Delta t}{\sqrt{1 - v^2/c^2}}$$

$$\Delta t' = \frac{\Delta t - \frac{v}{c^2} \Delta x}{\sqrt{1 - v^2/c^2}}$$

$$u_x' = \frac{\Delta x'}{\Delta t'} = \frac{\Delta x - v \Delta t}{\Delta t - \frac{v}{c^2} \Delta x}$$

$$= \frac{\Delta x - v \Delta t}{\Delta t - \frac{v}{c^2} \Delta x}$$

$$= \frac{\Delta x / \Delta t - v}{1 - \frac{v}{c^2} \frac{\Delta x}{\Delta t}}$$

$$= \frac{u_x - v}{1 - \frac{u_x v}{c^2}}$$

$v \rightarrow$ vel. of the frame

$u_x', u_x \rightarrow$ vel. of sm. that is moving

$$u_x = \frac{u_x' + v}{1 + \frac{u_x' v}{c^2}}$$

put $u_x' = c$

check u_x

$$u_x = \frac{c + v}{1 + \frac{cv}{c^2}} = \frac{c + v}{1 + \frac{v}{c^2}} - c \quad \checkmark$$

satisfies
Einstein's
postulate

for u_y :

$$\Delta y' = \Delta y$$

$$\textcircled{1} - \Delta t' = \frac{\Delta t - \frac{v}{c^2} \Delta x}{\sqrt{1 - v^2/c^2}}$$

$$\textcircled{2} - u_y' = \frac{\Delta y'}{\Delta t'} = \frac{\Delta y}{\Delta t - \frac{v}{c^2} \Delta x} \quad \sqrt{1 - v^2/c^2}$$

$$= \frac{1}{\gamma} \frac{u_y}{1 - \frac{v}{c^2} u_x} \quad ? \neq$$

$$u_y' = u_y \cdot \left(\frac{1}{1 - \frac{v}{c^2} u_x} \right)^{-1} \quad \gamma = \sqrt{1 - v^2/c^2}$$

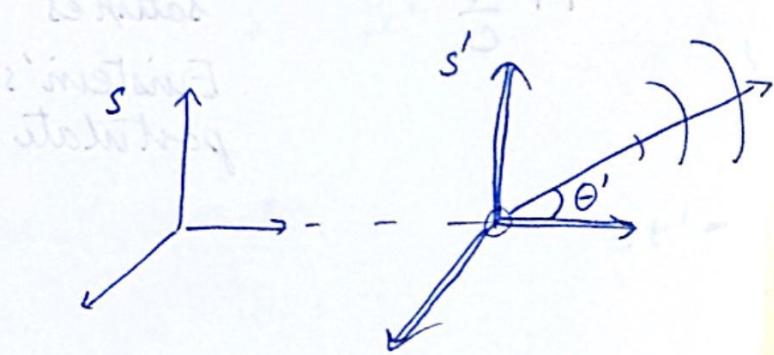
exclusive
Relativistic effect

"y velocity getting
affected by x motion."

Doing same math:

$$ax' = ax \cdot \frac{(1 - v^2/c^2)^{3/2}}{(1 - \frac{uxv}{c^2})^3}$$

Doppler effect & aberration:



wave: $\propto 2\pi \left[\frac{x' \cos \theta' + y' \sin \theta'}{\lambda'} - vt' \right] \quad \text{--- (1)}$

v nu
(freq.)

relate w/
v

$$\propto 2\pi \left[\frac{x \cos \theta + y \sin \theta}{\lambda} - vt \right] \quad \text{--- (2)}$$

* constraint: $\frac{v}{c} = v' \lambda' = v \lambda$

use L.T & sub. ω' & t' using x, t
and you get ① in terms of the vars. of

②. Now L.T. for ω &
 $\sin \theta$

① :

$$\cos 2\pi \left[\frac{\gamma}{\lambda} (x-vt) \omega_0' + \frac{y \sin \theta' - v' \gamma (1 - \frac{v}{c^2} x)}{\lambda'} \right]$$

(
Comparing with ② and ①)

$$\sin 2\pi \left[\left(\frac{\omega_0' + \beta}{\lambda'} \right) rx + \frac{\sin \theta' y}{\lambda'} - r (\beta \omega_0' + 1) v' t \right]$$

$$\beta = v/c$$

$$r = \frac{1}{\sqrt{1-v^2/c^2}}$$

Compare w/ ②

$$\Rightarrow \frac{\cos \theta}{\lambda} = \left(\frac{\cos \theta' + \beta}{\lambda'} \right) r \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{Aberration}$$

$$\frac{\sin \theta}{\lambda} = \frac{\sin \theta'}{\lambda'} \quad \left. \begin{array}{l} \\ \end{array} \right\}$$

$$v = v' (1 + \beta \cos \theta') \gamma \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{Doppler effect}$$

* $\beta = v/c$... first order in v/c is $T \cdot \sin \theta$.

* $\gamma = \frac{1}{\sqrt{1-\beta^2}} = (1-\beta^2)^{-1/2}$... may have
 $\approx 1 + \frac{1}{2} \beta^2$... second order
 $\approx 1 + \frac{1}{2} \cdot \frac{v^2}{c^2}$

[$(v-v')\cos\theta + v' \sin(\theta v - \phi)$] \Rightarrow
in order 1 in terms of β :

$v(\beta')$:

we have $v = v'(1 + \beta \cos \theta')$

useful i) we have $v = f(v', \theta)$ \Rightarrow v'
not $f(v', \theta')$

so we do,

$v' = v(1 - \beta \cos \theta) \gamma$

$\Rightarrow v = \frac{v'}{(1 - \beta \cos \theta) \gamma}$

$v = \frac{v' + \frac{1}{2} \beta^2 \frac{v'^2}{c^2}}{(1 - \beta \cos \theta) \gamma}$

* Special cases:

(i) $\theta = 0$

$$\Rightarrow v = v' \frac{\sqrt{1-\beta^2}}{1-\beta}$$

(ii) $\theta = \pi$

$$\Rightarrow v = v' \frac{\sqrt{1-\beta^2}}{1+\beta}$$

* Limiting approximations for classical mech:

(i) $v = v' (1) (1-\beta)^{-1}$

$$= v' (1+\beta) \rightarrow \text{checks out!}$$

(ii) $v = v' (1-\beta) \rightarrow$

: NO ISSUES - SWIFT

$O(\beta^2)$ terms are

ignored to show
C.M. doppler effect.

It comes in to
show relativistic effects

$\Sigma =$

* coming to exact expressions:

$$\theta = 0 \rightarrow v = v' \sqrt{\frac{1+\beta}{1-\beta}}$$

$$\theta = \pi \rightarrow v = v' \sqrt{\frac{1-\beta}{1+\beta}}$$

$$\text{put } \theta = \frac{\pi}{2}$$

$$\Rightarrow v = v' \sqrt{1-\beta^2} \quad \dots \text{the first term is } \beta^2 \rightarrow \text{not appearing in Newtonian mech., purely relativistic effect.}$$

Four-vectors:

$X \rightarrow$ our four vector

see ansatz (ϵ_{ij})

$X^0 = ct$ \rightarrow (multiplied by c to make dim. same)

$X^1 = x$

X^2 ~~temporarily~~ \rightarrow y

$X^3 = z$

$X^n \rightarrow n^{\text{th}}$ component
not power

$X' \rightarrow$ another f.v in S'

$$x^0' = \gamma(x^0 - \beta x^1)$$

$$x^1' = \gamma(x^1 - \beta x^0)$$

$$x^2' = x^2$$

$$x^3' = x^3$$

- lets write in matrix form:

$$\begin{pmatrix} x^0' \\ x^1' \\ x^2' \\ x^3' \end{pmatrix} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{pmatrix}$$

$$X'^{\mu} = \sum_{\nu=0}^3 \Lambda^{\mu}_{\nu} X^{\nu} \quad (\text{Expanded form of matrix multiplication})$$

$$\therefore X^0' = \sum_{\nu=0}^3 \Lambda^0_{\nu} X^{\nu}$$

$$\Lambda^0_0 X^0 = \gamma \cdot X^0$$

$$+ \Lambda^1_0 X^1 = -\gamma\beta \cdot X^1$$

$$+ \Lambda^2_0 X^2 = 0$$

$$+ \Lambda^3_0 X^3 = 0$$

& so on.

* any object

$$a^\mu = \sum_{\nu=0}^3 \lambda_\nu^\mu a^\nu$$

which obeys this,

is a four vector.

constraint :

$$-c^2 t^2 + x^2 + y^2 + z^2 = -c^2 t^2 + \cancel{x^2} + \cancel{y^2} + \cancel{z^2}$$

↑
(length
of four vector)

G

$$|ds|^2 = x^0 - x^0{}^2 + x^1{}^2 + x^2{}^2 + x^3{}^2$$

$$\bar{A} \cdot \bar{B} = \sum_1^3 A_i B_i$$

→ invariant on transforming

behaviour
to next
section
rest of it will be

space (3D)

same for four vectors in 4D

$$a \cdot b = \sum_0^3 a^\mu b_\mu = -a^0 b^0 + a^1 b^1 + a^2 b^2 + a^3 b^3$$

↔ invariant

$$|\Delta s|^2 = -c^2 \Delta t^2 + (\Delta d)^2$$

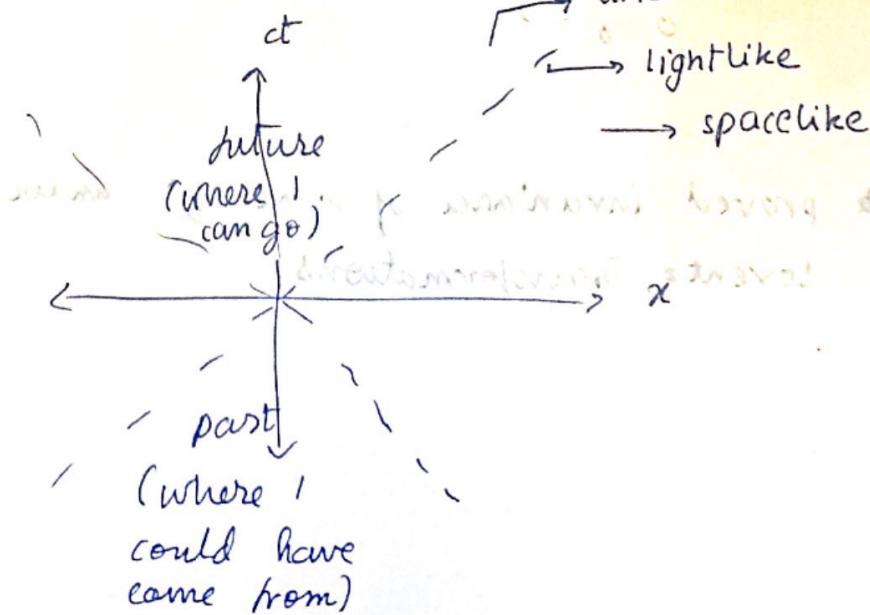
$|\Delta s|^2 > 0 \rightarrow$ spacelike

if two events are not simultaneous
i can change frame such
that they are ($\Delta t = 0$) but
i can never make $\Delta d = 0$
(make them happen at same
location)

$|\Delta s|^2 < 0 \rightarrow$ timelike
(vice versa)

$|\Delta s|^2 = 0 \rightarrow$ light like
(moves w/ speed of light)

Minkowski diagram:



* notation:

$$a_\mu = (a_0, a_1, a_2, a_3) \quad \text{or } \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{pmatrix}$$

$$\text{contravariant } a^\mu = (-a_0, a_1, a_2, a_3)$$

now convert several and i

but ($\eta = \text{diag}$) see page 207

$$\text{covariant } a_\mu = (-a_0, a^1, a^2, a^3)$$

so that we get the covariant form

$$\text{contravariant } a^\mu = (a^0, a^1, a^2, a^3)$$

$$a^\mu a_\mu = -a^0 a^0 + a^1 a^1 + a^2 a^2 + a^3 a^3$$

$$a^\mu = g_{\mu\nu} a^\nu \quad \text{and } \eta_{\mu\nu} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

↓

$$\begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

solving

* proved invariance of wave eqn under
Lorentz transformations.

we have $s = \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$

$$\Delta s = \begin{pmatrix} c\Delta t \\ \Delta x \\ \Delta y \\ \Delta z \end{pmatrix} \quad (\text{given}) = \begin{pmatrix} 8,000 \\ 3,000 \\ 4,000 \\ 2,000 \end{pmatrix} = \Delta s$$

lets get v : $\begin{pmatrix} \Delta x \\ \Delta y \\ \Delta z \end{pmatrix} = \frac{\Delta s}{\Delta t} = v$

we can't use $\frac{\Delta s}{\Delta t}$ because Δt is a changing parameter of Δs itself

~~we use Δt → proper time interval
(measured when moving
clock and gives the same vel. as clock)~~

$$4\text{-velocity} \quad (\text{proper rel.}) = \begin{pmatrix} c \frac{dt}{d\tau} \\ \frac{dx}{d\tau} \\ \frac{dy}{d\tau} \\ \frac{dz}{d\tau} \end{pmatrix} = \gamma \begin{pmatrix} c \\ \frac{dx/dt}{\sqrt{1 - (dx/dt)^2}} \\ \frac{dy/dt}{\sqrt{1 - (dx/dt)^2}} \\ \frac{dz/dt}{\sqrt{1 - (dx/dt)^2}} \end{pmatrix}$$

$$(x, y, z) = (0, 0, 0) \sin \theta$$

at $t = 0$ starts

$$(x, y, z) = (0, 0, 0)$$

$$(x, y, z) = (0, 0, 0)$$

* Quiz on 26th Aug.
(syllabus is whatever done till 19th Aug.)

$$\underline{s} = (ct, \vec{r})$$

$$\underline{ds} = (cdt, \vec{dr})$$

\underline{s} \rightarrow 4D vector

\vec{r} \rightarrow three vector

$$\underline{u} = \frac{\underline{ds}}{dt} = \left(\frac{cdt}{dt}, \frac{d\vec{r}}{dt} \right)$$

$$= \gamma(c, \vec{v})$$

* It follows transformation law: $\underline{u}'^\mu = \Lambda_\nu^\mu \underline{u}^\nu$
(from notes)

* Try finding rel. v. formula using four velocity formalism.

$$\begin{pmatrix} c \\ \vec{r}_b \\ \vec{v}_b \\ \vec{r}_b \end{pmatrix}$$

$$\gamma = \begin{pmatrix} \gamma_b \\ \vec{r}_b \\ \vec{v}_b \\ \vec{r}_b \end{pmatrix}$$

Projectiles - A
(for solving)

Let's define momentum:

$$\underline{p} = m_0 \underline{u}$$

$$= m_0 (c, \vec{v}) = (mc, m\vec{v}) \rightarrow \frac{d\vec{v}}{dt} \text{ not } \frac{d\vec{r}}{dt}$$

$$= (mc, \vec{p}) \quad \text{where } m = \gamma m_0$$

$$= (mc, \vec{p})$$

$m \rightarrow$ frame dependent

$$m = r m_0$$

↳ Rest mass

↳ Relativistic mass

$\vec{p} \rightarrow$ spatial comp. of momentum four vector

$$= m \vec{u}$$

$$= r m_0 \cdot \frac{d\vec{r}}{dt}$$

The time component of four vector \vec{p}

$$= (mc) \text{ and that is } = \frac{E}{c}$$

... we'll show why.

• what is force?

$$\begin{aligned} F &= \frac{d\vec{p}}{dt} = \left(\frac{d(mc)}{dt}, \frac{d(\vec{p})}{dt} \right) \\ \text{Minkowski} &\text{force} \end{aligned}$$

$$= \gamma \left(\frac{d(mc)}{dt}, \frac{d\vec{p}}{dt} \right)$$

$$= \gamma \left(\frac{d(mc)}{dt}, F \right)$$

* here we don't absorb any into the spatial comp. like we did for momentum bc that def. of \vec{p} helps us maintain momentum conservation.

* In 3D:

$$\text{Eqn of } \underline{\underline{F}} \cdot \underline{\underline{u}} = \frac{dE}{dt} \quad \text{from last}$$

lets try sm similar here

$$\begin{aligned}\underline{\underline{F}} \cdot \underline{\underline{u}} &= \cancel{\underline{\underline{F}}^{\mu} u_{\mu}} \text{ without p term} \\ &= \gamma \left(\frac{d(mc)}{dt}, \underline{\underline{F}} \right) \cdot \gamma(c, \underline{\underline{u}}) \mu \\ &= \gamma^2 \left(\underline{\underline{F}} \cdot \underline{\underline{u}} - \frac{d}{dt}(mc^2) \right)\end{aligned}$$

now work from ... formula using speed of light.

* This dot product $\underline{\underline{F}} \cdot \underline{\underline{u}}$ is invariant of frame.

lets examine it in the rest frame,

$$\text{where } \underline{\underline{u}} = (0, \frac{b}{Jb}, (mc) \frac{b}{Jb}) \quad \Rightarrow \frac{gb}{Jb} = \frac{b}{Jb} \text{ and}$$

$$\Rightarrow \underline{\underline{F}} \cdot \underline{\underline{u}} = 0$$

check the other term:

$$\frac{d}{dt} (mc^2) \Big|_{\underline{\underline{u}}=0} =$$

$$= \frac{d}{dt} \left(mc^2 \sqrt{1 - \frac{u^2}{c^2}} \right) \Big|_{\underline{\underline{u}}=0}$$

in rest frame we neglect $\frac{u^2}{c^2}$ term

$$= m_0 c^2 \left(-\frac{1}{2} \right) \frac{1}{(1 - u^2/c^2)^{3/2}} \cdot -2u \frac{du}{dt}$$

$$= \frac{m_0 c^2 \cdot u \cdot \frac{du}{dt}}{(1 - u^2/c^2)^{3/2}} \Big|_{\bar{u}=0}$$

$$= 0$$

\therefore They are both zero here and $\underline{F} \cdot \bar{u} = 0$ ~~invariant~~.
If you go to another frame: ~~then it's not~~

$\underline{E} \cdot \bar{u}$ might change

$\frac{d}{dt}(mc^2)$ might change

\therefore but $\underline{F} \cdot \bar{u} = 0$ will always hold

bec. dot product is frame invariant.

$$\Rightarrow \underline{F} \cdot \bar{u} = \frac{d}{dt}(mc^2) \quad (\text{in all frames})$$

$$\int \frac{d\underline{E}}{dt} = \int \frac{d}{dt}(mc^2)$$

$$\Rightarrow \underline{E} = mc^2$$

* Read R, G for the other method

now, clearly:

$$\underline{p} = \left(\frac{E}{c}, \bar{\underline{p}} \right) \quad \begin{matrix} \text{Energy} \\ \text{momentum} \\ \text{vector.} \end{matrix}$$

$$\underline{P}^M \cdot \underline{P}_M = \left(\frac{E}{c}, \bar{\underline{p}} \right)^M \left(\frac{E}{c}, \bar{\underline{p}} \right)_M$$

$$= |\bar{\underline{p}}|^2 - \frac{E^2}{c^2}$$

an invariant \rightarrow law and does not care about

\hookrightarrow in a rest frame

$$|\bar{\underline{p}}| = 0$$

$$= -\frac{E^2}{c^2} = m_0^2 c^2 = \boxed{-m_0^2 c^2}$$

start would like $\delta = 0$ \downarrow invariant

mississippi went to tulburg Feb 2011

$$|\bar{\underline{p}}|^2 - \frac{E^2}{c^2} = -m_0^2 c^2$$

(correct this m_0^2) \rightarrow $(\gamma m) \frac{h}{\sqrt{b}} = \frac{h}{\sqrt{b}}$

$$\Rightarrow \boxed{E^2 = |\bar{\underline{p}}|^2 c^2 + m_0^2 c^4}$$

\downarrow \downarrow \downarrow

total corr corr to rest
energy to KE mass energy

$E - m_0 c^2 \approx KE$ (so it should corr. to Newtonian mechanics)

$$= mc^2 - m_0 c^2$$

$$= m_0 c^2 (\gamma - 1)$$

$$= m_0 c^2 (r - 1)$$

$$= m_0 c^2 \left(\frac{1}{\sqrt{1 - \frac{u^2}{c^2}}} - 1 \right)$$

$$= m_0 c^2 \left(1 + \frac{1}{2} \frac{u^2}{c^2} - 1 \right)$$

$$= \frac{1}{2} m u^2 \quad \text{... checks out!}$$

Summary: $(\gamma - 1) \frac{p}{m} = (\gamma m_0) \frac{p}{m} = \frac{1}{2} m u^2$, or

$$\text{with } E = mc^2 = \gamma m_0 c^2 \text{ (dependent)}$$

$$E^2 = |\vec{p}|^2 c^2 + m_0^2 c^4$$

$$KE = E - m_0 c^2$$

* A particle w/o mass can still have mechanics

(non zero energy $E = pc$)

but they will have to travel at speed of light.

$$\text{because } \vec{p} = m_0 \gamma \vec{u}$$

$$= \frac{m_0}{\sqrt{1 - \frac{u^2}{c^2}}} \rightarrow 0 \quad \text{should also be 0 to cause indeterminacy so that } \vec{p} \text{ is finite}$$

Revisiting Newton's Laws:

① First law - checks out

(read Kleppner)

(Sokolow)

(first chap)

② Second law -

$$\bar{F} = \frac{d\bar{p}}{dt} \rightarrow \text{Newton: } \bar{p} = m\bar{u}$$

$$\rightarrow \text{Einstein: } \bar{p} = m\bar{u}$$

$$|\text{two relabs} \dots = \gamma m_0 \bar{u}$$

here, $\bar{F} = \frac{d}{dt}(m_0 \gamma u) = m_0 \frac{d(\gamma u)}{dt}$ HYDRODYNAMIC
time dependence

$$= m_0 \left[\gamma \frac{du}{dt} + u \frac{d\gamma}{dt} \right]$$

additional term to the usual acc. dependance.

$$\bar{F} = \frac{\bar{F} \cdot \bar{u}}{c^2} \bar{u} + m \bar{a}$$

with non zero \bar{a} and non zero \bar{F}

* you need non zero \bar{a} for non zero \bar{F}

but

$\bar{F} \parallel \bar{a}$ is not necessarily true!

think it's just a coincidence

$$\gamma = \frac{1}{\sqrt{1-u^2/c^2}}$$

$$\frac{d\gamma}{dt} = \frac{1}{\sqrt{1-u^2/c^2}}^{-1/2} \frac{-2u du}{dt}$$

$$= \frac{u \cdot \bar{a}}{(1-u^2/c^2)^{3/2}}$$

$$m_0 \bar{u} \frac{d\gamma}{dt} = \bar{u} (m_0 \cdot u \cdot a) \frac{\bar{F} \cdot \bar{u}}{(1-u^2/c^2)^{3/2}}$$

③ Action-reaction pair -

Newton: $F_{AB}(t) = -F_{BA}(t)$

→ forces are equal
at the same
instant

but in general, there
is a time delay for the
reaction force to come

This still works if it is a contact force (no diff in
OR if there is no time dependence of force $\Rightarrow t = t'$)

So, it may or may not hold.
(Frame dependent)

⇒ It is not true anymore

because a law cannot be
frame dependent.

$$(\vec{q}, \frac{d}{dt}) = (\vec{q}, \omega) = 0$$

Summary of new mechanics (consistent w/ Lorentz transformation)

$$\bar{u} = \frac{d\bar{r}}{dt}$$

$$\bar{p} = m\bar{u} = \gamma m_0 \bar{u}$$

$$\bar{F} = \frac{d\bar{p}}{dt}$$

$$E = mc^2 = \sqrt{|\bar{p}|^2 c^2 + m_0^2 c^4}$$

Real physical observables
in 3-space

$$KE = (\gamma - 1) m_0 c^2$$

$$\Delta = \sigma(ct, \bar{r})$$

4-space

$$\underline{u} = (\gamma c, \gamma \bar{u})$$

$$f = (mc, \bar{p}) = \left(\frac{E}{c}, \bar{p} \right)$$

$$F = \gamma \left(\frac{d}{dt}(mc), \bar{F} \right)$$

- This stuff helps us formulate relativistic definitions.
- New physical insight about spacetime structure.
- Easy to change frames (because of four vector formalism)

$$Q'^\mu = \Lambda^\mu_\nu Q^\nu$$

Q' , Q → some quantity in diff. frames

- Norms & dot products are invariant under transformation.

Some applications of new dynamics:

(A) $\sum \bar{F} = 0 \Rightarrow$ conservation of momentum & energy

(B) $\sum \bar{F} \neq 0 \Rightarrow$ trajectories of particles

* in relativistic mech, there is no concept of elastic & inelastic collision \Rightarrow if momentum is conserved,

total energy also must be conserved.

Examples:

① Inelastic $\rightarrow 0+0 \rightarrow 0$ } (A)
 $0 \rightarrow 0+0$

② Elastic $\rightarrow 0+0 \rightarrow 0+0$

③ constant force } (B)

Inelastic collision → KE totally lost
total E conserved

① initial speed $\frac{3}{5}c$ to source $\frac{3}{5}c$ and spreads to m_0
 m_0 \rightarrow forward $\leftarrow m_0$ before

final mass $M = ?$ after

unknown and Elsberg Job 3 energy

→ clearly $P_{\text{net}} = 0$ and $P_M = 0$ ~~and no net momentum observed~~

$$E_1 = \frac{m_0 c^2}{\sqrt{1 - \frac{3}{5}^2}} = \frac{m_0 c^2}{\sqrt{1 - \frac{9}{25}}} = \frac{5}{2} m_0 c^2$$

energy of neutrino to neutrino \oplus \ominus \oplus \ominus

$$E_{\text{tot}} = E_1 + E_2 = \frac{5}{2} m_0 c^2 + \frac{5}{2} m_0 c^2 = 5 m_0 c^2$$

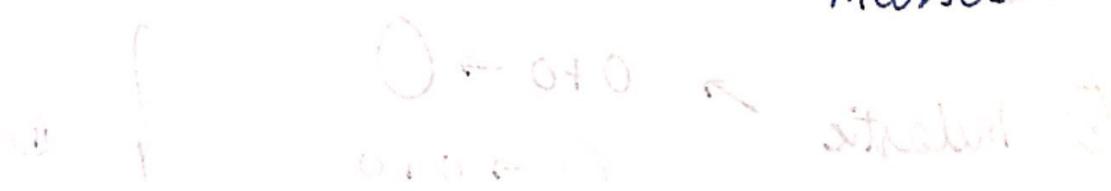
$$= \frac{5}{2} m_0 c^2 = M c^2$$

situations for leptons in a neutrino interaction in a

neutrino interaction $M = \frac{5}{2} m_0 > 2 m_0$ resulting in

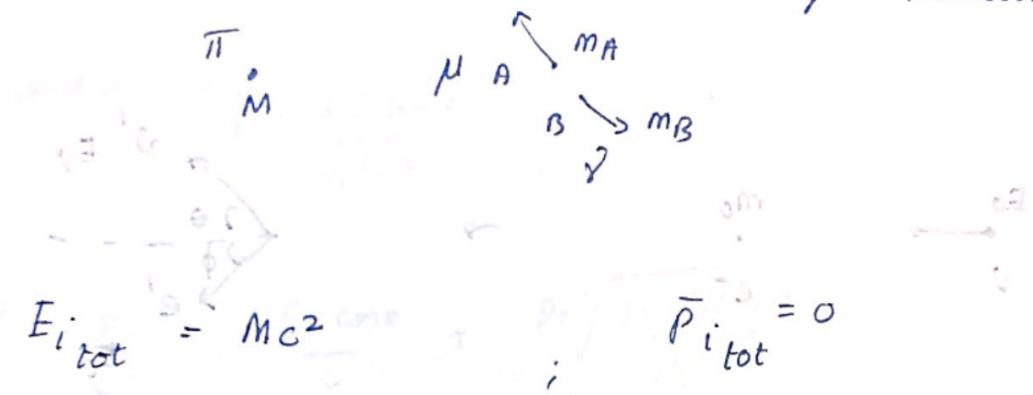
leptons in down also appear not
Final rest mass $>$ sum

of initial
rest
masses



② disintegration

π - pion
 μ - muon
 γ - neutrino



$$E_{f\text{tot}} = E_{f_A} + E_{f_B} \quad \text{with} \quad \bar{P}_{f\text{tot}} = \bar{P}_{f_A} + \bar{P}_{f_B}$$

$$\bar{P}_{f_A} = \bar{P}_{f_B} + \gamma^3$$

$$E_{f\text{tot}} = E_{f_A} + \sqrt{\bar{P}_{f_B}^2 c^2 + m_B^2 c^4} \quad \text{with} \quad \gamma^3 = Mc^2$$

$$E_{f_A} + \sqrt{\bar{P}_A^2 c^2 + m_A^2 c^4} = Mc^2$$

$$E_{f_A} + \sqrt{E_A^2 - m_A^2 c^4 + m_B^2 c^4} = Mc^2$$

(with $m_A^2 c^4 = \bar{P}_A^2 c^2$ and $m_B^2 c^4 = \bar{P}_{f_B}^2 c^2$)

→ only one unknown E_{f_A}

so solve

$$\Rightarrow E_{f_A} = \frac{c^2 (M^2 + m_A^2 c^2 - m_B^2 c^2)}{2M}$$

$$E_{f_A} = 0.733$$

Elastic collision:

$$E_0 \rightarrow m_0 v$$

→

$$v' E_v$$

find relation of E_v with θ .

$$E_{y_i} + E_{e_i} = E_{y_f} + E_{e_f} \dots \text{Energy cons.}$$

$$\begin{aligned} E_0 + m_0 c^2 &= E_y + E_e + \Delta E = p_r^2 \\ &= E_y + \sqrt{p_e^2 c^2 + m_0^2 c^4} - \textcircled{1} \end{aligned}$$

$$\begin{aligned} \text{vertical momentum conservation: } p_c \sin \phi &= p_y \sin \theta \\ p_c \sin \phi &= p_r \sin \theta \end{aligned}$$

$$\begin{aligned} \text{horizontal: } p_{r_i x} + p_{e_i x} &= p_{r_f x} + p_{e_f x} \end{aligned}$$

$$\frac{E_0}{c} + 0 = p_r \cos \theta + p_e \cos \phi$$

$$\sin \phi = \frac{E_r}{P_e c} \sin \theta$$

$$\cos \phi = \sqrt{1 - \frac{E_r^2 \sin^2 \theta}{P_e^2 c^2}}$$

$$\Rightarrow \frac{E_0}{c} = \frac{E_r \cos \theta}{c} + P_e \sqrt{1 - \frac{E_r^2 \sin^2 \theta}{P_e^2 c^2}}$$

$$\Rightarrow \boxed{E_Y = \frac{E_0}{1 + \frac{E_0}{m_0 c^2} (1 - \cos \theta)}}$$

$$\boxed{\lambda = \lambda_0 + \lambda_c (1 - \cos \theta)}$$

$$\lambda_c = \frac{h}{m_0 c} \left[\frac{1 - \cos \theta}{\sin \theta} \right]$$

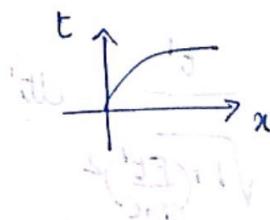
Trajectories:

$$\bar{F} = \text{constant.}$$

$$\text{Newtonian: } \ddot{x} = u t + \gamma_2 a t^2 ; \quad \frac{F}{m} = a$$

$$\text{if } u=0$$

$$x = \gamma_2 a t^2$$



Relativistically:

$$\frac{dp}{dt} = F \quad ; \quad p = \gamma m_0 u$$

= constant F

$$\Rightarrow p = \frac{Ft + c}{\sqrt{1 - \frac{u^2}{c^2}}} ; \quad \text{put } c = 0$$

$$\frac{m_0 u}{\sqrt{1 - \frac{u^2}{c^2}}} = Ft$$

solve for u

$$m_0^2 u^2 = F^2 t^2 - \frac{F^2 t^2 u^2}{c^2}$$

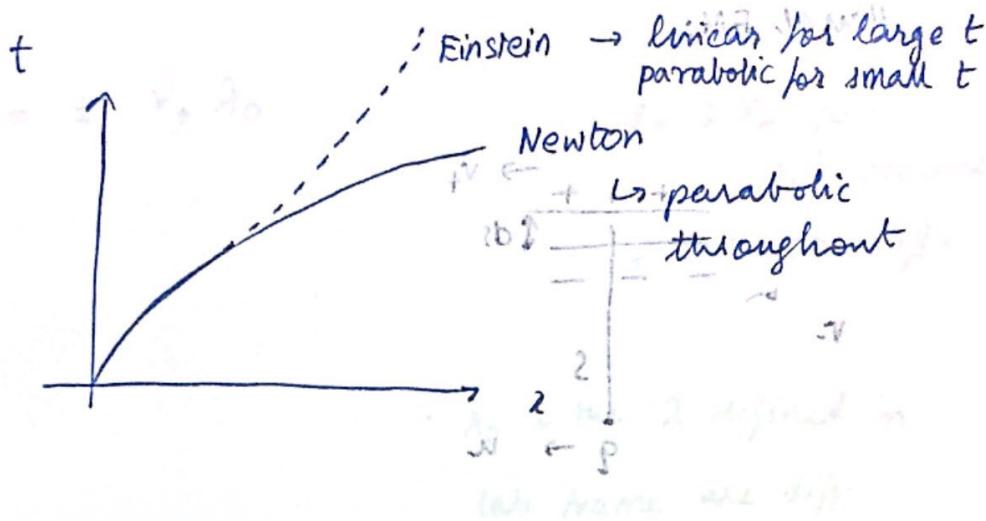
$$u^2 \left[m_0^2 + \frac{F^2 t^2}{c^2} \right] = F^2 t^2$$

$$u = \frac{Ft}{\sqrt{m_0^2 + \frac{F^2 t^2}{c^2}}} = \frac{\frac{F}{m_0} t}{\sqrt{1 + \left(\frac{Ft}{m_0 c}\right)^2}} : \text{cancel part}$$

$$\frac{dx}{dt} = \frac{F}{m_0} + \frac{dt}{\sqrt{1 + \left(\frac{F}{m_0 c}\right)^2 t^2}}$$

$$x = \int_0^t \frac{F}{m_0} dt' + \int_0^t \frac{dt'}{\sqrt{1 + \left(\frac{F}{m_0 c}\right)^2 t'^2}}$$

$$\Rightarrow x(t) = \frac{m_0 c^2}{F} \left[\sqrt{1 + \left(\frac{F t}{m_0 c} \right)^2} - 1 \right]$$



$x(t)$ for small t is shown in Fig. 1.

$$V_{LS} = \frac{m_0 c^2}{\frac{\Sigma M F N \cdot p}{2\pi h}} \left(1 + \frac{1}{2} \frac{F^2 t^2}{\frac{m_0 c^2}{2\pi h}} - 1 \right)$$

for large t :

$\left(\frac{Ft}{m\omega}\right)^2 > 1$ leads to activation mechanism

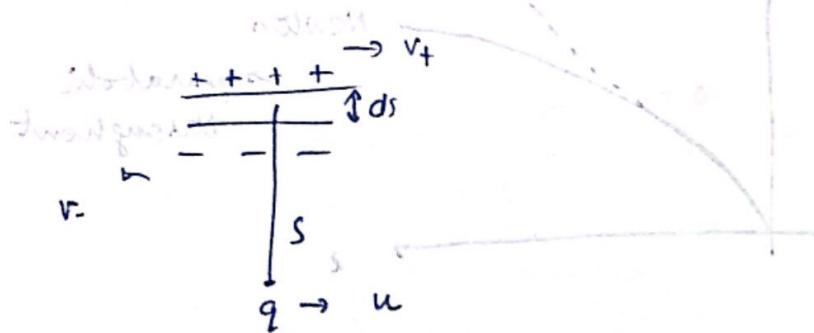
$$\Rightarrow x(t) = \frac{m_0 c^2}{F} \left[e^{\frac{Ft}{m_0 c}} - 1 \right]$$

reinforcements were at ends squared with the A

14 14 14 14

Relativistic electrodynamics:

→ Maxwell EM: \rightarrow discrete
 → from rel. motion



$$\underline{\underline{E}} \quad \underline{\underline{B}} \quad \underline{\underline{F}} \quad \rightarrow \text{Maxwell Eq. (4) :}$$

$$0 \quad \left(-\frac{\mu_0 I}{2\pi r} \hat{z} + \hat{z} \right) \quad g \cdot u = \frac{\mu_0 I}{2\pi r} \quad ; \quad I = 2Ar$$

$\frac{\mu_0 I}{2\pi r}$

(into paper)

\hat{z} (up)

now, sit in q frame:

transform velocities of line charges:

$$\left[1 - \frac{v^2}{c^2} = \right] \frac{v_+ u}{1 + \frac{v u}{c^2}}$$

$\hat{z} \times \hat{x}$

λ will also change due to length contraction

$$\lambda_{\pm} = \pm \frac{Q}{L_{\pm}} = \pm \frac{Q}{L_0 / \gamma_{\pm}}$$

L_0 - proper length

$$\lambda_{\pm} = \pm \frac{Q}{L_0} \sqrt{1 - \frac{v_{\pm}^2}{c^2}}$$

λ_0 - proper
charge
density

$$= \pm \gamma_{\pm} \lambda_0$$

γ_+ & γ_- are
diff because
 v_+ & v_- are diff.

- λ_0 & the λ defined in lab frame are diff.
- λ_0 is measured in a frame where charges are at rest
- λ " in lab frame, where charges are moving w/ v_+ & v_-
- λ_{\pm} is measured in q -frame

$$\lambda_{\pm} = \pm \gamma_{\pm} \lambda_0$$

- This connects
- \downarrow
- \downarrow

q frame to wire frame

- We want to connect q frame to lab frame

$$\therefore \pm \lambda = \pm \gamma \lambda_0$$

↓
lab frame

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$r = r_+ \frac{v_+}{v_-}$$

$$\Rightarrow \lambda_{\pm} = \pm \gamma_{\pm} \left(\frac{\lambda}{\gamma} \right)$$

$$\lambda_{\pm} = \pm \left(\frac{\gamma_{\pm}}{\gamma} \right) \lambda$$

↓ ↓
g frame lab frame

$\gamma_{\pm} \rightarrow r_+ \& r_-$
in g frame
(v_+ & v_-)

γ - with original
(v)

Let's recalculate!

* There is no modified \vec{B} as well.

* Lab frame: $\lambda_{\text{tot}} = 0 \Rightarrow \vec{E} = 0$

* g frame: no magnetic force

$$\lambda_{\text{tot}} = \lambda_+ + \lambda_-$$

$$= \frac{r_+ \lambda}{\gamma} - \frac{r_- \lambda}{\gamma}$$

$$= \frac{\lambda}{\gamma} (r_+ - r_-)$$

Simplify γ_{\pm} : you get :

$$\gamma_{\pm} = \gamma \cdot \frac{1 \mp \frac{uv}{c^2}}{\sqrt{1 - \frac{u^2}{c^2}}}$$

$$\frac{\gamma_+ - \gamma_-}{\gamma} = \frac{-2uv}{c^2 \sqrt{1 - \frac{u^2}{c^2}}}$$

$$\therefore \lambda_{\text{tot}} = \frac{-2\lambda uv}{c^2 \sqrt{1 - u^2/c^2}}$$

$$\bar{E} = \frac{\lambda_{\text{tot}}}{2\pi\epsilon_0 \cdot s}$$

* s is not contracted
bc its \perp to vel.

* There is a modified \bar{B} as well,
due to diff λ, v
but since in q frame, q 's vel = 0
 \Rightarrow no magnetic force

$$\therefore \bar{F} = \bar{F}_E = qE$$

$$= q \cdot \frac{\lambda_{\text{tot}}}{2\pi\epsilon_0 \cdot s}$$

$$= \frac{q}{2\pi\epsilon_0 \cdot s} \cdot \frac{(-2\lambda uv)}{c^2 \sqrt{1 - u^2/c^2}} \dots F \text{ in } q \text{ frame}$$

Aug 19th
2021. After "

Go back to lab frame:

$$F_{\text{lab}} = \sqrt{1-u^2/c^2} \times F_{\text{frame}}$$

$$= -\frac{\lambda v q u}{\pi \epsilon_0 c^2 s}$$

$$c^2 = \frac{1}{\mu_0 \epsilon_0}$$

$$= -q \cdot u \cdot 2\lambda v \cdot \mu_0$$

minus sign

$\equiv \bar{F}$ is opp to \bar{E}

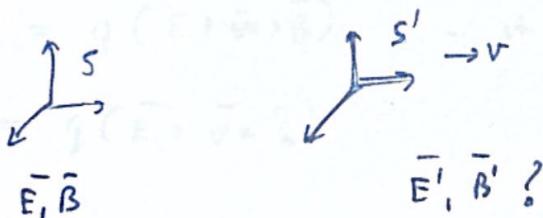
\equiv up dirn

= same as
before.

$$= \left(\frac{\mu_0 \cdot I}{2\pi s} \right) \cdot q \cdot u$$

= same as our original answer!

Now, let's find the transformation laws for \bar{E} & \bar{B} :



$$F_x = q(\bar{E}_x + \bar{v} \bar{u} \times \bar{B})$$

$$F_x = q(\bar{E}'_x + \bar{v}' \bar{u}' \times \bar{B})$$

$$\bar{F}'_x = q(\bar{E}'_x + \bar{v}' \bar{u}' \times \bar{B}')$$

& \bar{F} & \bar{F}' are connected by transformation laws
that we already know.

$$F_x = F'_x \quad \gamma = \frac{1}{\sqrt{1-v^2/c^2}}$$

$$F_y = \frac{F'_y}{\gamma}$$

$$F_z = \frac{F'_z}{\gamma}$$

Let $w = v$

$\Rightarrow q$ is in rest at in s'

so $\bar{F}_B' = 0$

& we can focus on \bar{F}_E'

$$\bar{F} = q \bar{E}'$$

$$\bar{F}'_{x,y,z} = q \bar{E}'_{x,y,z} \quad - \text{in } s'$$

$$F = q(\bar{E} + \bar{v} \times \bar{B}) \quad - \text{in } S$$

$$= q(\bar{E} + \bar{v} \times \bar{B})$$

$$F_x = q(\bar{E}_x + (\bar{v} \times \bar{B})_x)$$

$$F_y = q(\bar{E}_y + (\bar{v} \times \bar{B})_y) \quad \bar{v} = v \hat{x}$$

$$F_z = q(\bar{E}_z + (\bar{v} \times \bar{B})_z)$$

now compare F_x & F'_x

$$q(\bar{E}_x + (\bar{v} \times \bar{B})_x) = q \bar{E}'_x$$

$$\downarrow \\ 0$$

$$\underline{\underline{v}} = v \hat{x}$$

$$\Rightarrow E_x = E'_x$$

$$F_y = F'_y$$

$$q(\bar{E}_y + (\bar{v} \times \bar{B})_y) = q \bar{E}'_y \cdot \gamma$$

$$= q(\bar{E}_y + (v_z \vec{B}_x - B_z v_x) \hat{y}) = q \bar{E}'_y \cdot \gamma$$

\Rightarrow ~~Newton's Law~~

$$E_y - v_x B_z = \frac{E'_y}{\gamma}$$

$$\Rightarrow E'_y = \gamma (E_y - v_x B_z)$$

similarly :

$$E'_z = \gamma (E_z + v_x B_y)$$

Generalising :

$$E'_{||} = E_{||} \quad (\text{parallel to } v_{\text{rel}})$$

$$E'_{\perp} = \gamma [E_{\perp} + (\bar{v} \times \bar{B})_{\perp}]$$

Now, find \vec{B} transformation:



in S' , q is
moving up
w/ u

Doing some calc & using $\vec{E} - \vec{E}'$ transformations:

$$B_x' = B_x$$

$$B_y' = \gamma (B_y + \frac{v}{c^2} E_z)$$

$$B_z' = \gamma (B_z - \frac{v}{c^2} E_y)$$

$$B_{||}' = B_{||}$$

$$B_{\perp}' = \gamma (B_{\perp} + \frac{1}{c^2} (\vec{v} \times \vec{E})_{\perp})$$

Special cases:

(i) if $\vec{B} = 0$ in S

$$\vec{B}' = \frac{\gamma v}{c^2} (E_z \hat{j} - E_y \hat{z})$$

but we want to express in terms of E' not E

$$E_z' = \gamma E_z$$

$$E_y' = \gamma E_y$$

$$\Rightarrow \vec{B}' = \frac{v}{c^2} (E_z' \hat{j} - E_y' \hat{z}) = -\frac{1}{c^2} (\vec{v} \times \vec{E}')$$

(ii) if $\bar{E} = 0$ in S

$$\bar{E}' = -\gamma v (B_z \hat{y} - B_y \hat{z})$$

$$= -\gamma v \left(\frac{B_z' \hat{y}}{\gamma} - \frac{B_y' \hat{z}}{\gamma} \right)$$

$$= -v (B_z' \hat{y} - B_y' \hat{z})$$

$$\rightarrow \bar{E}' = \bar{v} \times \bar{B}'$$

Tensors:

$$a^\mu = \Lambda_\nu^\mu a^\nu \quad \dots \text{an object which obeys this is a four vector}$$

$$F^{\mu\lambda} = \Lambda_\nu^\mu \Lambda^\lambda_\sigma F^{\nu\sigma} \quad \dots \text{an object which obeys this is a second rank tensor}$$

F will be a 4×4 matrix

= 16 ind. terms

too many? We only need 6 (E_x, y, z)
 B_x, y, z

F symm matrix?

- 10 ind. terms \rightarrow still too many

anti-symm?

= 6 ind. terms = just right!

\therefore This will be an antisymmetric second rank tensor. ('This' = the superstructure which manifests as \bar{E} & \bar{B} fields in diff scenarios)

Expanding $F^{M\nu} = \Lambda_{\lambda}^M \Lambda_{\sigma}^{\nu} F^{\lambda\sigma}$

$$F^{01} = F^{01}$$

$$F^{02} = \gamma (F^{02} - \beta F^{12})$$

$$F^{03} = \gamma (F^{03} + \beta F^{31})$$

$$F^{12} = F^{23}$$

$$F^{31} = \gamma (F^{31} + \beta F^{03})$$

$$F^{12} = \gamma (F^{12} - \beta F^{02})$$

... match these w/ \bar{E} & \bar{B}
transformations and
construct F

\Rightarrow Two options:

$$\textcircled{1} \quad F^{01} = \frac{E_x}{c}, \quad F^{02} = \frac{E_y}{c}, \quad F^{03} = \frac{E_z}{c}$$

$$F^{12} = \beta_z, \quad F^{31} = \beta_y, \quad F^{23} = \beta_x$$

$$② \quad F^{01} = B_x, \quad F^{02} = B_y, \quad F^{03} = B_z$$

$$F^{12} = -\frac{E_z}{c}, \quad F^{31} = -\frac{E_y}{c}, \quad F^{23} = -\frac{E_x}{c}$$

① $F^{\mu\nu}$

... to interconvert

② $G^{\mu\nu}$ Force law
(mechanical)

$$\frac{\bar{E}}{c} \rightarrow \bar{B}$$

$$\bar{B} \rightarrow -\frac{\bar{E}}{c}$$

$\therefore F^{\mu\nu}$ is

$$\begin{pmatrix} 0 & \frac{E_x}{c} & \frac{E_y}{c} & \frac{E_z}{c} \\ -\frac{E_x}{c} & 0 & B_z & -B_y \\ -\frac{E_y}{c} & -B_z & 0 & -B_x \\ -\frac{E_z}{c} & B_y & B_x & 0 \end{pmatrix}$$

→ The Electromagnetic Field
Tensor

— x — x — x —
COURSE FIN.

Extra stuff:

• Four current $J^\mu = (cp, \vec{J})$

• Continuity eqn: $\frac{\partial J^\mu}{\partial x^\mu} = 0$

• Maxwell's eqn: $\frac{\partial F^{\mu\nu}}{\partial x^\nu} = \mu_0 J^\mu$

$$\frac{\partial G^{\mu\nu}}{\partial x^\nu} = 0$$

- Lorentz Force Law :

$$F^\mu = q v_\nu F^{\mu\nu}$$

+ charge
- sign change

- Magnetic vector potential :

$$A^\mu = \left(\frac{v}{c}, \vec{A} \right) ; v = \text{scalar pot. of } \vec{E}$$

• $F^{\mu\nu} = \frac{\partial A^\nu}{\partial x_\mu} - \frac{\partial A^\mu}{\partial x_\nu}$

• $\square^2 A^\mu = -\mu_0 J^\mu$

$$\square^2 = \frac{\partial}{\partial x_\nu} \frac{\partial}{\partial x^\mu} = \nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}$$



The D'Alembertian

* Norm of a tensor : (Learn this for exam)

$$F^{\mu\nu} F_{\mu\nu}$$

* to flip an index on top

(it should have at least one zero)

(flip it & put one minus per zero)

* if no zeros, you
flip it w/o
sign change

$$= F^{00} F_{00} = F^{00} F^{00}$$

$$+ F^{01} F_{01} = - F^{01} F^{01}$$

$$+ F^{12} F_{12} = F^{12} F^{12}$$

& so on.

The end.