# Agniva Sengupta

# PERSONAL DATA

ADDRESS: Rennes, France

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# **EDUCATION**

JULY 2012 Master of Technology in MECHANTRONICS, IIEST, Shibpur, India

summa cum laude | Master's Theses in Path planning for Mobile Robots Advisor: Dr. S. N. SHOME, Dr. Ranjit RAY, Prof. Subhasis BHAUMIK

AUGUST 2008 Bachelor of Technology in Information Technology

summa cum laude, West Bengal University of Technology, India

# **PUBLICATION**

• Sengupta, Agniva, and E. Shafeeq. "New feature detection mechanism for extended Kalman filter based monocular SLAM with 1-point RANSAC" *Lecture Notes in Artificial Intelligence, Springer*. Mining Intelligence and Knowledge Exploration, 2015.

- Sengupta, Agniva, Ranjit Ray, and S. N. Shome. "Virtual Stretched String: An Optimal Path Planning Technique over Polygonal Obstacles" *Proceedings of Conference on Advances In Robotics*. ACM, 2013.
- Sengupta, Agniva. "Obstacle Avoidant Path Planning Using Probabilistic Genetic Algorithm With Adaptive Performance Optimization" *Recent Advancement in Mechatronics Automation. BESUS*: s.n., 2011.

# PHD TOPIC & DETAILS

The objective of my thesis is the tracking and localization of objects of partially known shapes using depth cameras. I work in the LAGADIC research group of INRIA, Rennes. My thesis is supervised by Eric Marchand and Alexandre Krupa. I defend my PhD in/around December, 2019.

# WORK EXPERIENCE

| JAN 2017 TO PRESENT  | PhD Student at INRIA, RENNES, France  |
|----------------------|---|
| Nov 2015 to Dec 2016 | Computer Vision Research Engineer at WHODAT TECH PVT. LTD.,<br>Bangalore, India   |
| Aug 2014 to Nov 2015 | Senior Design Engineer at Kritikal Solutions Pvt. Ltd., Bangalore Working at client location for Continental Automotives (ADAS) |
| FEB 2013 - MAY 2014  | Engineer at Тесн BLA Solutions Pvt. Ltd., Calcutta, India   |
| Jul 2009 - Aug 2010  | Programmer at Accenture, Bangalore, India   |
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