Agniva Sengupta

PhD Student at Inria

Inria Rennes - Bretagne Atlantique
Campus universitaire de Beaulieu
35042 Rennes cedex - France
☎ 07 52 58 24 47
✉ agniva.sengupta@inria.fr
🖥 team.inria.fr/rainbow/fr/agniva-sengupta
⊕ github.com/agnivsen

Research summary

My doctoral research area is computer vision, specifically related to deformable object tracking using depth cameras.
Prior to my PhD, I have worked on multiple computer vision/machine vision projects such as: traffic sign recognition and ADAS using machine learning, monocular visual SLAM for Augmented Reality, visual odometry using monocular cameras and IMU, computational photography and motion planning for robots

Keywords: Deformation Tracking, Visual Tracking, FEM, Visual SLAM

Education

2017-20   **Pursuing Ph.D. degree in Computer Vision**, *INRIA, Rennes, France. Title: Non-rigid Object Tracking using RGB-D Cameras*, Tentative date of thesis defense: June 2020.
- **Summer School:** Robotic Vision Summer School (RVSS) at the Australian National University (ANU) in Canberra, Australia. Feb, 2018 cohort. *Organized by:* Australian Centre for Robotic Vision (ACRV)
- **Visiting Ph.D. Student:** March - April 2018 at SINTEF SeaLab, *Trondheim, Norway*

2012   **M.Tech in Mechatronics (Masters)**, *Indian Institute of Engineering Sciences and Technology, India.*

PhD Topic

The objective of my PhD is to track the 3D deformation of non-rigid objects using RGB-D cameras. A combination of classical computer vision techniques (direct photometric minimization, sparse correspondence, depth based error minimization) with co-rotational Finite Element Methods has been used for this purpose. This approach enables us to track large deformations in non-rigid objects irrespective of large changes in volume, as well as gather additional information about the deformation, such as magnitude of external forces (with just the depth camera) and estimation of material properties (Young's modulus, Poisson's ratio etc.). This thesis is supervised by *Eric Marchand* and *Alexandre Krupa.*

Positions held

2017 – present   **PhD Student at Inria**, *Rainbow team, Inria Rennes at Bretagne Atlantique, France.*
2015 – 2016   **Computer Vision Engineer**, *Whodat Tech Pvt. Ltd., India.*
2014 – 2015   **Product Engineer**, *Continental AG (as consultant from KritiKal Solutions Pvt. Ltd.).*
2012 – 2014   **Product Engineer**, *TechBLA Solutions, India.*
2009 – 2010   **Engineer**, *Accenture Services Pvt. Ltd..*

Technical Skills

- **Toolkits/libraries**: OpenCV, ViSP, PCL, VTK, SOFA, Eigen, NumPy/SciPy

- **Languages**: C/C++, Python, Matlab and Java. Also worked on OpenMP, SSE3 and CuBLAS based optimization.

Publications

1. Sengupta, Agniva, Romain Lagneau, Alexandre Krupa, Eric Marchand and Maud Marchal. "Simultaneous Tracking and Elasticity Parameter Estimation of Deformable Objects." *IEEE International Conference on Robotics and Automation (ICRA)* IEEE, 2020 - *accepted*

2. Sengupta, Agniva, Alexandre Krupa, and Eric Marchand. "Tracking of Non-Rigid Objects using RGB-D Camera." *IEEE SMC 2019: IEEE International Conference on Systems, Man, and Cybernetics)* IEEE, 2019.

3. Sengupta, Agniva, Alexandre Krupa, and Eric Marchand. "RGB-D tracking of complex shapes using coarse object models." *2019 IEEE International Conference on Image Processing (ICIP)* IEEE, 2019.

4. Sengupta, Agniva, and Shafeeq Elanattil. "New feature detection mechanism for extended Kalman filter based monocular SLAM with 1-point RANSAC." *International Conference on Mining Intelligence and Knowledge Exploration.* Springer, Cham, 2015.

5. Sengupta, Agniva, Ranjit Ray, and S. N. Shome. "Virtual Stretched String: An Optimal Path Planning Technique over Polygonal Obstacles." *Proceedings of Conference on Advances In Robotics.* ACM, 2013.