



# IRISWSNLAB

IRIS MOTE MODULE KIT PROJECT

Embedded Systems Project

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# IRISWSNLAB PROJECT OVERVIEW

In IrisWSNLab Project, I performed some of the tutorials proposed by TinyOS at the following link:

[http://tinyos.stanford.edu/tinyos-wiki/index.php/Main\\_Page](http://tinyos.stanford.edu/tinyos-wiki/index.php/Main_Page)

- 1.1
- 1.2
- 1.3
- 1.4
- 1.5
- 1.6
- 1.7
- 1.8
- 1.11
- 1.13
- 1.15

1.5.1 and 1.9 pages have been removed. I'm going to talk about useful commands and problems/solutions I found during these tutorials (other material and explanations are part of the tutorials themselves).

# ENVIRONMENT

In addition to the Iris Kit (WSN hardware modules), I used:

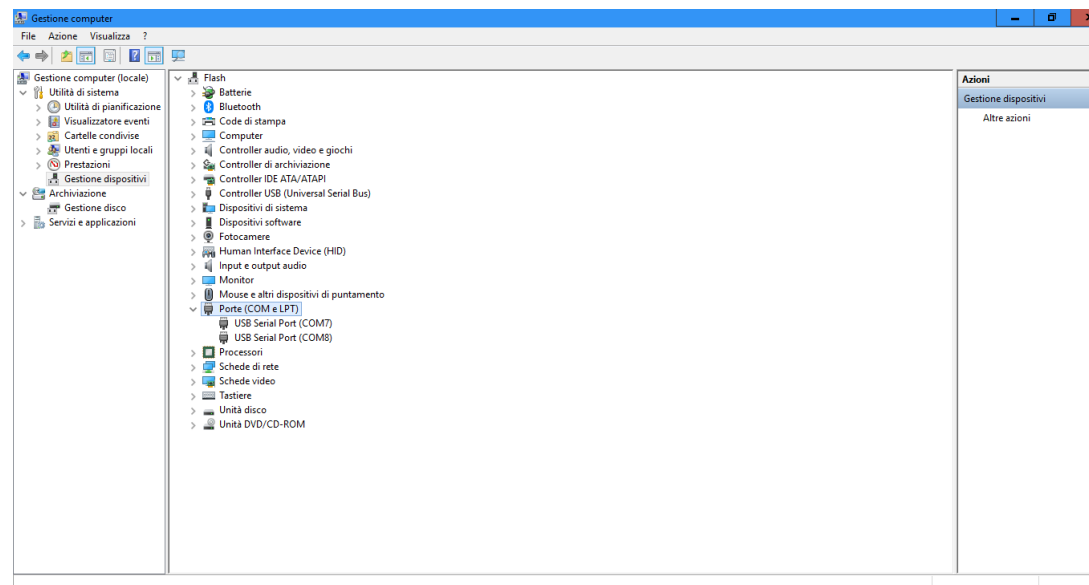
- A Debian 7 virtual machine (running on Windows 10) provided with TinyOS 2.1.2 and tutorials code (you can find it at tutorials link).
- VM Ware Workstation Player, a Virtualization Environment (to run the virtual machine):
  - <https://www.vmware.com>
- MIB520 drivers for Windows:
  - <http://www.ftdichip.com/Drivers/VCP.htm>



# MIB520 DRIVERS

To install MIB520 drivers on Windows 10:

- I plugged the MIB520 programming board (the only one provided with a USB port) to one of my PC USB ports:  
As you can see in Device Management, the device is detected as 2 COM ports.
- I download the executable file from the link (Windows denied me doing the manual installation) and I run it.



# TINYOS COMMANDS – COMPILING AND PROGRAMMING

To compile an application for an Iris Mote (a WSN sensor node), go inside the project folder and give the following command:

- `make iris`

To compile and program an Iris Mote, plug it to the programming board, connect the board to the PC, then go inside the project folder and give the following command:

- `make iris install.[<moteID>] mib510,/dev/ttyUSBx`

Mote ID is the unique identifier you can assign to the mote (or it will be provided with the default ID).

x is the USB port number the programming board is connected to.

To directly program an Iris Mote (without compiling it), the command is instead:

- `make iris reinstall[.<moteID>] mib510,/dev/ttyUSBx`

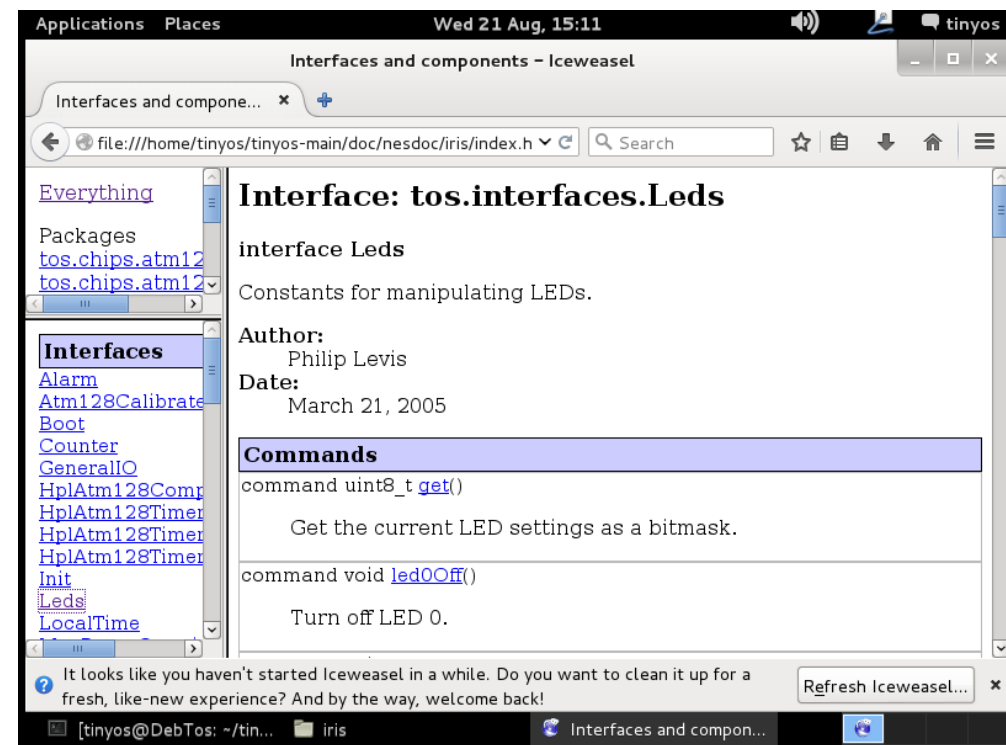
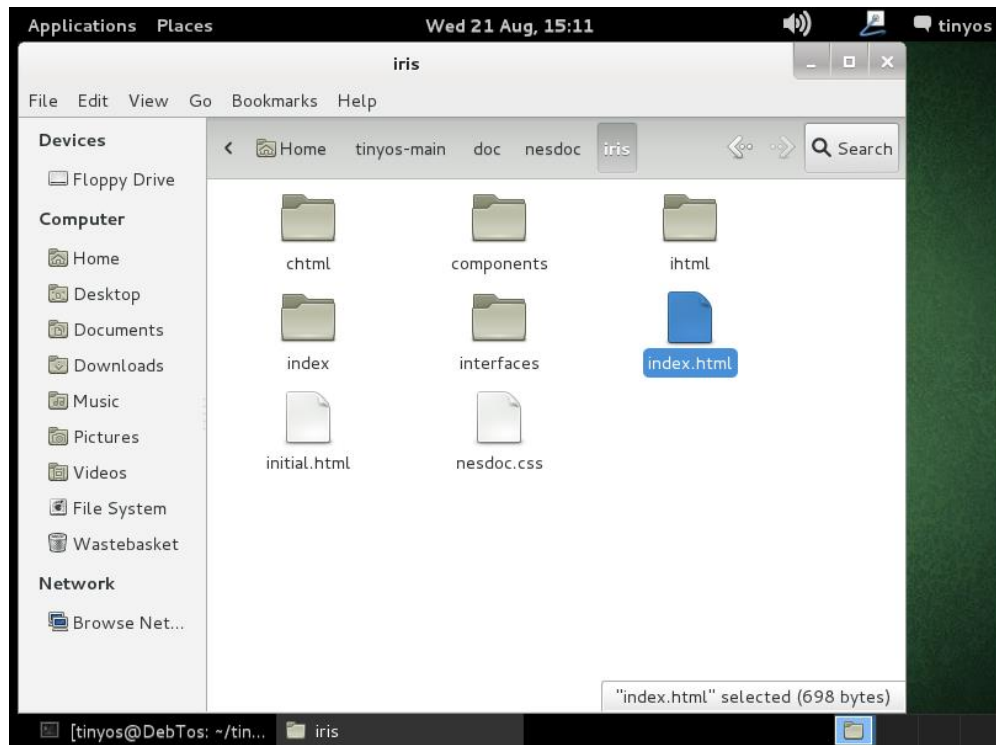


# TINYOS COMMANDS – REVERSE ENGINEERING

To see how your components are made and wired together, you can use reverse engineering by the command:

- make iris docs

The result is an html file (inside doc folder).



# TINYOS COMMANDS – LISTENING TO A SERIAL PORT

If you installed an application that sends data to the PC on one or more motes and the BaseStation app (that receives data) on the mote connected to the PC, you can see these data by giving the following command:

- `java net.tinyos.tools.Listen -comm serial@/dev/ttyUSBx:iris`

```
tinyos@DebTos:~/tinyos-main/apps/BaseStation$  
tinyos@DebTos:~/tinyos-main/apps/BaseStation$  
tinyos@DebTos:~/tinyos-main/apps/BaseStation$  
tinyos@DebTos:~/tinyos-main/apps/BaseStation$ java net.tinyos.tools.Listen  
serial@/dev/ttyUSB1:57600: resynchronising  
00 FF FF 00 00 02 00 89 00 44  
00 FF FF 00 00 02 00 89 00 45  
00 FF FF 00 00 02 00 89 00 46  
00 FF FF 00 00 02 00 89 00 47  
00 FF FF 00 00 02 00 89 00 48  
00 FF FF 00 00 02 00 89 00 49  
00 FF FF 00 00 02 00 89 00 4A  
00 FF FF 00 00 02 00 89 00 4B
```

To allow more than one application to listen to the motes, you have to use the Serial Forwarder:

- `java net.tinyos.sf.SerialForwarder -comm serial@/dev/ttyUSBx:iris`

# TINYOS COMMANDS – LISTENING TO A SERIAL PORT

Pay attention: if you forget to add the `–comm` option, an error will occur:

```
tinyos@DebTos:~/tinyos-main/apps/tests/TestSerial$  
tinyos@DebTos:~/tinyos-main/apps/tests/TestSerial$ java TestSerial  
sf@localhost:9002 died - exiting (java.net.ConnectException: Connection refused)  
tinyos@DebTos:~/tinyos-main/apps/tests/TestSerial$
```

To avoid writing the `–comm` parameter every time, you can give (once) the following command:

- `export MOTECOM=serial@/dev/ttyUSBx:iris`

```
tinyos@DebTos:~/tinyos-main/apps/tests/TestSerial$  
tinyos@DebTos:~/tinyos-main/apps/tests/TestSerial$ export MOTECOM=serial@/dev/ttyUSB1:iris  
tinyos@DebTos:~/tinyos-main/apps/tests/TestSerial$ java TestSerial  
serial@/dev/ttyUSB1:57600: resynchronising  
Sending packet 0  
Received packet sequence number 537  
Sending packet 1  
Received packet sequence number 538  
Sending packet 2  
Received packet sequence number 539  
Sending packet 3  
Received packet sequence number 540  
Sending packet 4  
Received packet sequence number 541  
Sending packet 5  
Received packet sequence number 542
```

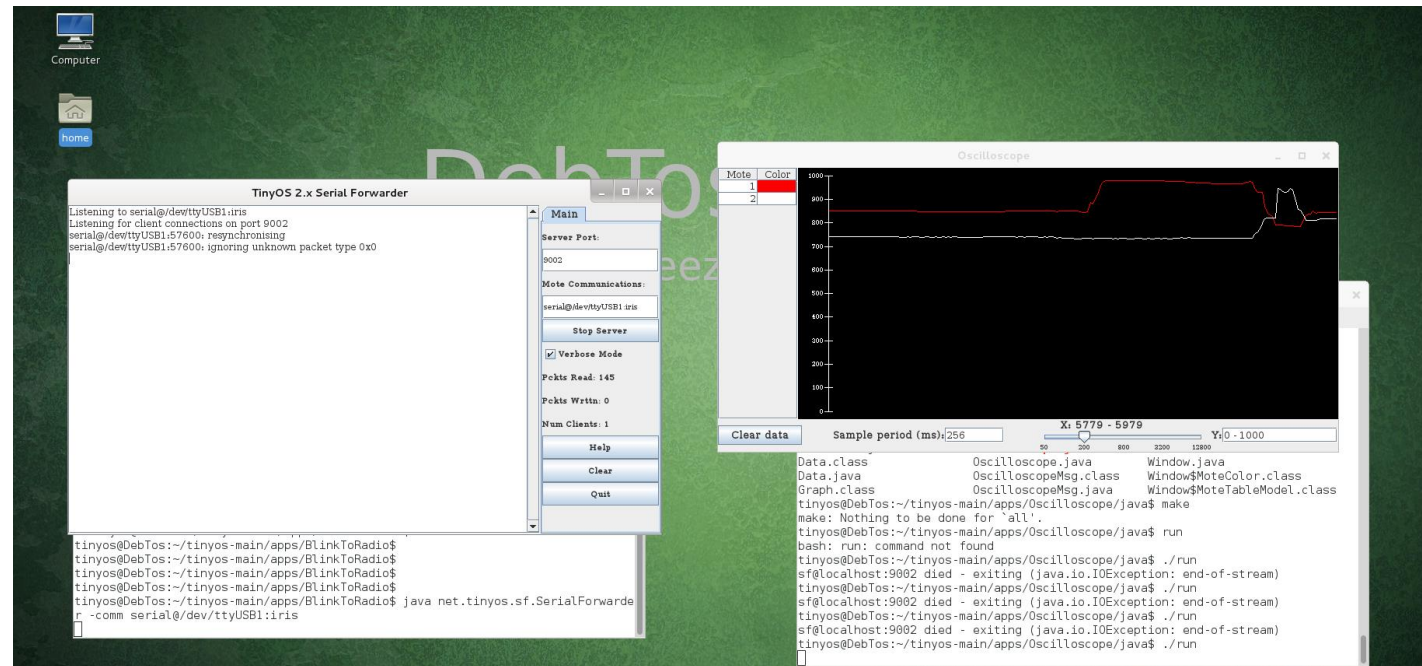


# TINYOS COMMANDS – LISTENING TO A SERIAL PORT

There are some TinyOS applications allowing you to see incoming data via a GUI, like Oscilloscope, you can use within the Serial Forwarder.

In order to use MDA100CB sensor board (having plugged it on the motes, programmed with a proper application) to take light sensor data (shown by Oscilloscope), I gave the following command:

- SENSORBOARD=mda100 make iris



# TINYOS COMMANDS – DEBUGGING

If you need an easy debugging, you can use TinyOS Printf library to show text messages in your application.

After installing the application on a mote, you can see these messages via the following command:

- `java net.tinyos.tools.PrintfClient -comm serial@/dev/ttyUSBx:iris`

[illegible]

# TINYOS COMMANDS – TOSSIM TUTORIAL ERROR

During Tossim tutorial, the following strange error occurred:

```
e/tinyos/tinyos-main/tos/lib/tossim/tossim_wrap.cxx -I/include/python2.7 -I/nome
/tinyos/tinyos-main/tos/lib/tossim -DHAVE_CONFIG_H
make: g++: Command not found
make: *** [sim_exe] Error 127
/tinyos@DebTos:~/tinyos-main/apps/RadioCountToLeds$ gcc -v
Using built-in specs.
COLLECT_GCC=gcc
COLLECT_LTO_WRAPPER=/usr/lib/gcc/i486-linux-gnu/4.7/lto-wrapper
Target: i486-linux-gnu
Configured with: ../src/configure -v --with-pkgversion='Debian 4.7.2-5' --with-b
ugurl=file:///usr/share/doc/gcc-4.7/README.Bugs --enable-languages=c,c++,go,fort
ran,objc,obj-c++ --prefix=/usr --program-suffix=-4.7 --enable-shared --enable-li
nker-build-id --with-system-zlib --libexecdir=/usr/lib --without-included-gettex
t --enable-threads=posix --with-gxx-include-dir=/usr/include/c++/4.7 --libdir=/u
sr/lib --enable-nls --with-sysroot=/ --enable-clocale=gnu --enable-libstdcxx-deb
ug --enable-libstdcxx-time=yes --enable-gnu-unique-object --enable-plugin --enab
le-objc-gc --enable-targets=all --with-arch-32=i586 --with-tune=generic --enable
-checking=release --build=i486-linux-gnu --host=i486-linux-gnu --target=i486-lin
ux-gnu
Thread model: posix
gcc version 4.7.2 (Debian 4.7.2-5)
/tinyos@DebTos:~/tinyos-main/apps/RadioCountToLeds$
```



THANKS FOR  
YOUR  
ATTENTION