

Pinball Template Code

```
#include <Pinball.h>

#include "arrays.h"

//-----PIN DEFINITIONS, FLAGS-----

int spkr_pin = 13;
Pb_speaker spkr(spkr_pin);           // Speaker pin 13
Pb_outputs shregs(10, 12, 11, 2);    // Shift registers (data, clk, latch, number of registers)
Pb_scoreboard myboard(8, 9);         // Scoreboard (clock, data)

byte serdata[2];                     // For the shift registers
// serdata[1,0] are each 8 independent LEDs

int ir_pin = A0, piezo_pin = A1;     // IR, Piezo pins
int roll_pin = A3, drain_pin = 7;    // roller, drain switch pins

// Switches for roll and drain
Pb_switch roll_sw(50), drain_sw(50);

// Flags for the same
int roll_flag, drain_flag;

// Game specific global variables
int ii, num_lives = 4, score = 0, score_flag = 0;
int ir_thresh = 800, piezo_thresh = 500;
int ir_val, piezo_val, ir_delay, piezo_delay = 1000;
int ir_flag = 0, piezo_flag = 0;

// Timed events
Pb_timedevent LEDflash(flash);
Pb_timedevent scoreflash(flashscore);

// Stopwatch for ir and piezo debounce
Pb_stopwatch mywatch, mywatch_ir, mywatch_piezo;
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//-----UPDATE FUNCTION-----

void update_music_and_events() {

    spkr.update();
    LEDflash.update();
    scoreflash.update();

}

//-----SETUP-----

void setup() {
    // put your setup code here, to run once:

    pinMode(roll_pin, INPUT); pinMode(drain_pin, INPUT);
    // Enable pullup resistors on digital input pins
    digitalWrite(roll_pin, HIGH); digitalWrite(drain_pin, HIGH);

    serdata[0] = 0b11111111; // blue LEDs
    serdata[1] = 0b00000000; // red LEDs

    shregs.update(serdata);
    delay(500);

    spkr.loopstart(beep_vals, beep_time, beep_len);

    myboard.setpartition(1); // Use scoreboard to keep track of lives
    myboard.predisplay(num_lives);
    myboard.postdisplay(score);
    delay(250);
    LEDflash.loopstart(flashloop, flashtime, 2);
    spkr.start(startup_vals, startup_time, startup_len);
    LEDflash.start(startup_vals, startup_time, startup_len);

}

//-----THE LOOP-----

void loop() {
    // put your main code here, to run repeatedly:

    if (num_lives > 0) {
        readinputs();
    }
}

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        dologic();
        writeoutputs();
    }

    update_music_and_events();
}

//-----INPUTS-----

void readinputs() {

    roll_flag = 0; drain_flag = 0;

    roll_flag = roll_sw.pushed(digitalRead(roll_pin));
    drain_flag = drain_sw.pushed(digitalRead(drain_pin));

    ir_val = analogRead(ir_pin);
    piezo_val = analogRead(piezo_pin);
}

//-----LOGIC-----

void dologic() {

    score_flag = 0; // Used to decide whether to update scoreboard

    if (roll_flag == 1) { score = score + 1; score_flag = 1; }

    if (ir_val > ir_thresh) {
        if (ir_flag == 0) {
            score = score + 5; score_flag = 2;
            ir_flag = 1;
            mywatch_ir.start();
        }
        else if (ir_flag > 0) {
            if (mywatch_ir.time() > ir_delay) {
                ir_flag = 0;
                mywatch_ir.stop();
            }
        }
    }
}

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    if (piezo_val > piezo_thresh) {
        if (piezo_flag == 0) {
            score = score + 5; score_flag = 3;
            piezo_flag = 1;
            mywatch_piezo.start();
        }
    } else if (piezo_flag > 0) {
        if (mywatch_piezo.time() > piezo_delay) {
            piezo_flag = 0;
            mywatch_piezo.stop();
        }
    }
}

if (drain_flag == 1) { num_lives = num_lives - 1; score_flag = 4;}

}

//-----OUTPUTS-----

void writeoutputs() {

    int shreg_flag = 0;

    switch (score_flag) {
        case 1:
            spkr.start(coin_vals, coin_time, 3);
            break;
        case 2:
            spkr.start(coin_vals, coin_time, 15);
            break;
        case 3:
            spkr.start(oneup_vals, oneup_time, oneup_len);
            break;
        // You can add more cases
    }

    if (drain_flag == 1) {
        shreg_flag = 1;
        spkr.start(life_vals, life_time, life_len);
        if (num_lives > 0) {
            LEDflash.start(lifeflash, lifetime, 20);
        } else {
            LEDflash.loopstop();
            LEDflash.start(deathLED, deathtime, 17);
        }
    }
}

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        scoreflash.loopstart(scflashvals, scflashtime,2);
        spkr.loopstop();
        spkr.start(death_vals, death_time, death_len);
    }
}

if (roll_flag > 0) {
    LEDflash.start(shiftpatvals, shiftpattime, 17);
    spkr.start(scoreone_vals, scoreone_time, scoreone_len);
}

myboard.predisplay(num_lives);
myboard.postdisplay(score);

if (shreg_flag > 0) { shregs.update(serdata); }
if (score_flag > 0) {
    myboard.predisplay(num_lives);
    myboard.postdisplay(score);
}

}

//-----SPECIAL FUNCTIONS-----

void flash(int val) {
    // Flash the LEDs
    if (serdata[0] == 0b00000000) { serdata[0] = 0b11111111; }
    else { serdata[0] = 0b00000000; }
    if (serdata[1] == 0b00000000) { serdata[1] = 0b11111111; }
    else { serdata[1] = 0b00000000; }

    shregs.update(serdata);
}

void flashscore(int val) {
    // Flash the scoreboard

    if (val == 1) {
        myboard.blankpredisplay();
        myboard.blankpostdisplay();
    }
    else {
        myboard.predisplay(num_lives);
    }
}

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        myboard.postdisplay(score);  
    }  
}
```