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| **pdf** | **Página web** | **Apartado memoria** |
| Yarp 03 - CAPITULO 3 - LIBRERIAS SOFTWARE | http://bibing.us.es/proyectos/abreproy/12095/fichero/VOLUMEN+1%252F03+-+CAPITULO+3+-+LIBRERIAS+SOFTWARE.pdf | Programa de adquisición de datos |
| yarp | https://www.researchgate.net/publication/221709988\_YARP\_Yet\_another\_robot\_platform | Programa de adquisición de datos |
| 0referencia\_inercial\_mti\_ahrs(en carpeta apendices) | http://www.sensores-de-medida.es/uploads/0referencia\_inercial\_mti\_ahrs.pdf | Xsens |
| p50-metta | http://delivery.acm.org/10.1145/1780000/1774683/p50-metta.pdf?ip=163.117.82.138&id=1774683&acc=ACTIVE%20SERVICE&key=DD1EC5BCF38B3699%2EAFCE2F3122C4D47C%2E4D4702B0C3E38B35%2E4D4702B0C3E38B35&\_\_acm\_\_=1532028775\_c3d27af62ce735cd28b4858d6077ef1a | Xsens icub |
| 3d linear pendulum(descripción resumida) | https://pdfs.semanticscholar.org/6a31/6e0d44e35a55c41a442b3f0d0eb1f9d4d0ca.pdf | Modelo Péndulo invertido |
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| Humanoid walking robot: modeling, inverse dynamics, and gain scheduling control | https://www.hindawi.com/journals/jr/2010/278597/ | Apartado 4 |
| Biped Walking Pattern Generation by using Preview Control of Zero-Moment Point | https://www.swarthmore.edu/NatSci/mzucker1/e91/readings/kajita2003preview.pdf | Apartado 4 |
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| control\_ZMP₁ | http://revistas.elpoli.edu.co/index.php/pol/article/viewFile/138/114 | Apartado 5.1.4 |
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