

filter by the impulse sequence $\delta(n)$, then from (4.11) and using $\mathcal{Z}[\delta(n)] = 1$, the output of the filter will be $x(n)$. (This is a numerical approach of computing the inverse z -transform; we will discuss the analytical approach in the next section.) We can compare this output with the given $x(n)$ to verify that $X(z)$ is indeed the transform of $x(n)$. This is illustrated in Example 4.6. An equivalent approach is to use the `impz` function discussed in Chapter 2.

4.2.1 SOME COMMON z -TRANSFORM PAIRS

Using the definition of z -transform and its properties, one can determine z -transforms of common sequences. A list of some of these sequences is given in Table 4.1.

TABLE 4.1 *Some common z -transform pairs*

<i>Sequence</i>	<i>Transform</i>	<i>ROC</i>
$\delta(n)$	1	$\forall z$
$u(n)$	$\frac{1}{1 - z^{-1}}$	$ z > 1$
$-u(-n - 1)$	$\frac{1}{1 - z^{-1}}$	$ z < 1$
$a^n u(n)$	$\frac{1}{1 - az^{-1}}$	$ z > a $
$-b^n u(-n - 1)$	$\frac{1}{1 - bz^{-1}}$	$ z < b $
$[a^n \sin \omega_0 n] u(n)$	$\frac{(a \sin \omega_0) z^{-1}}{1 - (2a \cos \omega_0) z^{-1} + a^2 z^{-2}}$	$ z > a $
$[a^n \cos \omega_0 n] u(n)$	$\frac{1 - (a \cos \omega_0) z^{-1}}{1 - (2a \cos \omega_0) z^{-1} + a^2 z^{-2}}$	$ z > a $
$na^n u(n)$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z > a $
$-nb^n u(-n - 1)$	$\frac{bz^{-1}}{(1 - bz^{-1})^2}$	$ z < b $

□ **EXAMPLE 4.6** Using z -transform properties and the z -transform table, determine the z -transform of

$$x(n) = (n - 2)(0.5)^{(n-2)} \cos \left[\frac{\pi}{3}(n - 2) \right] u(n - 2)$$

Solution Applying the sample-shift property,

$$X(z) = \mathcal{Z}[x(n)] = z^{-2} \mathcal{Z} \left[n(0.5)^n \cos \left(\frac{\pi n}{3} \right) u(n) \right]$$