

Kinematics

Linear

$$\begin{aligned}v_f &= v_i + at & \Delta x &= \frac{1}{2}(v_i + v_f)t \\v_f^2 &= v_i^2 + 2a\Delta x & \Delta x &= v_i t + \frac{1}{2}at^2\end{aligned}$$

Rotational

$$\begin{aligned}\omega &= \omega_i + \alpha t & \theta &= \frac{1}{2}(\omega_f - \omega_i)t \\ \omega^2 &= \omega_i^2 + 2\alpha\theta & \theta &= \omega_i t + \frac{1}{2}\alpha t^2\end{aligned}$$

Energy

Potential Energy

$$U_{gravity} = mgh \quad U_{spring} = \frac{1}{2}kx^2$$

Kinetic Energy

$$\begin{aligned}K &= \frac{1}{2}mv^2 & K_{rotational} &= \frac{1}{2}I\omega^2 \\ K_{rolling} &= \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2\end{aligned}$$

Conservation of Energy

$$\Delta K + \Delta U = 0$$

Projectile Motion

$$\begin{aligned}v_x &= v \cos \theta & \text{max height } h &= \frac{v_{yi}^2}{2g} \\ v_y &= v \sin \theta & \text{max range } r &= \frac{v_{xi}^2 \sin(2\theta)}{g} \\ \theta &= \tan^{-1} \frac{v_y}{v_x} & \text{distance } d &= \frac{1}{2}a_x t^2\end{aligned}$$

Circular Motion

$$\begin{aligned}F &= m \frac{v^2}{r} = m\omega^2 r & f &= \frac{rev}{sec} \\ \omega &= 2\pi f = \frac{v}{r} & 1 \frac{rev}{sec} &= 2\pi \frac{rad}{sec} \\ \alpha &= \frac{v^2}{r} = \frac{a}{r}\end{aligned}$$