# Numerical Analysis of Burgers' Equation\*

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#### 1 Introduction

### 1.1 The Inviscid Burgers' Equation

We have elected to study the Burgers' equation, or more correctly, the inviscid Burgers' equation.<sup>[1]</sup> Given  $u \in C^1(\Omega)$ , where  $\Omega \subset \mathbb{R}^{n+1}$  is a domain, the general form is written as

$$\partial_t u(\boldsymbol{x}, t) + u(\boldsymbol{x}, t) \cdot \nabla_{\boldsymbol{x}} u(\boldsymbol{x}, t) = 0 \tag{1}$$

where  $\nabla_{\boldsymbol{x}}$  denotes the gradient with respect to the spatial variable  $\boldsymbol{x} \in \mathbb{R}^n$ . For pragmatic reasons though, we will be focusing on the n=1 case. Then (1) simplifies to

$$\partial_t u(x,t) + u(x,t)\partial_x u(x,t) = 0. (2)$$

There are two key observations to make. The first is that (2) is really a statement about the directional derivative, that is

$$\nabla u(x,t) \cdot (u(x,t),1) = 0^{[2]} \tag{3}$$

so the derivative of u in the direction of (u, 1) is 0 - in other words, u is constant in this direction. This is a consequence of (2) being first-order. While on the surface it may seem problematic that (2) is quasilinear (and so the direction (u, 1) is varied), this does not complicate the finding of an analytic solution.

#### 1.2 The Method of Characteristics

Given data on some curve  $\Gamma \subset \overline{\Omega}$ , we are looking for parametric curves (x(t), t) which connect points  $(x, t) \in \Omega$  to  $\Gamma$ . The upshot is that on these *characteristic curves*, the PDE (2) degenerates into an ODE. So

$$\frac{dx}{dt} = u(x(t), t) \tag{4}$$

<sup>\*</sup>Placeholder title!

<sup>[1]</sup> We may decide later on to study the viscous Burgers' equation.

<sup>&</sup>lt;sup>[2]</sup>Technically we should be normalizing so that this is a unit vector.

Now supposing that u solves (2), let z(t) denote the value of u along a characteristic, i.e.

$$z(t) = u(x(t), t)$$

Then

$$\frac{dz}{dt} = \partial_x u(x(t), t) \frac{dx}{dt} u(x(t), t) + \partial_t u(x(t), t)$$
$$= \partial_t u(x(t), t) + u(x(t), t) \partial_x u(x(t), t)$$

## References

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