

# Sankalp (Sunny) Agrawal

[agrawal.268@buckeyemail.osu.edu](mailto:agrawal.268@buckeyemail.osu.edu) | [agrawal-sunny.github.io](https://agrawal-sunny.github.io) | [www.linkedin.com/in/sunny-agrawal-osu/](https://www.linkedin.com/in/sunny-agrawal-osu/)

## EDUCATION

**The Ohio State University**, Columbus OH.

Bachelor of Science in Electrical and Computer Engineering.

- Dean's List (all semesters), Minors: Robotics and Autonomous Systems, Physics

December 2025

**GPA: 3.98/4.0**

## COURSEWORK

**Graduate:** Machine Learning, Real Time Robotics, State-Space Control, Machine Learning for Data Analysis, Autonomous Vehicles

## TECHNICAL SKILLS

**Programming Languages & Tools:** Python, C++, MATLAB, ROS, Linux, Git, SolidWorks

**Libraries:** PyTorch, TensorFlow, scikit-learn, JAX, MuJoCo, IsaacGym, NumPy, SciPy, OpenCV

## RESEARCH & PROFESSIONAL EXPERIENCE

**Carnegie Mellon University** | [Interactive and Trustworthy Robotics Lab](#) | Advisor: [Andrea Bajcsy](#)

Undergraduate Research Fellow – Robotics Institute Summer Scholar ([RISS](#))

May 2025 – Dec 2025

- Developed a novel approach for conditioning safety behavior on an image of potential failure in robotic manipulation, adding the ability to adapt to changing safety requirements in the real world at deployment.
- Implemented world-model training and reinforcement learning algorithms, conducted hardware experiments and wrote a [first-author ICRA 2026 submission](#).

**University of Southern California** | [Learning and Interactive Robot Autonomy Lab](#) | Advisor: [Erdem Bıyık](#)

Amazon Research Fellow – Viterbi Summer Undergraduate Research Experience ([SURE](#)) May 2024 – Aug 2025

- Investigated improving the sample-efficiency of Bayes-Adaptive Meta-Reinforcement Learning by designing, testing, and analyzing new partially informed training strategies.
- Implemented reinforcement learning algorithms from scratch, validated them through experiments, and maintained a collaborative GitHub codebase for the research team.

**The Ohio State University** | [Cyberbotics Lab](#) | Advisor: [Ayonga Hereid](#)

Undergraduate Research Assistant

Sep 2022 – Dec 2025

- Researched reinforcement learning methods for sub-goal planning for humanoid navigation and contributed on [ICRA 2026 paper submission](#).

Undergraduate Research Fellow – Summer Research Opportunities Program ([SROP](#))

May 2023 – July 2023

- Investigated mass parallel training for humanoid locomotion, dramatically decreasing training times.

**Bilstein thyssenkrupp** | Industrial Robotics Intern

May 2022 – Aug 2022

- Automated production-line processes by integrating collaborative UR 6-axis robot manipulators, applying mechatronics and robotic automation principles to improve reliability and throughput.

## PROJECTS

**Self-Tuning Instrument** | Senior Capstone Project

Jan 2025 – Dec 2025

- Designed and built a self-tuning ukulele by integrating embedded hardware, motor actuation, and real-time signal processing.
- Implemented pitch detection, control logic, and software to automate tuning through closed loop feedback.
- Understood and integrated customer requirements, producing demonstrations, reports, and design reviews.
- Skills: Embedded Systems, Signal Processing, C++, Motor Control, Mechatronics

## PUBLICATIONS

---

- [1] **S. Agrawal\***, J. Seo\*, K. Nakamura, R. Tian, and A. Bajcsy, ‘AnySafe: Adapting Latent Safety Filters at Runtime via Safety Constraint Parameterization in the Latent Space’, *ICRA 2026 (in submission)*  
[Paper](#) | [Website](#)

- [2] C. Peng, Z. Zhang, S. Gong, **S. Agrawal**, K. A. Redmill, and A. Hereid, ‘Reinforcement Learning with Data Bootstrapping for Dynamic Subgoal Pursuit in Humanoid Robot Navigation’, *ICRA 2026 (in submission)*  
[Paper](#)

## POSTER PRESENTATIONS

---

- AnySafe: A Generalizable Framework for Constraint-Conditioned Latent Safety Analysis** Aug 2025  
• Presented at the 2025 CMU RISS Research Showcase [[Poster](#)]
- Using Partially Observed Belief States for Bayes-Adaptive Meta-RL** Aug 2024  
• Presented at the 2024 USC SURE Research Showcase [[Poster](#)]
- Investigating Mass Parallel Reinforcement Learning to Train Bipedal Robot Locomotion** April 2024  
• Presented at the 2024 Ohio State Spring Undergraduate Research Festival (SURF) [[Poster](#)]

## TEACHING & SERVICE

---

- ECE 5463: Introduction to Real Time Robotics Systems (Graduate), *Teaching Assistant* Spring 2024
- Ohio State Mathematics and Statistics Learning Center** Jan 2023 – April 2024  
Math Tutor  
• Tutored over twenty students in Linear Algebra and Differential Equations through weekly appointments.  
• Learned to effectively communicate and explain complex ideas.

## HONORS & AWARDS

---

- Google Undergraduate Research Fellow at Carnegie Mellon University** Summer 2025  
• Member of the Carnegie Mellon University RISS 2025 Cohort (1 of 39 Scholars).  
• Awarded scholarship from **Google Robotics** to conduct research on robot safety.
- Amazon Undergraduate Research Fellow at University of Southern California Viterbi** Summer 2024  
• Member of the USC Viterbi SURE 2024 Cohort (1 of 38 Scholars).  
• Awarded scholarship from **Amazon** to conduct research on Bayes-Adaptive Meta-RL methods.
- Dean's List** All Semesters
- Ohio State Maximus Merit Scholarship** May 2022
- IEEE College Scholarship for 1st place at Science Olympiad Nationals** May 2021

## LEADERSHIP & INVOLVEMENT

---

- Black x Bold Magazine**, *Senior Photographer* August 2023 – Dec 2025  
• Serve on the leadership team as Senior Photographer, contributing to magazine layout decisions and producing photography featured in five issues, including three cover photos.  
• Highlight multicultural student organizations through campus photography projects and lead outreach efforts that strengthen visibility, community engagement, and cross-cultural awareness.
- Buckeye Capture**, *Founder* January 2024 – Dec 2025  
• Founded and lead a 10-member photography team that provides free professional media support to student organizations.  
• Partnered with more than 25 clubs to deliver high-quality branding and outreach content, strengthening campus visibility and engagement.