Problem 3.

a) Nyquist Thronem.

Lets say we have a sinusoidal wave =)

=) exp (2 \(fm nts)

Sinusoids have period = 2TL

exp (2th fm nts) = exp (2th nts fm + 2th x)

 $= exp \left(2\pi \left(fm + \frac{\kappa}{nts} \right) nts \right)$

= $exp \left(2\pi \left(fm + pfs\right)hts\right)$

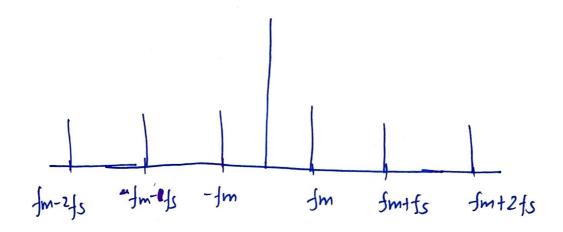
(4n = p)

fm + pfs = f'

= exp (2t f'nts)

> multiples of fm+ pfs

Therefore, any sampled sinusoid is equivalent to another sampled sinusoid with a frequency that is an integer multiple of sampling frequency away from the original frequency.



To avoid, aliasing, the alias mist lie outside

of band width = 2 fm

alias

-fw

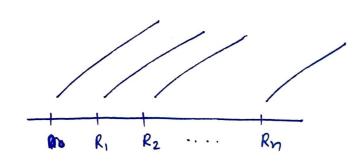
i fs 2 2 fm for it to not

have alianing?

That is for should alias to left of -for and -for should alias to right of for

Hence, proved.

b)



Let received signal at receiver array be y(t)

$$y(t) = \begin{cases} y_{R_1} \\ y_{R_2} \\ y_{R_3} \\ y_{R_3} \end{cases}$$

e d->

path difference = dcoso

phase difference = $\frac{d\cos\theta}{k} \cdot 2\pi = \phi$ $e^{j2\pi k\phi}$ $e^{j2\pi k\phi}$ $e^{j2\pi \delta} \cdot e^{j2\pi \delta} \cdot e^{j2\pi \delta} \cdot e^{j2\pi \delta}$ R5 Ko

$$\begin{cases}
y_{R_1} \\
y_{R_2} \\
y_{R_3}
\end{cases} =
\begin{cases}
\cos 2\pi f t + \phi \\
\cos 2\pi f t + \phi
\end{cases}$$

$$\cos 2\pi f t + \phi
\end{cases}$$

$$\cos 2\pi f t + (n-1) \phi$$

$$\cos 2\pi f t + (n-1) \phi$$

Steering matrix.

in case of motiple signal:

$$M = \begin{cases} ejo & ejo \\ ej\phi_1 & ej\phi_2 \end{cases}$$

$$e^{j2}d_1 & e^{j2}d_3 \\ e^{j3}d_1 & e^{j3}d_2 \end{cases}$$

$$e^{j3}d_1 & e^{j(n-1)}\phi_2$$

Problem 3.

$$P(S_{K}|m_{1:n}) = \frac{P(S_{K}, m_{1:n})}{P(m_{1:n})} z P(S_{K}, m_{1:n})$$

$$P(M_{1:n}) = \frac{P(S_{K}, m_{1:n})}{P(m_{1:n})} z P(S_{K}, m_{1:n})$$

$$P(S_K, m_{1:n}) = P(S_K, m_{1:K}, m_{Kt1:n})$$

Using chain rule,

$$= P(m_{K1}|n|SK)P(SK|m_{1:K})$$

backward forward

prediction

prediction

Problem 3.

d) chain rule on P (A,B,C,D)

P(A,B,C,D) = P(A|BCD) P(BCD) P(B|CD) P(CD) P(CID) I(D)

 $= P(A_1B,C_1D) = P(A_1BCD) P(B_1CD)$ $P(C_1D) P(D)$

= P(A|BCD) P(B|CD) P(CD)