

Recap:

①

minimize $f_0(x)$ Subject to

$$f_i(x) \leq 0, \quad i = 1, 2, \dots, m$$

$$h_i(x) = 0, \quad i = 1, 2, \dots, p$$

$$L(x, \lambda, \nu) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x)$$

$$p^* = \min_x \max_{\substack{\lambda_i \geq 0 \\ \nu_i}} L(x, \lambda, \nu)$$

$$d^* = \max_{\substack{\lambda_i \geq 0 \\ \nu_i}} \min_x L(x, \lambda, \nu)$$

KKT conditions :

If $p^* = d^*$, then if x^* be primal optimal and (λ^*, ν^*) be dual optimal, then

$$\nabla_x f_0(x^*) + \sum_{i=1}^m \lambda_i^* \nabla f_i(x^*) + \sum_{i=1}^p \nu_i^* \nabla h_i(x^*) = 0$$

$$f_i(x^*) \leq 0$$

$$h_i(x^*) = 0$$

$$\lambda_i^* \geq 0$$

$$\lambda_i^* f_i(x^*) = 0$$

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If f_i are convex and h_i are affine, and $\tilde{x}, \tilde{\lambda}, \tilde{\nu}$ are any points that satisfy KKT conditions then \tilde{x} is and $(\tilde{\lambda}, \tilde{\nu})$ are primal and dual optimal with zero duality gap.

SVM:

$$\text{Let } y_i = f(\bar{x}(i))$$

$$\text{minimize } \frac{1}{2} \|\omega\|_2^2$$

$$\text{subject to } y_i (\omega \cdot \bar{x}(i) + \omega_0) \geq 1, \quad i=1, 2, \dots, n$$

Dual:

$$\text{maximize } \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n y_i \lambda_i (\bar{x}(i) \cdot \bar{x}(j)) \quad y_j \lambda_j$$

$$\text{subject to } \sum_{i=1}^n \lambda_i y_i = 0, \quad \lambda_i \geq 0 \quad i=1, 2, \dots, n.$$

Moreover

$$\omega^* = \sum_{i=1}^n \lambda_i^* y_i \bar{x}(i)$$

$$\omega_0^* = y_i - \omega^* \cdot \bar{x}(i) \quad \text{for any } i \text{ s.t. } \lambda_i^* > 0$$

Gradient Descent:

~~min~~ we want to minimize $f(\underline{x})$ (~~min~~)

Starting from \underline{x}_0 (~~min~~)

~~Taylor Series Expansion:~~

$f(\underline{x}_0 + h \underline{u})$, \underline{u} unit vector
 $h > 0$ small step

Taylor Series expansion:

~~$f(\underline{x}_0)$~~ ~~\approx~~

$$\underbrace{f(\underline{x}_0 + h \underline{u})}_{\text{minimize}} \approx f(\underline{x}_0) + h \underline{u}^T \nabla_{\underline{x}} f(\underline{x}_0)$$

$$\underline{u}_0 = - \frac{\nabla_{\underline{x}} f(\underline{x}_0)}{\|\nabla_{\underline{x}} f(\underline{x}_0)\|}$$

$$\underline{x}_1 = \underline{x}_0 + h \underline{u}_0$$

Initialize \underline{x}_0

Repeat: ~~\underline{x}_{t+1}~~

$$\underline{x}_{t+1} = \underline{x}_t - \eta \nabla_{\underline{x}} f(\underline{x}_t)$$

stop if $\|\nabla_{\underline{x}} f(\underline{x}_{t+1})\| \leq \eta$

Stochastic Gradient descent:

Suppose objective function can be written as Sum over training examples:

$$\begin{aligned} \text{MSE}(\underline{w}) &= \sum_{i=1}^n (y_i - w \cdot \bar{x}(i))^2 \\ &= \sum_{i=1}^n g_i(w) \end{aligned}$$

Initialize w_0 :

Shuffle data $\bar{x}(1), \dots, \bar{x}(n)$

for $i=1, 2, \dots, n$:

$$w := w - \eta \nabla_w g_i(w)$$

Advantages:

- Faster than gradient descent
- online learning

Disadvantages

- ~~might not converge to local minimum~~

• performs frequent updates with high variance, hence might keep overshooting.

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