

# **C++ Course 12 : Concurrency.**

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# Concurrency in C++

Before C++ 11: No concurrency (Не было многопоточности).  
Windows vs Posix (Unix) threads. Boost threads, cross-platform.  
C++ 11: Concurrency in the standard library, cross-platform.

1. **async()** + **future** : Task-based approach
2. **thread** : Thread-based approach (lower level)
3. **promise**, **packaged\_task** : Using **future** in a **thread**
4. **mutex**, **atomic** : Protecting shared data
5. **condition\_variable** : A monitor with **wait/ notify** syntax.



Terminology : поток = thread ? поток = stream ? Почему не *нитка*?

[C++ Concurrency in Action: Practical Multithreading by Anthony Williams](#)

Physical thread : Implemented by the CPU

Logical thread : Implemented by the OS

# sleep\_for, sleep\_until and yield

Sleep for a while : Спать некоторое время : (`std::chrono::duration`)

```
this_thread::sleep_for(milliseconds(20));  
this_thread::sleep_for(seconds(2));  
using namespace std::chrono_literals;  
this_thread::sleep_for(100ms); // 100 milliseconds
```

Sleep until a time point : Спать до момента времени : (`std::chrono::time_point`)

```
this_thread::sleep_until(tp);
```

Sleep a bit :

```
this_thread::yield();
```

Print current thread id :

```
cout << this_thread::get_id() << " : starting !\n";
```

# future and async()

**future<int>** : Value of type **int** which can be obtained later

**future<int>** : Значение типа **int** , которое может быть получено позже

**async()** : Run a task synchronously or asynchronously

**async()** : Запустить задание синхронно или асинхронно

```
future<int> f = async([](int x, int y)->int{
    return x*y;
}, 3, 7);    // Calculate 3*7
...
f.wait();    // Optional
cout << "f.get() = " << f.get() << endl;    // Get the result
```

**get()** : Wait to the task to finish and return the result

**get()** : Дождаться окончания задания и вернуть результат

**wait()** : Wait for the task to finish (not really needed if we use **get()**)

**get()** can be only called once !

# Asynchronous (launch::async) vs deferred (launch::deferred)

Asynchronous launch (in a separate thread) : Параллельно !

```
future<int> f = async(launch::async, []{  
    cout << "launch::async !!!" << endl;  
});
```

Starts immediately, **f.wait()/f.get()** wait for the task to finish

Deferred launch (in the same thread, no concurrency) : Последовательно !

```
future<int> f = async(launch::deferred, []{  
    cout << "launch::deferred !!!" << endl;  
});
```

Starts, runs and finishes when **f.wait()/f.get()** is called !

Deferred launch : equivalent to :

```
future<int> f = async(launch::deferred | launch::async, []{ ... });  
async() decides itself what to do !
```

# What if a future is destroyed before wait()/get() is called ?

```
{  
    future<int> f = async(...);  
} // f is destroyed here
```

What does the destructor of **future** do ?

Asynchronous tasks : Асинхронные задания :

Wait for the task to finish (Implicit thread **join**). Дождаться окончания.

Deferred tasks : Отложенные задания :

The task is never started ! Задание никогда не запускается !

This is only for the futures created by **async()** !

Other futures : do nothing at all.

Conclusion : Use **wait()/get()** ! Используйте **wait()/get()** !

# Running tasks in parallel

```
// Print a char and sleep a bit (100 times)
auto lamChar = [](char c)->void{
    cout << this_thread::get_id() << " : starting !\n";
    for (int i = 0; i < 100; ++i) {
        cout << c;
        this_thread::sleep_for (milliseconds(1));    // Sleep a bit
    }
};

// Run 2 tasks in parallel
future<void> fA = async(launch::async, lamChar, 'A');
future<void> fB = async(launch::async, lamChar, 'B');
// The last one will never start, no get/wait !
future<void> fC = async(launch::deferred, lamChar, 'C');
```

```
6 : starting !
7 : starting !
BAABBAABABBABABABABAABABABBABABABAABBBABABABABAABABABBABABAABBBABAABABAB
ABABABBBABABAABABBABBAABABABABBABABABABAABABBABAABABABABBBAAABBABABABABAABABABABBABAB
ABAABABBABABAABABABABABABBAABABBABABABAABBABAA
```

# wait\_for() : a timed wait on a future f

```
future_status result = f.wait_for(milliseconds(100)); // f == some future
```

Returns the status *after* waiting :

**future\_status::deferred** : Deferred task, not started yet

**future\_status::ready** : The task has finished

**future\_status::timeout** : The task is running, not finished yet

**wait\_for()** does NOT start deferred tasks !

Use **wait\_for(seconds(0))** to check on a task :

```
while (f.wait_for(seconds(0)) == future_status::timeout) {  
    cout << "Still waiting ..." << endl;  
    this_thread::sleep_for(milliseconds(100));  
}
```

Of course we could have used **wait\_for(milliseconds(100))** ...



# future, async() and exceptions

```
future <int> f = async(launch::async, [](int x, int y)->int{
    if (x<0 || y<0) throw runtime_error("The user is an IDIOT !!!");
    return x*y;      // Suppose we don't like negative numbers ...
}, 7, -3);

cout << "Task started ..." << endl;
this_thread::sleep_for (milliseconds(10)); // Give it some time
cout << "Before get ..." << endl;
cout << "f.get() = " << f.get() << endl;
cout << "After get ..." << endl;
```

An exception is thrown inside an **async()** task !

What happens ?

# future, async() and exceptions

```
future <int> f = async(launch::async, [](int x, int y)->int{
    if (x<0 || y<0) throw runtime_error("The user is an IDIOT !!!");
    return x*y;      // Suppose we don't like negative numbers ...
}, 7, -3);

cout << "Task started ..." << endl;
this_thread::sleep_for (milliseconds(10)); // Give it some time
cout << "Before get ..." << endl;
cout << "f.get() = " << f.get() << endl;    // Thrown by get()!!!
cout << "After get ..." << endl;
```

An exception is thrown inside an **async()** task !

It's caught and remembered in the **future** !

**get()** rethrows the exception.

# Threads

**std::thread** is a handle to a software thread.

```
thread t([]{  
    cout << " A thread !" << endl;  
}); // Start a thread  
... // Thread runs in parallel  
t.join(); // Wait to finish
```

You must **join()** or **detach()** every software thread!

**join()** : Wait for the thread to finish

**detach()** : Detach software thread from the **std::thread** object

Otherwise the **std::thread** destructor stops the program!

**std::thread** does not return any results.

Uncaught exception in a thread terminates the program.

# Run 4 threads in parallel

```
// Print a char and sleep a bit (100 times)
auto lamChar = [](char c)->void{
    cout << this_thread::get_id() << " : starting !\n";
    for (int i = 0; i < 100; ++i) {
        cout << c;
        this_thread::sleep_for (milliseconds(1));    // Sleep a bit
    }
};

// Run 4 threads in parallel
thread tA(lamChar, 'A');    // Join tA, tB, t0, but not tC !
thread tB(lamChar, 'B');
thread tC(lamChar, 'C');
thread t0([]{cout << "IDIOT\n";});
tC.detach();    // Detach this one from the std::thread handle
cout << "Threads started ..." << endl;
this_thread::sleep_for (milliseconds(10));
cout << "About to join threads ..." << endl;
tA.join();
tB.join();
t0.join();
```

# Run 4 threads in parallel

12 : starting !

14 : starting !

A13 : starting !

CThreads started ...

BIDIOT

About to join threads ...CAB

BCACBACBABACBACABCACBABCACBBACBACACBABCACBACBCBABCABACBACBACBCAABCCBAABCCBACAB  
ACBBACABCACBACBABCABCACBACCBCBACBACBACBACBACBACBCBABACBCABACBACCABBCA  
CBACABCBAACBABCCABABCACBABCACBACBCBABACBACBACBACBACCBBABACBACBCABCACACABACBACB  
ACBACBACBBCACABABCACBABCBCABCACBACABCABCBCBACBABACABCABCACBABC

# Passing argument by reference : `std::ref()`

`thread` and `async` use an `std::bind`-like syntax to pass arguments. To pass arguments by reference, you must wrap them in `std::ref` !

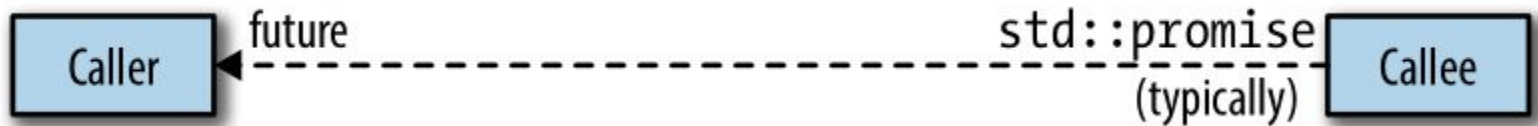
```
void doSomething(int par, int & data) {...}  
  
...  
int i, j;  
thread t(doSomething, 13, ref(i));  
future<void> f = async(doSomething, 14, ref(j));
```

Alternative: use a lambda wrapper:

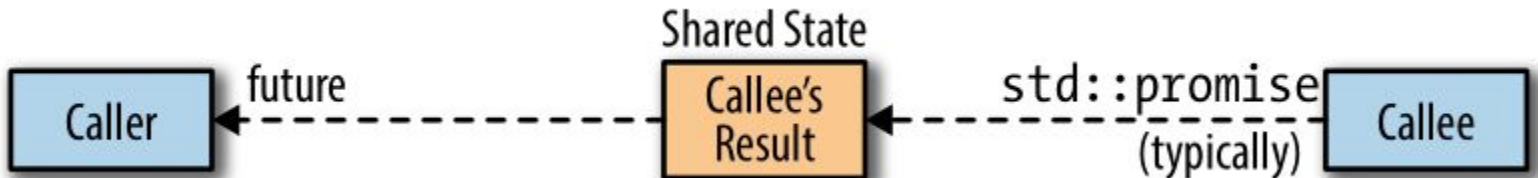
```
thread t([&i]() {  
    doSomething(13, i);  
});  
future<void> f = async([&j]() {  
    doSomething(14, j);  
}); // DANGER ! With detach() variables i, j can run out of scope !!!
```

# Promise and future

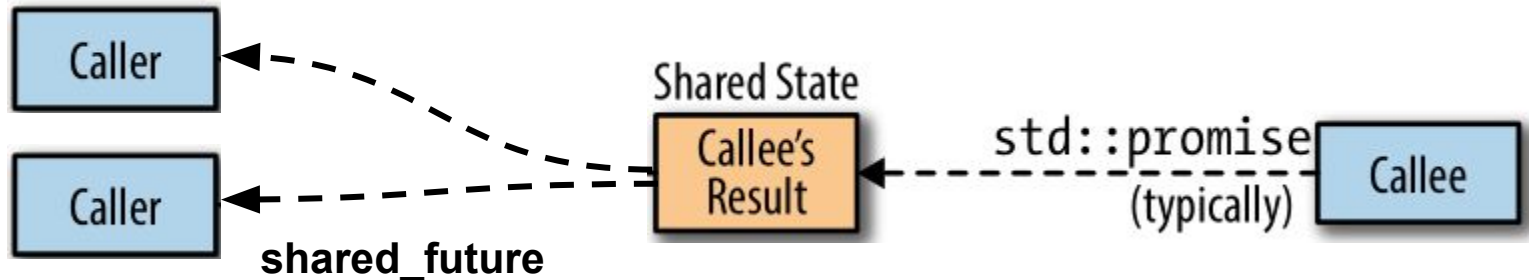
`std::promise` provides a result (or exception) to `std::future`



The result (or exception) is kept in *shared state* until you call `get()`



`shared_future` is a version which can be copied, and you can call `get()` many times



# Using promise and future with threads (without async)

1. Create a **promise** + **future** pair
2. Pass **promise** and/or **future** by reference to threads
3. Store the result/exception into **promise** in one thread : **set\_value()**, **set\_exception()**
4. And call **get()** on the **future** in the other one

```
promise<int> p; // Create a promise/future pair
future<int> f = p.get_future();

// Now we start the thread, capturing promise by ref
thread t([&p](int x, int y)->void{
    // We use set_value() on promise instead of return !!!
    p.set_value(x*y);
}, 3, 7);

// Now we run get() on the future as usual
cout << "f.get() = " << f.get() << endl;
t.join(); // Don't forget to join, before or after get()
```



# Storing exceptions into `std::promise : set_exception()`

Exceptions in C++ can be of *any type*, not only `std::exception` !

There is a standard wrapper : `std::exception_ptr`.

There are 2 options (`p` = some `promise`) :

1. Create an `exception_ptr` directly by `make_exception_ptr()` :

```
p.set_exception(make_exception_ptr(runtime_error("The user is an IDIOT !!!")));
```

2. Use `current_exception()` within a `catch` clause:

```
try {
```

```
    ...
```

```
} catch(...) {
```

```
    p.set_exception(current_exception());
```

```
}
```

# Using packaged\_task in a thread

**packaged\_task** is a template similar to **function**, which stores result and exceptions in a **future**

```
auto lam = [](int x, int y)->int{
    if (x<0 || y<0)
        throw runtime_error("The user is an IDIOT !!!");
    else
        return x*y;
};
packaged_task<int(int, int)> pt3(lam), pt4(lam); // Create 2 tasks
```

**packaged\_task** can be launched in a **thread**, get result with **get()** :

```
future<int> f3 = pt3.get_future(); // Create future from packaged_task
thread t3(move(pt3), 3, 7);        // Must move !
f3.join();                         // Join thread before or after get()
cout << "f3.get() = " << f3.get() << endl;

future<int> f4 = pt4.get_future(); // Same with pt4
thread t4(move(pt4), 3, -7);       // Wrong input !
f4.join();
cout << "f4.get() = " << f4.get() << endl; // Exception is thrown here !
```

# Data shared between threads : Data Race !

```
vector<string> data;  
thread t1([& data]() { ... });  
thread t2([& data]() { ... });
```

If both **t1** and **t2** only *read* data, everything is OK !

If *either* **t1** or **t2** *write* data : DATA RACE = **BAD** !

C++ standard: the behavior is **UNDEFINED** !

Глупые люди скажут:

...А я пробовал все работало...

...А что там может случиться...

...У меня не класс, а примитивный тип...

...А я видел пример в интернете...

...А я делал по простому...

...А я думал что...

...Это все фигня на самом деле все работает...

# Data shared between threads : Data Race !

```
vector<string> data;  
thread t1([& data]() { ... });  
thread t2([& data]() { ... });
```

If both **t1** and **t2** only *read* data, everything is OK !

If *either* **t1** or **t2** *write* data : DATA RACE = **BAD** !

C++ standard: the behavior is **UNDEFINED** !

A good programmer will say:

No fooling around !

I want my code reliable !

I'll protect my data with **atomic** or **mutex** !

# Data race demo :

```
int result = 0;
auto lam = [& result]{
    for (int i=0; i < 10000; ++i)
        ++result;
};
vector <thread> v;
for (int i=0; i < 100; ++i)
    v.emplace_back(lam);
for (auto & t : v)
    t.join();
cout << "result = " << result << endl;
```

What is the result ???

# Data race demo :

```
int result = 0;
auto lam = [& result]{
    for (int i=0; i < 10000; ++i)
        ++result;
};
vector <thread> v;
for (int i=0; i < 100; ++i)
    v.emplace_back(lam);
for (auto & t : v)
    t.join();
cout << "result = " << result << endl;
```

The result should be 1'000'000 (one million), but ...

Actually it can be anywhere between 900'000 and one million !

And this was Debug build, can be worse with optimization !

# Are standard types thread safe?

Most C++ types are NOT thread safe, including primitives !  
Atomics, mutexes *are* thread-safe.

Especially strings and containers are dangerous !

I/O streams (such as **cout**) are *partly* thread-safe:  
They don't get broken by writing, but the results can mix up.

Thread 1:

```
cout << "a = " << 17 << endl;
```

Thread 2:

```
cout << "b = " << 20 << endl;
```

Can give (for example):

```
a=b=1720
```

With 2 newlines in the end.

# atomic variables

`atomic<T>` is an atomic wrapper of type `T`.

`T` must be trivially copyable, so `int` is OK, `string` or `vector` are not!

Example:

```
atomic<int> a1(17); // Ctor
```

```
atomic<int> a2;
```

```
a2.store(18);      // Set a value
```

```
a2 = 18;          // The same
```

```
++a1;
```

```
a2 += 3;
```

```
int i = a1.load(); // Get a value
```

```
int i = a1;        // The same
```

```
a2 = a1;           // Error ! Atomics cannot be copied !
```

Atomics cannot be copied nor moved !

Using `load()` and `store()` is a good practice



# atomic<int> example :

```
atomic<int> result(0);
auto lam = [& result]{
    for (int i=0; i < 10000; ++i)
        ++result;
};
vector <thread> v;
for (int i=0; i < 100; ++i)
    v.emplace_back(lam);
for (auto & t : v)
    t.join();
cout << "result = " << result.load() << endl;
```

The result is exactly 1'000'000 (one million) !

**atomic<int>** works !

# mutex (MUTual EXclusion)

**mutex** is a simple lock:

```
vector<string> data;
```

```
mutex m;
```

In thread 1:

```
m.lock();           // Wait for m to unlock (if locked), then lock
```

```
m.push_back(s);
```

```
m.unlock();        // Unlock
```

In thread 2:

```
m.lock();           // Wait for m to unlock (if locked), then lock
```

```
for (const string & s : data)
```

```
    cout << s << endl;
```

```
m.unlock();        // Unlock
```

# Is everything OK with the code ?

```
set<string> data;  
mutex m;  
...  
m.lock();  
if (data.empty())  
    throw runtime_error("No data !!!");  
else if (data.count("QUIT"))  
    return -1;  
else  
    ... // Do something with the data  
m.unlock();
```

# Solution lock\_guard !

```
set<string> data;  
mutex m;  
...  
{  
    lock_guard<mutex> lock(m);    // Lock until '}'  
    if (data.empty())  
        throw runtime_error("No data !!!");  
    else if (data.count("QUIT"))  
        return -1;  
    else  
        ... // Do something with the data  
}    // Unlock here
```

When the lock is destroyed, the mutex is unlocked !

Resource acquisition is initialization (RAII) pattern (like **ofstream**, **unique\_ptr**).

Versions which can be moved or copied: **unique\_lock<mutex>**, **shared\_lock<mutex>**

# mutex example :

```
int result = 0;
mutex m;
auto lam = [& result, & m]{
    for (int i=0; i < 10000; ++i) {
        lock_guard<mutex> lock(m);    // Lock until '}'
        ++result;
    }                                // Unlock here
};
vector <thread> v;
for (int i=0; i < 100; ++i)
    v.emplace_back(lam);
for (auto & t : v)
    t.join();
cout << "result = " << result << endl;
```

The result is exactly 1'000'000 (one million) !

**mutex** works !

# Thread interaction 1: flag

```
atomic<bool> stop(false);  
auto lam = [&stop]{  
    int i = 0;  
    while (!stop) {  
        cout << i++;  
        this_thread::sleep_for(milliseconds(50));  
    }  
};  
  
thread t1(lam), t2(lam);  
this_thread::sleep_for(milliseconds(500));  
stop = true; // Signal stop  
t1.join();  
t2.join();
```

Prints (for example) : 001122334455667788

# Thread interaction 2: condition variables

A **condition\_variable** implements **wait()** and **notify()** logic:

1. Thread 1 calls **wait(condition)** and waits.
2. Thread 2 calls **notify\_one()** or **notify\_all()** .
3. Thread 1 wakes up if **condition** is true.

**wait()** can be used without condition, but it's a BAD practice !

*Spurious wakeup* : Thread 1 can wake without **notify()** ! C++ standard allows it !

Note : **condition\_variable** requires a **mutex**.

Dangerous: **notify()** before **wait()** means waiting forever: FREEZE !

# Condition variables: example

```
vector<string> data;
mutex m;           // mutex protects both cv and data
condition_variable cv;

thread worker([&data, &m, &cv]{
    unique_lock<mutex> lk(m);    // We must use unique_lock
    cv.wait(lk, [&data]{return !data.empty();}); // Wait for data
    for (const string &s : data)
        cout << s << " ";
    cout << endl;
}); // Here we release the mutex

this_thread::sleep_for(milliseconds(10)); // Don't notify too soon !
m.lock();
data = {"Karin", "Lucia", "Anastasia"}; // Supply the data
m.unlock();
cv.notify_one();
worker.join();
```



# Thread interaction 3: promise and future for a 1-shot event

```
promise<void> p;    // promise + future pair
future<void> f = p.get_future();

thread t([&f]{
    f.get();          // Wait for the signal
    cout << "One !\n";
    this_thread::sleep_for(milliseconds(10));
    cout << "Two !\n";
    this_thread::sleep_for(milliseconds(10));
    cout << "Three !\n";
});

for (int i = 0; i < 10; ++i) {
    cout << i << endl;
    if (4 == i)
        p.set_value();          // Send the signal
    this_thread::sleep_for(milliseconds(10));
}

t.join();
```

**Thank you for your attention !**

**title**

text