

7.26.22

Tuesday, July 26, 2022 8:57 AM

4 - Vectors for real.

3 - Vectors : $\vec{x} = (x, y, z)$
 $\vec{v} = (v_x, v_y, v_z)$ } Contain information ONLY about space

4 - Vector :

$x^\mu = (ct, \overbrace{x, y, z}^{\vec{x}})$
 4 - Position $\xrightarrow{\text{take } \frac{d}{dt}}$

$u^\mu = (c, v_x, v_y, v_z)$
 4 - Velocity $\xrightarrow{\text{multiply by } \gamma mc}$

$p^\mu = (\gamma E, \gamma p_x c, \gamma p_y c, \gamma p_z c)$. "γ" means that WE may not in the rest frame
 4 - Momentum
 Measured in the rest frame of the object

Natural Units

$$c = 1, \hbar = 1$$

$$E = mc^2 \quad \& \quad E = hf$$

$$\text{If } c=1, \text{ then } \frac{m}{s} = 1$$

so meters & seconds mean the same thingNotation :

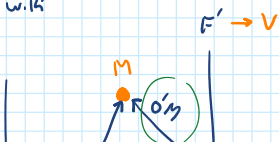
$$x^\mu = (ct, \vec{x}), \mu \text{ indexes the components}$$

$$\mu = 0, 1, 2, 3$$

$$x^0 = ct, \text{ "}\mu=0\text{" as the "time" or "energy" component}$$

$$x^3 = z$$

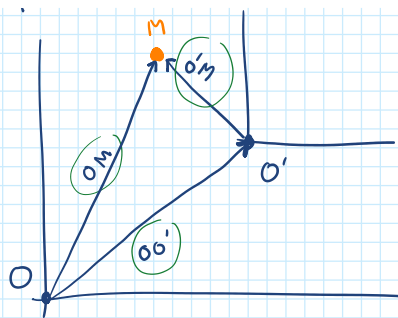
$$x^\mu = (ct, x^i)$$

Spatial index, $i = 1, 2, 3$ How do 4-Vectors TransformFrame with
F

Frame F' move at speed V relative to frame F.

$$\vec{OM} = \vec{OO'} + \vec{O'M}$$

For simplicity choose M to



$$\vec{OM} = \vec{OO'} + \vec{O'M}$$

For simplicity, choose M to be along the x -axis ($y = z = 0$)

$$x = vt + x'/\gamma$$

Solve for x' rest frame

$$x' = \gamma(x - vt)$$

Different Frame

How fast is moving

This is how spatial components transform under special relativity

"Lorentz Transformation"

What about time?

$$x' = \gamma(x - vt) \quad \text{invert all primes}$$

$$x = \gamma(x' - vt') \quad \text{solve for } t'$$

$$\downarrow \left(\frac{x}{\gamma} - x' \right) \frac{1}{v} = t'$$

$$t' = \frac{\gamma x' - x}{v}$$

$$-\left(\frac{x}{\gamma} - \gamma(x - vt) \right) \frac{1}{v} = t'$$

$$-\frac{1}{\gamma v} (x - \gamma^2(x - vt)) = t'$$

$$-\frac{1}{\gamma v} (x - \gamma^2 x + \gamma^2 vt) = t'$$

$$-\frac{1}{\gamma v} (x(1 - \gamma^2) + \gamma^2 vt) = t' \quad \gamma^2 = \frac{1}{1 - (v/c)^2}$$

$$-\frac{x(1 - \gamma^2)}{\gamma v} - \gamma t = t'$$

$$\frac{1 - \gamma^2}{1 - (v/c)^2} = \frac{1 - (v/c)^2 - 1}{1 - (v/c)^2} = \frac{- (v/c)^2}{1 - (v/c)^2} = - \frac{v^2}{c^2} \gamma^2$$

$$+ \frac{x(-v^2/c^2 \gamma^2)}{\gamma v} - \gamma t = t'$$

The result is correct but there is a sign error somewhere in the derivation.

$$t' = \gamma t - \gamma \frac{xv}{c^2}$$

This is how the time components transform.

The point

$$x^\mu = \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} \quad x'^\mu = \begin{pmatrix} \gamma(t - xv/c^2) \\ \gamma(x - vt) \\ y \\ z \end{pmatrix}$$

Formulate this as a matrix.

Want matrix M that satisfies

$$M X^{\mu} = X'^{\mu}, \quad \textcircled{1} \text{ } M \text{ must be a } 4 \times 4$$

$$\underbrace{\begin{pmatrix} \gamma/c - \gamma v_z^2/c^2 & 0 & 0 \\ -\gamma v_z^2/c^2 & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}}_{M, \text{ "Lorentz Matrix" }} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \gamma ct - \gamma x v_z^2/c^2 \\ \gamma x - \gamma v_z ct \\ y \\ z \end{pmatrix}$$

Lorentz matrices & Notation

$$(ct, x, y, z) = X^{\mu}$$

$$\begin{pmatrix} \dots \\ \dots \end{pmatrix} = M^{\mu}_{\nu}$$

\downarrow row #
 \uparrow column #
 What the entries are

$$M^{\mu}_{\nu} X^{\nu} = X'^{\mu}$$

Why would we ever do this?

$$\begin{pmatrix} - & - & - \end{pmatrix} \begin{pmatrix} \vdots \\ \vdots \\ \vdots \end{pmatrix} = \begin{pmatrix} \vdots \\ \vdots \\ \vdots \end{pmatrix}$$

Notational shorthand.

$$M^{\mu}_{\nu} X^{\nu} = X'^{\mu}$$

$$\textcircled{1} X^{\mu} = X^{\nu} = X^{\alpha} = X^{\beta} = \dots$$

We are only choosing a greek letter to index X , doesn't matter which letter.

★ $\textcircled{2}$ Rule: repeated indices are summed over

$\textcircled{3}$ Free indices must match.

$$\text{ex: } M^i_j = \begin{pmatrix} M^1_1 & M^1_2 & M^1_3 \\ M^2_1 & M^2_2 & M^2_3 \\ M^3_1 & M^3_2 & M^3_3 \end{pmatrix} \quad X^i = \begin{pmatrix} x^1 \\ x^2 \\ x^3 \end{pmatrix}$$

Compute $M^i_j X^j$ using rule $\textcircled{2}$.

$$X'^i = M^i_j X^j$$

★ pick $i = 2$

$$X'^2 = M^2_j X^j$$

$$= M^2_1 X^1 + M^2_2 X^2 + M^2_3 X^3 \rightarrow \begin{pmatrix} \bullet \\ \bullet \\ \bullet \end{pmatrix}$$

ex:

$$A^i_j = \begin{pmatrix} A^1_1 & A^1_2 \\ A^2_1 & A^2_2 \end{pmatrix} \quad B^i_j = \begin{pmatrix} B^1_1 & B^1_2 \\ B^2_1 & B^2_2 \end{pmatrix}$$

$$\text{Compute } A^i_j B^j_k = C^i_k$$