



# Forecasting: principles and practice

Rob J Hyndman

2 ARIMA models

#### **Outline**

- 1 Stationarity and differencing
- 2 Backshift notation
- 3 Autoregressive models
- 4 Moving Average models
- 5 Non-seasonal ARIMA models
- **6** Estimation and order selection
- 7 ARIMA modelling in R
- 8 Lab session 16

#### **Stationarity**

#### Definition

If  $\{y_t\}$  is a stationary time series, then for all s, the distribution of  $(y_t, \ldots, y_{t+s})$  does not depend on t.

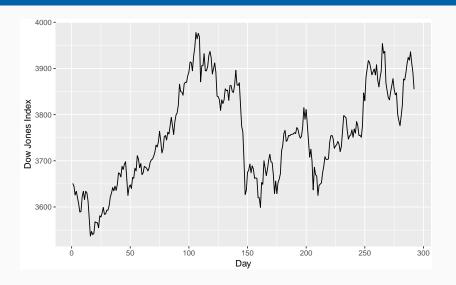
## **Stationarity**

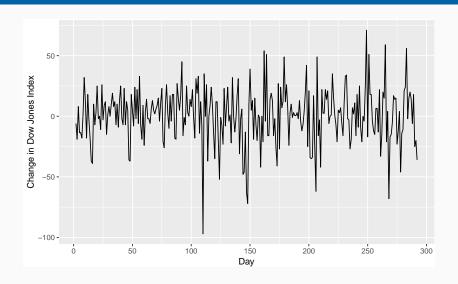
#### **Definition**

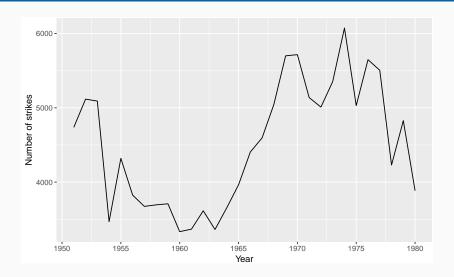
If  $\{y_t\}$  is a stationary time series, then for all s, the distribution of  $(y_t, \ldots, y_{t+s})$  does not depend on t.

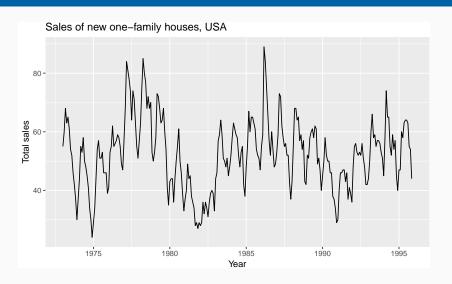
#### A stationary series is:

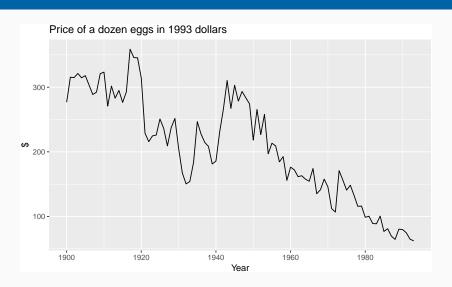
- roughly horizontal
- constant variance
- no patterns predictable in the long-term

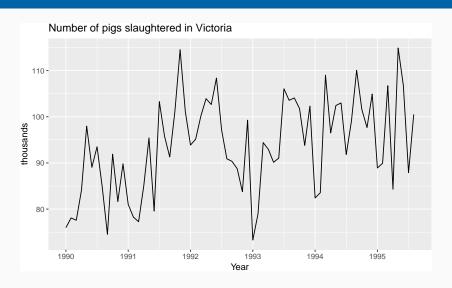


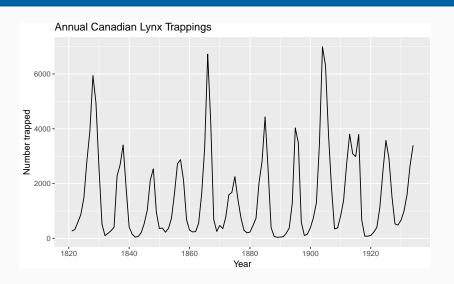


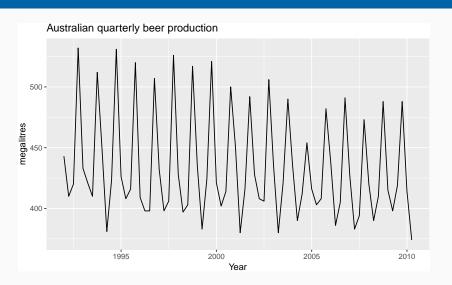












#### **Stationarity**

#### **Definition**

If  $\{y_t\}$  is a stationary time series, then for all s, the distribution of  $(y_t, \ldots, y_{t+s})$  does not depend on t.

### **Stationarity**

#### **Definition**

If  $\{y_t\}$  is a stationary time series, then for all s, the distribution of  $(y_t, \ldots, y_{t+s})$  does not depend on t.

Transformations (e.g., logs) help to **stabilize the** variance.

For ARIMA modelling, we also need to **stabilize the mean**.

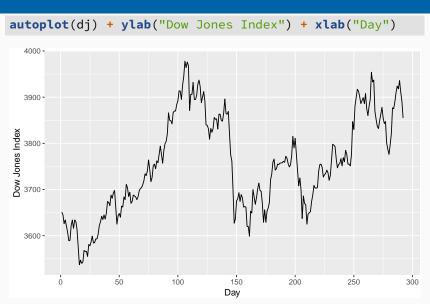
#### Differencing

- Differencing helps to stabilize the mean.
- The differenced series is the *change* between each observation in the original series:

$$\mathsf{y}_t' = \mathsf{y}_t - \mathsf{y}_{t-1}.$$

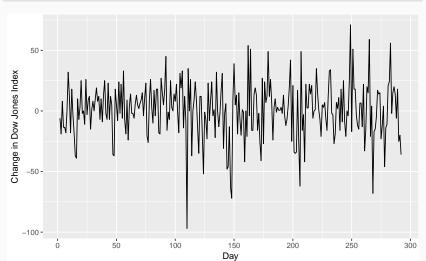
■ The differenced series will have only T-1 values since it is not possible to calculate a difference  $y'_1$  for the first observation.

## **Example: Dow-Jones index**



### **Example: Dow-Jones index**

```
autoplot(diff(dj)) +
  ylab("Change in Dow Jones Index") + xlab("Day")
```



#### **Second-order differencing**

Occasionally the differenced data will not appear stationary and it may be necessary to difference the data a second time:

#### Second-order differencing

Occasionally the differenced data will not appear stationary and it may be necessary to difference the data a second time:

$$y_t'' = y_t' - y_{t-1}'$$

$$= (y_t - y_{t-1}) - (y_{t-1} - y_{t-2})$$

$$= y_t - 2y_{t-1} + y_{t-2}.$$

#### Second-order differencing

Occasionally the differenced data will not appear stationary and it may be necessary to difference the data a second time:

$$y_t'' = y_t' - y_{t-1}'$$

$$= (y_t - y_{t-1}) - (y_{t-1} - y_{t-2})$$

$$= y_t - 2y_{t-1} + y_{t-2}.$$

- $y_t''$  will have T-2 values.
- In practice, it is almost never necessary to go beyond second-order differences.

A seasonal difference is the difference between an observation and the corresponding observation from the previous year.

A seasonal difference is the difference between an observation and the corresponding observation from the previous year.

$$y_t' = y_t - y_{t-m}$$

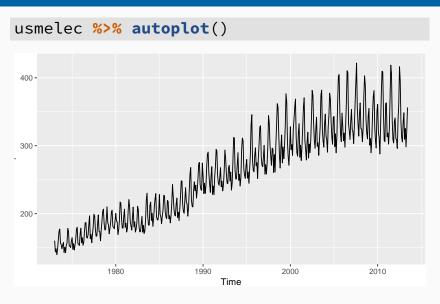
where m = number of seasons.

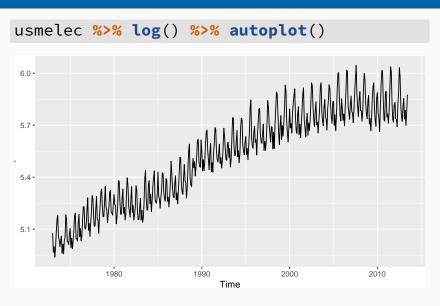
A seasonal difference is the difference between an observation and the corresponding observation from the previous year.

$$y_t' = y_t - y_{t-m}$$

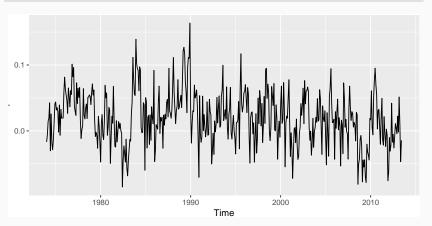
where m = number of seasons.

- For monthly data m = 12.
- For quarterly data m = 4.



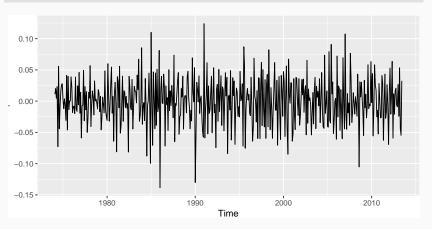


```
usmelec %>% log() %>% diff(lag=12) %>%
autoplot()
```



```
usmelec %>% log() %>% diff(lag=12) %>%

diff(lag=1) %>% autoplot()
```



- Seasonally differenced series is closer to being stationary.
- Remaining non-stationarity can be removed with further first difference.

If  $y'_t = y_t - y_{t-12}$  denotes seasonally differenced series, then twice-differenced series is

$$y_t^* = y_t' - y_{t-1}'$$

$$= (y_t - y_{t-12}) - (y_{t-1} - y_{t-13})$$

$$= y_t - y_{t-1} - y_{t-12} + y_{t-13}.$$

When both seasonal and first differences are applied...

When both seasonal and first differences are applied...

- it makes no difference which is done first—the result will be the same.
- If seasonality is strong, we recommend that seasonal differencing be done first because sometimes the resulting series will be stationary and there will be no need for further first difference.

When both seasonal and first differences are applied...

- it makes no difference which is done first—the result will be the same.
- If seasonality is strong, we recommend that seasonal differencing be done first because sometimes the resulting series will be stationary and there will be no need for further first difference.

It is important that if differencing is used, the differences are interpretable.

### Interpretation of differencing

- first differences are the change between one observation and the next:
- seasonal differences are the change between one year to the next.

## Interpretation of differencing

- first differences are the change between one observation and the next:
- seasonal differences are the change between one year to the next.

But taking lag 3 differences for yearly data, for example, results in a model which cannot be sensibly interpreted.

#### **Outline**

- 1 Stationarity and differencing
- 2 Backshift notation
- 3 Autoregressive models
- 4 Moving Average models
- 5 Non-seasonal ARIMA models
- **6** Estimation and order selection
- 7 ARIMA modelling in R
- 8 Lab session 16

#### **Backshift notation**

A very useful notational device is the backward shift operator, *B*, which is used as follows:

$$By_t = y_{t-1} .$$

#### **Backshift notation**

A very useful notational device is the backward shift operator, *B*, which is used as follows:

$$By_t = y_{t-1} .$$

In other words, B, operating on  $y_t$ , has the effect of shifting the data back one period.

A very useful notational device is the backward shift operator, *B*, which is used as follows:

$$By_t = y_{t-1} .$$

In other words, B, operating on  $y_t$ , has the effect of shifting the data back one period. Two applications of B to  $y_t$  shifts the data back two periods:

$$B(By_t) = B^2y_t = y_{t-2}.$$

A very useful notational device is the backward shift operator, *B*, which is used as follows:

$$By_t = y_{t-1} .$$

In other words, B, operating on  $y_t$ , has the effect of shifting the data back one period. Two applications of B to  $y_t$  shifts the data back two periods:

$$B(By_t) = B^2y_t = y_{t-2}$$
.

For monthly data, if we wish to shift attention to "the same month last year," then  $B^{12}$  is used, and the notation is  $B^{12}y_t = y_{t-12}$ .

The backward shift operator is convenient for describing the process of differencing.

The backward shift operator is convenient for describing the process of *differencing*. A first difference can be written as

$$y'_t = y_t - y_{t-1} = y_t - By_t = (1 - B)y_t$$
.

The backward shift operator is convenient for describing the process of *differencing*. A first difference can be written as

$$y'_t = y_t - y_{t-1} = y_t - By_t = (1 - B)y_t$$
.

Note that a first difference is represented by (1 - B).

The backward shift operator is convenient for describing the process of *differencing*. A first difference can be written as

$$y'_t = y_t - y_{t-1} = y_t - By_t = (1 - B)y_t$$
.

Note that a first difference is represented by (1 - B).

Similarly, if second-order differences (i.e., first differences of first differences) have to be computed, then:

$$y_t'' = y_t - 2y_{t-1} + y_{t-2} = (1 - B)^2 y_t$$
.

- Second-order difference is denoted  $(1 B)^2$ .
- Second-order difference is not the same as a second difference, which would be denoted  $1 B^2$ ;
- In general, a *d*th-order difference can be written as

$$(1-B)^d y_t$$
.

 A seasonal difference followed by a first difference can be written as

$$(1-B)(1-B^m)y_t$$
.

The "backshift" notation is convenient because the terms can be multiplied together to see the combined effect.

$$(1 - B)(1 - B^{m})y_{t} = (1 - B - B^{m} + B^{m+1})y_{t}$$
$$= y_{t} - y_{t-1} - y_{t-m} + y_{t-m-1}.$$

The "backshift" notation is convenient because the terms can be multiplied together to see the combined effect.

$$(1 - B)(1 - B^{m})y_{t} = (1 - B - B^{m} + B^{m+1})y_{t}$$
$$= y_{t} - y_{t-1} - y_{t-m} + y_{t-m-1}.$$

For monthly data, m = 12 and we obtain the same result as earlier.

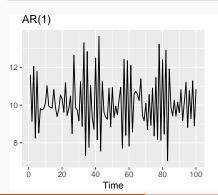
# **Outline**

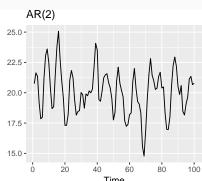
- 1 Stationarity and differencing
- **2** Backshift notation
- 3 Autoregressive models
- 4 Moving Average models
- 5 Non-seasonal ARIMA models
- **6** Estimation and order selection
- 7 ARIMA modelling in R
- 8 Lab session 16

# **Autoregressive models**

### **Autoregressive (AR) models:**

 $y_t = c + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \cdots + \phi_p y_{t-p} + \varepsilon_t$ , where  $\varepsilon_t$  is white noise. This is a multiple regression with **lagged values** of  $y_t$  as predictors.





# **Stationarity conditions**

We normally restrict autoregressive models to stationary data, and then some constraints on the values of the parameters are required.

#### **General condition for stationarity**

Complex roots of  $1 - \phi_1 z - \phi_2 z^2 - \cdots - \phi_p z^p$  lie outside the unit circle on the complex plane.

# **Stationarity conditions**

We normally restrict autoregressive models to stationary data, and then some constraints on the values of the parameters are required.

## **General condition for stationarity**

Complex roots of  $1 - \phi_1 z - \phi_2 z^2 - \cdots - \phi_p z^p$  lie outside the unit circle on the complex plane.

- For p = 1:  $-1 < \phi_1 < 1$ .
- For p = 2:

$$-1 < \phi_2 < 1$$
  $\phi_2 + \phi_1 < 1$   $\phi_2 - \phi_1 < 1$ .

■ More complicated conditions hold for  $p \ge 3$ .

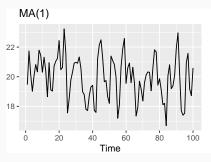
# **Outline**

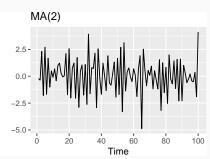
- 1 Stationarity and differencing
- 2 Backshift notation
- 3 Autoregressive models
- 4 Moving Average models
- 5 Non-seasonal ARIMA models
- **6** Estimation and order selection
- 7 ARIMA modelling in R
- 8 Lab session 16

# Moving Average (MA) models

# **Moving Average (MA) models:**

 $y_t = c + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \theta_2 \varepsilon_{t-2} + \cdots + \theta_q \varepsilon_{t-q}$ , where  $\varepsilon_t$  is white noise. This is a multiple regression with **past errors** as predictors. Don't confuse this with moving average smoothing!





# **Invertibility**

 Invertible models have property that distant past has negligible effect on forecasts. Requires consraints on MA parameters.

### **General condition for invertibility**

Complex roots of  $1 + \theta_1 z + \theta_2 z^2 + \cdots + \theta_q z^q$  lie outside the unit circle on the complex plane.

# Invertibility

 Invertible models have property that distant past has negligible effect on forecasts. Requires consraints on MA parameters.

### **General condition for invertibility**

Complex roots of  $1 + \theta_1 z + \theta_2 z^2 + \cdots + \theta_q z^q$  lie outside the unit circle on the complex plane.

- For  $q = 1: -1 < \theta_1 < 1$ .
- For q = 2:

$$-1 < \theta_2 < 1$$
  $\theta_2 + \theta_1 > -1$   $\theta_1 - \theta_2 < 1$ .

■ More complicated conditions hold for  $q \ge 3$ .

# **Outline**

- 1 Stationarity and differencing
- 2 Backshift notation
- 3 Autoregressive models
- 4 Moving Average models
- 5 Non-seasonal ARIMA models
- **6** Estimation and order selection
- 7 ARIMA modelling in R
- 8 Lab session 16

### **Autoregressive Moving Average models:**

$$y_t = c + \phi_1 y_{t-1} + \dots + \phi_p y_{t-p} + \theta_1 e_{t-1} + \dots + \theta_q e_{t-q} + e_t.$$

#### **Autoregressive Moving Average models:**

$$y_t = c + \phi_1 y_{t-1} + \dots + \phi_p y_{t-p} + \theta_1 e_{t-1} + \dots + \theta_q e_{t-q} + e_t.$$

- Predictors include both lagged values of y<sub>t</sub> and lagged errors.
- Conditions on coefficients ensure stationarity.
- Conditions on coefficients ensure invertibility.

#### **Autoregressive Moving Average models:**

$$y_t = c + \phi_1 y_{t-1} + \dots + \phi_p y_{t-p} + \theta_1 e_{t-1} + \dots + \theta_q e_{t-q} + e_t.$$

- Predictors include both lagged values of y<sub>t</sub> and lagged errors.
- Conditions on coefficients ensure stationarity.
- Conditions on coefficients ensure invertibility.

# **Autoregressive Integrated Moving Average models**

- Combine ARMA model with differencing.
- $(1-B)^d y_t$  follows an ARMA model.

#### **Autoregressive Integrated Moving Average models**

#### ARIMA(p, d, q) model

- AR: p = order of the autoregressive part
  - I: d =degree of first differencing involved
- MA: q =order of the moving average part.
  - White noise model: ARIMA(0,0,0)
  - Random walk: ARIMA(0,1,0) with no constant
  - Random walk with drift: ARIMA(0,1,0) with const.
  - $\blacksquare$  AR(p): ARIMA(p,0,0)
  - $\blacksquare$  MA(q): ARIMA(0,0,q)

### **Backshift notation for ARIMA**

ARMA model:

$$\begin{aligned} \mathbf{y}_t &= \mathbf{c} + \phi_1 \mathbf{B} \mathbf{y}_t + \dots + \phi_p \mathbf{B}^p \mathbf{y}_t + \varepsilon_t + \theta_1 \mathbf{B} \varepsilon_t + \dots + \theta_q \mathbf{B}^q \varepsilon_t \\ \text{or} \quad & (\mathbf{1} - \phi_1 \mathbf{B} - \dots - \phi_p \mathbf{B}^p) \mathbf{y}_t = \mathbf{c} + (\mathbf{1} + \theta_1 \mathbf{B} + \dots + \theta_q \mathbf{B}^q) \varepsilon_t \end{aligned}$$

ARIMA(1,1,1) model:

$$(1 - \phi_1 B)$$
  $(1 - B)y_t = c + (1 + \theta_1 B)\varepsilon_t$ 
 $\uparrow$   $\uparrow$   $\uparrow$ 
AR(1) First MA(1)
difference

# **Backshift notation for ARIMA**

ARMA model:

$$\begin{aligned} \mathbf{y}_t &= \mathbf{c} + \phi_1 \mathbf{B} \mathbf{y}_t + \dots + \phi_p \mathbf{B}^p \mathbf{y}_t + \varepsilon_t + \theta_1 \mathbf{B} \varepsilon_t + \dots + \theta_q \mathbf{B}^q \varepsilon_t \\ \text{or} \quad & (\mathbf{1} - \phi_1 \mathbf{B} - \dots - \phi_p \mathbf{B}^p) \mathbf{y}_t = \mathbf{c} + (\mathbf{1} + \theta_1 \mathbf{B} + \dots + \theta_q \mathbf{B}^q) \varepsilon_t \end{aligned}$$

ARIMA(1,1,1) model:

Written out:

$$y_t = c + y_{t-1} + \phi_1 y_{t-1} - \phi_1 y_{t-2} + \theta_1 \varepsilon_{t-1} + \varepsilon_t$$

39

## R model

#### **Intercept form**

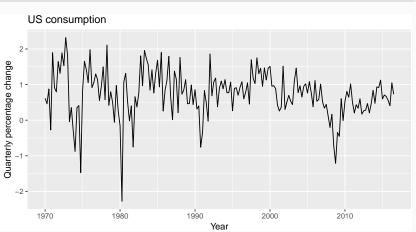
$$(1 - \phi_1 B - \dots - \phi_p B^p) y_t' = c + (1 + \theta_1 B + \dots + \theta_q B^q) \varepsilon_t$$

#### Mean form

$$(1 - \phi_1 B - \dots - \phi_p B^p)(y_t' - \mu) = (1 + \theta_1 B + \dots + \theta_q B^q)\varepsilon_t$$

- $y_t' = (1 B)^d y_t$
- $\blacksquare$   $\mu$  is the mean of  $\mathbf{y}_t'$ .
- $c = \mu(1 \phi_1 \cdots \phi_p).$
- R uses mean form.

```
autoplot(uschange[,"Consumption"]) +
  xlab("Year") + ylab("Quarterly percentage change") +
  ggtitle("US consumption")
```



## Series: uschange[, "Consumption"] ## ARIMA(2,0,2) with non-zero mean ## ## Coefficients: ## ar1 ar2 ma1 ma2 mean ## 1.391 -0.581 -1.180 0.558 0.746 ## s.e. 0.255 0.208 0.238 0.140 0.084 ## ## sigma^2 estimated as 0.351: log likelihood=-165.1 ## AIC=342.3 AICc=342.8 BIC=361.7

(fit <- auto.arima(uschange[,"Consumption"]))</pre>

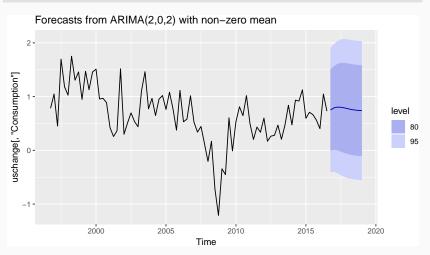
```
## Series: uschange[, "Consumption"]
## ARIMA(2,0,2) with non-zero mean
##
## Coefficients:
##
         ar1 ar2 ma1 ma2
                                    mean
## 1.391 -0.581 -1.180 0.558 0.746
## s.e. 0.255 0.208 0.238 0.140 0.084
##
## sigma^2 estimated as 0.351: log likelihood=-165.1
## AIC=342.3 AICc=342.8 BIC=361.7
```

(fit <- auto.arima(uschange[,"Consumption"]))</pre>

#### ARIMA(2,0,2) model:

```
y_t = c + 1.391y_{t-1} - 0.581y_{t-2} - 1.180\varepsilon_{t-1} + 0.558\varepsilon_{t-2} + \varepsilon_t,
where c = 0.746 \times (1 - 1.391 + 0.581) = 0.142 and \varepsilon_t \sim N(0, 0.351).
```





# **Understanding ARIMA models**

# **Long-term forecasts**

```
zero c = 0, d = 0

non-zero constant c = 0, d = 1 c \neq 0, d = 0

linear c = 0, d = 2 c \neq 0, d = 1

quadratic c = 0, d = 3 c \neq 0, d = 2
```

#### Forecast variance and d

- The higher the value of *d*, the more rapidly the prediction intervals increase in size.
- For d = 0, the long-term forecast standard deviation will go to the standard deviation of the historical data.

# **Outline**

- 1 Stationarity and differencing
- 2 Backshift notation
- 3 Autoregressive models
- 4 Moving Average models
- 5 Non-seasonal ARIMA models
- **6** Estimation and order selection
- 7 ARIMA modelling in R
- 8 Lab session 16

# **Maximum likelihood estimation**

Having identified the model order, we need to estimate the parameters  $c, \phi_1, \ldots, \phi_p, \theta_1, \ldots, \theta_q$ .

# Maximum likelihood estimation

Having identified the model order, we need to estimate the parameters  $c, \phi_1, \ldots, \phi_p, \theta_1, \ldots, \theta_q$ .

 MLE is very similar to least squares estimation obtained by minimizing

$$\sum_{t=1}^{T} e_t^2$$

- The Arima() command allows CLS or MLE estimation.
- Non-linear optimization must be used in either case.
- Different software will give different estimates.

## Information criteria

## **Akaike's Information Criterion (AIC):**

$$AIC = -2 \log(L) + 2(p + q + k + 1),$$

where L is the likelihood of the data,

$$k = 1 \text{ if } c \neq 0 \text{ and } k = 0 \text{ if } c = 0.$$

## Information criteria

#### **Akaike's Information Criterion (AIC):**

$$AIC = -2 \log(L) + 2(p + q + k + 1),$$

where L is the likelihood of the data,

$$k = 1 \text{ if } c \neq 0 \text{ and } k = 0 \text{ if } c = 0.$$

#### **Corrected AIC:**

AICc = AIC + 
$$\frac{2(p+q+k+1)(p+q+k+2)}{T-p-q-k-2}$$

### Information criteria

#### **Akaike's Information Criterion (AIC):**

$$AIC = -2\log(L) + 2(p + q + k + 1),$$

where L is the likelihood of the data,

$$k = 1 \text{ if } c \neq 0 \text{ and } k = 0 \text{ if } c = 0.$$

#### **Corrected AIC:**

AICc = AIC + 
$$\frac{2(p+q+k+1)(p+q+k+2)}{T-p-q-k-2}$$

### **Bayesian Information Criterion:**

$$BIC = AIC + \log(T)(p + q + k - 1).$$

## **Information** criteria

### **Akaike's Information Criterion (AIC):**

$$AIC = -2\log(L) + 2(p + q + k + 1),$$

where *L* is the likelihood of the data, k = 1 if  $c \ne 0$  and k = 0 if c = 0.

### **Corrected AIC:**

AICc = AIC + 
$$\frac{2(p+q+k+1)(p+q+k+2)}{T-p-q-k-2}$$

### **Bayesian Information Criterion:**

$$BIC = AIC + \log(T)(p + q + k - 1).$$

Good models are obtained by minimizing either the AIC, AICc or BIC. My preference is to use the AICc.

## **Outline**

- 1 Stationarity and differencing
- **2** Backshift notation
- 3 Autoregressive models
- 4 Moving Average models
- 5 Non-seasonal ARIMA models
- **6** Estimation and order selection
- 7 ARIMA modelling in R
- 8 Lab session 16

## How does auto.arima() work?

### A non-seasonal ARIMA process

$$\phi(B)(1-B)^d y_t = c + \theta(B)\varepsilon_t$$

Need to select appropriate orders: p, q, d

## Hyndman and Khandakar (JSS, 2008) algorithm:

- Select no. differences d and D via KPSS test and seasonal strength measure.
- Select p, q by minimising AICc.
- Use stepwise search to traverse model space.

## How does auto.arima() work?

**Step 1:** Select values of *d* and *D*.

**Step 2:** Select current model (with smallest AICc) from:

ARIMA(2, d, 2)

ARIMA(0, d, 0)

ARIMA(1, d, 0)

ARIMA(0, d, 1)

# How does auto.arima() work?

**Step 1:** Select values of *d* and *D*.

**Step 2:** Select current model (with smallest AICc) from:

ARIMA(2, d, 2)

ARIMA(0, d, 0)

ARIMA(1, d, 0)

ARIMA(0, d, 1)

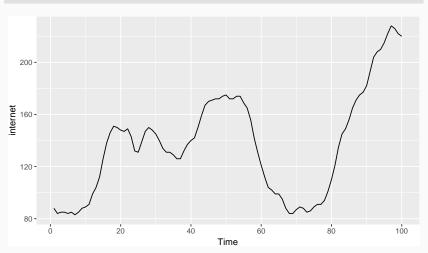
**Step 3:** Consider variations of current model:

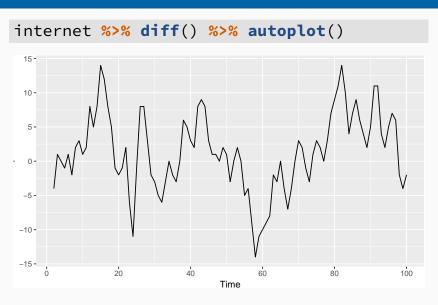
- vary one of p, q, from current model by  $\pm 1$ ;
- p, q both vary from current model by  $\pm 1$ ;
- Include/exclude *c* from current model.

Model with lowest AICc becomes current model.

Repeat Step 3 until no lower AICc can be found.

### autoplot(internet)





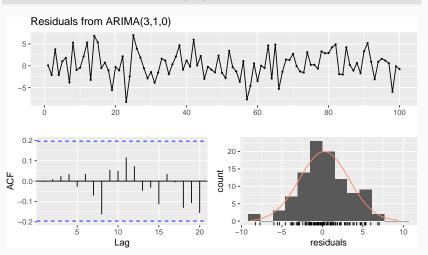
```
(fit <- auto.arima(internet))</pre>
## Series: internet
## ARIMA(1,1,1)
##
## Coefficients:
##
          arl mal
       0.650 0.526
##
## s.e. 0.084 0.090
##
## sigma^2 estimated as 10:
                            log likelihood=-254.2
## ATC=514.3 ATCc=514.5
                           BTC=522.1
```

```
(fit <- auto.arima(internet, stepwise=FALSE,
    approximation=FALSE))</pre>
```

```
## Series: internet
## ARIMA(3,1,0)
##
## Coefficients:
##
          ar1 ar2 ar3
## 1.151 -0.661 0.341
## s.e. 0.095 0.135
                      0.094
##
## sigma^2 estimated as 9.66: log likelihood=-252
## ATC=512 ATCc=512.4 BTC=522.4
```

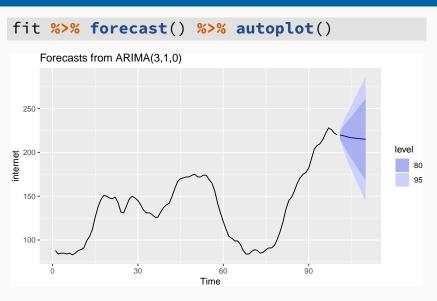
##

### checkresiduals(fit, plot=TRUE)



### checkresiduals(fit, plot=FALSE)

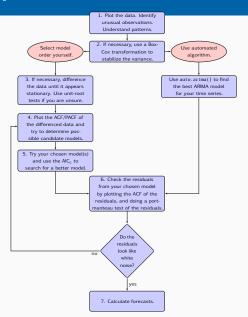
```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(3,1,0)
## Q* = 4.5, df = 7, p-value = 0.7
##
## Model df: 3. Total lags used: 10
```



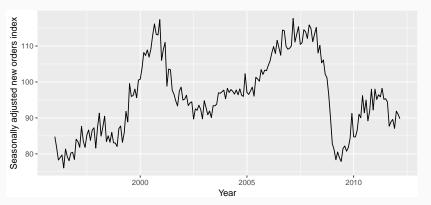
## Modelling procedure with auto.arima

- Plot the data. Identify any unusual observations.
- If necessary, transform the data (using a Box-Cox transformation) to stabilize the variance.
- Use auto.arima to select a model.
- Check the residuals from your chosen model by plotting the ACF of the residuals, and doing a portmanteau test of the residuals. If they do not look like white noise, try a modified model.
- Once the residuals look like white noise, calculate forecasts.

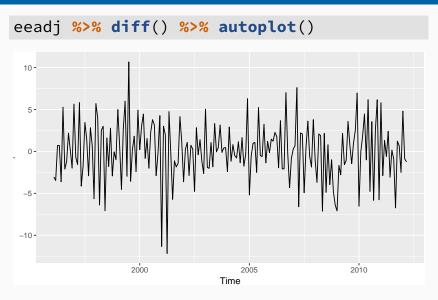
## **Modelling procedure**



```
eeadj <- seasadj(stl(elecequip, s.window="periodic"
autoplot(eeadj) + xlab("Year") +
  ylab("Seasonally adjusted new orders index")</pre>
```



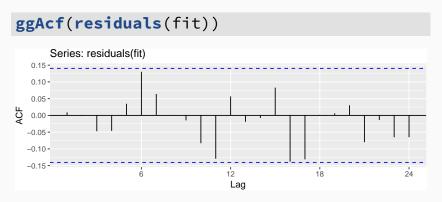
- Time plot shows sudden changes, particularly big drop in 2008/2009 due to global economic environment. Otherwise nothing unusual and no need for data adjustments.
- No evidence of changing variance, so no Box-Cox transformation.
- Data are clearly non-stationary, so we take first differences.



fit <- auto.arima(eeadj, stepwise=FALSE, approximation=FALSE)
summary(fit)</pre>

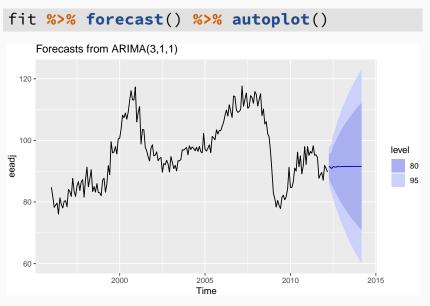
```
## Series: eeadj
## ARIMA(3,1,1)
##
## Coefficients:
        ar1 ar2 ar3 ma1
##
   0.004 0.092 0.370 -0.392
##
## s.e. 0.220 0.098 0.067 0.243
##
## sigma^2 estimated as 9.58: log likelihood=-492.7
  AIC=995.4 AICc=995.7 BIC=1012
##
##
  Training set error measures:
##
                   MF
                       RMSE MAE MPE MAPE MASE
## Training set 0.03288 3.055 2.357 -0.00647 2.482 0.2884
                  ACF1
##
```

ACF plot of residuals from ARIMA(3,1,1) model look like white noise.



#### checkresiduals(fit, plot=FALSE)

```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(3,1,1)
## Q* = 24, df = 20, p-value = 0.2
##
## Model df: 4. Total lags used: 24
```



### **Outline**

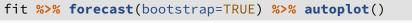
- 1 Stationarity and differencing
- 2 Backshift notation
- 3 Autoregressive models
- 4 Moving Average models
- 5 Non-seasonal ARIMA models
- **6** Estimation and order selection
- 7 ARIMA modelling in R
- 8 Lab session 16

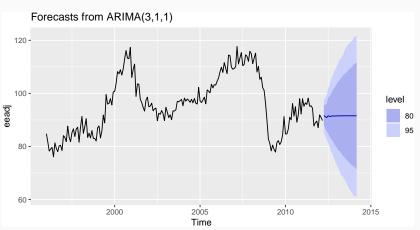
# **Lab Session 16**

### **Prediction intervals**

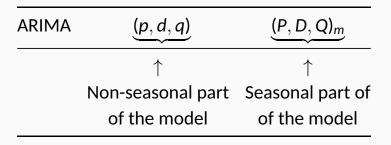
- Prediction intervals increase in size with forecast horizon.
- Calculations assume residuals are uncorrelated and normally distributed.
- Prediction intervals tend to be too narrow.
  - the uncertainty in the parameter estimates has not been accounted for.
  - the ARIMA model assumes historical patterns will not change during the forecast period.
  - the ARIMA model assumes uncorrelated future errors

## **Bootstrapped prediction intervals**





No assumption of normally distributed residuals. #
 Seasonal ARIMA models

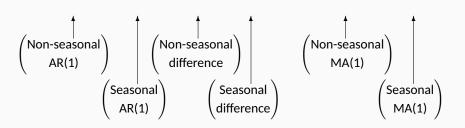


where m = number of observations per year.

E.g., ARIMA $(1, 1, 1)(1, 1, 1)_4$  model (without constant)

E.g., ARIMA(1, 1, 1)(1, 1, 1)<sub>4</sub> model (without constant) 
$$(1-\phi_1B)(1-\Phi_1B^4)(1-B)(1-B^4)y_t = (1+\theta_1B)(1+\Theta_1B^4)\varepsilon_t$$
.

E.g., ARIMA(1, 1, 1)(1, 1, 1)<sub>4</sub> model (without constant) 
$$(1-\phi_1B)(1-\Phi_1B^4)(1-B)(1-B^4)y_t = (1+\theta_1B)(1+\Theta_1B^4)\varepsilon_t$$
.



E.g., ARIMA(1, 1, 1)(1, 1, 1)<sub>4</sub> model (without constant) 
$$(1-\phi_1B)(1-\Phi_1B^4)(1-B)(1-B^4)y_t = (1+\theta_1B)(1+\Theta_1B^4)\varepsilon_t$$
.

All the factors can be multiplied out and the general model written as follows:

$$\begin{aligned} y_t &= (1+\phi_1)y_{t-1} - \phi_1 y_{t-2} + (1+\Phi_1)y_{t-4} \\ &- (1+\phi_1+\Phi_1+\phi_1\Phi_1)y_{t-5} + (\phi_1+\phi_1\Phi_1)y_{t-6} \\ &- \Phi_1 y_{t-8} + (\Phi_1+\phi_1\Phi_1)y_{t-9} - \phi_1\Phi_1 y_{t-10} \\ &+ \varepsilon_t + \theta_1 \varepsilon_{t-1} + \Theta_1 \varepsilon_{t-4} + \theta_1 \Theta_1 \varepsilon_{t-5}. \end{aligned}$$

## **Understanding ARIMA models**

### **Long-term forecasts**

```
zero c = 0, d + D = 0

non-zero constant c = 0, d + D = 1 c \neq 0, d + D = 0

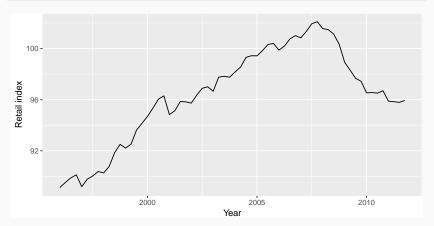
linear c = 0, d + D = 2 c \neq 0, d + D = 1

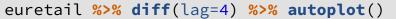
quadratic c = 0, d + D = 3 c \neq 0, d + D = 2
```

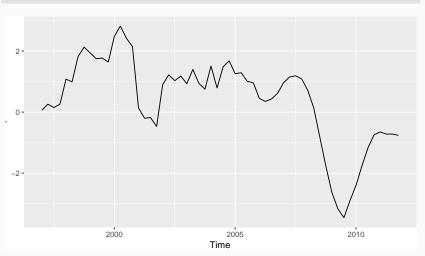
### Forecast variance and d + D

- The higher the value of d + D, the more rapidly the prediction intervals increase in size.
- For d + D = 0, the long-term forecast standard deviation will go to the standard deviation of the historical data.

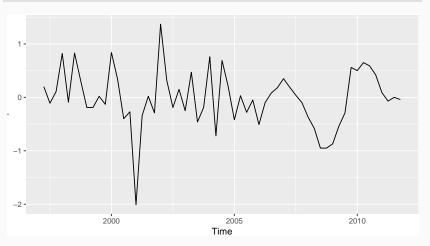
```
autoplot(euretail) +
  xlab("Year") + ylab("Retail index")
```







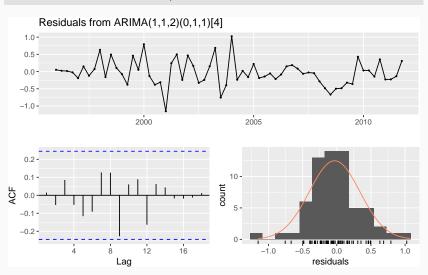
```
euretail %>% diff(lag=4) %>% diff() %>%
autoplot()
```



```
(fit <- auto.arima(euretail))</pre>
## Series: euretail
## ARIMA(1,1,2)(0,1,1)[4]
##
## Coefficients:
##
          arl mal ma2 sma1
##
       0.736 - 0.466 \ 0.216 - 0.843
## s.e. 0.224 0.199 0.210
                              0.188
##
## sigma^2 estimated as 0.159: log likelihood=-29.62
## ATC=69.24 ATCc=70.38 BTC=79.63
```

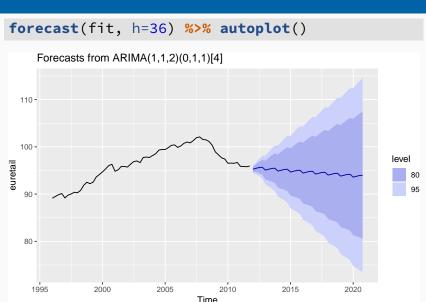
```
(fit <- auto.arima(euretail, stepwise=TRUE,
 approximation=FALSE))
## Series: euretail
## ARIMA(1,1,2)(0,1,1)[4]
##
## Coefficients:
##
          ar1
                 ma1
                         ma2
                              sma1
##
        0.736 - 0.466 \ 0.216 - 0.843
## s.e. 0.224 0.199 0.210
                               0.188
##
## sigma^2 estimated as 0.159: log likelihood=-29.62
## ATC=69.24 ATCc=70.38
                           BTC=79.63
```

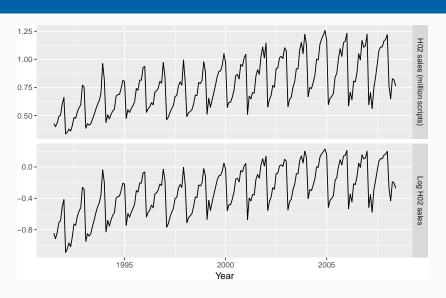
### checkresiduals(fit, test=FALSE)



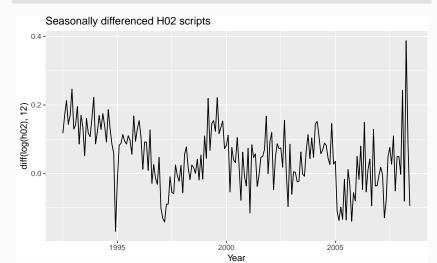
```
checkresiduals(fit, plot=FALSE)
```

```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(1,1,2)(0,1,1)[4]
## Q* = 4.9, df = 4, p-value = 0.3
##
## Model df: 4. Total lags used: 8
```





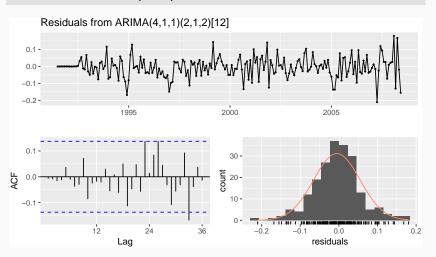
```
autoplot(diff(log(h02),12), xlab="Year",
    main="Seasonally differenced H02 scripts")
```



```
(fit <- auto.arima(h02, lambda=0, max.order=9,
    stepwise=FALSE, approximation=FALSE))</pre>
```

```
## Series: h02
## ARIMA(4,1,1)(2,1,2)[12]
## Box Cox transformation: lambda= 0
##
## Coefficients:
                 ar2 ar3 ar4
##
           ar1
                                      ma1
                                            sar1
##
        -0.042 0.210 0.202 -0.227 -0.742 0.621
## s.e. 0.217 0.181 0.114 0.081 0.207 0.242
##
         sar2
                 sma1
                       sma2
       -0.383 -1.202 0.496
##
      0.118 0.249
                      0.214
## S.e.
```

### checkresiduals(fit)



```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(4,1,1)(2,1,2)[12]
## Q* = 16, df = 15, p-value = 0.4
##
## Model df: 9. Total lags used: 24
```