



Forecasting: principles and practice

Rob J Hyndman

2.3 Stationarity and differencing

Outline

- 1 Stationarity
- 2 Differencing
- 3 Unit root tests
- 4 Lab session 15
- **5** Backshift notation
- 6 Autoregressive models
- 7 Moving Average models
- 8 Non-seasonal ARIMA models

Stationarity

Definition

If $\{y_t\}$ is a stationary time series, then for all s, the distribution of (y_t, \ldots, y_{t+s}) does not depend on t.

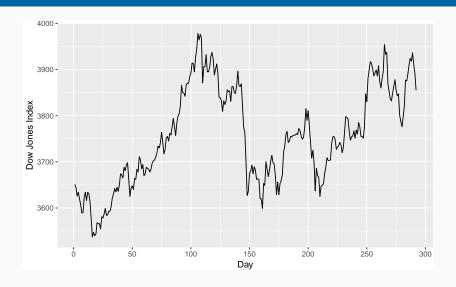
Stationarity

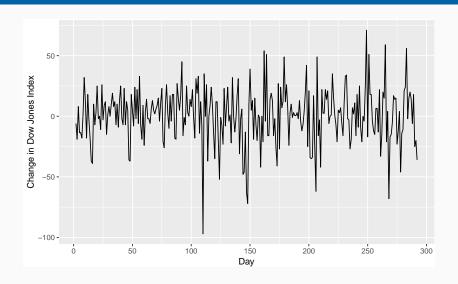
Definition

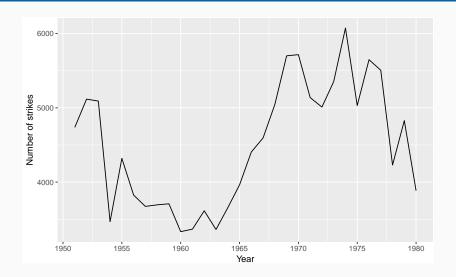
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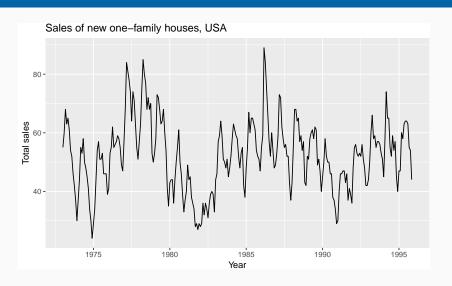
A stationary series is:

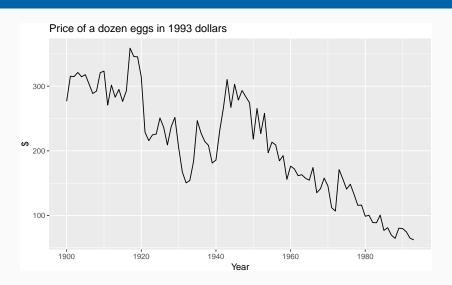
- roughly horizontal
- constant variance
- no patterns predictable in the long-term

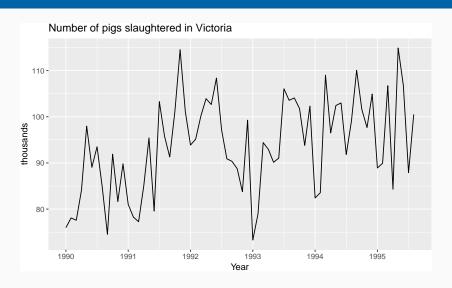


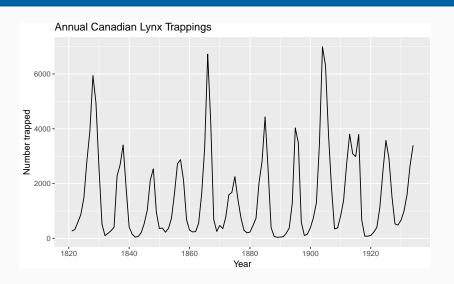


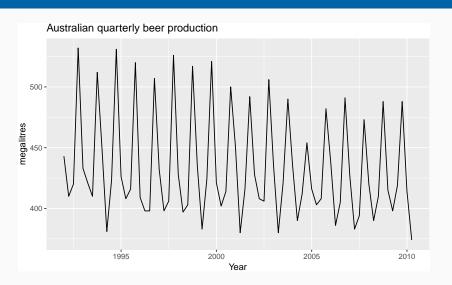












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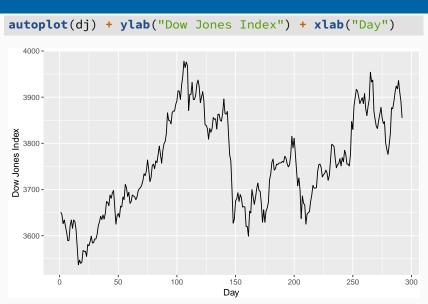
Transformations help to **stabilize the variance**.

For ARIMA modelling, we also need to **stabilize the mean**.

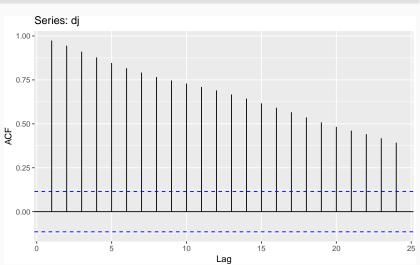
Non-stationarity in the mean

Identifying non-stationary series

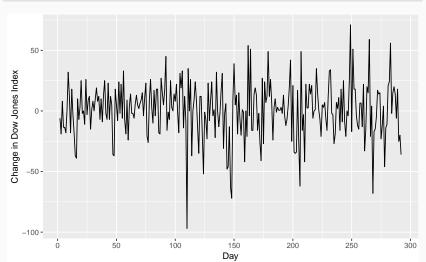
- time plot.
- The ACF of stationary data drops to zero relatively quickly
- The ACF of non-stationary data decreases slowly.
- For non-stationary data, the value of r_1 is often large and positive.



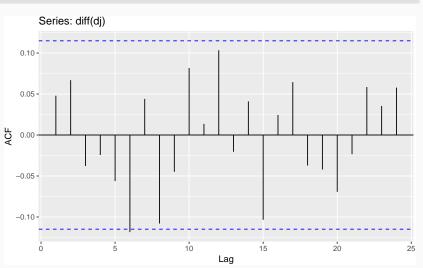




```
autoplot(diff(dj)) +
  ylab("Change in Dow Jones Index") + xlab("Day")
```







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Differencing

- Differencing helps to stabilize the mean.
- The differenced series is the *change* between each observation in the original series:

$$\mathsf{y}_t' = \mathsf{y}_t - \mathsf{y}_{t-1}.$$

■ The differenced series will have only T-1 values since it is not possible to calculate a difference y'_1 for the first observation.

Second-order differencing

Occasionally the differenced data will not appear stationary and it may be necessary to difference the data a second time:

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$$y_t'' = y_t' - y_{t-1}'$$

$$= (y_t - y_{t-1}) - (y_{t-1} - y_{t-2})$$

$$= y_t - 2y_{t-1} + y_{t-2}.$$

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- y_t'' will have T-2 values.
- In practice, it is almost never necessary to go beyond second-order differences.

A seasonal difference is the difference between an observation and the corresponding observation from the previous year.

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$$y_t' = y_t - y_{t-m}$$

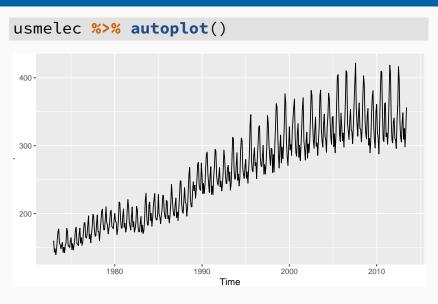
where m = number of seasons.

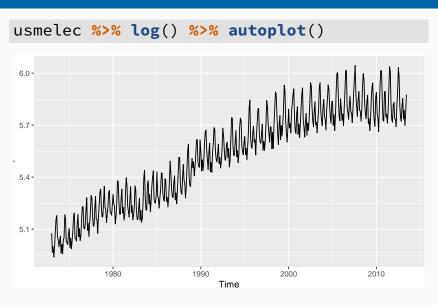
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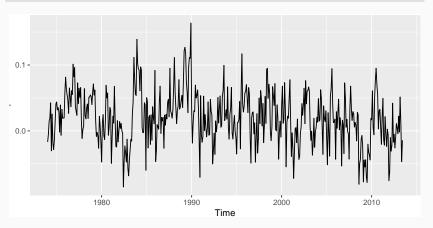
where m = number of seasons.

- For monthly data m = 12.
- For quarterly data m = 4.



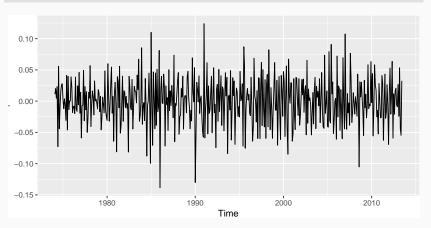


```
usmelec %>% log() %>% diff(lag=12) %>%
autoplot()
```



```
usmelec %>% log() %>% diff(lag=12) %>%

diff(lag=1) %>% autoplot()
```



- Seasonally differenced series is closer to being stationary.
- Remaining non-stationarity can be removed with further first difference.

If $y'_t = y_t - y_{t-12}$ denotes seasonally differenced series, then twice-differenced series is

$$y_t^* = y_t' - y_{t-1}'$$

$$= (y_t - y_{t-12}) - (y_{t-1} - y_{t-13})$$

$$= y_t - y_{t-1} - y_{t-12} + y_{t-13}.$$

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- it makes no difference which is done first—the result will be the same.
- If seasonality is strong, we recommend that seasonal differencing be done first because sometimes the resulting series will be stationary and there will be no need for further first difference.

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It is important that if differencing is used, the differences are interpretable.

Interpretation of differencing

- first differences are the change between one observation and the next:
- seasonal differences are the change between one year to the next.

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But taking lag 3 differences for yearly data, for example, results in a model which cannot be sensibly interpreted.

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Unit root tests

Statistical tests to determine the required order of differencing.

- Augmented Dickey Fuller test: null hypothesis is that the data are non-stationary and non-seasonal.
- Kwiatkowski-Phillips-Schmidt-Shin (KPSS) test: null hypothesis is that the data are stationary and non-seasonal.
- Other tests available for seasonal data.

KPSS test

```
library(urca)
summary(ur.kpss(goog))
```

```
##
  #########################
## # KPSS Unit Root Test #
## ######################
##
## Test is of type: mu with 7 lags.
##
## Value of test-statistic is: 10.72
##
## Critical value for a significance level of:
##
                   10pct 5pct 2.5pct 1pct
## critical values 0.347 0.463 0.574 0.739
```

KPSS test

[1] 1

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ndiffs(goog)
```

Automatically selecting differences

STL decomposition:
$$y_t = T_t + S_t + R_t$$

Seasonal strength $F_s = \max \left(0, 1 - \frac{\text{Var}(R_t)}{\text{Var}(S_t + R_t)}\right)$
If $F_s > 0.64$, do one seasonal difference.

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```
usmelec %>% log() %>% nsdiffs()

## [1] 1

usmelec %>% log() %>% diff(lag=12) %>% ndiffs()

## [1] 1
```

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Lab Session 15

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$$By_t = y_{t-1} .$$

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$$B(By_t) = B^2y_t = y_{t-2}.$$

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$$B(By_t) = B^2y_t = y_{t-2}.$$

For monthly data, if we wish to shift attention to "the same month last year," then B^{12} is used, and the notation is $B^{12}y_t = y_{t-12}$.

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.

Note that a first difference is represented by (1 - B).

Similarly, if second-order differences (i.e., first differences of first differences) have to be computed, then:

$$y_t'' = y_t - 2y_{t-1} + y_{t-2} = (1 - B)^2 y_t$$
.

- Second-order difference is denoted $(1 B)^2$.
- Second-order difference is not the same as a second difference, which would be denoted $1 B^2$;
- In general, a *d*th-order difference can be written as

$$(1-B)^d y_t$$
.

 A seasonal difference followed by a first difference can be written as

$$(1-B)(1-B^m)y_t$$
.

The "backshift" notation is convenient because the terms can be multiplied together to see the combined effect.

$$(1 - B)(1 - B^{m})y_{t} = (1 - B - B^{m} + B^{m+1})y_{t}$$
$$= y_{t} - y_{t-1} - y_{t-m} + y_{t-m-1}.$$

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For monthly data, m = 12 and we obtain the same result as earlier.

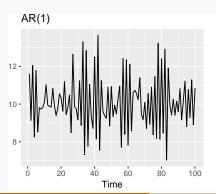
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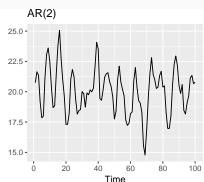
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Autoregressive models

Autoregressive (AR) models:

 $y_t = c + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \cdots + \phi_p y_{t-p} + \varepsilon_t$, where ε_t is white noise. This is a multiple regression with **lagged values** of y_t as predictors.

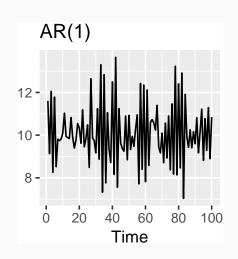




AR(1) model

$$y_t = 2 - 0.8y_{t-1} + \varepsilon_t$$

 $\varepsilon_{t} \sim N(0, 1)$, T = 100.



AR(1) model

$$y_t = c + \phi_1 y_{t-1} + \varepsilon_t$$

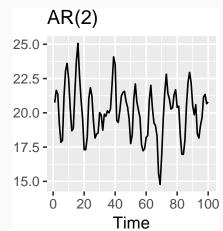
- When ϕ_1 = 0, y_t is **equivalent to WN**
- When ϕ_1 = 1 and c = 0, y_t is **equivalent to a RW**
- When ϕ_1 = 1 and $c \neq 0$, y_t is **equivalent to a RW** with drift
- When ϕ_1 < 0, y_t tends to oscillate between positive and negative values.

AR(2) model

$$y_t = 8 + 1.3y_{t-1} - 0.7y_{t-2} + \varepsilon_t$$

 $arepsilon_{t}\sim extsf{N(0,1)},$

T = 100.



Stationarity conditions

We normally restrict autoregressive models to stationary data, and then some constraints on the values of the parameters are required.

General condition for stationarity

Complex roots of $1 - \phi_1 z - \phi_2 z^2 - \cdots - \phi_p z^p$ lie outside the unit circle on the complex plane.

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- For p = 1: $-1 < \phi_1 < 1$.
- For p = 2:

$$-1 < \phi_2 < 1$$
 $\phi_2 + \phi_1 < 1$ $\phi_2 - \phi_1 < 1$.

■ More complicated conditions hold for $p \ge 3$.

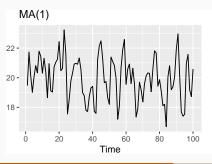
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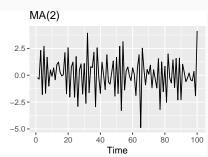
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Moving Average (MA) models

Moving Average (MA) models:

 $y_t = c + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \theta_2 \varepsilon_{t-2} + \cdots + \theta_q \varepsilon_{t-q}$, where ε_t is white noise. This is a multiple regression with **past errors** as predictors. Don't confuse this with moving average smoothing!

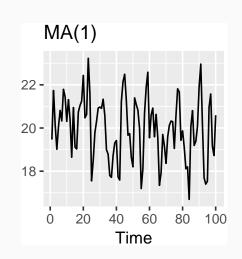




MA(1) model

$$y_t = 20 + \varepsilon_t + 0.8\varepsilon_{t-1}$$

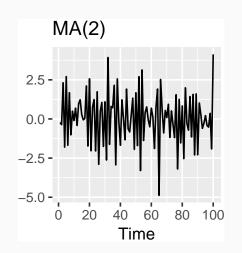
 $\varepsilon_t \sim N(0, 1), T = 100.$



MA(2) model

$$y_t = \varepsilon_t - \varepsilon_{t-1} + 0.8\varepsilon_{t-2}$$

 $\varepsilon_t \sim N(0, 1), T = 100.$



Invertibility

 Invertible models have property that distant past has negligible effect on forecasts. Requires consraints on MA parameters.

General condition for invertibility

Complex roots of $1 + \theta_1 z + \theta_2 z^2 + \cdots + \theta_q z^q$ lie outside the unit circle on the complex plane.

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 $\theta_2 + \theta_1 > -1$ $\theta_1 - \theta_2 < 1$.

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ARIMA models

Autoregressive Moving Average models:

$$y_t = c + \phi_1 y_{t-1} + \dots + \phi_p y_{t-p} + \theta_1 e_{t-1} + \dots + \theta_q e_{t-q} + e_t.$$

ARIMA models

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- Predictors include both lagged values of y_t and lagged errors.
- Conditions on coefficients ensure stationarity.
- Conditions on coefficients ensure invertibility.

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Autoregressive Moving Average models:

$$y_t = c + \phi_1 y_{t-1} + \dots + \phi_p y_{t-p} + \theta_1 e_{t-1} + \dots + \theta_q e_{t-q} + e_t.$$

- Predictors include both lagged values of y_t and lagged errors.
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- Conditions on coefficients ensure invertibility.

Autoregressive Integrated Moving Average models

- Combine ARMA model with differencing.
- $(1-B)^d y_t$ follows an ARMA model.

ARIMA models

Autoregressive Integrated Moving Average models

ARIMA(p, d, q) model

- AR: p = order of the autoregressive part
 - I: d =degree of first differencing involved
- MA: q =order of the moving average part.
 - White noise model: ARIMA(0,0,0)
 - Random walk: ARIMA(0,1,0) with no constant
 - Random walk with drift: ARIMA(0,1,0) with const.
 - \blacksquare AR(p): ARIMA(p,0,0)
 - \blacksquare MA(q): ARIMA(0,0,q)

Backshift notation for ARIMA

ARMA model:

$$\begin{aligned} \mathbf{y}_t &= \mathbf{c} + \phi_1 \mathbf{B} \mathbf{y}_t + \dots + \phi_p \mathbf{B}^p \mathbf{y}_t + \varepsilon_t + \theta_1 \mathbf{B} \varepsilon_t + \dots + \theta_q \mathbf{B}^q \varepsilon_t \\ \text{or} \quad & (\mathbf{1} - \phi_1 \mathbf{B} - \dots - \phi_p \mathbf{B}^p) \mathbf{y}_t = \mathbf{c} + (\mathbf{1} + \theta_1 \mathbf{B} + \dots + \theta_q \mathbf{B}^q) \varepsilon_t \end{aligned}$$

ARIMA(1,1,1) model:

$$(1 - \phi_1 B)$$
 $(1 - B)y_t = c + (1 + \theta_1 B)\varepsilon_t$
 \uparrow \uparrow \uparrow
AR(1) First MA(1)
difference

Backshift notation for ARIMA

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 $(1 - B)y_t = c + (1 + \theta_1 B)\varepsilon_t$
 \uparrow \uparrow \uparrow \uparrow
AR(1) First MA(1)
difference

Written out:

$$y_t = c + y_{t-1} + \phi_1 y_{t-1} - \phi_1 y_{t-2} + \theta_1 \varepsilon_{t-1} + \varepsilon_t$$

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R model

Intercept form

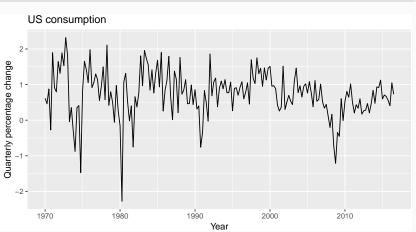
$$(1 - \phi_1 B - \dots - \phi_p B^p) y_t' = c + (1 + \theta_1 B + \dots + \theta_q B^q) \varepsilon_t$$

Mean form

$$(1 - \phi_1 B - \dots - \phi_p B^p)(y_t' - \mu) = (1 + \theta_1 B + \dots + \theta_q B^q)\varepsilon_t$$

- $y'_t = (1 B)^d y_t$
- \blacksquare μ is the mean of y'_t .
- $c = \mu(1 \phi_1 \cdots \phi_p).$
- R uses mean form.

```
autoplot(uschange[,"Consumption"]) +
  xlab("Year") + ylab("Quarterly percentage change") +
  ggtitle("US consumption")
```



```
(fit <- auto.arima(uschange[,"Consumption"]))</pre>
## Series: uschange[, "Consumption"]
## ARIMA(2,0,2) with non-zero mean
##
## Coefficients:
##
          ar1
                 ar2 ma1
                               ma2
                                     mean
## 1.391 -0.581 -1.180 0.558 0.746
## s.e. 0.255 0.208 0.238 0.140 0.084
##
## sigma^2 estimated as 0.351: log likelihood=-165.1
## AIC=342.3 AICc=342.8 BIC=361.7
```

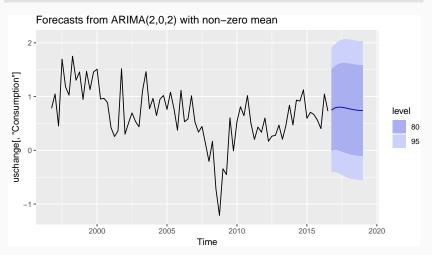
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```

(fit <- auto.arima(uschange[,"Consumption"]))</pre>

ARIMA(2,0,2) model:

```
y_t = c + 1.391y_{t-1} - 0.581y_{t-2} - 1.180\varepsilon_{t-1} + 0.558\varepsilon_{t-2} + \varepsilon_t, where c = 0.746 \times (1 - 1.391 + 0.581) = 0.142 and \varepsilon_t \sim N(0, 0.351).
```





Understanding ARIMA models

Long-term forecasts

```
zero c = 0, d = 0

non-zero constant c = 0, d = 1 c \neq 0, d = 0

linear c = 0, d = 2 c \neq 0, d = 1

quadratic c = 0, d = 3 c \neq 0, d = 2
```

Forecast variance and d

- The higher the value of *d*, the more rapidly the prediction intervals increase in size.
- For d = 0, the long-term forecast standard deviation will go to the standard deviation of the historical data.

Understanding ARIMA models

Cyclic behaviour

- For cyclic forecasts, $p \ge 2$ and some restrictions on coefficients are required.
- If p = 2, we need $\phi_1^2 + 4\phi_2 < 0$. Then average cycle of length

$$(2\pi)/\left[\arccos(-\phi_1(1-\phi_2)/(4\phi_2))\right]$$
.

Outline

- 1 Stationarity
- 2 Differencing
- 3 Unit root tests
- 4 Lab session 15
- **5** Backshift notation
- 6 Autoregressive models
- 7 Moving Average models
- 8 Non-seasonal ARIMA models

Maximum likelihood estimation

Having identified the model order, we need to estimate the parameters $c, \phi_1, \ldots, \phi_p, \theta_1, \ldots, \theta_q$.

Maximum likelihood estimation

Having identified the model order, we need to estimate the parameters $c, \phi_1, \ldots, \phi_p, \theta_1, \ldots, \theta_q$.

 MLE is very similar to least squares estimation obtained by minimizing

$$\sum_{t=1}^{T} e_t^2$$

- The Arima() command allows CLS or MLE estimation.
- Non-linear optimization must be used in either case.
- Different software will give different estimates.

Akaike's Information Criterion (AIC):

$$AIC = -2 \log(L) + 2(p + q + k + 1),$$

where *L* is the likelihood of the data,

$$k = 1 \text{ if } c \neq 0 \text{ and } k = 0 \text{ if } c = 0.$$

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Corrected AIC:

AICc = AIC +
$$\frac{2(p+q+k+1)(p+q+k+2)}{T-p-q-k-2}$$

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Corrected AIC:

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$$\frac{2(p+q+k+1)(p+q+k+2)}{T-p-q-k-2}$$

Bayesian Information Criterion:

$$BIC = AIC + \log(T)(p + q + k - 1).$$

Good models are obtained by minimizing either the AIC, AICc or BIC. My preference is to use the AICc.

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How does auto.arima() work?

A non-seasonal ARIMA process

$$\phi(B)(1-B)^d y_t = c + \theta(B)\varepsilon_t$$

Need to select appropriate orders: p, q, d

Hyndman and Khandakar (JSS, 2008) algorithm:

- Select no. differences d and D via KPSS test and seasonal strength measure.
- Select p, q by minimising AICc.
- Use stepwise search to traverse model space.

How does auto.arima() work?

Step 1: Select values of *d* and *D*.

Step 2: Select current model (with smallest AICc) from:

ARIMA(2, d, 2)

ARIMA(0, d, 0)

ARIMA(1, d, 0)

ARIMA(0, d, 1)

How does auto.arima() work?

Step 1: Select values of *d* and *D*.

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ARIMA(2, d, 2)

ARIMA(0, d, 0)

ARIMA(1, d, 0)

ARIMA(0, d, 1)

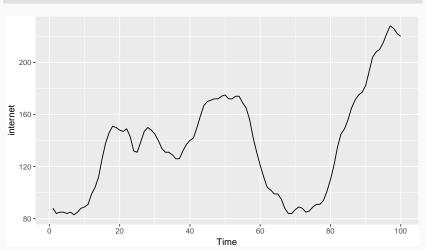
Step 3: Consider variations of current model:

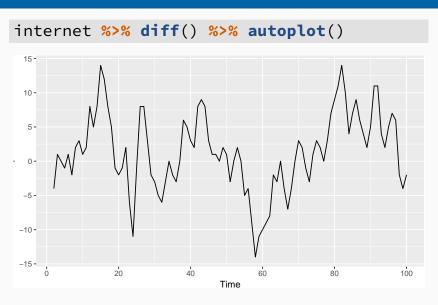
- vary one of p, q, from current model by ± 1 ;
- p, q both vary from current model by ± 1 ;
- Include/exclude *c* from current model.

Model with lowest AICc becomes current model.

Repeat Step 3 until no lower AICc can be found.

autoplot(internet)





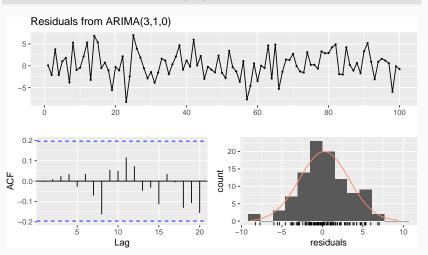
```
(fit <- auto.arima(internet))</pre>
## Series: internet
## ARIMA(1,1,1)
##
## Coefficients:
##
          arl mal
       0.650 0.526
##
## s.e. 0.084 0.090
##
## sigma^2 estimated as 10:
                            log likelihood=-254.2
## ATC=514.3 ATCc=514.5
                           BTC=522.1
```

```
(fit <- auto.arima(internet, stepwise=FALSE,
    approximation=FALSE))</pre>
```

```
## Series: internet
## ARIMA(3,1,0)
##
## Coefficients:
##
          ar1 ar2 ar3
## 1.151 -0.661 0.341
## s.e. 0.095 0.135
                      0.094
##
## sigma^2 estimated as 9.66: log likelihood=-252
## ATC=512 ATCc=512.4 BTC=522.4
```

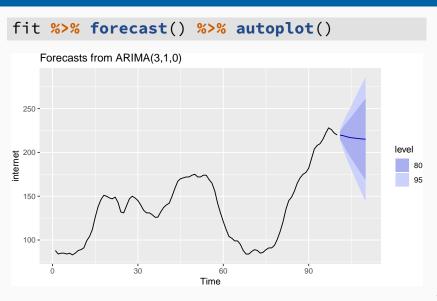
##

checkresiduals(fit, plot=TRUE)



checkresiduals(fit, plot=FALSE)

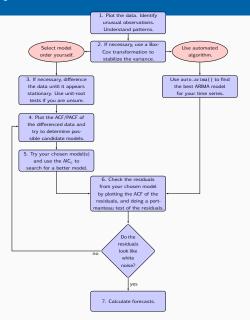
```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(3,1,0)
## Q* = 4.5, df = 7, p-value = 0.7
##
## Model df: 3. Total lags used: 10
```



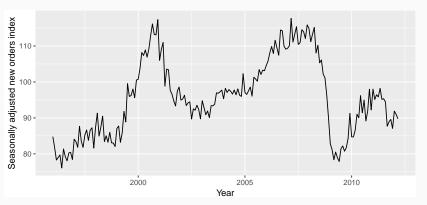
Modelling procedure with auto.arima

- Plot the data. Identify any unusual observations.
- If necessary, transform the data (using a Box-Cox transformation) to stabilize the variance.
- Use auto.arima to select a model.
- Check the residuals from your chosen model by plotting the ACF of the residuals, and doing a portmanteau test of the residuals. If they do not look like white noise, try a modified model.
- Once the residuals look like white noise, calculate forecasts.

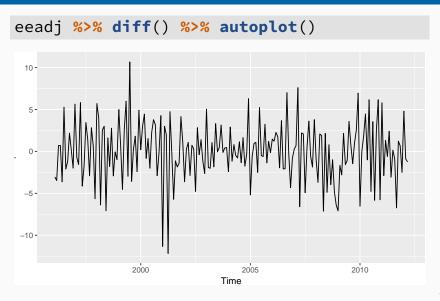
Modelling procedure



```
eeadj <- seasadj(stl(elecequip, s.window="periodic"
autoplot(eeadj) + xlab("Year") +
   ylab("Seasonally adjusted new orders index")</pre>
```



- Time plot shows sudden changes, particularly big drop in 2008/2009 due to global economic environment. Otherwise nothing unusual and no need for data adjustments.
- No evidence of changing variance, so no Box-Cox transformation.
- Data are clearly non-stationary, so we take first differences.

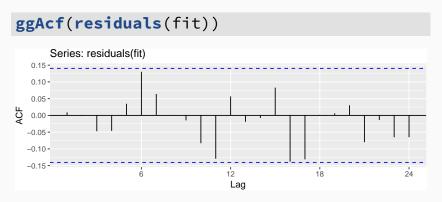


fit <- auto.arima(eeadj, stepwise=FALSE, approximation=FALSE)
summary(fit)</pre>

```
## Series: eeadj
## ARIMA(3,1,1)
##
## Coefficients:
        ar1 ar2 ar3 ma1
##
     0.004 0.092 0.370 -0.392
##
## s.e. 0.220 0.098 0.067 0.243
##
## sigma^2 estimated as 9.58: log likelihood=-492.7
  AIC=995.4 AICc=995.7 BIC=1012
##
##
  Training set error measures:
##
                   MF
                       RMSE MAE MPE MAPE MASE
## Training set 0.03288 3.055 2.357 -0.00647 2.482 0.2884
                  ACF1
##
```

Seasonally adjusted electrical equipment

ACF plot of residuals from ARIMA(3,1,1) model look like white noise.

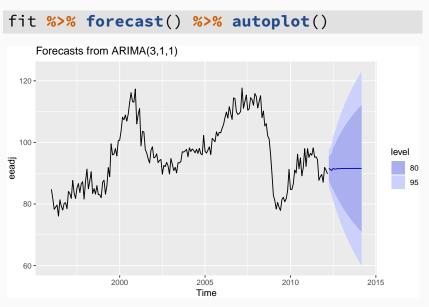


Seasonally adjusted electrical equipment

checkresiduals(fit, plot=FALSE)

```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(3,1,1)
## Q* = 24, df = 20, p-value = 0.2
##
## Model df: 4. Total lags used: 24
```

Seasonally adjusted electrical equipment



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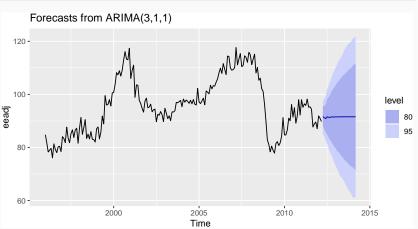
Lab Session 16

Prediction intervals

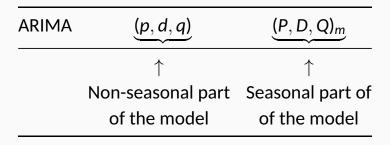
- Prediction intervals increase in size with forecast horizon.
- Calculations assume residuals are uncorrelated and normally distributed.
- Prediction intervals tend to be too narrow.
 - the uncertainty in the parameter estimates has not been accounted for.
 - the ARIMA model assumes historical patterns will not change during the forecast period.
 - the ARIMA model assumes uncorrelated future errors

Bootstrapped prediction intervals





No assumption of normally distributed residuals. #
 Seasonal ARIMA models

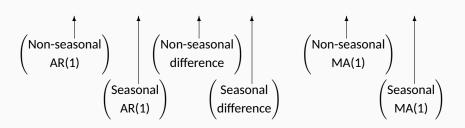


where m = number of observations per year.

E.g., ARIMA $(1, 1, 1)(1, 1, 1)_4$ model (without constant)

E.g., ARIMA(1, 1, 1)(1, 1, 1)₄ model (without constant)
$$(1-\phi_1B)(1-\Phi_1B^4)(1-B)(1-B^4)y_t = (1+\theta_1B)(1+\Theta_1B^4)\varepsilon_t$$
.

E.g., ARIMA(1, 1, 1)(1, 1, 1)₄ model (without constant)
$$(1-\phi_1B)(1-\Phi_1B^4)(1-B)(1-B^4)y_t = (1+\theta_1B)(1+\Theta_1B^4)\varepsilon_t$$
.



E.g., ARIMA(1, 1, 1)(1, 1, 1)₄ model (without constant)
$$(1-\phi_1B)(1-\Phi_1B^4)(1-B)(1-B^4)y_t = (1+\theta_1B)(1+\Theta_1B^4)\varepsilon_t$$
.

All the factors can be multiplied out and the general model written as follows:

$$\begin{aligned} y_t &= (1+\phi_1)y_{t-1} - \phi_1y_{t-2} + (1+\Phi_1)y_{t-4} \\ &- (1+\phi_1+\Phi_1+\phi_1\Phi_1)y_{t-5} + (\phi_1+\phi_1\Phi_1)y_{t-6} \\ &- \Phi_1y_{t-8} + (\Phi_1+\phi_1\Phi_1)y_{t-9} - \phi_1\Phi_1y_{t-10} \\ &+ \varepsilon_t + \theta_1\varepsilon_{t-1} + \Theta_1\varepsilon_{t-4} + \theta_1\Theta_1\varepsilon_{t-5}. \end{aligned}$$

Common ARIMA models

The US Census Bureau uses the following models most often:

ARIMA(0,1,1)(0,1,1) _m	with log transformation
$ARIMA(0,1,2)(0,1,1)_m$	with log transformation
$ARIMA(2,1,0)(0,1,1)_m$	with log transformation
$ARIMA(0,2,2)(0,1,1)_m$	with log transformation
$ARIMA(2,1,2)(0,1,1)_m$	with no transformation

Understanding ARIMA models

Long-term forecasts

```
zero c = 0, d + D = 0

non-zero constant c = 0, d + D = 1 c \neq 0, d + D = 0

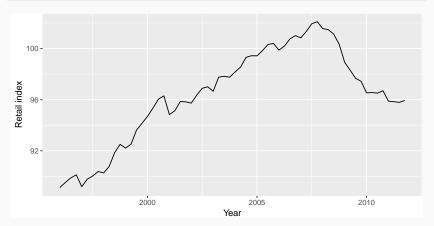
linear c = 0, d + D = 2 c \neq 0, d + D = 1

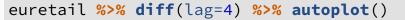
quadratic c = 0, d + D = 3 c \neq 0, d + D = 2
```

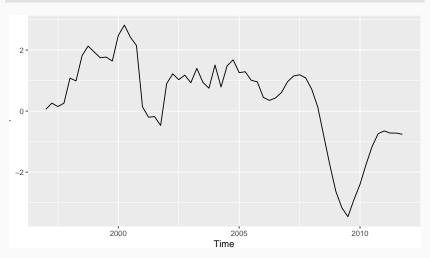
Forecast variance and d + D

- The higher the value of d + D, the more rapidly the prediction intervals increase in size.
- For d + D = 0, the long-term forecast standard deviation will go to the standard deviation of the historical data.

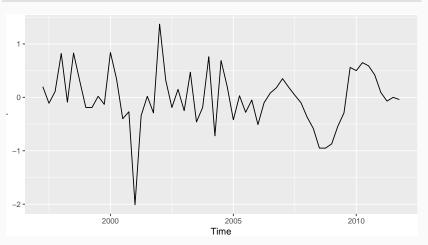
```
autoplot(euretail) +
   xlab("Year") + ylab("Retail index")
```







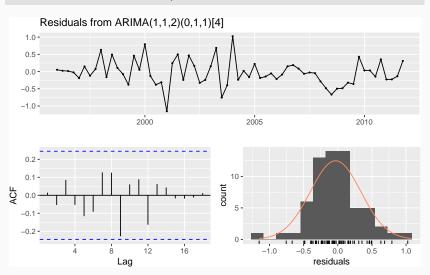
```
euretail %>% diff(lag=4) %>% diff() %>%
autoplot()
```



```
(fit <- auto.arima(euretail))</pre>
## Series: euretail
## ARIMA(1,1,2)(0,1,1)[4]
##
## Coefficients:
##
          arl mal ma2 sma1
##
       0.736 - 0.466 \ 0.216 - 0.843
## s.e. 0.224 0.199 0.210
                              0.188
##
## sigma^2 estimated as 0.159: log likelihood=-29.62
## ATC=69.24 ATCc=70.38 BTC=79.63
```

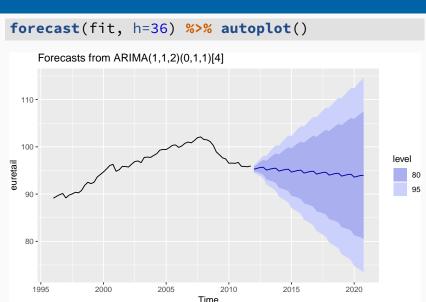
```
(fit <- auto.arima(euretail, stepwise=TRUE,
 approximation=FALSE))
## Series: euretail
## ARIMA(1,1,2)(0,1,1)[4]
##
## Coefficients:
##
          ar1
                 ma1
                         ma2
                              sma1
##
        0.736 - 0.466 \ 0.216 - 0.843
## s.e. 0.224 0.199 0.210
                               0.188
##
## sigma^2 estimated as 0.159: log likelihood=-29.62
## ATC=69.24 ATCc=70.38
                           BTC=79.63
```

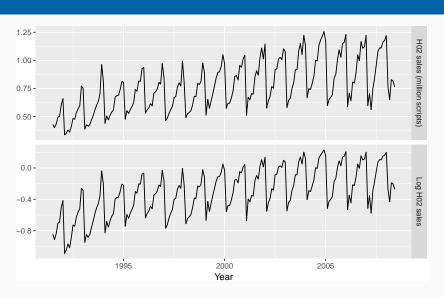
checkresiduals(fit, test=FALSE)



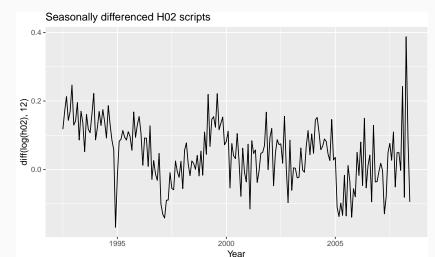
```
##
...
checkresiduals(fit, plot=FALSE)
```

```
## Ljung-Box test
##
## data: Residuals from ARIMA(1,1,2)(0,1,1)[4]
## Q* = 4.9, df = 4, p-value = 0.3
##
## Model df: 4. Total lags used: 8
```





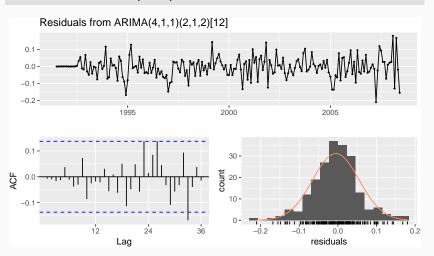
```
autoplot(diff(log(h02),12), xlab="Year",
    main="Seasonally differenced H02 scripts")
```



```
(fit <- auto.arima(h02, lambda=0, max.order=9,
    stepwise=FALSE, approximation=FALSE))</pre>
```

```
## Series: h02
## ARIMA(4,1,1)(2,1,2)[12]
## Box Cox transformation: lambda= 0
##
## Coefficients:
                 ar2 ar3 ar4
##
           ar1
                                      ma1
                                            sar1
##
        -0.042 0.210 0.202 -0.227 -0.742 0.621
## s.e. 0.217 0.181 0.114 0.081 0.207 0.242
##
         sar2
                 sma1
                       sma2
       -0.383 - 1.202 0.496
##
      0.118 0.249
                       0.214
## S.e.
```

checkresiduals(fit)



```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(4,1,1)(2,1,2)[12]
## Q* = 16, df = 15, p-value = 0.4
##
## Model df: 9. Total lags used: 24
```

Training data: July 1991 to June 2006

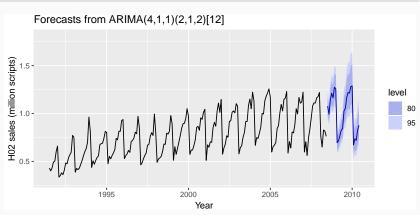
Test data: July 2006-June 2008

```
getrmse <- function(x,h,...)</pre>
  train.end <- time(x)[length(x)-h]
  test.start <- time(x)[length(x)-h+1]
  train <- window(x,end=train.end)</pre>
  test <- window(x,start=test.start)</pre>
  fit <- Arima(train,...)</pre>
  fc <- forecast(fit,h=h)</pre>
  return(accuracy(fc,test)[2,"RMSE"])
}
getrmse(h02,h=24,order=c(3,0,0),seasonal=c(2,1,0),lambda=0)
getrmse(h02,h=24,order=c(3,0,1),seasonal=c(2,1,0),lambda=0)
getrmse(h02,h=24,order=c(3,0,2),seasonal=c(2,1,0),lambda=0)
\mathbf{ratrmse}(\mathbf{h} \mathbf{0}) \mathbf{h} = 24 \text{ order} = \mathbf{c}(3 \mathbf{0} \mathbf{1}) \text{ seasonal} = \mathbf{c}(1 \mathbf{1} \mathbf{0}) \text{ lambda} = \mathbf{0}
```

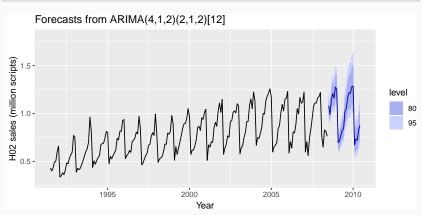
Model	RMSE
ARIMA(4,1,2)(2,1,2)[12]	0.0614
ARIMA(4,1,1)(2,1,2)[12]	0.0615
ARIMA(3,0,1)(0,1,2)[12]	0.0622
ARIMA(3,0,1)(1,1,1)[12]	0.0630
ARIMA(2,1,4)(0,1,1)[12]	0.0632
ARIMA(2,1,3)(0,1,1)[12]	0.0634
ARIMA(4,1,2)(1,1,2)[12]	0.0634
ARIMA(3,1,2)(2,1,2)[12]	0.0636
ARIMA(3,0,3)(0,1,1)[12]	0.0639
ARIMA(2,1,5)(0,1,1)[12]	0.0640
ARIMA(3,0,1)(0,1,1)[12]	0.0644
ARIMA(3,0,2)(0,1,1)[12]	0.0644
ARIMA(3 0 2)(2 1 0)[12]	0 0645

- Models with lowest AICc values tend to give slightly better results than the other models.
- AICc comparisons must have the same orders of differencing. But RMSE test set comparisons can involve any models.
- Use the best model available, even if it does not pass all tests.

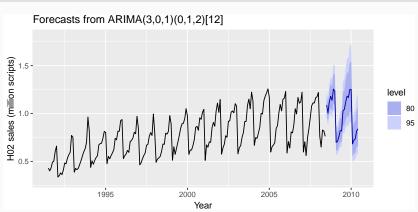
```
fit <- Arima(h02, order=c(4,1,1), seasonal=c(2,1,2),
    lambda=0)
autoplot(forecast(fit)) + xlab("Year") +
    ylab("H02 sales (million scripts)") + ylim(0.3,1.8)</pre>
```



```
fit <- Arima(h02, order=c(4,1,2), seasonal=c(2,1,2),
  lambda=0)
autoplot(forecast(fit)) + xlab("Year") +
  ylab("H02 sales (million scripts)") + ylim(0.3,1.8)</pre>
```



```
fit <- Arima(h02, order=c(3,0,1), seasonal=c(0,1,2),
  lambda=0)
autoplot(forecast(fit)) + xlab("Year") +
  ylab("H02 sales (million scripts)") + ylim(0.3,1.8)</pre>
```



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Lab Session 17