An example of interfacing mxCuBE with a non-ESRF control system : the TINE case

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TINE

- TINE: Three-fold Integrated Networking Environment
- Control system designed and used at DESY
- Multi-platform
- Multi-protocol
- Multi-Architectrure (multicast capabilities)
- Different API supported: C/C++, Java, Labview, Matlab...
- but not Python
- More info at tine.desy.de



PyTine

- Python bindings for Tine (using Python.h)
- Exporting the functionality of the Tine C library
- Support of synchronous and asynchronous calls
- Support of data structures
- First release available
 - http://adweb.desy.de/mcs/tine/TineArchive/PyTine-0.9.tar.gz



Our Scenario

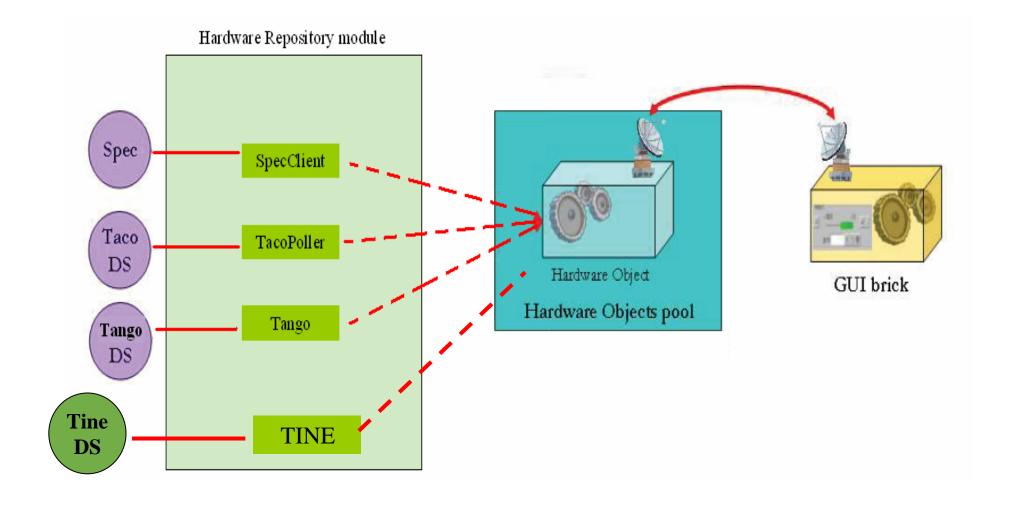
- Connect mxCuBE with our system (Tine-based)
- Control the data collections from this interface
- Main problems
 - We do not know the system in detail
 - The HO are sometimes dependent of the CS
 - TINE does not support Python directly

Solutions

- 1. Get support from ESRF
- 2. Look into the source code and learn about system
- 3. Provide a generic connection between TINE and Python: PyTine
- 4. Provide a generic connection between the HO and PyTine
- 5. Rebuild some of the HO



Our Scenario





Our Approach: Command package

- Command package is the place to put command launchers and channel readers/writers modules
- Command launchers and channels derive from CObject class of the HardwareRepository.
 CommandContainer module
- The modules are organised by control software (Spec, Taco, Tango) and should emit the appropriate Qt signals.
- In our case we need similar Tine-controlled module that calls Tine through PyTine interface.



Our Approach: Command package - Tine.py

- Implementation of Tine.py inside the HardwareRepository (CommandContainer)
- Follows the same architecture as the Tango.py
- Definition of the connection inside the XML
- The HO access Command & Channels
 - In a generic way
 - Independently of the Control System
- Implemented together with Matias Guijarro



Example1: Hardware Object - Attenuators

Adapted to TINE without code modification

```
import logging
from HardwareRepository.BaseHardwareObjects import Device
class Attenuators(Device):
  def init (self, name):
    Device. init (self, name)
    self.labels = []
    self.bits = []
    self.attno = 0
  def init(self):
    self.cmdsetTransmission = self.getCommandObject('setTransmission')
    self.cmdsetTransmission.connectSignal('connected', self.connected)
    self.cmdsetTransmission.connectSignal('disconnected', self.disconnected)
    self.chanAttState = self.getChannelObject('attstate')
    self.chanAttState.connectSignal('update', self.attStateChanged)
    self.chanAttFactor = self.getChannelObject('attfactor')
```

self.chanAttFactor.connectSignal('update', self.attFactorChanged)



Example1: Hardware Object - Attenuators

Needs only modification inside XML

ESRF Configuration XML

```
<device class = "Attenuators">
    <username>Attenuators</username>
    <command type="spec" name="setTransmission">transmission</command>
    <channel type="spec" name="attstate">MATT_STATE</channel>
    <channel type="spec" name="attfactor">ATT_FACTOR</channel>
    </device>
```

EMBL-HH Configuration XML



Example2: Hardware Object – Shutter

Needs reimplementation of HO code

EMBL-HH Configuration XML

ESRF Configuration XML

```
<device class = "Shutter">
  <username>Saf. Shutter</username>
  <taconame>id14/bsh/9</taconame>
  <interval>2000</interval>
</device>
```



Open discussion

- HO should be control system independent
 - Use of commands and channels
 - What happens with different data types and data sizes
 - Ideally we will only want to change the XML config files
- Do we reimplement the control system dependent HO or we keep doing TineHO (example TineShutter)
- Documentation
- How we share our code (under discussion)

