

Problem set 3.5)

2) Let $A = [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3 \ \vec{v}_4 \ \vec{v}_5 \ \vec{v}_6]$

We have $A = \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 1 & 1 & 0 \\ 0 & -1 & 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 0 & -1 & -1 \end{bmatrix} \xrightarrow{R_2+R_1} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & -1 & 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 0 & -1 & -1 \end{bmatrix} \xrightarrow{R_3+R_2} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & -1 & 0 & -1 & -1 \end{bmatrix}$

$\xrightarrow{R_4+R_3} \begin{bmatrix} \textcircled{1} & 1 & 1 & 0 & 0 & 0 \\ 0 & \textcircled{1} & 1 & 1 & 1 & 0 \\ 0 & 0 & \textcircled{1} & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$
3 pivots

So the largest possible number of independent vectors among $\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4, \vec{v}_5, \vec{v}_6\}$ is 3. For example $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$

11) a) The two vectors are linearly dependent: $(1, 1, -1) = -1(-1, -1, 1)$. So the subspace spanned by them is a line.

b) The subspace spanned by $(0, 1, 1)$, $(1, 1, 0)$, and $(0, 0, 0)$ is the same as the subspace spanned by $(0, 1, 1)$ and $(1, 1, 0)$, which is a plane since the vectors are linearly independent.

c) The subspace spanned in this case is all of \mathbb{R}^3 . For example, three such vectors are $(1, 0, 0)$, $(0, 1, 0)$, $(0, 0, 1)$.

d) The subspace spanned in this case is all of \mathbb{R}^3 . All of three of these independent vectors span \mathbb{R}^3 .

20) The plane $x - 2y + 3z = 0$ is the nullspace of $A = \begin{bmatrix} \textcircled{1} & -2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

$\vec{ss}_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$ and $\vec{ss}_2 = \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$ So $\{\vec{ss}_1, \vec{ss}_2\}$ is a basis for the plane.

• The intersection of the plane $x - 2y + 3z = 0$ with the xy -plane is a line. In addition, we have \vec{ss}_1 in both planes. So a basis for this intersection is $\{\vec{ss}_1\}$.

• We need only find a vector with $\vec{n} = (a, b, c)$ such that $\vec{n} \cdot \vec{ss}_1 = \vec{n} \cdot \vec{ss}_2 = 0 \Leftrightarrow 2a + b = -3a + c = 0 \Leftrightarrow 5a + b - c = 0$

If $a = 1$, $b = -2$, $c = 3$, then a basis for this subspace is $\{\vec{n} = (1, -2, 3)\}$.

$$23) A = \begin{bmatrix} 1 & 3 & 2 \\ 0 & 1 & 1 \\ 1 & 3 & 2 \end{bmatrix} \quad U = \begin{bmatrix} 1 & 3 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

• A basis for the column space of U is $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} \right\}$

• A basis for $C(A)$ is $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 3 \end{bmatrix} \right\}$

• A basis for $R(A)$ is the same as for $R(U)$ and is $\left\{ \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$

The row spaces stay fixed during elimination.

41) The five possible permutation matrices are

$$P_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad P_2 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \quad P_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \quad P_4 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}, \quad \text{and } P_5 = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\text{We get } P_1 + P_2 + P_3 = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \quad \text{and} \quad P_4 + P_5 = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

$$\text{Therefore, } I = P_1 + P_2 + P_3 - P_4 - P_5$$

Assume $\exists c_1, \dots, c_5$ such that $c_1 P_1 + \dots + c_5 P_5 = 0$.

$$\text{This means } \begin{bmatrix} c_3 & c_1 + c_4 & c_2 + c_5 \\ c_1 + c_5 & c_2 & c_3 + c_4 \\ c_2 + c_4 & c_3 + c_5 & c_1 \end{bmatrix} = 0_3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

In particular, we have $c_1 = c_2 = c_3 = 0$ (from the diagonal). Therefore $c_4 = c_5 = 0$ as well.

The only possibility for $c_1 P_1 + \dots + c_5 P_5 = 0$ is that $c_i = 0 \forall i = 1, \dots, 5$. Therefore P_1, \dots, P_5 are linearly independent and form a basis for the subspace of 3×3 matrices with row and column sums all equal.

Problem set 3.6)

1) a) the matrix has $\underset{(m)}{7}$ rows, $\underset{(n)}{9}$ columns. $r=5$.

$$\dim(C(A)) = r = 5$$

$$\dim(N(A)) = n - r = 4$$

$$\dim(C(A^T)) = r = 5$$

$$\dim(N(A^T)) = m - r = 2$$

the sum of the four dimensions is
 $r + n - r + r + m - r = n + m = 16$.

b) the matrix has $m=3$ rows and $n=4$ columns. $r=3$.

$$\dim(C(A)) = r = 3 \text{ and } C(A) \subset \mathbb{R}^3. \text{ So } C(A) = \mathbb{R}^3$$

$$\dim(N(A^T)) = m - r = 0 \text{ So the left nullspace is } \{\vec{0}\}.$$

4) a) A such that $C(A)$ contains $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$, $R(A^T)$ contains $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ and $\begin{bmatrix} 2 \\ 5 \end{bmatrix}$.

So since $C(A) \subset \mathbb{R}^3$, $m=3$ A has 3 rows.

since $C(A^T) \subset \mathbb{R}^2$, $n=2$ A has 2 columns.

$$R = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \rightarrow A = \begin{bmatrix} 1 & 2 \\ 1 & 2 \\ 2 & 5 \end{bmatrix}$$

b) A such that $C(A)$ has basis $\{(1, 1, 3)\}$ and $N(A)$ has basis $\{(3, 1, 1)\}$.

Since $C(A) \subset \mathbb{R}^3$, $m=3$ A has 3 rows.

Since $N(A) \subset \mathbb{R}^3$, $n=3$ A has 3 columns.

Also, $r=1$ and $\dim(N(A)) = 1$, which is impossible, since
 $\dim(N(A)) = n - r = 2$

c) A such that $\dim(N(A)) = 1 + \dim(N(A^T))$.

We know that $\dim(N(A^T)) = m - r$, and $\dim(N(A)) = n - r$

So we need to find A such that $n - r = 1 + m - r \Leftrightarrow n = 1 + m$

A is any 2×3 matrix with two pivots. For example

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

d) A such that $N(A^T)$ contains $(1, 3)$ and $C(A^T)$ contains $(3, 1)$.

$$\dim(N(A^T)) = m - r = 1$$

$$\dim(C(A^T)) = r = 1 \text{ So } m = 2$$

Since $C(A^T) \subset \mathbb{R}^2$, $n=2$

$$A = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 3 \\ 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 3 & 1 \\ 0 & 0 \end{bmatrix}$$

We have two cases:

• $A = \begin{bmatrix} 3 & 1 \\ a & b \end{bmatrix}$ then we must have $\begin{bmatrix} 3 & a \\ 1 & b \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Leftrightarrow \begin{cases} 3+3a=0 \\ -1+3b=0 \end{cases} \Leftrightarrow \begin{cases} a=-1 \\ b=1/3 \end{cases}$

then A exists and $A = \begin{bmatrix} 3 & 1 \\ -1 & 1/3 \end{bmatrix}$

• $A = \begin{bmatrix} a & b \\ 3 & 1 \end{bmatrix}$ then we must have $\begin{bmatrix} a & b \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Leftrightarrow \begin{cases} a+3b=0 \\ b+3=0 \end{cases} \Leftrightarrow \begin{cases} a=-9 \\ b=-3 \end{cases}$

then A exists and $A = \begin{bmatrix} -9 & -3 \\ 3 & 1 \end{bmatrix}$

e) A such that $C(AT) = C(A)$ and $N(A) \neq N(AT)$

14) $A = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 6 & 1 & 0 \\ 9 & 8 & 1 \end{bmatrix}}_L \underbrace{\begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 \end{bmatrix}}_U$ We have $m=3$ and $n=4$, and $r=3$

• A basis of $C(A)$ is $\left\{ \begin{bmatrix} 1 \\ 6 \\ 9 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 8 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

• A basis of $C(AT)$ is $\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 2 \end{bmatrix} \right\}$

• We have $U \Rightarrow \begin{bmatrix} 1 & 0 & 3 & 6 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \Rightarrow \vec{ss}_1 = \begin{bmatrix} 0 \\ 1 \\ -2 \\ 1 \end{bmatrix}$

A basis of $N(A)$ is $\left\{ \begin{bmatrix} 0 \\ 1 \\ -2 \\ 1 \end{bmatrix} \right\}$

• $\dim(N(AT)) = m - r = 0$. So a basis of $N(AT)$ is $\{\vec{0}\}$.

24) $AT\vec{y} = \vec{d}$ is solvable if $\vec{d} \in C(AT)$. The solution \vec{y} is unique when the left nullspace contains only $\vec{0}$.

25) a) True. $\dim(C(A^T)) = \dim(C(A)) = r$, and r is the number of pivots in the matrix.

b) False. If A is $(m \times n)$, ^{and $m \neq n$} then $\dim(N(A^T)) = m - r$, and ~~dim~~
 $\dim(N((A^T)^T)) = \dim(N(A)) = n - r$. ~~So~~

c) False. Let $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ then $C(A) = C(A^T) = \mathbb{R}^2$

d) True. If $A^T = -A$, then $C(A^T) = C(-A) = C(A)$

26) If $AB = C$, the rows of C are combinations of the rows of B . So the rank of C is not greater than the rank of B . Since $B^T A^T = C^T$, the rank of C is also not greater than the rank of A .

Problem set 4.1)

3) a) We try $A = \begin{bmatrix} 1 & 2 & a \\ 2 & -3 & b \\ -3 & 5 & c \end{bmatrix}$ such that $\begin{cases} 1+2+a=0 \\ 2-3+b=0 \\ -3+5+c=0 \end{cases} \Rightarrow \begin{cases} a=-3 \\ b=1 \\ c=-2 \end{cases}$

We get $A = \begin{bmatrix} 1 & 2 & -3 \\ 2 & -3 & 1 \\ -3 & 5 & -2 \end{bmatrix}$. We can verify that we get $R = \begin{bmatrix} 1 & 2 & 3 \\ 0 & -7 & 7 \\ 0 & 0 & 0 \end{bmatrix}$

So A answers the problem

~~b) We try $A = \begin{bmatrix} 1 & 2 & -3 \\ 2 & -3 & 5 \\ a & b & c \end{bmatrix}$ with where $\begin{cases} 1+2-3=0 \\ 2-3+5=0 \\ a+b+c=0 \end{cases}$~~
~~In addition, we get $R = \begin{bmatrix} 1 & 2 & -3 \\ 0 & -7 & 11 \\ 0 & 0 & c+3a-\frac{5}{2}b \end{bmatrix}$~~

~~We need $c+3a-\frac{5}{2}b=0 \Leftrightarrow 14a-\frac{5}{2}b+c=0$~~

~~We need to solve~~

~~$\begin{cases} 14a-\frac{5}{2}b+c=0 \\ a+b+c=0 \end{cases} \Leftrightarrow \begin{cases} 13a-\frac{13}{2}b=0 \\ a+b+c=0 \end{cases} \Rightarrow \begin{cases} a=\frac{b}{2} \\ c=-\frac{3}{2}b \end{cases}$~~

~~So $A = \begin{bmatrix} 1 & 2 & -3 \\ 2 & -3 & 5 \\ \frac{1}{2} & 1 & -\frac{3}{2} \end{bmatrix}$ answers the problem.~~

b) We know that $N(A) \perp C(A^T)$. However, we have $1 \cdot 2 + 2 \cdot (-3) + (-3) \cdot 5 \neq 0$. So no such matrix exists.

c) If $A^T \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$, then $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \in N(A^T)$. Therefore, the first column of A^T is $(0, 0, 0)$. This means that the first row of A is $[0 \ 0 \ 0]$, which is impossible if $Ax = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ has a solution.

d) If every row is orthogonal to every column, then $A \cdot A = 0 \Leftrightarrow A^2 = 0$.
For example, $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ answers the problem.

e) No such matrix exists. If all columns add to 0, then the sum of all elements of A adds to 0. However, since all rows add to 1, then the sum of all elements of A adds to 1. We have a contradiction.

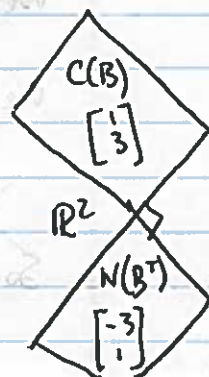
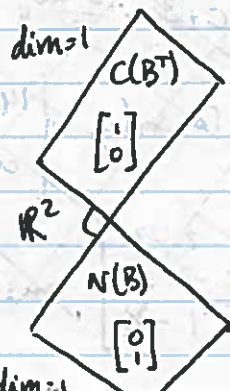
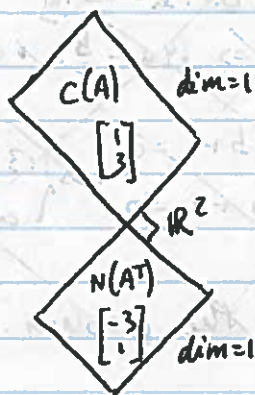
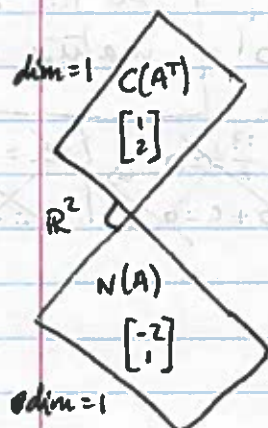
4) If $AB = 0$, then the columns of B are in the nullspace of A . The rows of A are in the left nullspace of B .

If A and B were 3×3 matrices of rank 2, then $\dim(N(A)) = \dim(N(A^T)) = \dim(N(B)) = \dim(N(B^T)) = 1$, which is impossible because $m = n = 3$ and $r = 2$ (then $m - r = n - r = 1$).

7) If $y_1 = 1$, $y_2 = 1$, and $y_3 = -1$, we get $1(x_1 - x_2) + 1(x_2 - x_3) - 1(x_1 - x_3) = 1$
($\Rightarrow 0 = 1$)

$$11) A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \Rightarrow C(A) = \left\{ \begin{bmatrix} 1 \\ 3 \end{bmatrix} \right\}, N(A) = \left\{ \begin{bmatrix} -2 \\ 1 \end{bmatrix} \right\}, C(A^T) = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}, N(A^T) = \left\{ \begin{bmatrix} -3 \\ 1 \end{bmatrix} \right\}$$

$$B = \begin{bmatrix} 1 & 0 \\ 3 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \Rightarrow C(B) = \left\{ \begin{bmatrix} 1 \\ 3 \end{bmatrix} \right\}, N(B) = \left\{ \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}, C(B^T) = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}, N(B^T) = \left\{ \begin{bmatrix} -3 \\ 1 \end{bmatrix} \right\}$$



21) S is spanned by $\vec{v} = (1, 2, 2, 3)$ and $\vec{w} = (1, 3, 3, 2)$. \vec{v} and \vec{w} are linearly independent, so S is a plane in \mathbb{R}^4 . Therefore, S^\perp is also a plane in \mathbb{R}^4 .

If we have A such that $C(A^T) = S = \{\vec{v}, \vec{w}\}$, then we only need to find $N(A)$, since $C(A^T)^\perp = N(A) = S^\perp$.

$$\text{We get } A = \begin{bmatrix} 1 & 2 & 2 & 3 \\ 1 & 3 & 3 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 2 & 3 \\ 0 & 1 & 1 & -1 \end{bmatrix}$$

$$\text{So } \vec{ss}_1 = \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} \text{ and } \vec{ss}_2 = \begin{bmatrix} -5 \\ 1 \\ 0 \\ 1 \end{bmatrix} \Rightarrow N(A) = S^\perp = \left\{ \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ 1 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

Problem set 4.2)

$$1) a) \text{ We get } \vec{p} = \frac{[1 \ 1 \ 1] \cdot \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}}{[1 \ 1 \ 1] \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \frac{5}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 5/3 \\ 5/3 \\ 5/3 \end{bmatrix}$$

$$\text{So } \vec{e} = \vec{b} - \vec{p} = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} - \begin{bmatrix} 5/3 \\ 5/3 \\ 5/3 \end{bmatrix} = \begin{bmatrix} -2/3 \\ 1/3 \\ 1/3 \end{bmatrix} \text{ and } \vec{e} \cdot \vec{a} = -\frac{2}{3} \cdot 1 + \frac{1}{3} \cdot 1 + \frac{1}{3} \cdot 1 = 0$$

So $\vec{e} \perp \vec{a}$

$$1) b) A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} \text{ and } \vec{b} = \begin{bmatrix} 4 \\ 4 \\ 6 \end{bmatrix}. \text{ We also have } A^T = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\text{So } A^T A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 3 \end{bmatrix} \text{ and } A^T \vec{b} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 4 \\ 4 \\ 6 \end{bmatrix} = \begin{bmatrix} 8 \\ 14 \end{bmatrix}$$

$$\text{So we need to solve } \begin{bmatrix} 2 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 8 \\ 14 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 2 & 2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 8 \\ 6 \end{bmatrix} \Rightarrow \boxed{\hat{x} = \begin{bmatrix} -2 \\ 6 \end{bmatrix}}$$

$$\text{Therefore } \vec{p} = A\hat{x} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -2 \\ 6 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \\ 6 \end{bmatrix} = \vec{b}$$

$$\text{We get } \vec{e} = \vec{b} - \vec{p} = \vec{0}$$

$$13) A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$$

$$C(A) = \mathbb{R}^3, \text{ so } \vec{p} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix} \text{ and } \vec{e} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}. \text{ Therefore } P = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \text{ (we remove the last coordinate of } \vec{b} \text{)}$$

$$21) P = A(A^T A)^{-1} A^T$$

$$\Rightarrow P^2 = A(A^T A)^{-1} A^T \cdot A(A^T A)^{-1} A^T$$

$$= A(A^T A)^{-1} A^T$$

$$= P$$

Geometrically, when we do $P\vec{b}$, we project \vec{b} onto \vec{a} , so $P\vec{b}$ is on \vec{a} . Therefore, by ~~even~~ any further projections won't do anything i.e. $P(P\vec{b}) = P\vec{b}$, so $P^2 = P$. The vector $P\vec{b}$ is in the column space so its projection is itself.

Problem set 4.3)

$$1) \text{ We have } A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \\ 1 & 4 \end{bmatrix} \text{ and } \vec{b} = \begin{bmatrix} 0 \\ 8 \\ 8 \\ 20 \end{bmatrix}. \text{ So } A^T = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 3 & 4 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 4 & 8 \\ 8 & 26 \end{bmatrix} \text{ and } A^T \vec{b} = \begin{bmatrix} 36 \\ 112 \end{bmatrix}$$

$$\text{So we need to solve } \begin{bmatrix} 4 & 8 \\ 8 & 26 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 36 \\ 112 \end{bmatrix} \Rightarrow \begin{bmatrix} 4 & 8 \\ 0 & 10 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 36 \\ 40 \end{bmatrix} = \hat{x} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

So the best straight line, we get ~~$b = 1 + 4t$~~ $b = 1 + 4t$

$$\text{therefore, from figure 4.9, we get } \begin{cases} p_1 = 1 + 4 \cdot 0 = 1 \\ p_2 = 1 + 4 \cdot 1 = 5 \\ p_3 = 1 + 4 \cdot 3 = 13 \\ p_4 = 1 + 4 \cdot 4 = 17 \end{cases} \Rightarrow \begin{cases} e_1 = |1 - 0| = 1 \\ e_2 = |5 - 8| = 3 \\ e_3 = |13 - 8| = 5 \\ e_4 = |17 - 20| = 3 \end{cases}$$

12) a) $\vec{a}^T \vec{a} = m$ and $\vec{a}^T \vec{b} = \sum_{i=1}^m b_i$
 So $\vec{a}^T \vec{a} \hat{x} = \vec{a}^T \vec{b} \Leftrightarrow m \hat{x} = \sum_{i=1}^m b_i \Leftrightarrow \hat{x} = \frac{\sum_{i=1}^m b_i}{m}$. \hat{x} is the mean of the b_i 's.

b) $\vec{e} = \vec{b} - \vec{a} \hat{x} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix} - \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \hat{x} = \begin{bmatrix} b_1 - \hat{x} \\ \vdots \\ b_m - \hat{x} \end{bmatrix}$

So $\|\vec{e}\|^2 = (b_1 - \hat{x})^2 + \dots + (b_m - \hat{x})^2 = \sum_{i=1}^m (b_i - \hat{x})^2$

and $\|\vec{e}\| = \sqrt{(b_1 - \hat{x})^2 + \dots + (b_m - \hat{x})^2} = \sqrt{\sum_{i=1}^m (b_i - \hat{x})^2}$

c) $\vec{e} = \vec{b} - \vec{p} = \begin{bmatrix} 1 \\ 2 \\ 6 \end{bmatrix} - \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix} = \begin{bmatrix} -2 \\ -1 \\ 3 \end{bmatrix}$ and $\vec{e} \cdot \vec{p} = -2 \cdot 3 + 1 \cdot 3 + 3 \cdot 3 = 0$ so $\vec{e} \perp \vec{p}$.

We have $A = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, and $P = A(A^T A)^{-1} A^T$. $A^T A = 3$, $(A^T A)^{-1} = \frac{1}{3}$

So $P = \frac{1}{3} A A^T = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix}$.

16) If we know the average \hat{x}_9 of b_1, \dots, b_9 , we can quickly find the average \hat{x}_{10} with one more number b_{10} by doing the following calculation

$\boxed{\hat{x}_{10} = \frac{9}{10} \hat{x}_9 + \frac{1}{10} b_{10}}$ $\frac{9}{10}$ multiplies \hat{x}_9 in computing \hat{x}_{10} .

~~26) We need to solve~~ ~~$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & -1 & 0 \\ 1 & 0 & -1 \end{bmatrix} \vec{x} = \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix}$~~

~~$\begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & -1 & 0 & 0 \\ 1 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & -1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & -2 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix}$~~

26) We have $A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & -1 & 0 \\ 1 & 0 & -1 \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix}$. So $A^T = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{bmatrix}$

$A^T A = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ and $A^T \vec{b} = \begin{bmatrix} 8 \\ -3 \\ -3 \end{bmatrix}$

So we need to solve $\begin{bmatrix} 4 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ -3 \\ -3 \end{bmatrix} \Rightarrow \hat{x} = \begin{bmatrix} 2 \\ -3/2 \\ -3/2 \end{bmatrix}$

At the center of the square, we get $2 + (-3/2) \cdot 0 + (-3/2) \cdot 0 = 2 = \frac{0+1+3+4}{4}$

$$\| \hat{x} - d \|_2^2 = (\hat{x}_1 - d_1)^2 + \dots + (\hat{x}_n - d_n)^2 = \| \hat{x} - d \|_2^2$$

$$\| \hat{x} - d \|_2^2 = (\hat{x}_1 - d_1)^2 + \dots + (\hat{x}_n - d_n)^2 = \| \hat{x} - d \|_2^2$$

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\frac{1}{2} = \frac{1}{2} (A^T A) \quad \hat{x} = A^T A \quad \text{and} \quad \frac{1}{2} = \frac{1}{2} (A^T A) \quad \text{and} \quad \frac{1}{2} = \frac{1}{2} (A^T A)$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix}$$

$$\hat{x} = \frac{1}{2} A^T A \quad \hat{x} = \frac{1}{2} A^T A \quad \hat{x} = \frac{1}{2} A^T A$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = A^T A$$