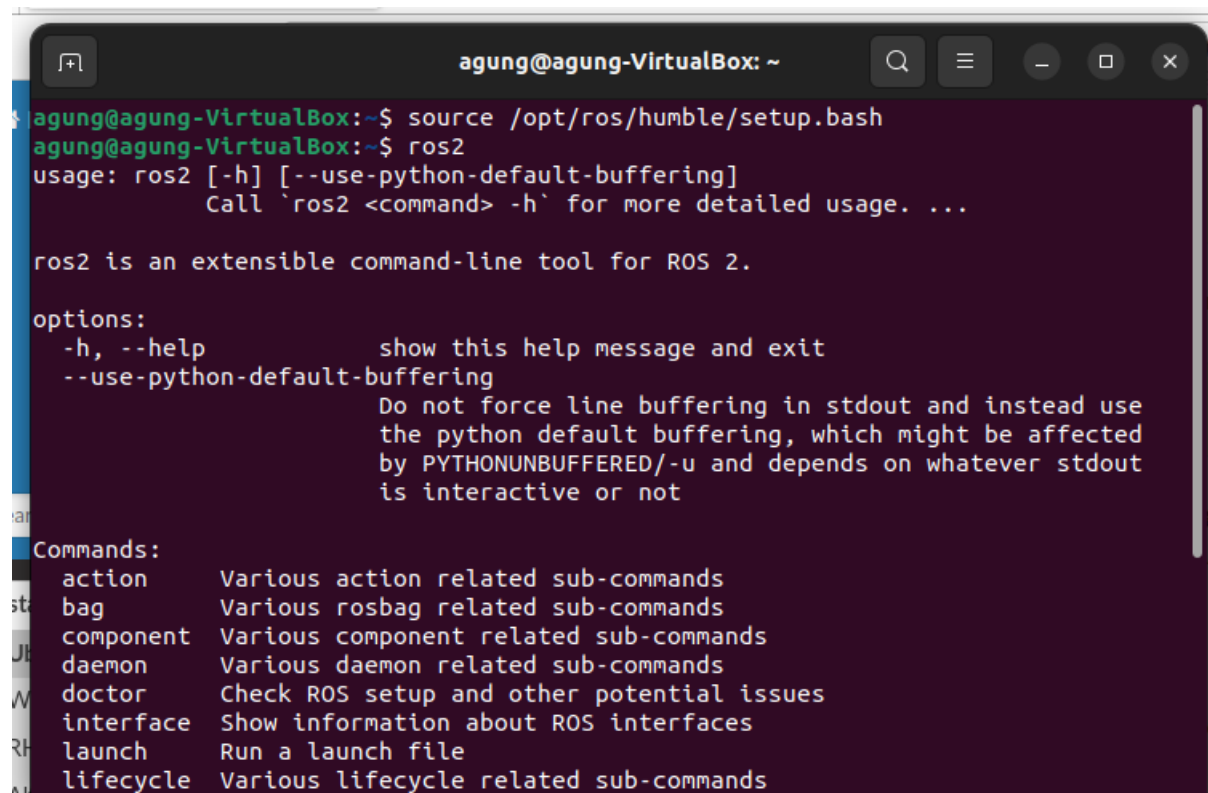


Ros2



A terminal window titled 'agung@agung-VirtualBox: ~' showing the execution of ROS2 setup and help commands. The user sources the setup script and then runs 'ros2', which displays usage information and a list of sub-commands.

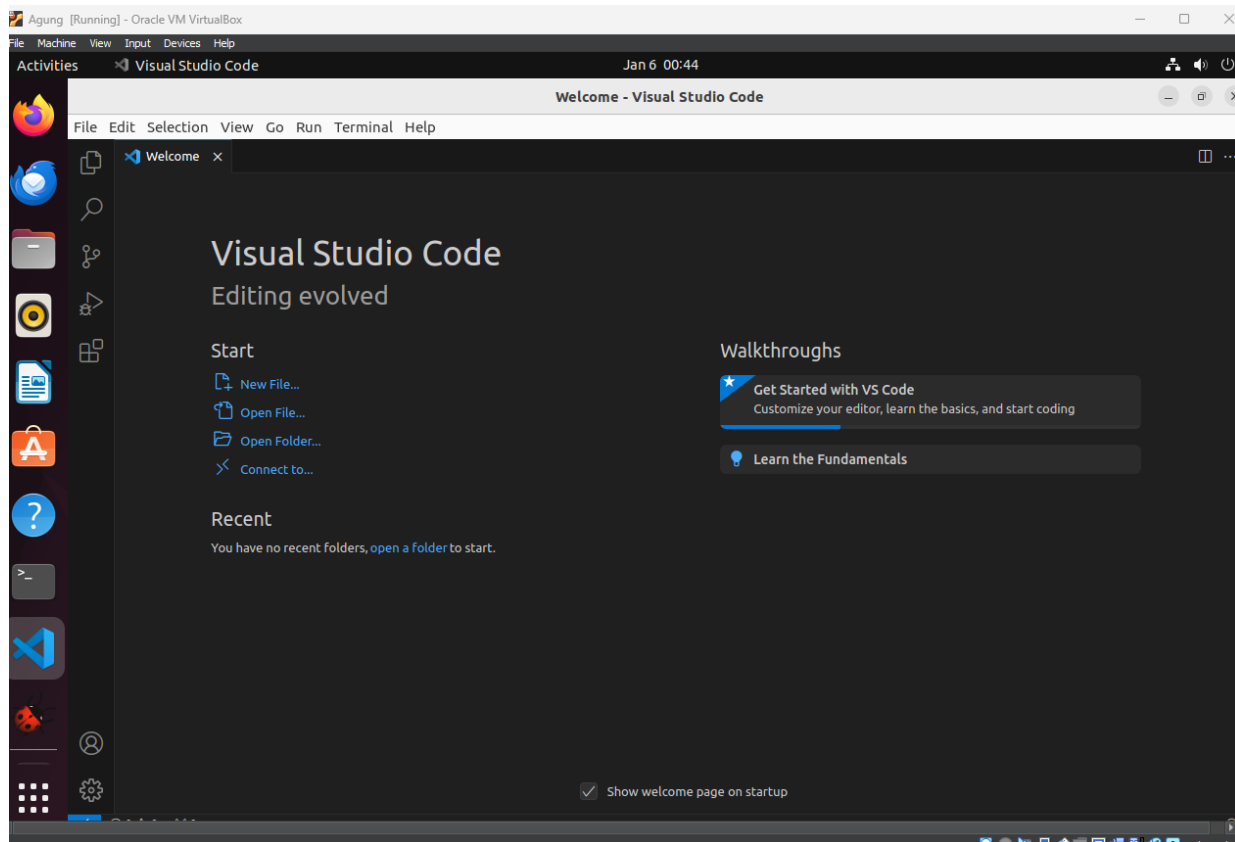
```
agung@agung-VirtualBox:~$ source /opt/ros/humble/setup.bash
agung@agung-VirtualBox:~$ ros2
usage: ros2 [-h] [--use-python-default-buffering]
          Call 'ros2 <command> -h' for more detailed usage. ...

ros2 is an extensible command-line tool for ROS 2.

options:
  -h, --help            show this help message and exit
  --use-python-default-buffering
                        Do not force line buffering in stdout and instead use
                        the python default buffering, which might be affected
                        by PYTHONUNBUFFERED/-u and depends on whatever stdout
                        is interactive or not

Commands:
  action                Various action related sub-commands
  bag                   Various rosbag related sub-commands
  component             Various component related sub-commands
  daemon               Various daemon related sub-commands
  doctor                Check ROS setup and other potential issues
  interface             Show information about ROS interfaces
  launch                Run a launch file
  lifecycle              Various lifecycle related sub-commands
```

Vs code



Weboots

