

Name: \_\_\_\_\_

**ENG ME403**

## Atmospheric Flight Mechanics, Class Project

<b>Introduction (10)</b>	<input type="checkbox"/> Brief description of the aircraft, including its purpose (fighter, passenger, etc.) its history, and its manufacturer <input type="checkbox"/> Clearly state whether you will focus on longitudinal or lateral dynamics
<b>Correct First Report (25)</b>	<input type="checkbox"/> Dynamic Characteristics – tables eigenvalues, eigenvectors/mode shapes. <input type="checkbox"/> Comparison to acceptable ranges in Nelson's text. Flying Performance level assessment. <input type="checkbox"/> Compare eigenvalues to approximate formulae <input type="checkbox"/> Plot transient responses (all 4) to more than one set of initial conditions. <input type="checkbox"/> All tables of contents use section and subsection headings. <input type="checkbox"/> Describe in words, with as few equations as possible, what was done <input type="checkbox"/> Proposed control system (for first report)
<b>Define control objective (15)</b>	<input type="checkbox"/> May include simulation results of stick-fixed flying to demonstrate dynamic behavior of system, goal of control system. <input type="checkbox"/> If relevant, give a quantitative description of the control objective in terms of flying qualities and modal properties, such as damping factors and periods.
<b>Feedback Controller Design (25)</b>	<input type="checkbox"/> Design a control system to achieve the performance objective <input type="checkbox"/> Show by analysis and simulation that you have (or have not) achieved the objective. <input type="checkbox"/> Try using the same feedback for a different flight condition, and see if the performance is still improved. <input type="checkbox"/> Identify your transfer function $G(s)$ <ul style="list-style-type: none"> <li>○ Why did you choose it?</li> <li>○ Document its calculation</li> <li>○ Compute step response</li> </ul> <input type="checkbox"/> Describe the goal of your control effort <input type="checkbox"/> Create and describe a root locus plot of your $G(s)$ for proportional control <input type="checkbox"/> Choose at least two control strategies (e.g. phase lead, PID). <input type="checkbox"/> Implement your control strategy <ul style="list-style-type: none"> <li>○ Compute step response</li> <li>○ Compute performance metrics</li> <li>○ Compute steady-state errors</li> </ul>
<b>Appendix (15)</b>	<input type="checkbox"/> Table of plane parameters & stability derivatives, source cited <input type="checkbox"/> Include calculation for remaining coefficient needed for equations of motion. Justify any neglected quantities. <input type="checkbox"/> Matlab scripts
<b>Overall Clarity and Presentation</b>	<input type="checkbox"/>
<b>Bonus</b>	<input type="checkbox"/> Nelson's Appendix <input type="checkbox"/> Lateral dynamics

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