DMOR Term Project (VRP & VRPTW)

This notebook was based on:

- X. Gan et al. Mathematical Problems in Engineering (2012).
- 2005 Book ColumnGeneration, Desaulnier
- https://github.com/agustingu/Cplex-Python (https://github.com/agustingu/Cplex-Python)

Data

- Set of costumers $N = \{1, 2, ..., n\}$, where n = 50 in this case.
- Set of vertices $V = \{0\} \cup N$, equal to the number of clients plus the depot located at (0,0).
- Set of arcs, $A = \{(i, j) \in V^2 : i \neq j\}$, i.e., all possible combinations of incoming and outgoing arcs excluding the case when i = j.
- Cost of traveling on each arc, c_{i,i} ∈ A. In this case the cost is relate to distance.
- Vehicle capacity, Q.
- Costumer demand, $q_i, \forall i \in N$.

Decision Variables

- Binary variable $x_{i,j}$ for when the arc is use (1); (0) otherwhise.
- Cummulative demand of costumer i, MTZ notation $u_i \ \forall i \in N$
- Indicator variable for time

IVRs

• Decision variable is binary $x_{i,j} \in \{0,1\}, \forall i,j \in A$.

Constraints

Each customer vertex is connected to two other vertices, which are its predecessor and successor:

 From each node we can only visit only one node, e.g., if I'm in node 2 I can only visit 1 node $\{0,1,3,..n\}.$

$$\sum_{i \in V, j \neq i} x_{i,j} = 1, \ \forall j \in N$$

 Each node could only be visisted from one node, e.g., if I'm in node 2 I can only be visited from node {0,1,3,..n}.

$$\sum_{j \in V, i \neq j} x_{i,j} = 1, \ \forall i \in N$$

- According to the literature if one arc is active, the cumulative demant until j point is the demand up to the previous node.
- · Number of vehicles leaving the depot or (DC) is the same as entering

$$\sum_{i \in V} x_{i0} = K$$

$$\sum_{i \in V} x_{0i} = K$$

$$\sum_{j \in V} x_{0j} = K$$

· Routes must be connected, demand on each rout should not exceed capacity

$$\sum_{i,j\in\mathcal{S}}\geq r(s),\ \forall S\subseteq\{N\},\ S\neq\phi$$

Replacing the previous three constraint by MTZ notation proposed by Christofides, Mingozzi and Toth we have:

if
$$x_{i,j} = 1 \implies u_i + q_j = u_j \ i, j \in A : j \neq 0, i \neq 0$$

$$q_i \leq u_i \leq Q, \ \forall i \in N$$

This last indicator constraint imposed the capacity and connectivity constraints

• If xij==1 the cummulative in uj = cum (ui) prev node + demand at node j qj

Algebraic Notation of VRP

$$\begin{aligned} & \min \quad & \sum_{i,j \in A} c_{ij} x_{ij} \\ & \text{s.t.} \quad & \sum_{i \in V, j \neq i} x_{i,j} = 1, \ \forall j \in N \\ & \sum_{j \in V, i \neq j} x_{i,j} = 1, \ \forall i \in N \\ & \text{if } x_{i,j} = 1 \ \Rightarrow \ u_j = u_i + q_j \ \forall (i,j) \in A : j \neq 0, i \neq 0 \\ & q_i \leq u_i \leq Q, \ \forall i \in N \\ & x_{i,j} \in \{0,1\}, \forall i,j \in A \end{aligned}$$

Data Creation

```
In [21]: # Load data
filename = '../Data.csv'
df = pd.read_csv(filename)
df.info()
```

<class 'pandas.core.frame.DataFrame'>
RangeIndex: 50 entries, 0 to 49
Data columns (total 8 columns):

#	Column	Non-Null Count	Dtype
0	Node No.	50 non-null	int64
1	X	50 non-null	float64
2	Υ	50 non-null	float64
3	demand (pounds)	50 non-null	int64
4	service-time	50 non-null	object
5	<pre>time-window(start; h:m)</pre>	50 non-null	object
6	<pre>time-window(end; h:m)</pre>	50 non-null	object
7	Can this demand be split	50 non-null	object

dtypes: float64(2), int64(2), object(4)

memory usage: 3.2+ KB

Out[22]:

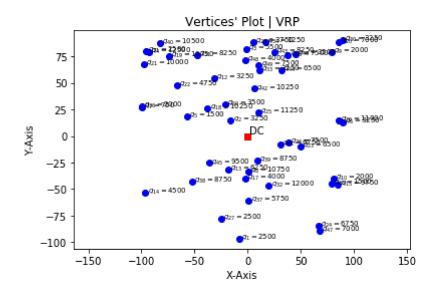
	Node No.	x	Y	demand (pounds)	service- time	time- window(start; h:m)	time- window(end; h:m)	Can this demand be split
0	1	-8.20	-96.68	2500	0:02	3:42	3:54	Υ
1	2	-16.01	14.95	3250	0:03	22:58	23:53	N
2	3	-1.26	82.05	5500	0:05	18:35	18:56	N
3	4	-93.17	78.92	12500	0:10	21:29	21:52	Υ
4	5	-57.10	18.67	1500	0:02	10:56	11:38	N

```
In [23]:
         ▶ # Set of costumer n in N
             N = df.loc[:, 'Node No.'].values.tolist()
             # Set of Vertices
             V = [0] + N
             # demand per node or costumer
             demand = df.loc[:, "demand (pounds)"].values.tolist()
             # Trick capacity in pounds
             Q = 20000
             # Dictionary demand for each costumer
             q = {i: (demand[i-1]) for i in N}
             # Nodes coordinates
             x = df.loc[:, "X"].values
             y = df.loc[:, "Y"].values
             # Insert distribution center coordinates at 0,0
             loc_x = np.insert(x, 0, 0)
             loc_y = np.insert(y, 0, 0)
             # Travel cost
             t_cost = 3
```

Plotting Vertices

```
In [24]:
             # Plot vertices
             plt.scatter(loc_x[1:], loc_y[1:], c='b')
             # Add Labels
             for i in N:
                 plt.annotate('$q_{%d}=%d$' % (i, q[i]), (loc_x[i]+2, loc_y[i]),
                               fontsize=7)
             plt.annotate('DC',(loc_x[0]+2,loc_y[0]+2))
             # Highlight depot
             plt.plot(loc_x[0], loc_y[0], c='r', marker='s')
             # Add axis
             plt.axis('equal')
             plt.xlabel("X-Axis")
             plt.ylabel("Y-Axis")
             # Add title
             plt.title("Vertices' Plot | VRP")
             # Save plot
             # plt.savefig("VRP_Plot", dpi=300, bbox_inches='tight')
```

Out[24]: Text(0.5, 1.0, "Vertices' Plot | VRP")



Data Structure for Arcs and Distances

Model

Variables

$$x_{i,j}$$

$$u_i, \ \forall i \in N$$

min
$$\sum_{i,j\in A} c_{ij} x_{ij}$$
s.t.
$$\sum_{i\in V, j\neq i} x_{i,j} = 1, \ \forall j\in N$$

$$\sum_{j\in V, i\neq j} x_{i,j} = 1, \ \forall i\in N$$
if $x_{i,j} = 1 \Rightarrow u_i + q_j = u_j \ \forall (i,j) \in A: j\neq 0, i\neq 0$

$$q_i \leq u_i \leq Q, \ \forall i\in N$$

$$x_{i,j} \in \{0,1\}, \forall i,j\in A$$

Objective

$$\min \quad \sum_{i,j \in A} c_{ij} x_{ij}$$

Constrainst

s.t.
$$\sum_{i \in V, j \neq i} x_{i,j} = 1, \ \forall j \in N$$

$$\sum_{j \in V, i \neq j} x_{i,j} = 1, \ \forall i \in N$$
 if $x_{i,j} = 1 \Rightarrow u_i + q_j = u_j \ i, j \in A : j \neq 0, i \neq 0$
$$q_i \leq u_i \leq Q, \ \forall i \in N$$

$$x_{i,j} \in \{0, 1\}, \forall i, j \in A$$

```
In [28]:
             # Constraints for enetering an Leaving
             mdl.add_constraints(mdl.sum(x[i, j] for j in V if j != i) == 1 for i in N)
             mdl.add_constraints(mdl.sum(x[i, j] for i in V if i != j) == 1 for j in N)
             # Indicator constraints for capacity and continuity
             mdl.add_indicator_constraints(mdl.indicator_constraint(x[i, j], u[i]+q[j] ==
             # Indicator constraint qi<=ui
             mdl.add_constraints(u[i] >= q[i] for i in N)
             print(mdl.export_to_string())
              0 <= x 34 40 <= 1
              0 <= x_17_32 <= 1
              0 <= x_37_45 <= 1
              0 <= x 23 14 <= 1
              0 <= x_45_29 <= 1
              0 <= x_10_1 <= 1
              0 <= x_35_27 <= 1
              0 <= x 0 23 <= 1
              0 <= x_38_4 <= 1
              0 <= x 25 17 <= 1
              0 <= x_14_45 <= 1
              0 <= x_1_8 <= 1
              0 <= x_39_31 <= 1
              0 <= x 4 3 <= 1
              0 <= x_26_48 <= 1
              0 <= x 29 5 <= 1
              0 <= x 16 6 <= 1
              0 <= x_2_41 <= 1
              0 <= x 41 2 <= 1
                /_ V 22 // /_ 1
In [42]:
          # Time limit and solving the model
             mdl.parameters.timelimit = 120
             solution = mdl.solve(log_output=True)
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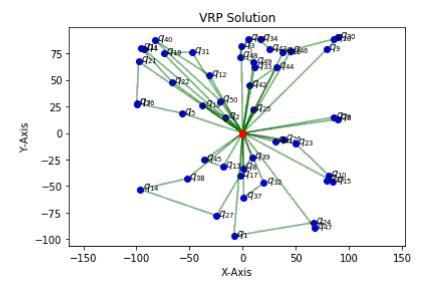
In [44]:

```
▶ solution.display()
In [43]:
               solution for: VRPTW
               objective: 9776.813
               x_9_0 = 1
               x_16_20 = 1
               x_23_0 = 1
               x_35_10 = 1
               x_48_3 = 1
               x_21_7 = 1
               x_30_9 = 1
               x_31_19 = 1
               x_24_1 = 1
               x_6_0 = 1
               x_0_{49} = 1
               x_0_8 = 1
               x_8_{39} = 1
               x_0_15 = 1
               x 19 0 = 1
              x_0^- 0_2^- 0_2^- 0_2^- 0_2^- 0_2^-
               x_38_14 = 1
```

Out[44]: <JobSolveStatus.FEASIBLE_SOLUTION: 1>

▶ solution.solve_status

```
In [45]:
             # Actives arcs
             active_arcs = [a for a in A if x[a].solution_value > 0.9]
             plt.scatter(loc_x[1:], loc_y[1:], c='b')
             # add Labels to each node
             for i in N:
                 plt.annotate('$q_{%d}$' % (i,), (loc_x[i]+2, loc_y[i]))
             # plot arcs
                 for i, j in active_arcs:
                     plt.plot([loc_x[i], loc_x[j]], [loc_y[i], loc_y[j]], c='g', alpha=0.@
             plt.plot(loc_x[0], loc_y[0], c='r', marker='s')
             plt.axis('equal')
             # Add axis
             plt.axis('equal')
             plt.xlabel("X-Axis")
             plt.ylabel("Y-Axis")
             # Add title
             plt.title("VRP Solution")
             # Save plot
             plt.savefig("VRP_Solved", dpi=300, bbox_inches='tight')
```



```
In [33]: ▶ active_arcs
```

```
Out[33]: [(25, 3),
           (40, 11),
           (23, 0),
           (35, 10),
           (36, 0),
           (21, 7),
           (31, 19),
           (24, 1),
           (6, 0),
           (0, 49),
           (0, 8),
           (8, 39),
           (0, 15),
           (19, 0),
           (0, 29),
           (38, 14),
           (47, 24),
           (17, 0),
           (2, 0),
           (0, 45),
           (9, 20),
           (44, 0),
           (42, 44),
           (15, 35),
           (11, 5),
           (0, 46),
           (28, 33),
           (7, 36),
           (10, 23),
           (49, 48),
           (0, 31),
           (0, 22),
           (4, 2),
           (29, 6),
           (18, 50),
           (39, 0),
           (43, 34),
           (0, 47),
           (32, 37),
           (0, 38),
           (27, 17),
           (37, 0),
           (0, 25),
           (0, 16),
           (50, 0),
           (26, 41),
           (22, 21),
           (5, 0),
           (48, 0),
           (14, 27),
           (33, 0),
           (0, 32),
           (3, 0),
           (0, 12),
           (34, 28),
```

```
(0, 26),
(16, 9),
(1, 0),
(30, 0),
(20, 30),
(0, 42),
(12, 40),
(0, 4),
(13, 0),
(46, 43),
(0, 18),
(41, 0),
(45, 13)]
```

Solution

The solution implemented in jupyter notebook and python was solved by using the cplex API for python. A feasible solution of \$9730.86 was found for the objective function, 18 routes were required which translate to a fix cost of $$300 \times 18 = 5400 . Therefore the total cost of the VRP with this solution is \$15130.86. The list below show the routes for each truck:

Routes No. Arcs

```
x 0 49=1,x 49 48=1,x 48 3=1,x 3 0=1,,
x 0 8=1,x 8 39=1,x 39 0=1,,,
x 0 22=1,x 22 21=1,x 21 7=1,x 7 36=1,x 36 0=1,
x 0 29=1,x 29 6=1,x 6 0=1,,,
x 0 15=1,x 15 35=1,x 35 10=1,x 10 23=1,x 23 0=1,
x \ 0 \ 31=1, x \ 31 \ 19=1, x \ 19 \ 0=1, \dots
x 0 47=1,x 47 24=1,x 24 1=1,x 1 27=1,x 27 0=1,
x_0_38=1,x_38_14=1,x_14_17=1,x_17_0=1,,
x_0_{12=1,x_12_40=1,x_40_2=1,x_20=1,,}
x \ 0 \ 18=1, x \ 18 \ 50=1, x \ 50 \ 0=1, \dots
x_0_45=1,x_45_13=1,x_13_0=1,,,
x_0_16=1,x_16_9=1,x_9_20=1,x_20_30=1,x_30_0=1,
x \ 0 \ 32=1, x \ 32 \ 37=1, x \ 37 \ 0=1, \dots
x_0_42=1,x_42_44=1,x_44_0=1,,,
x_0_46=1,x_46_43=1,x_43_34=1,x_34_28=1,x_28_33=1,x_33_0=1
x \ 0 \ 4=1, x \ 4 \ 11=1, x \ 11 \ 5=1, x \ 5 \ 0=1,
```