

# Advanced Macroeconomics II

## Handout 5 - Integration

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# Short recap

Prototypical DP problem:

$$\begin{aligned} V(k, z) &= \max_{\{c, k'\}} u(c) + \beta E \left[ V(k', z') | z \right] \\ \text{s.t. } c + k' &= f(k, z) \\ z' &= h(z, \eta); \eta \text{ stochastic} \end{aligned}$$

- ▶ We are looking for functions  $\mathbf{V}, \mathbf{g}^c, \mathbf{g}^k$ : We cannot solve this.

We need to solve an approximate problem:

- ▶ Approximate continuous function: **Interpolation**
  - ▶ Requires “exact” solution of maximization problem: **Optimization**
  - ▶ Requires computing expectations: **Integration**

# Integration - Many options

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1. Monte Carlo integration
2. Quadrature methods
3. Discretize state space
  - ▶ Tauchen (1986)
  - ▶ Tauchen & Hussey (1991)
  - ▶ Rouwenhorst (2008)
  - ▶ Gaussian mixture (i.a. Civalé, Diez-Catalan & Fazilet, 2017)

# Monte Carlo Integration

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- ▶ Idea: Exploit the law of large numbers

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n f(x_i) = E[f(x)] = \int f(x) dG(x)$$

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- ▶ Approximate your integral with a sum
- ▶ Key: Where to evaluate it... we need draws from  $x \sim G$ 
  - ▶ Actually, we need a lot of draws
  - ▶ Monte Carlo relies on large numbers to get relative frequencies right
  - ▶ If density of  $x \sim G$  at  $a$  is higher, there will be more draws  $x_i$  close to  $a$

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  - ▶ If density of  $x \sim G$  at  $a$  is higher, there will be more draws  $x_i$  close to  $a$
- ▶ Monte Carlo is generally costly, requires too many function evaluations.

# Monte Carlo integration - Expectations

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**Algorithm 1:** Expectation by Monte Carlo

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**input** : Number of seeds ( $N_0$ ) and number of candidates ( $N^*$ )

**output:**  $E[V(k', z') | z]$  with  $z' = h(z, \eta)$  and  $\eta \sim G$

1. Generate  $N$  random draws for  $\eta \sim G$ . Call them  $\{\eta_i\}_{i=1}^N$

**Note:** Do this once at the beginning of the code ;

**for**  $i=1:N$  **do**

2. Evaluate  $f_i = V(k', h(z, \eta_i))$

**Note:** This step requires interpolation of  $V$  in the  $z$  direction ;

3. Return average:  $E[V(k', z') | z] \approx \frac{1}{N} \sum_i f_i$
-

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- ▶ It is a good tool for other integrals
  - ▶ Model simulation (with and without heterogeneity)
- ▶ It is the easiest method to parallelize
  - ▶ Depends on your computational resources

# Quadrature Methods



# Gaussian Quadrature methods

- ▶ Idea: Approximate  $\int$  with  $\sum$ , like in Monte Carlo, but with less points

$$\int_a^b f(x) dx = \sum_{i=1}^N \omega_i f(x_i)$$

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**Note:** For equally spaced grid points and non-smooth functions use Romberg integration (see Numerical Recipes, Sec. 4.3)

# Gaussian Quadrature methods

**Objective:** Get a method with exact results for integrals of the type:

$$\int_a^b f(x) dx = \int_a^b W(x) h(x) dx = \sum_{i=1}^N w_i h(x_i)$$

where  $h(\cdot)$  is a polynomial and  $W(\cdot)$  is a weighting function

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- ▶ This method will give approximate results for functions ( $f$ ) that are well approximated by a polynomial ( $h$ ) times a weighting function ( $W$ )
- ▶ We only need that our original function satisfies:  $f(x) \approx W(x) h(x)$
- ▶ We can always choose  $W(x) = 1$  and then  $h(x) = f(x)$

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- ▶ We can always choose  $W(x) = 1$  and then  $h(x) = f(x)$
- ▶ We don't actually need to know  $h$ . We can define  $h(x) = f(x_i)/W(x_i)$ :

$$\int_a^b f(x) dx = \int_a^b W(x) h(x) dx \approx \sum_{i=1}^N \omega_i f(x_i) \quad \text{where } \omega_i = \frac{w_i}{W(x_i)}$$

# Gaussian Quadrature methods

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## Algorithm 2: Gaussian Quadrature

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**input** : Number of points  $N$ , integrand  $f$ , weighting function  $W$

**output**: Points  $\{x_i\}$ , weights  $\{\omega_i\}$ , integral  $\int_a^b f(x)dx \approx \sum_i \omega_i f(x_i)$

1. Choose a weighting function  $W$ ;
2. Construct the family of orthonormal polynomials wrt  $W$  up to degree  $N$ ;
3. Obtain roots of the polynomial of degree  $N$  in  $[a, b]$

These roots are the points  $\{x_i\}$  ;

4. Evaluate the auxiliary weights  $w_i = \frac{\langle p_{N-1} | p_{N-1} \rangle}{p_{N-1}(x_i) p'_N(x_i)}$

The weights we look for are  $\omega_i = \frac{w_i}{W(x_i)}$  ;

5. Evaluate the integral:  $\int_a^b f(x)dx \approx \sum_i \omega_i f(x_i)$
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See Numerical Recipes for more results (including weights)

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**Note:** Use Gauss-Hermite for integrating Gaussian shocks.

Let  $h(x) = \frac{1}{\sqrt{\pi}} V(k', h(z, \sqrt{2}\sigma_\eta x + \mu_\eta))$  and

$$W(x) = e^{-x^2} \propto \Phi(x)$$

Careful with extrapolation...  $x \in (-\infty, \infty)$

# Gaussian Quadrature - Problems

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- ▶ From NR: “[ $W(x)$  is ] ready to give high-order accuracy to integrands of the form polynomials times  $W(x)$ , and ready to *deny* high order accuracy to integrands that are otherwise perfectly smooth and well behaved.”
- ▶ Methods are not nested: going from  $N$  to  $N + 1$  changes all  $\{x_i, w_i\}$
- ▶ Bad performance when function has kinks, or doesn't look polynomial



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- ▶ This should be your go-to method
- ▶ Uses nested Gaussian quadrature to iteratively evaluate the integral
  - ▶ The nested part helps by reusing old function evaluations
- ▶ Provides a practical error bound from the change in the integral
- ▶ Better than Gaussian quadrature if function is not polynomial

# Discretizing the State Space

# General idea

- ▶ Instead of approximating the integral approximate the stochastic process
  - ▶ Discretize  $z$  (and  $h(z, \eta)$ ) instead of  $\eta$
  - ▶ Approximate process for  $z$  with a discrete Markov process

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- ▶ Instead of approximating the integral approximate the stochastic process
  - ▶ Discretize  $z$  (and  $h(z, \eta)$ ) instead of  $\eta$
  - ▶ Approximate process for  $z$  with a discrete Markov process
- ▶ Markov process characterized by:
  - ▶ Discrete state space:  $z \in \{z_1, \dots, z_N\}$
  - ▶ Transition matrix:  $\Pi = [\pi_{ij}]$ , s.t.  $\Pr(z' = z_j | z = z_i) = \pi_{ij}$ ,  $\sum_j \pi_{ij} = 1$

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  - ▶ Transition matrix:  $\Pi = [\pi_{ij}]$ , s.t.  $\Pr(z' = z_j | z = z_i) = \pi_{ij}$ ,  $\sum_j \pi_{ij} = 1$
- ▶ Compute expectation:

$$E \left[ V(k', z') | z = z_i \right] = \sum_{j=1}^N \pi_{ij} V(k', z_j)$$

**Note:** No approximation. No interpolation.

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## 1. Full blown estimation

- ▶ Set a grid for  $z$ :  $\{z_1, \dots, z_N\}$
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- ▶ Moments of  $z$  or moments of the model
- ▶  $N(N - 1)$  numbers to estimate

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## 2. Parametrize process for $z$

- ▶ Typical assumption is AR(1):  $z' = h(z, \eta) = \rho z + \eta$
- ▶ Use a method to choose  $\Pi$  to match properties of AR(1)
- ▶ Only have to choose  $\rho$  and  $\sigma_\eta$

# Tauchen (1986)

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- ▶ Start from an equally spaced grid centered at 0:  $\{z_1, \dots, z_N\}$ 
  - ▶ Heuristic: Extend grid  $\Omega$  standard deviations around mean

$$z_1 = -\Omega\sigma_\eta, \dots, z_n = z_{n-1} + \Delta_z, \dots, z_N = \Omega\sigma_\eta \quad \text{where: } \Delta_z = \frac{2\Omega\sigma_\eta}{N-1}$$

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- ▶ Usually  $\Omega = 3$ , but this depends on what you are modeling
- ▶ Fill in transition probabilities from normal distribution:

$$\pi_{ij} = \begin{cases} \Phi\left(\frac{z_j - \rho z_i + \Delta_z/2}{\sigma_\eta}\right) & \text{if } j = 1 \\ \Phi\left(\frac{z_j - \rho z_i + \Delta_z/2}{\sigma_\eta}\right) - \Phi\left(\frac{z_j - \rho z_i - \Delta_z/2}{\sigma_\eta}\right) & \text{if } j = 2, \dots, N-1 \\ 1 - \Phi\left(\frac{z_j - \rho z_i - \Delta_z/2}{\sigma_\eta}\right) & \text{if } j = N \end{cases}$$

# Tauchen (1986)

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## Algorithm 3: Tauchen (1986)

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**input** : Number of points  $N$ , width of grid  $\Omega$ , process parameters  $\rho, \sigma_\eta$

**output**: Discrete approximation of  $z' = \rho z + \eta$ ,  $\eta \sim N(0, \sigma_\eta)$ :  $z$  grid and  $\Pi$

1. Construct grid:  $z = \text{range}(-\Omega\sigma_\eta, \Omega\sigma_\eta, \text{length} = N)$ ,  $\Delta_z = 2\Omega\sigma_\eta/N-1$  ;

**for**  $i=1:N, j=1:N$  **do**

2. Fill in  $\pi_{ij}$  as:

$$\pi_{ij} = \begin{cases} \Phi\left(\frac{z_j - \rho z_i + \Delta_z/2}{\sigma_\eta}\right) & \text{if } j = 1 \\ \Phi\left(\frac{z_j - \rho z_i + \Delta_z/2}{\sigma_\eta}\right) - \Phi\left(\frac{z_j - \rho z_i - \Delta_z/2}{\sigma_\eta}\right) & \text{if } j = 2, \dots, N-1 \\ 1 - \Phi\left(\frac{z_j - \rho z_i - \Delta_z/2}{\sigma_\eta}\right) & \text{if } j = N \end{cases}$$

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- ▶ Without persistence (say  $z' \sim N(\mu, \sigma)$ ) we get:

$$E \left[ V(k', z') \right] = \int V(k', z') \phi \left( \frac{z' - \mu}{\sigma} \right) dz' \approx \sum_{j=1}^N \frac{w_j}{\sqrt{\pi}} V(k', \sqrt{2}\sigma x_j + \mu)$$

with  $\{x_i\}$  the roots of the Hermite polynomials and  $\{w_i\}$  the weights



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- ▶ With persistence we get:  $E \left[ V(k', z') | z \right] = \int V(k', z') \phi \left( \frac{z' - \rho z}{\sigma_\eta} \right) dz'$

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**Issue:** Conditional mean of  $z'$  varies with  $z$ .

- ▶ We would have to evaluate objective for different values with each  $z$

# Tauchen & Hussey (1991)

**Solution:** Express integral wrt unconditional normal, apply formula

$$\begin{aligned} E \left[ V \left( k', z' \right) | z \right] &= \int \left( V \left( k', z' \right) \frac{\phi \left( \frac{z' - \rho z}{\sigma_\eta} \right)}{\phi \left( \frac{z'}{\sigma_\eta} \right)} \right) \phi \left( \frac{z'}{\sigma_\eta} \right) dz' \\ &\approx \sum_{j=1}^N \frac{w_j}{\sqrt{\pi}} V \left( k', \sqrt{2} \sigma_\eta x_j \right) \frac{\phi \left( \frac{\sqrt{2} \sigma_\eta x_j - \rho z}{\sigma_\eta} \right)}{\phi \left( \frac{\sqrt{2} \sigma_\eta x_j}{\sigma_\eta} \right)} \end{aligned}$$

# Tauchen & Hussey (1991)

**Solution:** Express integral wrt unconditional normal, apply formula

$$E \left[ V(k', z') | z \right] = \int \left( V(k', z') \frac{\phi\left(\frac{z' - \rho z}{\sigma_\eta}\right)}{\phi\left(\frac{z'}{\sigma_\eta}\right)} \right) \phi\left(\frac{z'}{\sigma_\eta}\right) dz'$$
$$\approx \sum_{j=1}^N \frac{w_j}{\sqrt{\pi}} V(k', \sqrt{2}\sigma_\eta x_j) \frac{\phi\left(\frac{\sqrt{2}\sigma_\eta x_j - \rho z}{\sigma_\eta}\right)}{\phi\left(\frac{\sqrt{2}\sigma_\eta x_j}{\sigma_\eta}\right)}$$

► Fixed grid points:  $z_i = \sqrt{2}\sigma_\eta x_i$ , where  $\{x_i\}$  are Gauss-Hermite nodes

► Define  $\omega_i = w_i/\sqrt{\pi}$ , where  $\{w_i\}$  are Gauss-Hermite weights

► Probabilities:  $\pi_{ij} = \frac{\phi\left(\frac{z_j - \rho z_i}{\sigma_\eta}\right)}{\phi\left(\frac{z_j}{\sigma_\eta}\right)} \frac{\omega_i}{s_i}$ , where  $s_i = \sum_n \frac{\phi\left(\frac{z_n - \rho z_i}{\sigma_\eta}\right)}{\phi\left(\frac{z_n}{\sigma_\eta}\right)} \omega_i$

# Tauchen & Hussey (1991)

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## Algorithm 4: Tauchen & Hussey (1991)

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**input** : Number of points  $N$ , process parameters  $\rho, \sigma_\eta$

**output**: Discrete approximation of  $z' = \rho z + \eta$ ,  $\eta \sim N(0, \sigma_\eta)$ :  $z$  grid and  $\Pi$

1. Obtain Gauss-Hermite nodes and weights  $\{x, w\}$  ;

2. Define grid as  $z_i = \sqrt{2}\sigma_\eta x_i$  ;

**for**  $i=1:N, j=1:N$  **do**

    3. Fill in  $\pi_{ij} = \frac{\phi\left(\frac{z_j - \rho z_i}{\sigma_\eta}\right)}{\phi\left(\frac{z_j}{\sigma_\eta}\right)} \frac{\omega_i}{s_i}$  where  $\omega_i = w_i/\sqrt{\pi}$  and  $s_i = \sum_n \frac{\phi\left(\frac{z_n - \rho z_i}{\sigma_\eta}\right)}{\phi\left(\frac{z_n}{\sigma_\eta}\right)} \omega_i$  ;

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**Steps:**

1. Construct a particular type of Markov Process
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## Steps:

1. Construct a particular type of Markov Process
  - ▶ Construction is recursive
2. Derive properties of the Markov Process
  - ▶ Find stationary distribution and conditional moments



# Rouwenhorst (1995)

**Objective:** Construct a Markov Process that matches moments of  $z'$

- ▶ Instead of starting from a grid and getting transition probabilities

## Steps:

1. Construct a particular type of Markov Process
  - ▶ Construction is recursive
2. Derive properties of the Markov Process
  - ▶ Find stationary distribution and conditional moments
3. Match moments from AR(1) process

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- ▶ Pick size of the grid:  $N \geq 2$
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- ▶ Construct transition matrix recursively:
$$\Pi_2 = \begin{bmatrix} p & 1-p \\ 1-q & q \end{bmatrix}$$
$$\Pi_N = p \begin{bmatrix} \Pi_{N-1} & \vec{0} \\ \vec{0}^T & 0 \end{bmatrix} + (1-p) \begin{bmatrix} \vec{0} & \Pi_{N-1} \\ 0 & \vec{0}^T \end{bmatrix} + (1-q) \begin{bmatrix} \vec{0}^T & 0 \\ \Pi_{N-1} & \vec{0} \end{bmatrix} + q \begin{bmatrix} 0 & \vec{0}^T \\ \vec{0} & \Pi_{N-1} \end{bmatrix}$$
where  $\vec{0}$  is an  $(N-1) \times 1$  zero vector. We need to find  $p$  and  $q$ .
- ▶ Divide all rows by 2 to ensure they sum to 1 (except top and bottom)

# Rouwenhorst (1995) - Moments

Results from Kopecky & Suen (2010)

Conditional Mean	$E[z'   z = z_i]$	$(q - p)\psi + (p + q - 1)z_i$
Conditional Var	$V[z'   z = z_i]$	$\frac{4\psi^2}{(N-1)^2} [(N-i)(1-p)p + (i-1)q(1-q)]$
Unconditional Mean	$E[z]$	$\frac{q-p}{2-(p+q)}\psi$
Unconditional Var	$V[z] = E[z^2]$	$\psi^2 \left[ 1 - 4s(1-s) + \frac{4s(1-s)}{N-1} \right]; \text{ where } s = \frac{1-q}{2-(p+q)}$
Autocovariance	$Cov[z', z]$	$(p + q - 1)V[z]$
Autocorrelation	$Corr[z', z]$	$p + q - 1$

Moreover, the stationary distribution is Binomial  $(N - 1, 1 - s)$ .

# Rouwenhorst (1995) - Matching the AR(1)

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- ▶ Unconditional moments:  $E[z] = 0 \quad V[z] = \frac{\sigma_\eta^2}{1-\rho^2}$
- ▶ Matching moments gives:

$$p = q \quad p + q - 1 = \rho \longrightarrow p = q = \frac{1 + \rho}{2}$$

$$\sigma_\eta^2 = \frac{4\psi^2}{(N-1)^2} [(N-i)(1-p)p + (i-1)q(1-q)] \longrightarrow \psi = \sqrt{N-1} \frac{\sigma_\eta}{\sqrt{1-\rho^2}}$$

# Rouwenhorst (1995)

---

**Algorithm 5:** Rouwenhorst (1995): Discretize AR(1)

---

**Function** Rouwenhorst( $N, \rho, \sigma_\eta$ ):

1. Define  $p = 1+\rho/2$  and  $\psi = \sigma_\eta \sqrt{N-1/1-\rho^2}$
2. Construct grid:  $z = \text{range}(-\psi, \psi, \text{length} = N)$ ,  $\Delta_z = 2\psi/N-1$
- if  $N==2$  then
  - 3.1. Define  $\Pi_2 = \begin{bmatrix} p & 1-p \\ 1-q & q \end{bmatrix}$
- else
  - 3.2.1.  $\Pi_{N-1} = \text{Rouwenhorst}(N-1, \rho, \sigma_\eta)$
  - 3.2.2.  $\Pi_N = p \begin{bmatrix} \Pi_{N-1} & \vec{0} \\ \vec{0}^T & 0 \end{bmatrix} + (1-p) \begin{bmatrix} \vec{0} & \Pi_{N-1} \\ 0 & \vec{0}^T \end{bmatrix} + (1-q) \begin{bmatrix} \vec{0}^T & 0 \\ \Pi_{N-1} & \vec{0} \end{bmatrix} + q \begin{bmatrix} 0 & \vec{0}^T \\ \vec{0} & \Pi_{N-1} \end{bmatrix}$
  - 3.2.3. Adjust intermediate rows to sum to 1
4. Bonus: Return stationary distribution  $G = \text{Binomial}(N-1, 1/2)$

# Gaussian Mixtures

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**Solution:** Use Gaussian Mixture Models

- ▶ Shocks come from a mixture of gaussian sources
- ▶ More sources of variation allow us to capture higher order moments

# Matching higher moments

Results from Civalé, Diez-Catalan & Fazilet (2015)

$$z' = \rho z + \eta \quad \text{where } \eta \sim \begin{cases} N(\mu_1, \sigma_1) & \text{with prob. } p \\ N(\mu_2, \sigma_2) & \text{with prob. } 1 - p \end{cases}$$

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- ▶ This process is flexible enough to generate skewness and kurtosis in  $\eta$ 
  - ▶ These properties are inherited by  $z$
- ▶ The process imposes constraints
  - ▶ Parameter  $\rho$  is key
  - ▶ Given  $\rho$  and moments of  $z$  we get moments of  $\Delta_k z$
  - ▶ Moments of  $\Delta_k z$  are often the target in the data

# How to use Gaussian mixtures

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**Bad news:** Results are sensitive to choice of state space grid

- ▶ Civale, Diez-Catalan & Fazilet (2015) propose optimizing over grid
  - ▶ They use the method of moments
- ▶ Process is incompatible with persistence of Skewness and Kurtosis
  - ▶ See Appendix B.2. where they propose a method to address this

# Gaussian mixtures - Very popular

Gaussian mixtures used widely, mostly for income fluctuation problems

- ▶ Housing Wealth Effects: The Long View (Guren, McKay, Nakamura, Steinsson, 2020)
- ▶ Time-Varying Idiosyncratic Risk and Aggregate Consumption Dynamics (McKay, 2017)
- ▶ Countercyclical Labor Income Risk and Portfolio Choices over the Life-Cycle (Catherine, 2020)
- ▶ Nonlinear household earnings dynamics, self-insurance, and welfare (DeNardi, Fella, Paz-Pardo, 2020)
- ▶ Monetary policy according to HANK (Kaplan, Moll, Violante, 2018)
  - ▶ Continuous time methods mixing a jump process for kurtosis

# Final Words on Methods

# Literature's take: Use Rouwenhorst



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- ▶ Three separate papers get to the same conclusion
  - ▶ Kopecky & Suen (2010)
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“A 5 point grid Rouwenhurst approximation is generally as accurate as a 25 grid point approximation with other methods”

  - ▶ Other methods suffer when  $\rho \rightarrow 1$ . Rouwenhorst suffers much less.
  - ▶ Rouwenhorst's design to match moments makes it better
  - ▶ Rouwenhorst does not target higher order moments, but still outperforms other methods at low grid sizes.

# An example

- ▶ Discretize  $z' = \rho z + \eta$ , where  $\eta \sim N(\mu_\eta, \sigma_\eta^2)$
- ▶ Choose  $\rho = 0.95$ ,  $\mu_\eta = 0$  and  $\sigma_\eta = 0.2$
- ▶ Simulate 10.000 periods of the Markov Chain

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	Exact		Tauchen			Rouwenhorst		
	Moments		N=5	N=11	N=21	N=5	N=11	N=21
$E[z]$	$\frac{\mu_\eta}{1-\rho}$	0	-0.01	-0.02	0.01	-0.03	0.00	0.01
$\sqrt{V[z]}$	$\frac{\sigma_\eta}{\sqrt{1-\rho^2}}$	0.64	0.40	0.38	0.37	0.65	0.63	0.63
$corr(z, z')$	$\rho$	0.95	0.87	0.88	0.88	0.95	0.95	0.95

# Relevant Extensions

- ▶ Correlated AR(1) process (like a VAR)
  - ▶ Galindev & Lkhagvasuren (2010)
  - ▶ Method reduces to decomposing covariance matrix to get independent shocks
  - ▶ Then apply a modified version of Rouwenhorst

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  - ▶ Fella, Gallipoli & Pan (2019)
  - ▶ Methods are extensions of Tauchen or Rouwenhorst
- ▶ Many other methods...Read the papers!



# Application:

## GE capitalist/union economy

# The economy: Two agents

## Capitalists:

- ▶ Infinitively lived derive utility from consumption:  $u(c) = c^{1-\gamma}/1-\gamma$
- ▶ Produce output with capital and labor (CRS technology):  $y = zk^\alpha \ell^{1-\alpha}$
- ▶ Use their own capital (no borrowing), hire labor in market at wage  $w$

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## Union:

- ▶ Infinitively lived derive utility from consumption:  $u(c) = c^{1-\gamma}/1-\gamma$
- ▶ Weird union preferences: Demand constant wage
- ▶ Union internalizes effect on wages and controls labor to adjust price
- ▶ Hand-to-mouth (no borrowing or savings)

# Capitalists

$$V(z, k; w) = \max_{\{c, k'\}} u(c) + \beta E \left[ V(z', k'; w') | z \right]$$

$$\text{s.t. } c + k' \leq \pi(z, k; w)$$

$$\pi(z, k; w) = \max_{\ell} z k^{\alpha} \ell^{1-\alpha} - w \ell + (1 - \delta) k$$

$$\log z' = \rho \log z + \eta; \quad \eta \sim N(0, \sigma_{\eta}^2)$$

Law of motion for wages (more on this later)

# Capitalists

$$V(z, k; w) = \max_{\{c, k'\}} u(c) + \beta E \left[ V(z', k'; w') \mid z \right]$$

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Law of motion for wages (more on this later)

- ▶ Note that capitalists have to take  $w$  as given
  - ▶ We will talk how to deal with this explicitly later
  - ▶ For now: leap of faith

# Capitalists - Profits

$$\pi(z, k; w) = \max_{\ell} z k^{\alpha} \ell^{1-\alpha} - w\ell + (1 - \delta) k$$

Optimal labor choice:

$$\ell^* = \left( \frac{1 - \alpha}{w} z \right)^{\frac{1}{\alpha}} k$$

Optimal profits:

$$\pi(z, k; w) = \left[ \underbrace{\alpha \left( \frac{1 - \alpha}{w} \right)^{\frac{1-\alpha}{\alpha}} z^{\frac{1}{\alpha}} + (1 - \delta)}_{\Gamma(z; w)} \right] k$$

# Capitalists - Homothetic-Homogeneous DP

We are in luck!

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- ▶ Particularly constraint is homogenous of degree 1

$$V(z, k; w) = \max_{\{c, k'\}} u(c) + \beta E \left[ V(z', k'; w') \mid z \right]$$
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$$\begin{aligned} V(z, k; w) &= \max_{\{c, k'\}} u(c) + \beta E \left[ V(z', k'; w') \mid z \right] \\ \text{s.t. } c + k' &\leq \Gamma(z; w) k \end{aligned}$$

- ▶ We can guess that the problem is separable in  $z$  and  $k$

$$V(z, k; w) = v(z; w) u(k)$$

# Capitalists - Guess and verify

$$V(z, k; w) = \max_{k'} \frac{(\Gamma(z; w)k - k')^{1-\gamma}}{1-\gamma} + \underbrace{\beta E \left[ v(z'; w') | z \right]}_{\Upsilon(z)} \frac{(k')^{1-\gamma}}{1-\gamma}$$

order condition:

$$\begin{aligned} (\Gamma(z; w)k - k')^{-\gamma} &= \Upsilon(z) (k')^{-\gamma} \\ \Gamma(z; w)k &= \left(1 + (\Upsilon(z))^{\frac{-1}{\gamma}}\right) k' \end{aligned}$$

function: Save a fraction of income

$$k' = \underbrace{\frac{\Upsilon(z)^{\frac{1}{\gamma}}}{1 + \Upsilon(z)^{\frac{1}{\gamma}}}}_{s(z; w)} \underbrace{\Gamma(z; w)k}_{\pi(z, k; w)}$$

## Capitalists - Guess and verify

$$v(z; w) \frac{k^{1-\gamma}}{1-\gamma} = ((1-s(z; w))\Gamma(z; w))^{1-\gamma} \frac{k^{1-\gamma}}{1-\gamma} + \Upsilon(z)(s(z; w)\Gamma(z; w))^{1-\gamma} \frac{k^{1-\gamma}}{1-\gamma}$$

$$v(z; w) = ((1-s(z; w))\Gamma(z; w))^{1-\gamma} + \Upsilon(z)(s(z; w)\Gamma(z; w))^{1-\gamma}$$

$$v(z; w) = \left[ (1-s(z; w))^{1-\gamma} + \Upsilon(z)s(z; w)^{1-\gamma} \right] \Gamma(z; w)^{1-\gamma}$$

$$v(z; w) = \left[ 1 + \Upsilon(z)^{\frac{1}{\gamma}} \right] \left( \frac{\Gamma(z; w)}{1 + \Upsilon(z)^{\frac{1}{\gamma}}} \right)^{1-\gamma}$$

$$v(z; w) = \left[ 1 + \Upsilon(z)^{\frac{1}{\gamma}} \right]^{\gamma} (\Gamma(z; w))^{1-\gamma}$$

$$v(z; w) = \left[ 1 + \left( \beta E \left[ v(z'; w') | z \right] \right)^{\frac{1}{\gamma}} \right]^{\gamma} (\Gamma(z; w))^{1-\gamma}$$

# Workers' Union

$$W = u(\bar{w}) + \beta W \longrightarrow W = \frac{1}{1 - \beta} u(\bar{w})$$

Not much to do here... sorry

# General equilibrium

Market clearing:

- ▶ Union sets  $\ell^s(z, k)$  such that:

$$w^* = (1 - \alpha) z \left( \frac{k}{\ell^s(z, k)} \right)^\alpha = \bar{w}$$

- ▶ Labor depends on  $z$  and  $k$ , but not wages

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- ▶ Labor depends on  $z$  and  $k$ , but not wages
- ▶ Capitalists do not take into account their effect on aggregate prices
- ▶ However, **we know** how capital and productivity affect prices

# Dynamic Programming: Final

$$v(z) = \left[ 1 + \left( \beta E \left[ v(z') | z \right] \right)^{\frac{1}{\gamma}} \right]^{\gamma} (\Gamma(z))^{1-\gamma}$$

where

$$\Gamma(z) = \alpha \left( \frac{1-\alpha}{\bar{w}} \right)^{\frac{1-\alpha}{\alpha}} z^{\frac{1}{\alpha}} + (1-\delta)$$

- Looks the same... but we dropped  $w$  as it is constant in equilibrium



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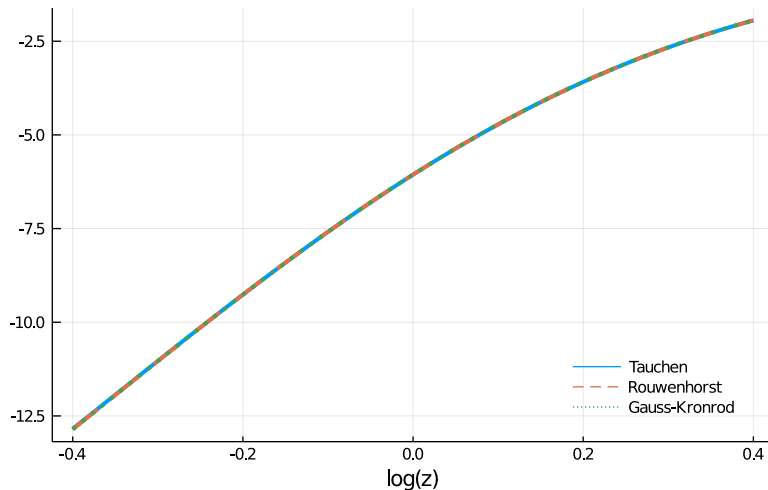
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- ▶ Looks the same... but we dropped  $w$  as it is constant in equilibrium
- ▶ To solve the dynamic programming problem we need to integrate
  - ▶ No max involved, only integrals

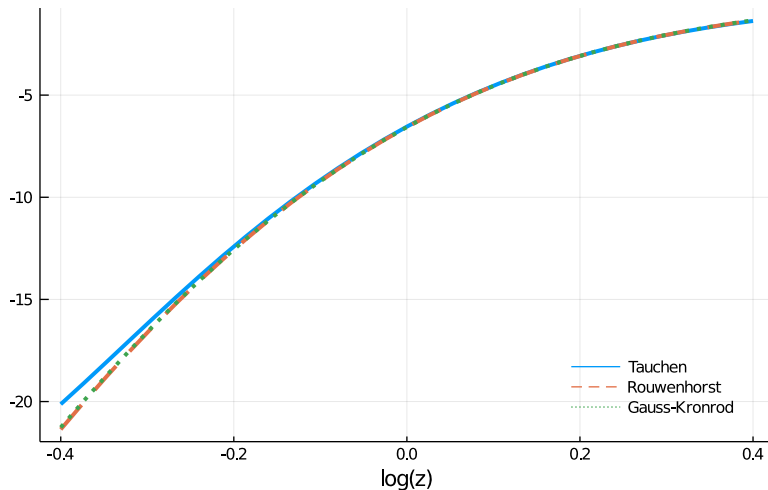
# Dynamic Programming: Result

Value Function:  $v(z)/(1-\gamma)$  -  $\rho=0.5$ ,  $N=31$



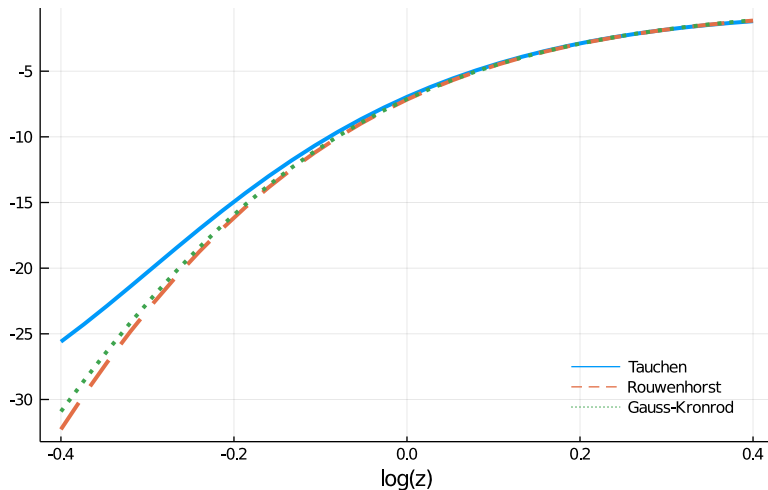
# Dynamic Programming: Result

Value Function:  $v(z)/(1-\gamma)$  -  $\rho=0.8$ ,  $N=31$



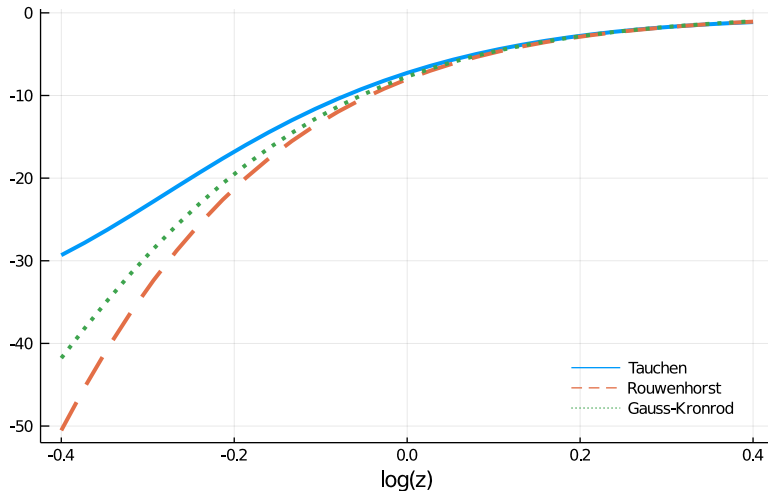
# Dynamic Programming: Result

Value Function:  $v(z)/(1-\gamma)$  -  $\rho=0.9$ ,  $N=31$



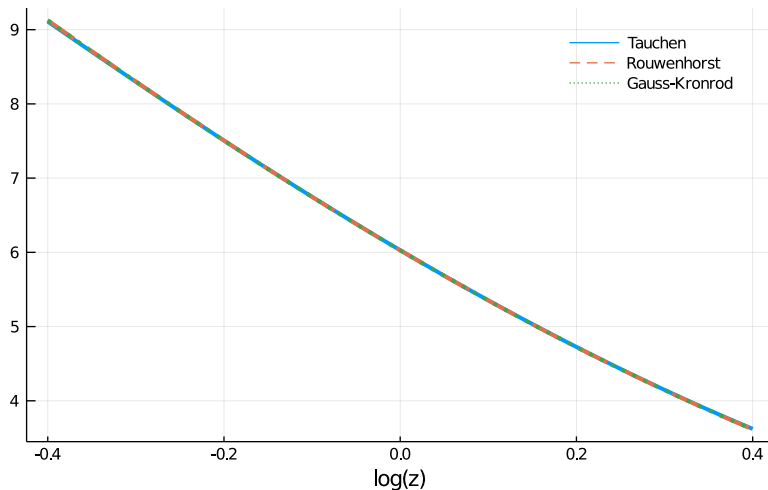
# Dynamic Programming: Result

Value Function:  $v(z)/(1-\gamma) - \rho=0.95, N=31$



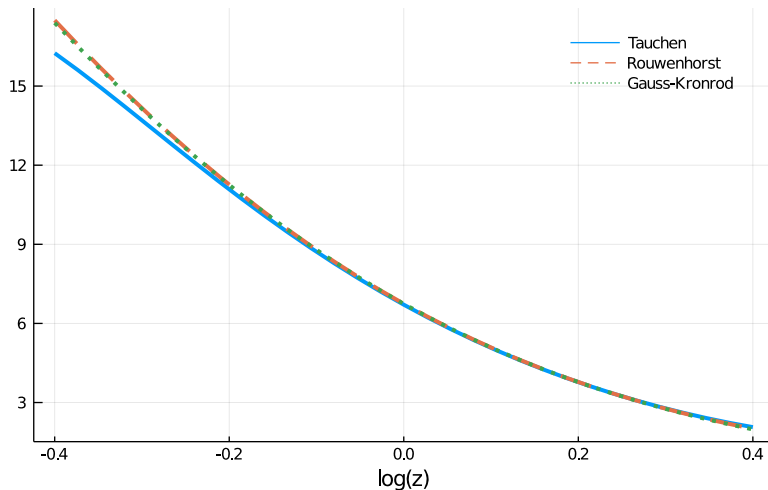
# Differences in expectations

Expectation:  $\beta E[v(z')|z] - \rho=0.5, N=31$



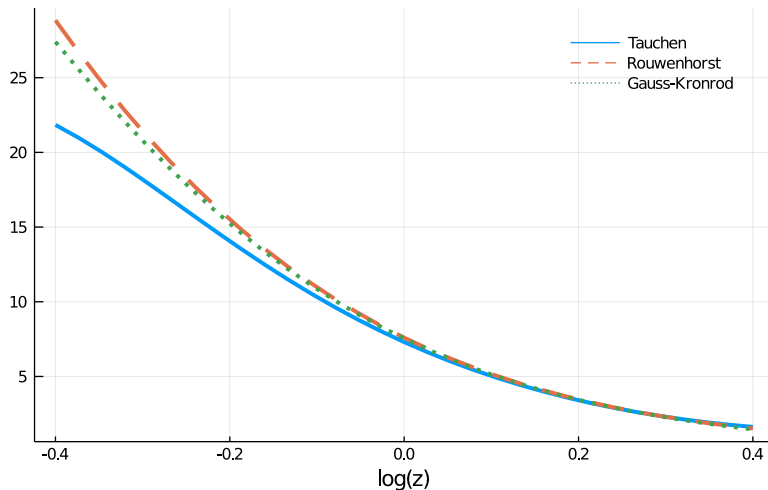
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Expectation:  $\beta E[v(z')|z] - \rho=0.8, N=31$



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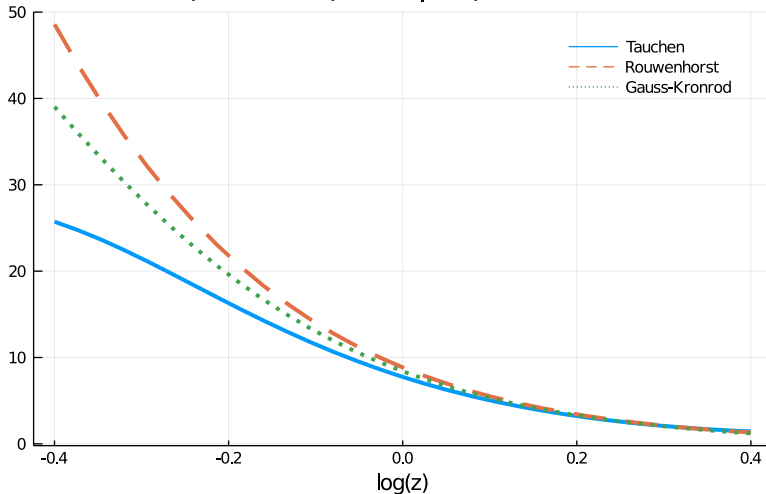
Expectation:  $\beta E[v(z')|z] - \rho=0.9, N=31$





# Differences in expectations

Expectation:  $\beta E[u(z')|z] - \rho = 0.95$ ,  $N=31$



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- ▶ Rouwenhorst vs Gauss-Kronrod
  - ▶ Hard to tell because GK uses a lot of extrapolation

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  - ▶ Differences in the expectations using Tauchen for  $\rho > 0.5$
- ▶ Rouwenhorst vs Gauss-Kronrod
  - ▶ Hard to tell because GK uses a lot of extrapolation
- ▶ Rouwenhorst seems like the best option
  - ▶ Computationally feasible
  - ▶ Reliable for high persistence values