

Here we discuss the DBSCAN Implementation in R.

## KENT STATE.

#### **DBSCAN** Implementations

- Two R packages have implemented DBSCAN clustering algorithm:
  - fpc and
  - dbscan
- There are few difference between these two implementations.
- 'dbscan' is a newer and computationally most efficient implementation.
- In addition 'factoextra' package can be used for visualizing clusters.
- As before these clusters should be installed using install.packages() method (e.g. install.packages('dbscan')) first and then the library should be called before using the functions.

All code for this module are available at https://github.com/KSU-MSBA/64060.git



R contains implementations of DBSCAN in the packages dbscan and fpc. Both packages support arbitrary distance functions via distance matrices. The package fpc does not have index support (and thus has quadratic runtime and memory complexity) and is rather slow due to the R interpreter. The package dbscan provides a fast C++ implementation using k-d trees (for Euclidean distance only) and also includes implementations of DBSCAN\*, HDBSCAN\*, OPTICS, OPTICSXi, and other related methods. For the most part, we will use dbscan. Remember to install the package before first use.

```
Library("dbscan")

library('factoextra')

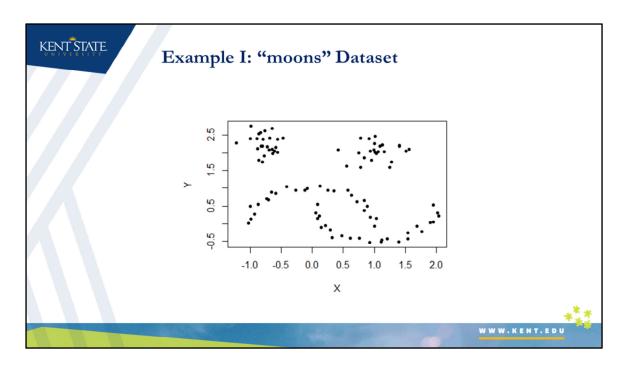
library('fpc')

#moons dataset Contains 100 2-D points, half of which are contained in two # moons or "blobs" (25 points each blob), and the other half in asymmetric # facing crescent shapes.

data("moons")

plot(moons, pch=20) # plot original data points
```

We now apply dbscan package to a sample dataset. Please see the github account for the code.



This data contains nonlinearity as well differing densities.

```
Example I: DBSCAN Implementation

db <- dbscan::dbscan(moons, eps = 0.5, minPts = 5) #perform clustering

print(db) #print cluster details

## DBSCAN clustering for 100 objects.

## Parameters: eps = 0.5, minPts = 5

## The clustering contains 3 cluster(s) and 0 noise points.

##

## 1 2 3

## 50 25 25

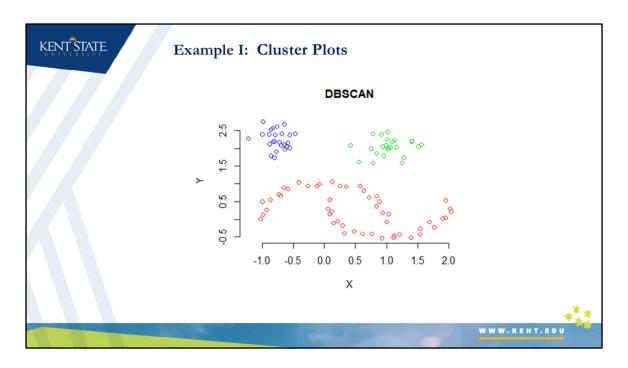
Clusters' Details

##

## Available fields: cluster, eps, minPts

plot(db, moons, main = "DBSCAN", frame = FALSE) #plot cluster details
```

The output from dbscan provides cluster details, which we can visualize using the plot command.



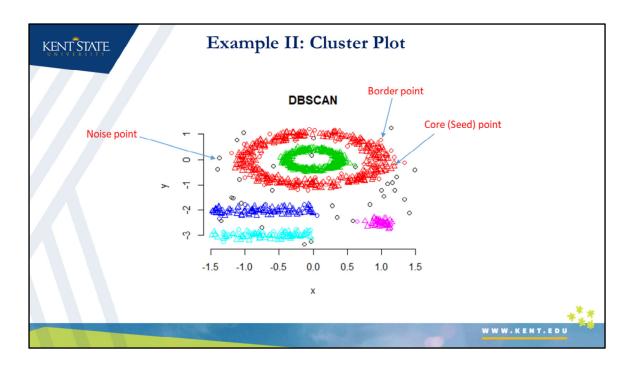
Clearly, dbscan has done well in identifying the clusters.

```
Example II: fpc Package
KENT STATE.
              library("dbscan")
              library('factoextra')
              library('fpc')
              df <- multishapes[, 1:2]</pre>
              set.seed(123)
              db <- fpc::dbscan(df, eps = 0.15, MinPts = 5) # DBSCAN using fpc package
              print(db) # show clusters' details
 Noise points
              ## dbscan Pts=1100 MinPts=5 eps=0.15
                        0 1 2 3 4 5
              ##
              ## border 31 24
                                 1
                        0 386 404 99 92 50

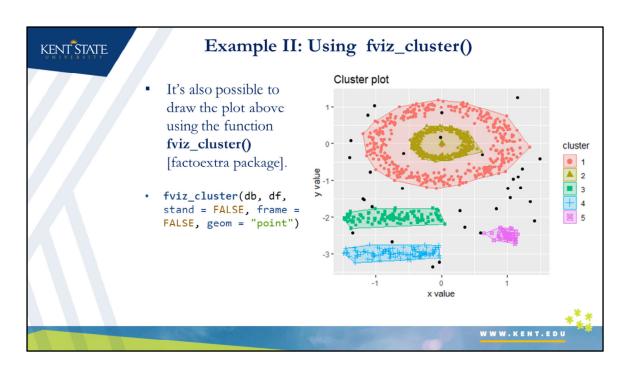
    Core (Seed) points for each cluster

              ## total 31 410 405 104 99 51
              # Plot DBSCAN results
              plot(db, df, main = "DBSCAN", frame = FALSE)
                                                                       WWW.KENT.EDL
```

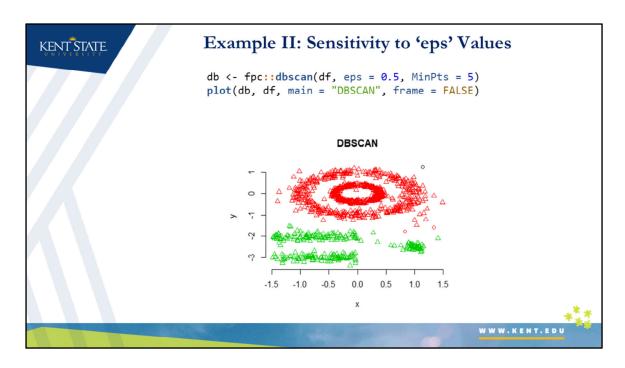
Now we apply the fpc package to a sample problem. The output identifies 31 border points. The values in the row seed indicate core points. A graphical depiction of this is shown in the next slide.



Noise, or outlier points are also identified as black circles in the graph.



An alternative way to depict the previous graph.



How do you choose eps? dbscan is sensitive to the choice of eps. Note here that there are fewer outliers and border points, in addition to fewer clusters.

## KENT STATE.

### Determining the Optimal 'eps' Value I

- The method proposed here consists of computing the *k*-nearest neighbor distances in a matrix of points.
- The idea is to calculate, the average of the distances of every point to its k nearest neighbors. The value of k will be specified by the user and corresponds to MinPts.



The method proposed here uses the concept of k-nearest neighbor distances. We calculate the average distance of every point to its k nearest neighbors. The value of k is chosen by the modeler and corresponds to MinPts. We will then plot these distances against the sampled points, and then identify the value at which there is a sharp change in values. This is similar to identifying the elbow when determining k in k-means.

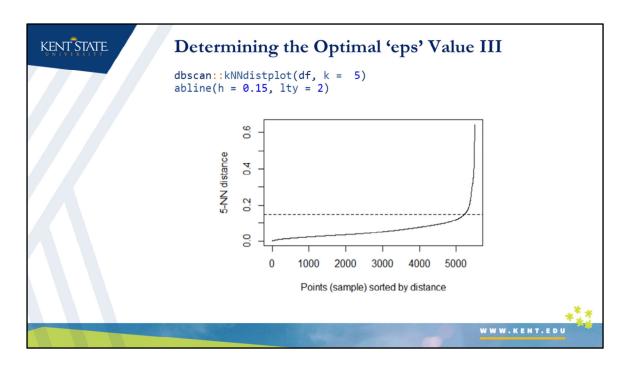
# KENT STATE

## Determining the Optimal 'eps' Value II

- Next, these *k*-distances are plotted in an ascending order. The aim is to determine the "knee", which corresponds to the optimal eps parameter.
- A knee corresponds to a threshold where a sharp change occurs along the kdistance curve.
- The function kNNdistplot() [in dbscan package] can be used to draw the kdistance plot:



The plot of distance versus sampled points can be plotted using the kNNdistplot function, and is shown in the next slide.



The optimal eps value according the plot is approximately 0.15.

This concludes our discussion on dbscan.