

Worksheet 10 for November 3rd and 5th

1. Let $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ and $\mathbf{v}_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \\ -1 \end{bmatrix}$. Using Gram-Schmidt, find an orthonormal basis for $W = \text{span}(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$, using $\mathbf{v}_1, \mathbf{v}_2$, and \mathbf{v}_3 .

Solution. Set

$$\mathbf{u}_1 = \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|} = \frac{\begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}}{\left\| \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\|} = \begin{bmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix}$$

Then

$$\mathbf{u}_2 = \frac{\mathbf{v}_2 - (\mathbf{u}_1 \cdot \mathbf{v}_2)\mathbf{u}_1}{\|\mathbf{v}_2 - (\mathbf{u}_1 \cdot \mathbf{v}_2)\mathbf{u}_1\|} = \frac{\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \left(\begin{bmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right) \begin{bmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix}}{\left\| \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \left(\begin{bmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right) \begin{bmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} \right\|} = \frac{\begin{bmatrix} \frac{2}{3} \\ 0 \\ -\frac{1}{3} \\ -\frac{1}{3} \end{bmatrix}}{\left\| \begin{bmatrix} \frac{1}{2} \\ 0 \\ -\frac{1}{2} \end{bmatrix} \right\|} = \sqrt{\frac{3}{2}} \begin{bmatrix} \frac{2}{3} \\ 0 \\ -\frac{1}{3} \\ -\frac{1}{3} \end{bmatrix} = \begin{bmatrix} \frac{2}{\sqrt{6}} \\ 0 \\ -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \end{bmatrix}$$

Tutoring Room (443 Altgeld Hall): Mon 4-6 PM, Tue 5-7 PM, Wed 6-8 PM

Midterm Date: November 19 7-8:15 PM, Conflict November 20, 8-9:20AM and 9:30-10:50AM, Conflict sign up deadline: November 13

Final Date: December 17 8-11AM, Conflict December 15, 8-11AM. You are allowed to take the conflict exam if you have more than two examination within 24 hours. Conflict sign up deadline: November 30

Finally,

$$\begin{aligned}
\mathbf{u}_3 &= \frac{\mathbf{v}_3 - (\mathbf{u}_1 \cdot \mathbf{v}_3)\mathbf{u}_1 - (\mathbf{u}_2 \cdot \mathbf{v}_3)\mathbf{u}_2}{\|\mathbf{v}_3 - (\mathbf{u}_1 \cdot \mathbf{v}_3)\mathbf{u}_1 - (\mathbf{u}_2 \cdot \mathbf{v}_3)\mathbf{u}_2\|} \\
&= \frac{\begin{bmatrix} 2 \\ 1 \\ 0 \\ -1 \end{bmatrix} - \left(\begin{bmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 0 \\ -1 \end{bmatrix} \right) \begin{bmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} - \left(\begin{bmatrix} \frac{2}{\sqrt{6}} \\ 0 \\ -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 0 \\ -1 \end{bmatrix} \right) \begin{bmatrix} \frac{2}{\sqrt{6}} \\ 0 \\ -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \end{bmatrix}}{\left\| \begin{bmatrix} 2 \\ 1 \\ 0 \\ -1 \end{bmatrix} - \left(\begin{bmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 0 \\ -1 \end{bmatrix} \right) \begin{bmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix} - \left(\begin{bmatrix} \frac{2}{\sqrt{6}} \\ 0 \\ -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 0 \\ -1 \end{bmatrix} \right) \begin{bmatrix} \frac{2}{\sqrt{6}} \\ 0 \\ -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \end{bmatrix} \right\|} \\
&= \sqrt{\frac{2}{3}} \begin{bmatrix} 0 \\ 1 \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \end{bmatrix}
\end{aligned}$$

Now $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthonormal basis of W . □

2. Let $A = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$.

- (i) Calculate $A^T A$. What does this tell you about the columns of A ?
- (ii) Find an orthonormal basis $\{q_1, q_2\}$ for $\text{Col}(A)$ (starting with the columns of A !). Put $Q = [q_1 \ q_2]$. What is Q^{-1} ?

Solution. (i) We have:

$$A^T A = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

Since only entries on the main diagonal are nonzero, columns of A are orthogonal to each other.

- (ii) Since we already know that columns of A are orthogonal to each other, to find an orthonormal basis for $\text{Col}(A)$ it is enough to divide each column by its length. Hence: (note that for non-zero vectors, orthogonality implies linear independence)

$$Q = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

Q is an orthogonal matrix, so:

$$Q^{-1} = Q^T = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \quad \square$$

3. Let

$$Q_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix},$$

the matrix for rotation by the angle θ (counterclockwise).

- (i) Calculate $Q_\theta^T Q_\theta$. What does this tell you about the columns of Q_θ ?

- (ii) What is Q_θ^{-1} ? Express Q_θ^{-1} in terms of another rotation matrix Q_ϕ .
- (iii) Show that if $\mathbf{x} = \begin{bmatrix} a \\ b \end{bmatrix}$ then the vector \mathbf{x} and the rotated vector $Q_\theta \mathbf{x}$ have the same length.

Solution. (i) We have:

$$Q_\theta^T Q_\theta = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} \cos^2 \theta + \sin^2 \theta & 0 \\ 0 & \cos^2 \theta + \sin^2 \theta \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

This shows that the columns of Q_θ form an orthonormal basis for \mathbb{R}^2 .

- (ii) By the first part, we have $Q_\theta^{-1} = Q_\theta^T = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$. It is easy to see that the inverse of the rotation by θ is the rotation by $-\theta$, therefore:

$$Q_\theta^{-1} = Q_{-\theta}$$

- (iii) We have:

$$Q_\theta \mathbf{x} = Q_\theta \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} a \cos \theta - b \sin \theta \\ a \sin \theta + b \cos \theta \end{bmatrix}$$

Thus,

$$\begin{aligned} \text{length}(Q_\theta \mathbf{x}) &= \sqrt{(a \cos \theta - b \sin \theta)^2 + (a \sin \theta + b \cos \theta)^2} = \sqrt{a^2(\cos^2 \theta + \sin^2 \theta) + b^2(\cos^2 \theta + \sin^2 \theta)} \\ &= \sqrt{a^2 + b^2} = \text{length}(\mathbf{x}) \end{aligned} \quad \square$$

4. Let P be the matrix

$$P = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

- (i) Compute the dot products between every two columns of P .
- (ii) What is P^{-1} ?

Now let P be an arbitrary $n \times n$ permutation matrix, so each row and each column has a single non zero entry 1. Write $P = [P_1 \ P_2 \ \cdots \ P_n]$.

- (iii) What is the dot product between the columns of P , i.e., what is $P_i^T P_j$?
- (iv) What is P^{-1} ?

Solution. (i) See (iii) below.

- (ii) See (iv) below. The inverse of P is:

$$P^{-1} = P^T = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

- (iii) We have $P_i^T P_j = 0$ if $i \neq j$ and $P_i^T P_i = 1$. This is because the columns of P are the standard basis vectors of \mathbb{R}^n in a different order.
- (iv) From the first part, we know that columns of P form an orthonormal basis, i.e., P is orthogonal. Hence, we have:

$$P^{-1} = P^T \quad \square$$

5. Let $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}$.

a. Find the QR decomposition of A : write $A = QR$ where Q is a matrix with orthonormal columns and R is an upper triangular matrix.

b. Let $\mathbf{b} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$. Use the QR decomposition of A to find the least squares solution of $A\hat{\mathbf{x}} = \mathbf{b}$ (by solving $R\hat{\mathbf{x}} = Q^T\mathbf{b}$).

Solution. a. We start with columns of $A (= [\mathbf{v}_1 \ \mathbf{v}_2])$ and we use Gram-Schmidt to find columns of $Q (= [\mathbf{q}_1 \ \mathbf{q}_2])$:

$$\mathbf{q}_1 = \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|} = \frac{\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}}{\left\| \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\|} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

and,

$$\mathbf{q}_2 = \frac{\mathbf{v}_2 - (\mathbf{q}_1 \cdot \mathbf{v}_2)\mathbf{q}_1}{\|\mathbf{v}_2 - (\mathbf{q}_1 \cdot \mathbf{v}_2)\mathbf{q}_1\|} = \frac{\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \left(\begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right) \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}}{\left\| \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \left(\begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right) \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix} \right\|} = \frac{\begin{bmatrix} -\frac{1}{2} \\ 1 \\ \frac{1}{2} \end{bmatrix}}{\left\| \begin{bmatrix} -\frac{1}{2} \\ 1 \\ \frac{1}{2} \end{bmatrix} \right\|} = \sqrt{\frac{2}{3}} \begin{bmatrix} -\frac{1}{2} \\ 1 \\ \frac{1}{2} \end{bmatrix} = \begin{bmatrix} -\frac{1}{\sqrt{6}} \\ \frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{6}} \end{bmatrix}$$

Hence,

$$Q = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} \\ 0 & \frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \end{bmatrix}$$

We have:

$$R = Q^T A = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{6}} & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{6}} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} \sqrt{2} & \frac{1}{\sqrt{2}} \\ 0 & \frac{3}{\sqrt{6}} \end{bmatrix}$$

b. We have to solve $R\hat{\mathbf{x}} = Q^T\mathbf{b}$:

$$\begin{bmatrix} \sqrt{2} & \frac{1}{\sqrt{2}} \\ 0 & \frac{3}{\sqrt{6}} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{6}} & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{6}} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{6}} \end{bmatrix}$$

Therefore, $\hat{\mathbf{x}} = \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \end{bmatrix}$. □

6. a. Recall that the orthogonal projection onto $\text{Col}(A)$ has projection matrix $A(A^T A)^{-1}A^T$. How does this formula simplify in the case when A has orthonormal columns?

b. Let $Q = \begin{bmatrix} 1 & 0 \\ 0 & \frac{3}{5} \\ 0 & -\frac{4}{5} \end{bmatrix}$. What is the projection matrix corresponding to the orthogonal projection onto $\text{Col}(Q)$?

c. Let $Q = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{3}{5} & \frac{4}{5} \\ 0 & -\frac{4}{5} & \frac{3}{5} \end{bmatrix}$. What is the projection matrix corresponding to the orthogonal projection onto $\text{Col}(Q)$? Explain why your answer is not surprising.

Solution. a. If A has orthonormal columns then $A^T A = I$. So the projection matrix is:

$$A(A^T A)^{-1} A^T = AA^T$$

b. Since Q has orthonormal columns, the projection matrix is:

$$QQ^T = \begin{bmatrix} 1 & 0 \\ 0 & \frac{3}{5} \\ 0 & -\frac{4}{5} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{3}{5} & -\frac{4}{5} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{9}{25} & -\frac{12}{25} \\ 0 & -\frac{12}{25} & \frac{16}{25} \end{bmatrix}$$

c. Q has orthonormal columns, so the projection matrix is QQ^T which is equal to I (since Q is orthogonal). Since columns of Q are linearly independent and Q has 3 columns, columns of Q form a basis for \mathbb{R}^3 . Hence, $\text{Col}(Q) = \mathbb{R}^3$ and projection of each vector in \mathbb{R}^3 onto $\text{Col}(Q)$ is itself, i.e., the projection matrix is I . \square

7. Quarterly economic data is subject to seasonal fluctuations. A curve that approximates the gross domestic product (GDP) of a country might be of the form

$$y = \beta_0 + \beta_1 x + \beta_2 \sin(2\pi x/4),$$

where x is the time in quarters of a year. The term $\beta_0 + \beta_1 x$ gives the basic GDP growth trend of the economy, while the sine term reflects the seasonal changes. Assume the GDP data are $(x_1, y_1), \dots, (x_n, y_n)$.

(i) Give the design matrix that leads to a least-square fit to the equation above.

(ii) (Highly Optional) GDP data for US economy is available at <http://www.bea.gov/>. Using the above, can you find the GDP growth trend of the US economy.

Solution. (i) Plugging in our data points we get that our design matrix is

$$\begin{bmatrix} 1 & x_1 & \sin(2\pi x_1/4) \\ 1 & x_2 & \sin(2\pi x_2/4) \\ \vdots & \vdots & \vdots \\ 1 & x_n & \sin(2\pi x_n/4) \end{bmatrix}$$

(ii) This is left as an exercise. \square

8. According to Kepler's first law, a comet should have an elliptic, parabolic or hyperbolic orbit. In suitable polar coordinates, the position (r, θ) of a comet satisfies an equation

$$r = \beta + e(r \cdot \cos(\theta)),$$

where β is a constant and e is the eccentricity of the orbit, with $0 \leq e < 1$ for an ellipse, $e = 1$ for a parabola and $e > 1$ for a hyperbola. Suppose observations of a newly discovered comet provide the data below.

$$\begin{array}{c|ccccc} \theta & .88 & 1.10 & 1.42 & 1.77 & 2.14 \\ \hline r & 3.00 & 2.30 & 1.65 & 1.25 & 1.01 \end{array}$$

Use least square methods to find the type of the orbit, and predict where the comet will be when $\theta = 4.6$ (radians).

Solution. We first set up the design matrix. Plugging in our values for r and θ , we get the following overdetermined system.

$$B = \begin{bmatrix} 1 & 3.00 \cos(.88) \\ 1 & 2.30 \cos(1.10) \\ 1 & 1.65 \cos(1.42) \\ 1 & 1.25 \cos(1.77) \\ 1 & 1.01 \cos(2.14) \end{bmatrix} \begin{bmatrix} \beta \\ e \end{bmatrix} = \begin{bmatrix} 3.00 \\ 2.30 \\ 1.65 \\ 1.25 \\ 1.01 \end{bmatrix}$$

Multiplying both sides of this by B^T and truncating at 3 significant figures, we get

$$\begin{bmatrix} 5 & 2.41 \\ 2.41 & 5.16 \end{bmatrix} \begin{bmatrix} \beta \\ e \end{bmatrix} = \begin{bmatrix} 9.21 \\ 7.68 \end{bmatrix}$$

Solving this numerically, we get that $\beta \approx 1.45$, and $e \approx .810$. Thus this comet has an elliptical orbit. \square