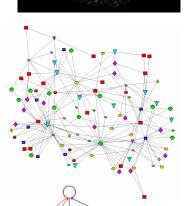
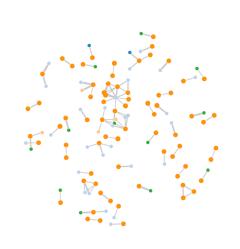
Today's announcements:

MP7 available. Due 12/8, 11:59p. EC due 12/1, 11:59p.

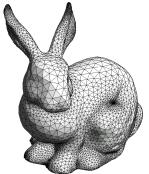


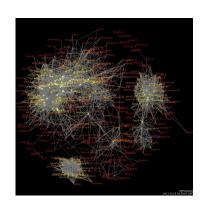




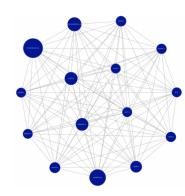
How do we get from here to there? Need:

- 1. Common Vocabulary
- 2. Graph implementation
- 3. Traversal
- 4. Algorithms.

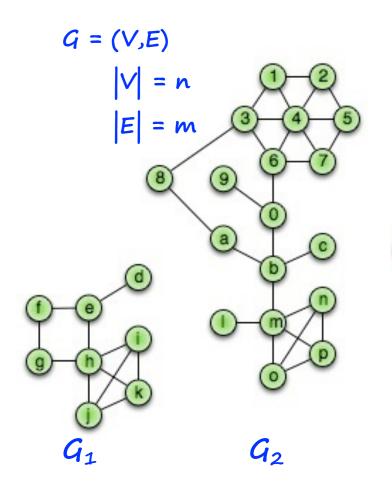








Graph Vocabulary:



Degree(v): |I|

Adjacent vertices(v): $A = \{x: (x,v) \text{ in } E\}$

Path(G₂) - sequence of vertices connected by edges.

 G_3 Cycle(G_1) - path with common begin and end vertex.

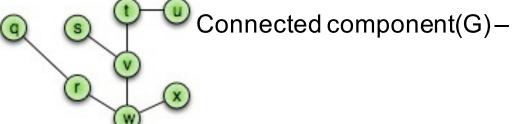
Simple graph(G) - graph with no self-loops and no multi-edges.

Graph Vocabulary:

Subgraph(G) – G' = (V', E'), V' V, E' L, and (u,v) L E' implies u V' and v V'.

Complete subgraph(G₂)-

Connected subgraph(G)-

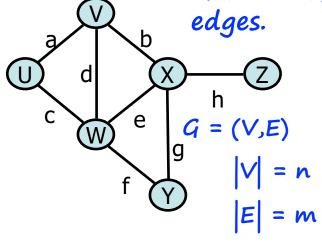


Acyclic subgraph (G_2) –

G₃ Spanning tree(G₁) –

Graphs: theory that will help us in analysis

Running times often reported in terms of n, the number of vertices, but they often depend on m, the number of



How many edges?

At least:

connected -

not connected -

At most:

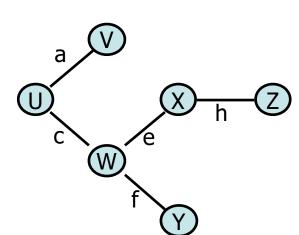
simple -

not simple -

Relationship to degree sum:

$$\sum_{v \in V} \deg(v) =$$

Thm: Every minimally connected graph G=(V,E) has |V|-1 edges.



Proof: Consider an arbitrary minimally connected graph G=(V,E).

Lemma: Every connected subgraph of G is minimally connected.

(easy proof by contradiction)

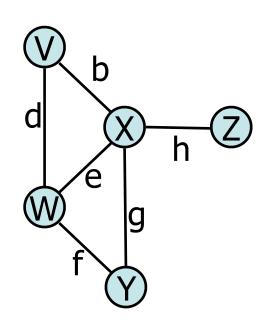
IH: For any j < |V|, any minimally connected graph of j vertices has j-1 edges.

Suppose |V| = 1: A minimally connected graph of 1 vertex has no edges, and 0 = 1-1.

Suppose |V| > 1: Choose any vertex and let d denote its degree. Remove its incident edges, partitioning the graph into _____ components, $C_0=(____,____)$, ... $C_d=(____,____)$, each of which is a minimally connected subgraph of G. This means that $|E_k| = _____$ by ____.

Now we'll just add up edges in the original graph:

Graphs: Toward implementation...(ADT)



Data:

Vertices

Edges

+ some structure that reflects the connectivity of the graph

```
Functions: (merely a smattering...)

insertVertex(pair keyData)

insertEdge(vertex v1, vertex v2, pair keyData)

removeEdge(edge e);

removeVertex(vertex v);

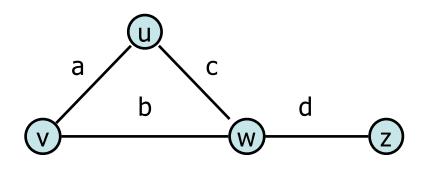
incidentEdges(vertex v);
```

areAdjacent(vertex v1, vertex v2);

origin(edge e);

destination(edge e);

Graphs: Edge List (a first implementation)



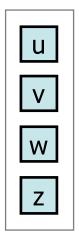
Some functions we'll compare:

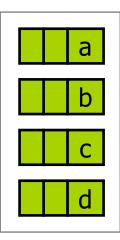
insertVertex(vertex v)

removeVertex(vertex v)

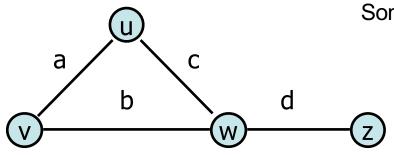
areAdjacent(vertex v, vertex u)

incidentEdges(vertex v)





Graphs: Adjacency Matrix



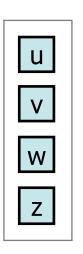
Some functions we'll compare:

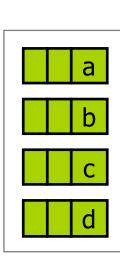
insertVertex(vertex v)

removeVertex(vertex v)

areAdjacent(vertex v, vertex u)

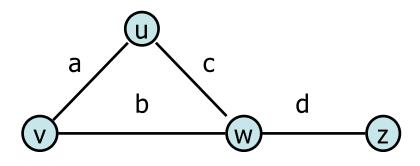
incidentEdges(vertex v)





	u	V	W	Z
u				
V				
W				
Z				

Graphs: Adjacency List



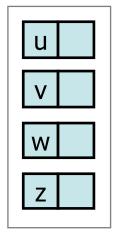
Some functions we'll compare:

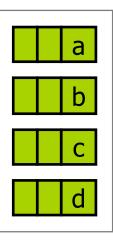
insertVertex(vertex v)

removeVertex(vertex v)

areAdjacent(vertex v, vertex u)

incidentEdges(vertex v)





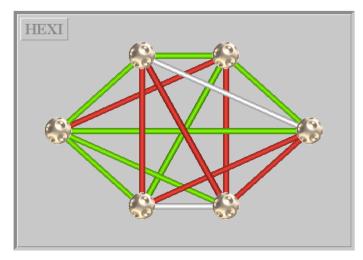
Graphs: Asymptotic Performance

 n vertices, m edges no parallel edges no self-loops Bounds are big-O 	Edge List	Adjacency List	Adjacency Matrix
Space	n + m	n + m	n^2
incidentEdges(v)	m	deg(v)	n
areAdjacent (v, w)	m	$\min(\deg(v), \deg(w))$	1
insertVertex(o)	1	1	n^2
insertEdge(v, w, o)	1	1	1
removeVertex(v)	m	deg(v)	n^2
removeEdge(e)	1	1	1

planarity.net



http://www.dbai.tuwien.ac.at/proj/ramsey/



http://www.math.binghamton.edu/somnath/Teaching/CTY_Oct09.pdf1