Pipelining the MIPS Datapath

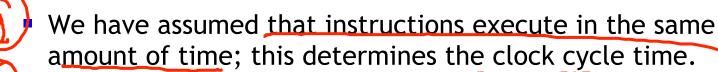
Handout

Today's lecture

- Pipeline implementation
 - Single-cycle Datapath
 - Pipelining performance
 - Pipelined datapath
 - Example

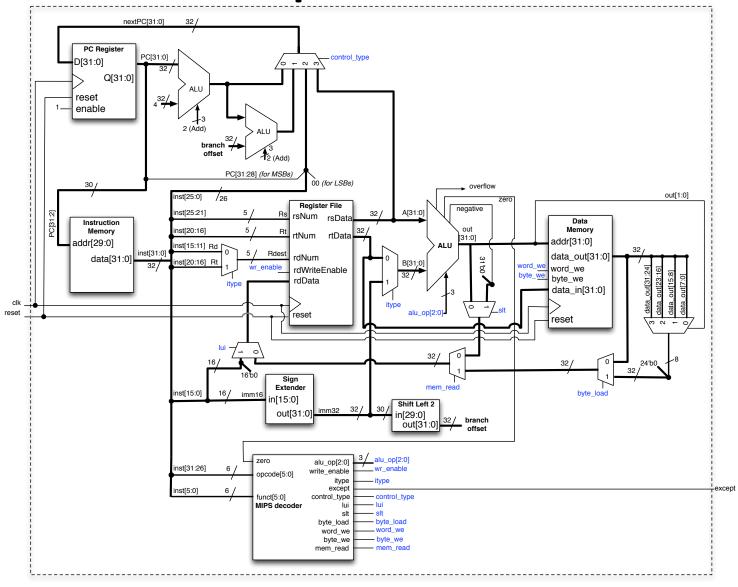
Single-cycle implementation

So far we have built a single-cycle implementation of a subset of the MIPS-based instruction set.



We have implemented the datapath and the control unit.

Full Machine Datapath – Lab 6



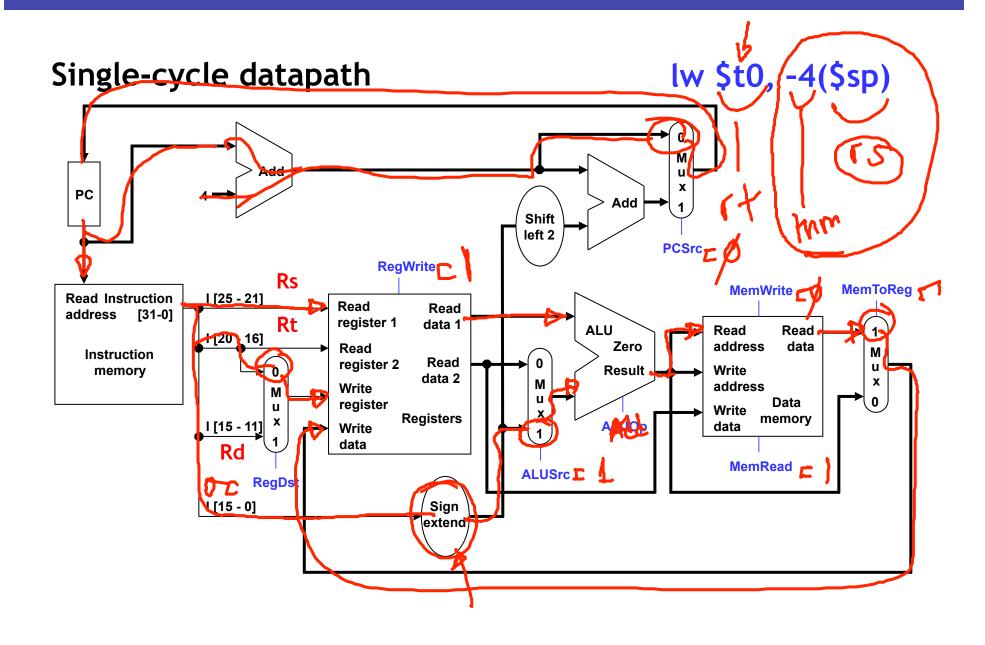
Single-cycle implementation

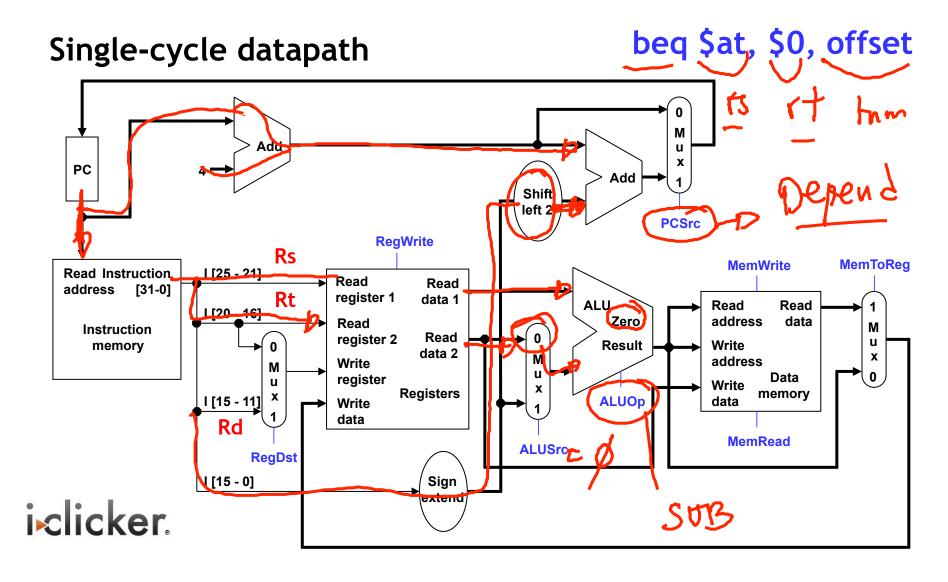
For the following lectures, we will use a simpler implementation of the MIPSbased instruction set supporting just the following operations.

Arithmetic: add sub and or slt

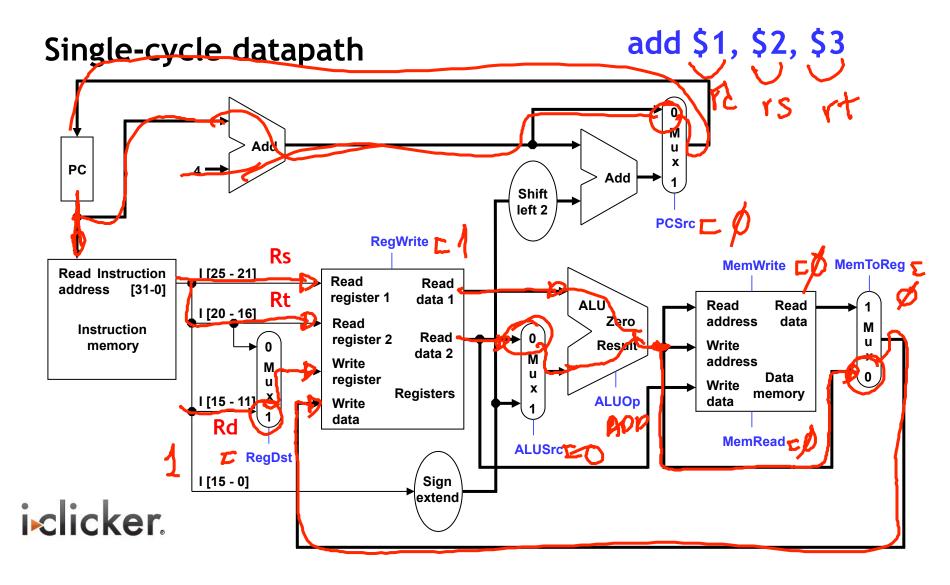
Data Transfer: lw sw

Control: beq

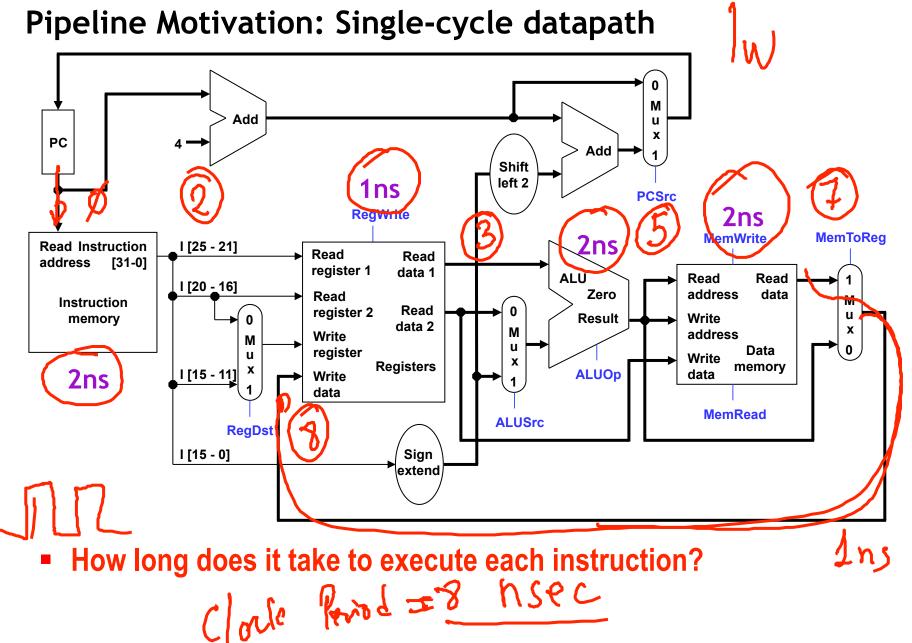


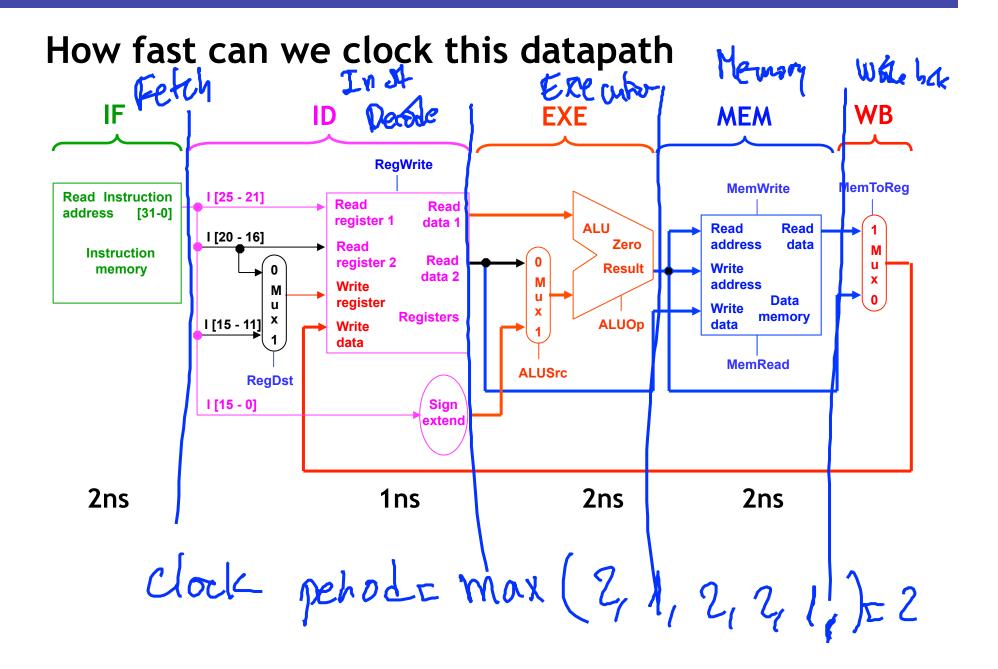


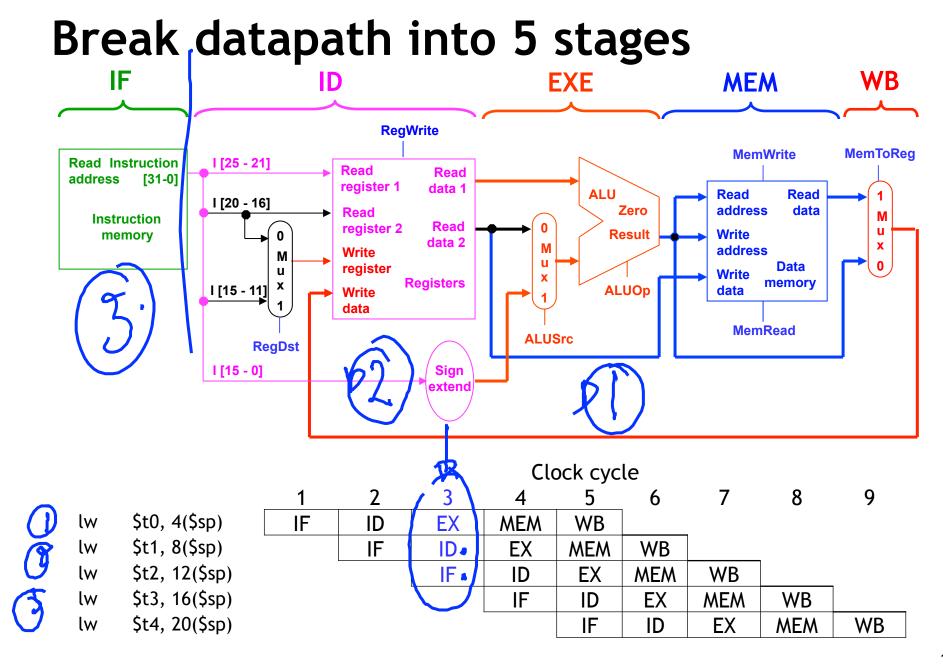
A) ALUSrc=0 B) ALUSrc=1



- A) ALUSrc=0 RegDst=0
- B) ALUSrc=0 RegDst=1
- C) ALUSrc=1 RegDst=0
- D) ALUSrc=1 RegDst=1







Pipelining Performance



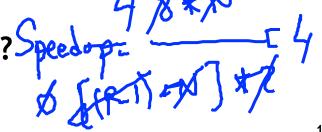
lw	\$t0, 4(\$sp)
lw	\$t1, 8(\$sp)
lw	\$t2, 12(\$sp)
lw	\$t3, 16(\$sp)
lw	\$t4, 20(\$sp)

5 to										
1	2	3	4	5 🔥	61	7	8	9		
IF	ID	EX	MEM	WB	6					
	IF	ID	EX	MEM	WB	16		•		
		IF	ID	EX	MEM	WB	•			
			IF	ID	EX	MEM	WB	V		
				IF ,	ID	EX	MEM	WB		
	filli	ing	/						1	

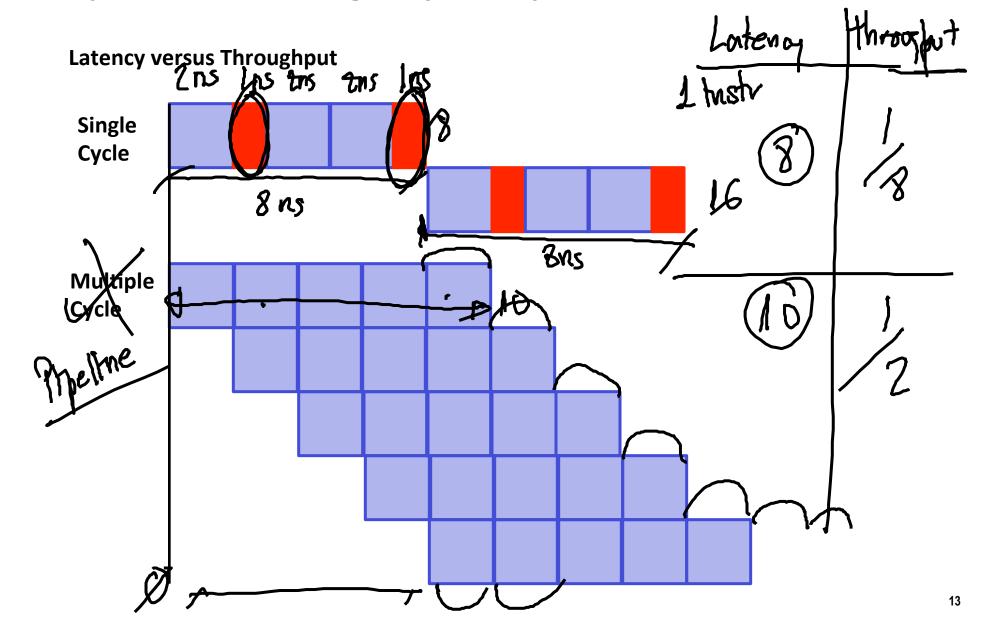
znsec

Clock cycle

- Execution time on ideal pipeline:
 - time to fill the pipeline + one cycle per instruction
 - How long for N instructions?
- Compare with other implementations.
- Compare with other implementations:
 - Single Cycle: (8ns clock period) —
- How much faster is pipelining for N=1000 ? Speedop=

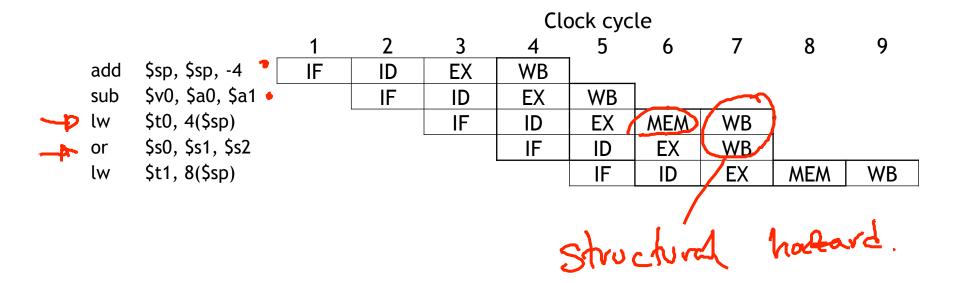


Pipeline versus Single Cycle implementation

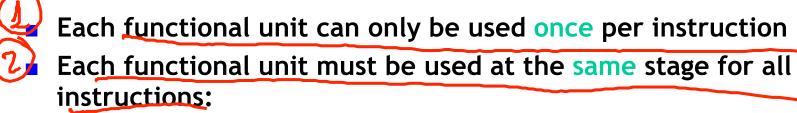


Pipelining other instruction types

- R-type instructions only require 4 stages: IF, ID, EX, and WB
 - We don't need the MEM stage
- What happens if we try to pipeline loads with R-type instructions?



Important Observation

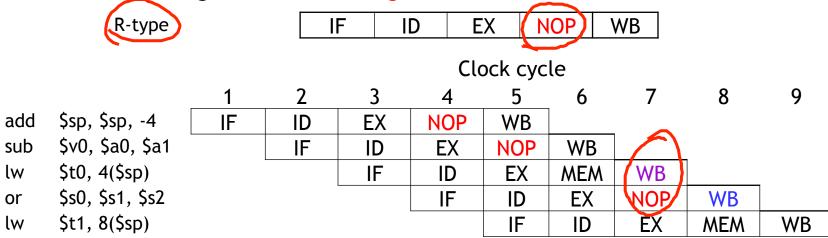


- Load uses Register File's Write Port during its 5th stage
- R-type uses Register File's Write Port during its 4th stage

			Clock cycle									
			1	2	3	4	5	6	7	8	9	
	add	\$sp, \$sp, -4	IF	ID	EX	WB		_			ı.A	
	sub	\$v0, \$a0, \$a1		IF	ID	EX	WB			, 5	やり	
-b	lw	\$t0, 4(\$sp)			IF	ID	EX	MEM	WB		- И.	
	or	\$s0, \$s1, \$s2				IF	ID	EX	WB	-	7 TU	
	lw	\$t1, 8(\$sp)					IF	ID	EX	MEM	WB	

A solution: Insert NOP stages

- Enforce uniformity
 - Make all instructions take 5 cycles.
 - Make them have the same stages, in the same order
 - Some stages will do nothing for some instructions



Stores and Branches have NOP stages, too...

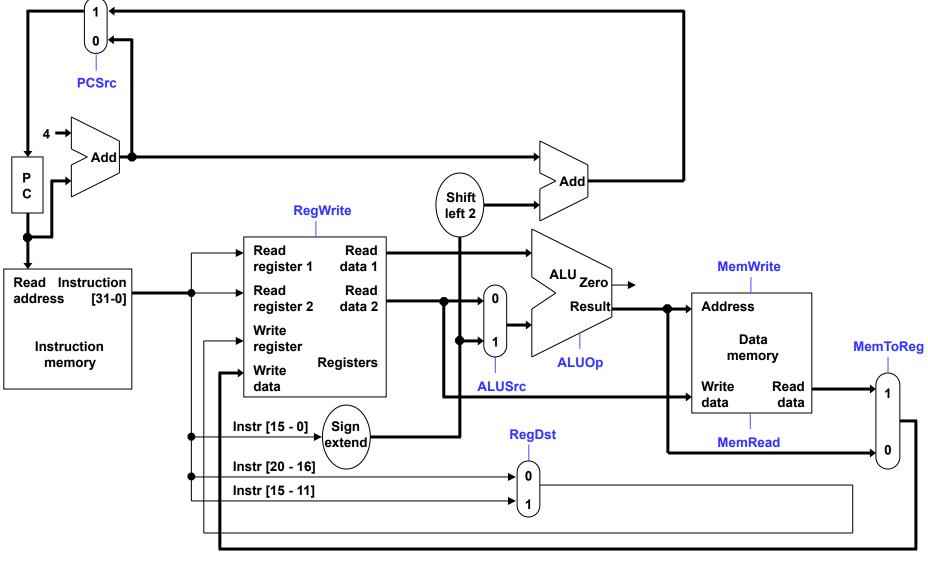
store branch

IF	עו	EX	MEM	NOP
IF	ID	EX	NOP	NOP

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Pipelining

Single-cycle datapath, slightly rearranged



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Pipelined datapath and control

Pipeline registers

- We'll add intermediate registers to our pipelined datapath.
- There's a lot of information to save, however. We'll simplify our diagrams by drawing just one big pipeline register between each stage.
- The registers are named for the stages they connect.

IF/ID

ID/EX

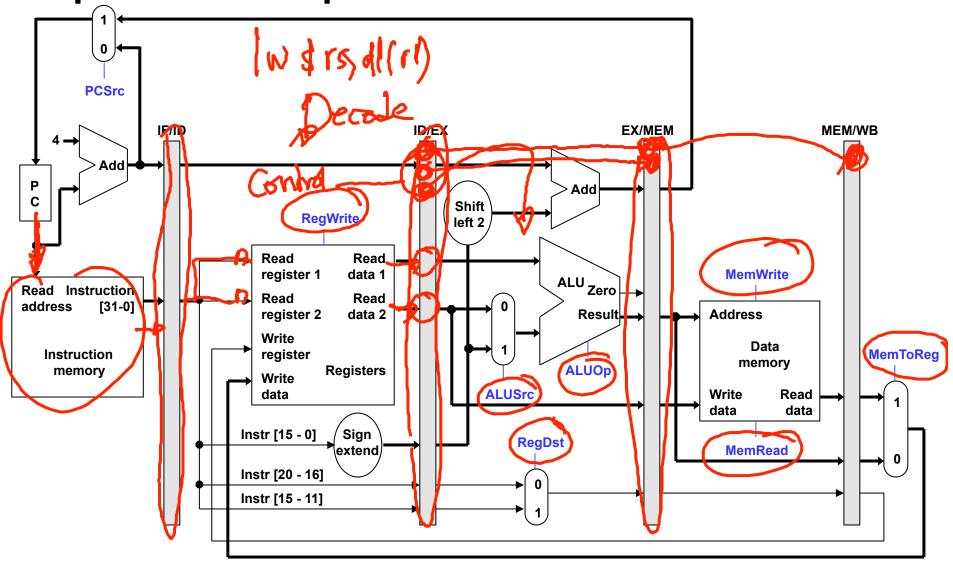
EX/MEM

MEM/WB

 No register is needed after the WB stage, because after WB the instruction is done.



Pipelined datapath



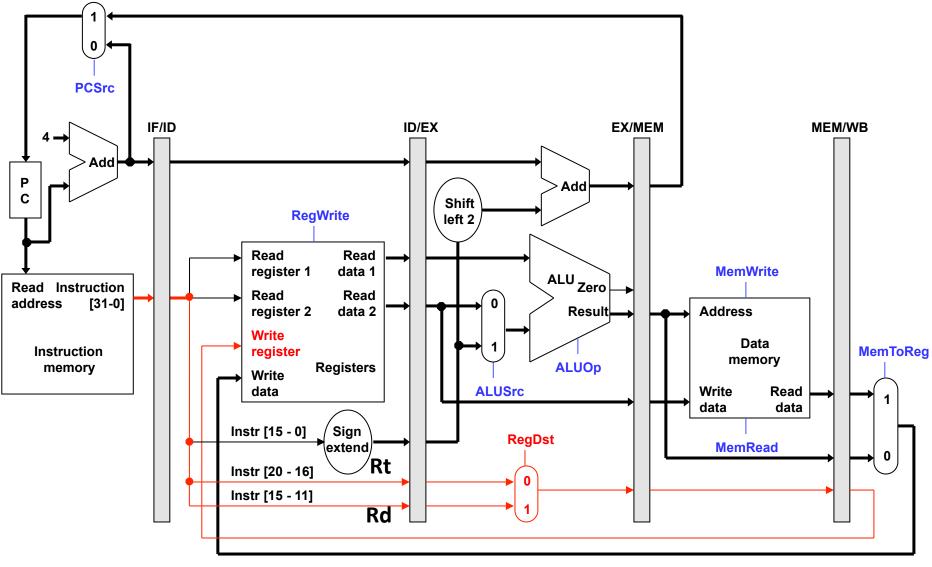
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Pipelined datapath and control

Propagating values forward

- Any data values required in later stages must be propagated through the pipeline registers.
- The most extreme example is the destination register.
 - The rd field of the instruction word, retrieved in the first stage (IF), determines the destination register. But that register isn't updated until the fifth stage (WB).
 - Thus, the rd field must be passed through all of the pipeline stages, as shown in red on the next slide.
- Notice that we can't keep a single "instruction register," because the pipelined machine needs to fetch a new instruction every clock cycle.

The destination register



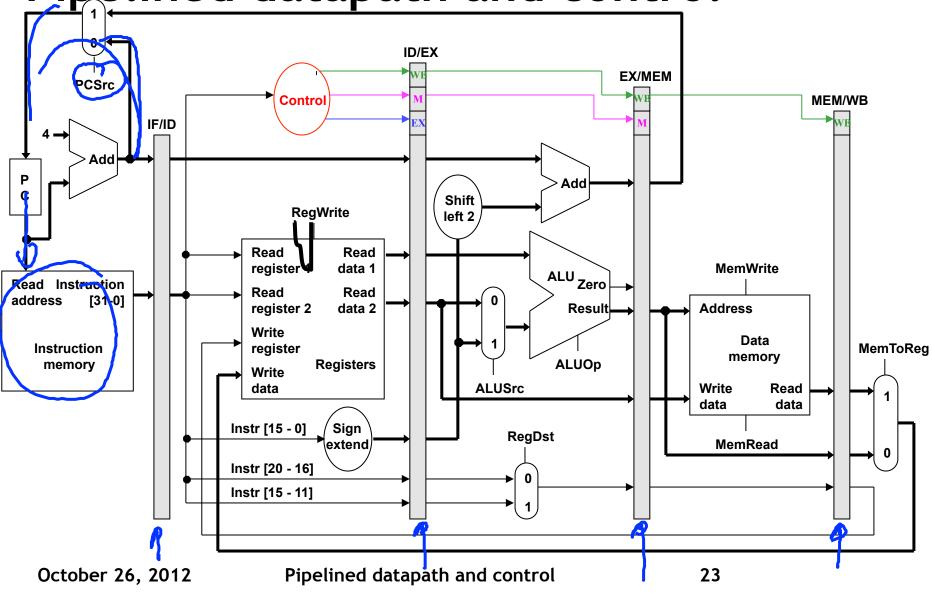
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Pipelined datapath and control

What about control signals?

- The control signals are generated in the same way as in the single-cycle processor—after an instruction is fetched, the processor decodes it and produces the appropriate control values.
- But just like before, some of the control signals will not be needed until some later stage and clock cycle.
- These signals must be propagated through the pipeline until they reach the appropriate stage. We can just pass them in the pipeline registers, along with the other data.
- Control signals can be categorized by the pipeline stage that uses them.

Pipelined datapath and control

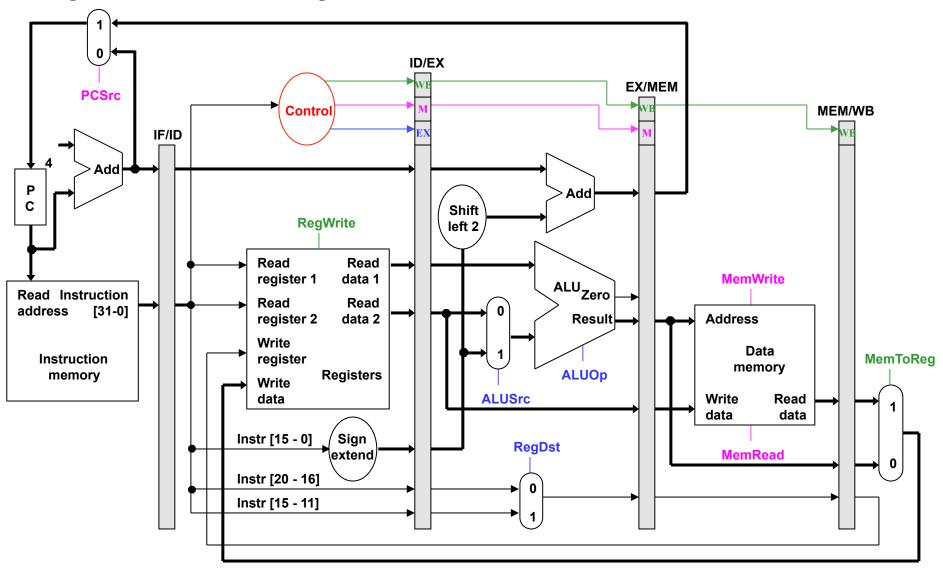


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Stage	Control signals needed							
EX	ALUSrc	ALUOp	RegDst					
MEM	MemRead	MemWrite	PCSrc					
WB	RegWrite	MemToReg						

Pipelined datapath and control



Notes about the diagram

- The control signals are grouped together in the pipeline registers, just to make the diagram a little clearer.
- Not all of the registers have a write enable signal.
 - PC must also be updated on each clock cycle. Including a write enable for the PC would be redundant.
 - Similarly, the <u>pipeline registers</u> are also written on every cycle, so no explicit write signals are needed.

An example execution sequence

Here's a sample sequence of instructions to execute.

```
addresses in
decimal

1000: lw $8, 4($29)

1004: sub $2, $4, $5

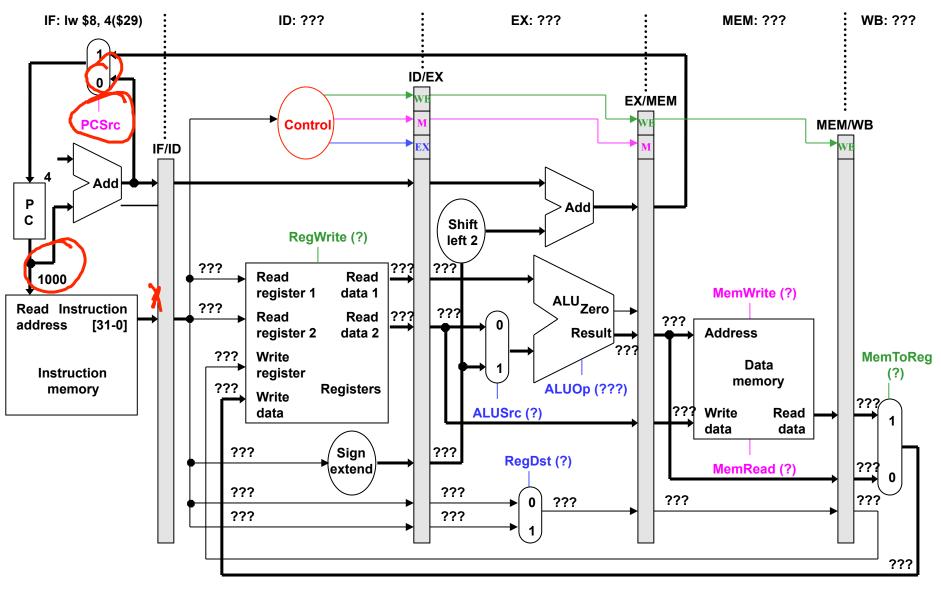
1008: and $9, $10, $11

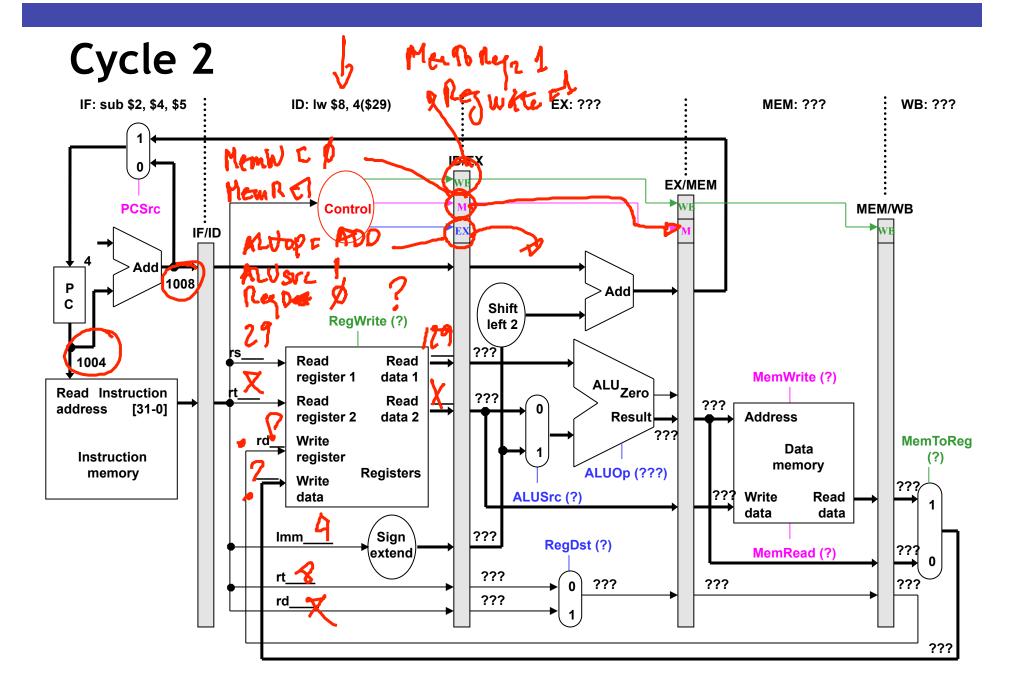
1012: or $16, $17, $18

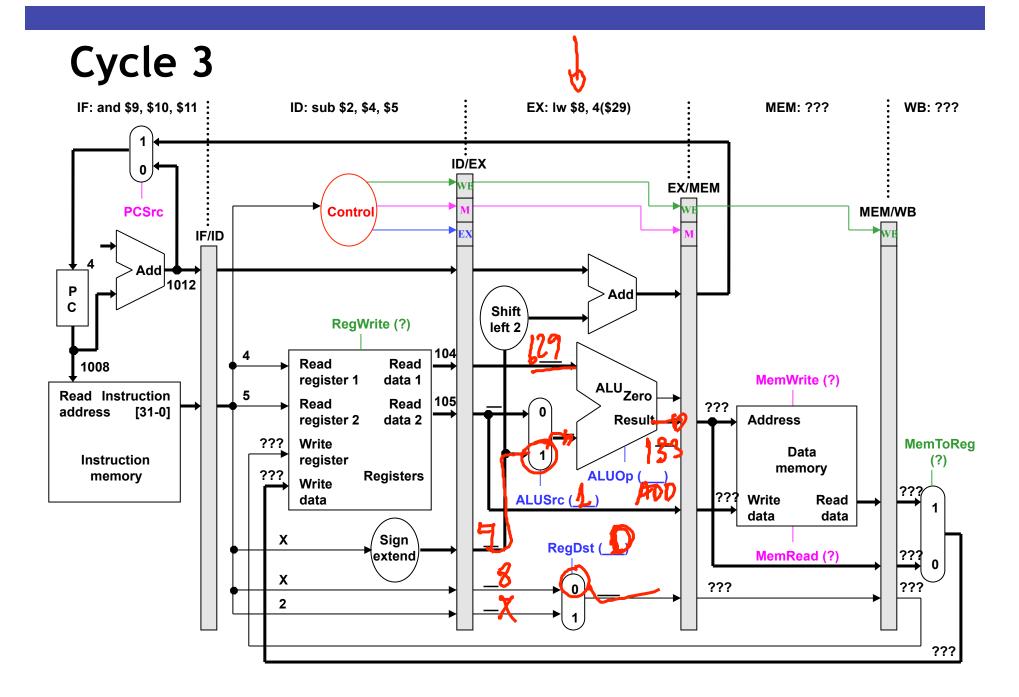
1016: add $13, $14, $0
```

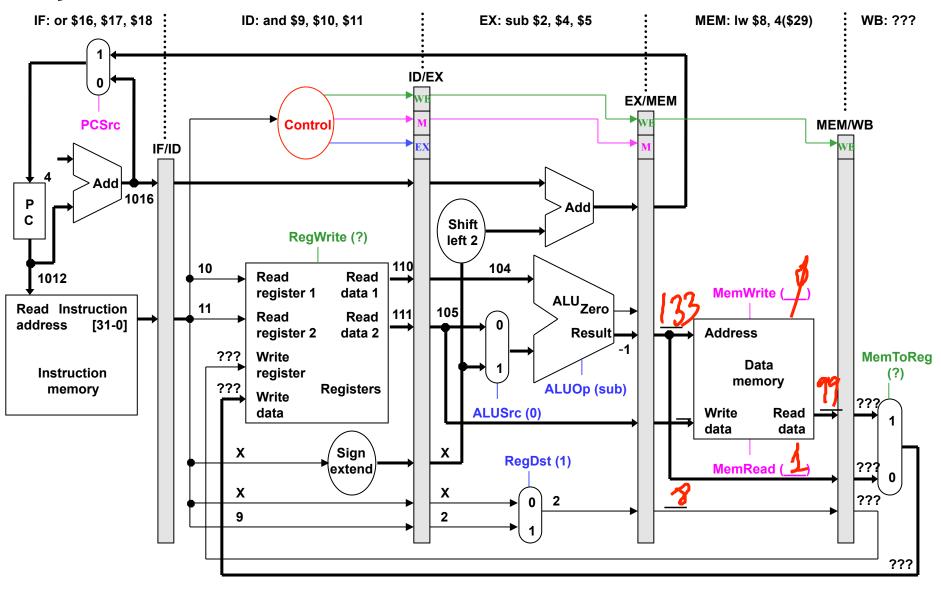
- We'll make some assumptions, just so we can show actual data values.
 - Each register contains its number plus 100. For instance, register \$8 contains 108, register \$29 contains 129, and so forth.
 - Every data memory location contains 99.
- Our pipeline diagrams will follow some conventions.
 - An X indicates values that aren't important, like the constant field of an R-type instruction.
 - Question marks ??? indicate values we don't know, usually resulting from instructions coming before and after the ones in our example.

Cycle 1 (filling)

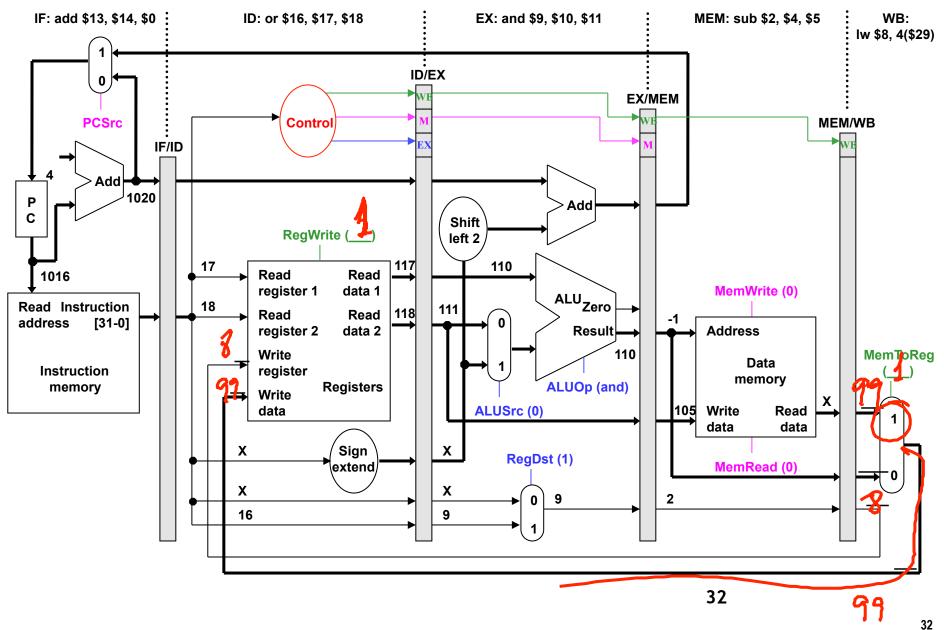


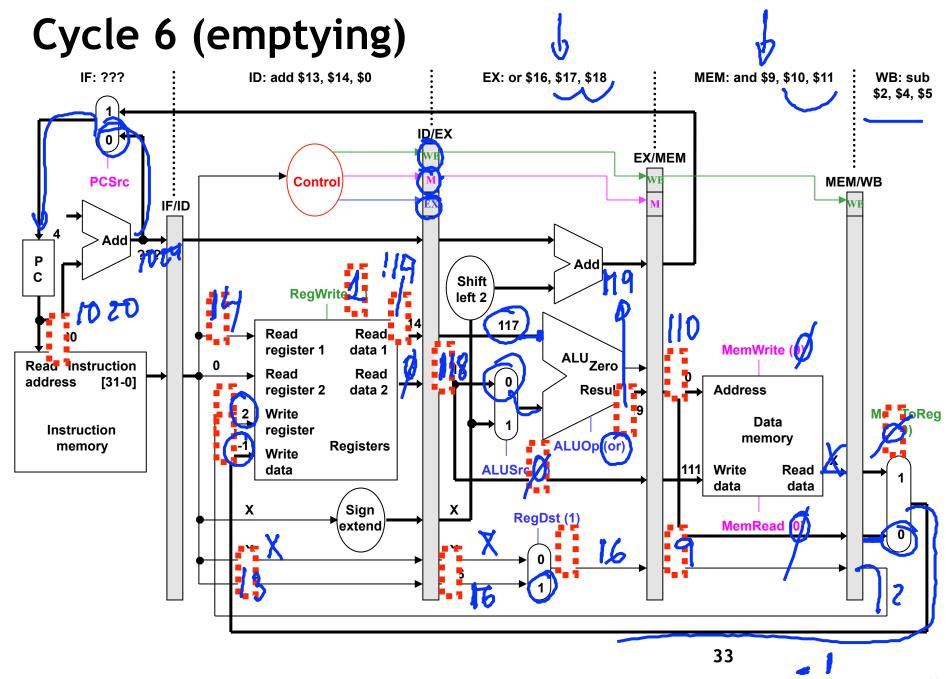


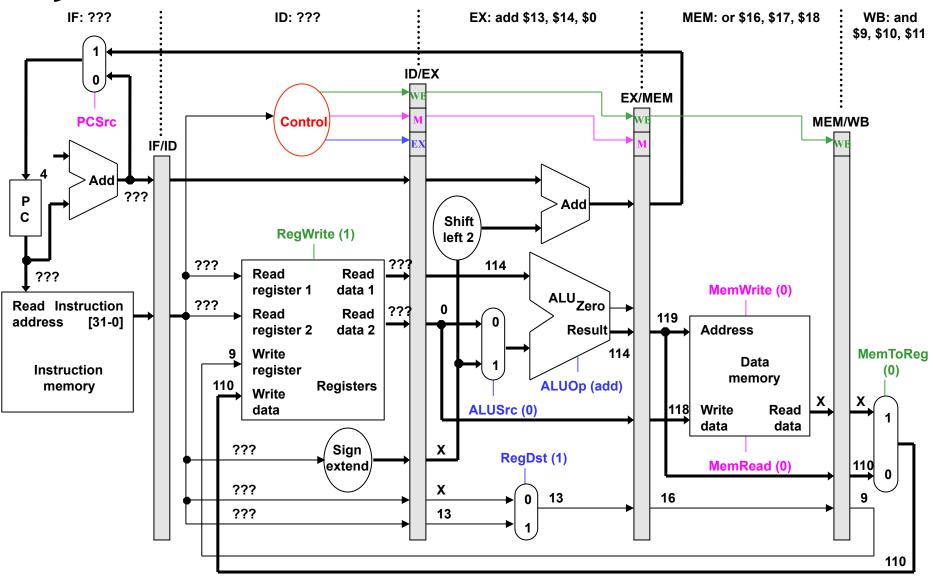


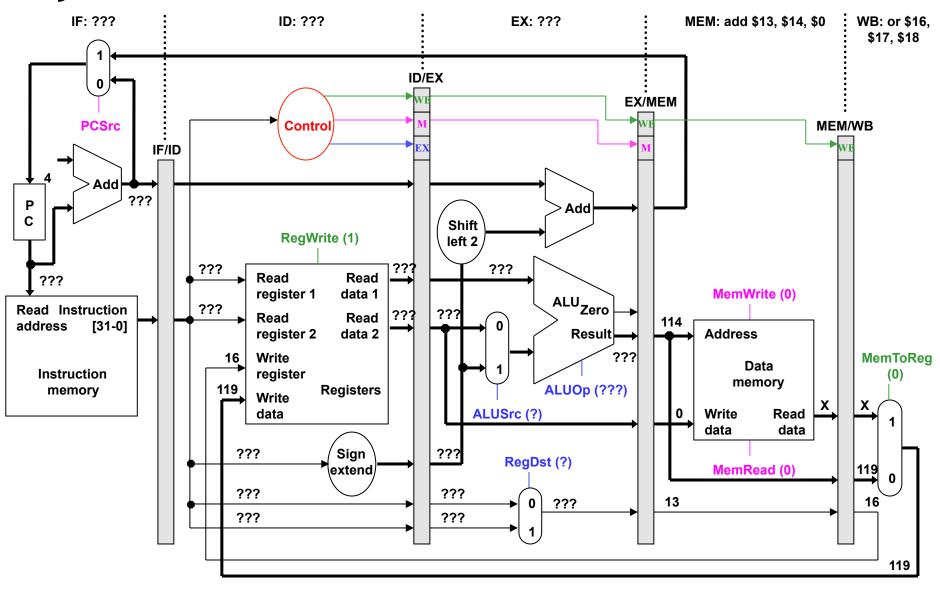


Cycle 5 (full)



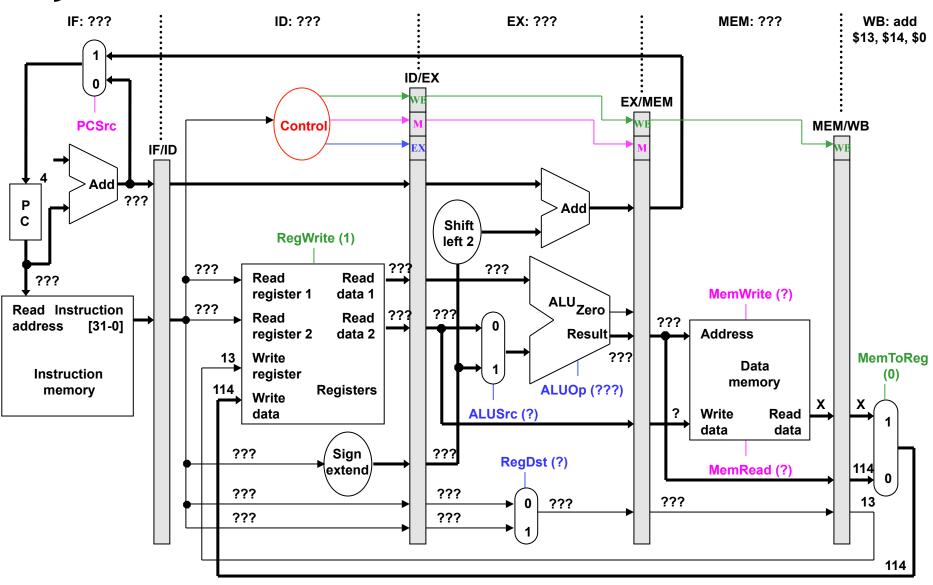






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Pipelined datapath and control



That's a lot of diagrams there

		Clock Cycle									
		1	2	3	4	5	6	7	8	9	
lw	\$t0, 4(\$sp)	IF	ID	EX	MEM	WB					
sub	\$v0, \$a0, \$a1		IF	ID	EX	MEM	WB				
and	\$t1, \$t2, \$t3			IF	ID	EX	MEM	WB			
or	\$s0, \$s1, \$s2				IF	ID	EX	MEM	WB		
add	\$t5, \$t6, \$0					IF	ID	EX	MEM	WB	

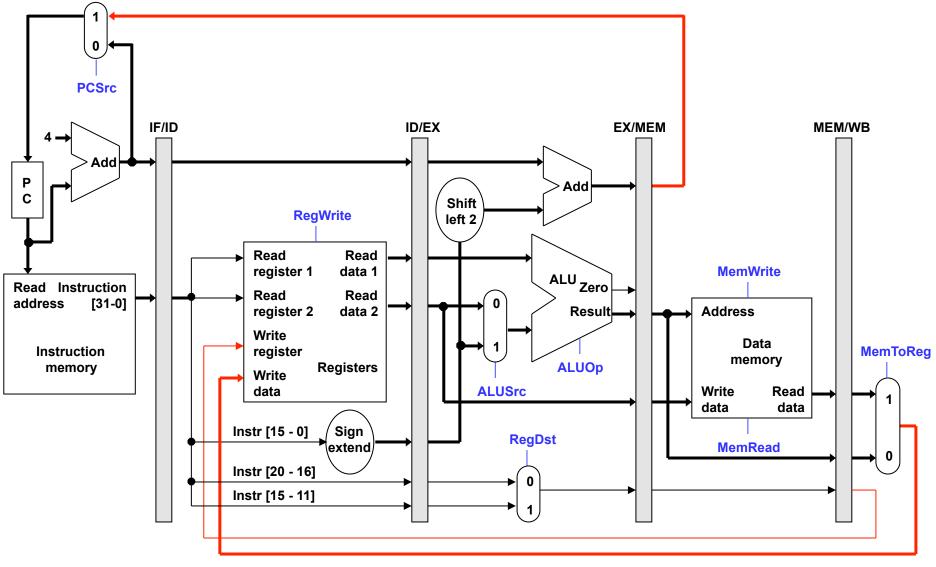
- Compare the last nine slides with the pipeline diagram above.
 - You can see how instruction executions are overlapped.
 - Each functional unit is used by a different instruction in each cycle.
 - The pipeline registers save control and data values generated in previous clock cycles for later use.
 - When the pipeline is full in clock cycle 5, all of the hardware units are utilized. This is the ideal situation, and what makes pipelined processors so fast.
- Try to understand this example or the similar one in the book at the end of Section 6.3.

Summary

- The pipelined datapath extends the single-cycle processor that we saw earlier to improve instruction throughput.
 - Instruction execution is split into several stages.
 - Multiple instructions flow through the pipeline simultaneously.
- Pipeline registers propagate data and control values to later stages.
- The MIPS instruction set architecture supports pipelining with uniform instruction formats and simple addressing modes.
- Next lecture, we'll start talking about Hazards.



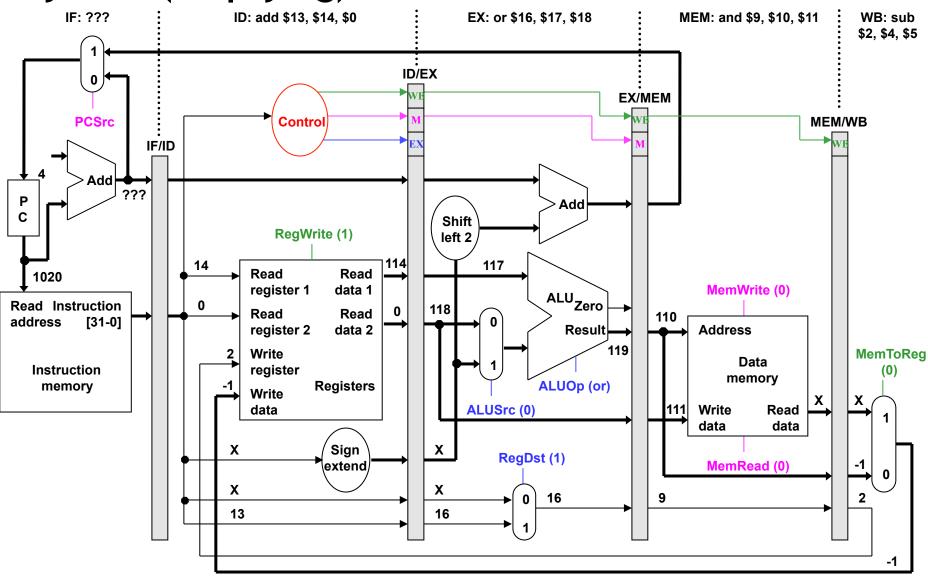
Note how everything goes left to right, except ...



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Pipelined datapath and control

Cycle 6 (emptying)



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Pipelined datapath and control