

# MATH 415 – Lecture 13

18 February 2015

Review

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(i.e. if  $\mathbf{u} \in W$  and  $c \in \mathbb{R}$ , then  $c\mathbf{u} \in W$ )
- $\text{span}\{\mathbf{v}_1, \dots, \mathbf{v}_m\}$  is always a subspace of  $V$ .  
( $\mathbf{v}_1, \dots, \mathbf{v}_m$  are vectors in  $V$ )



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## Example

Is  $W = \left\{ \begin{bmatrix} 2a - b & 0 \\ b & 3 \end{bmatrix} : a, b \in \mathbb{R} \right\}$  a subspace of  $M_{2 \times 2}$ , the space of  $2 \times 2$  matrices?

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**Solution.** No.  $W$  does not contain the zero matrix.

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**Solution.** Write “vectors” in  $W$  in the form

$$\begin{bmatrix} 2a - b & 0 \\ b & 3a \end{bmatrix} = a \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} + b \begin{bmatrix} -1 & 0 \\ 1 & 0 \end{bmatrix}$$

to see that

$$W = \text{span} \left\{ \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}, \begin{bmatrix} -1 & 0 \\ 1 & 0 \end{bmatrix} \right\}.$$

Like any span,  $W$  is a vector space.

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Yes.  $W_2 = \text{span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & -2 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} \right\}.$

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Hence,  $W_2$  is a subspace of the vector space  $M_{2 \times 2}$  of all  $2 \times 2$  matrices.

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Yes. If  $p'(2) = 0$  and  $q'(2) = 0$ , then

$(p + q)'(2) = p'(2) + q'(2) = 0$ . Likewise for scaling.

Hence,  $W_5$  is a subspace of the vector space of all polynomials.

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We still have

$$W_3 = \begin{bmatrix} 0 & 0 \\ 0 & 7 \end{bmatrix} + \text{span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & -2 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} \right\}.$$

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Equivalently, we have to check whether

$$\begin{bmatrix} a+c & -2b \\ b+3c & c+7 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

has solutions  $a, b, c$ . There is no solution.

What we learned before vector spaces

# Linear systems

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Sometimes, we represent the system by its augmented matrix.

$$\left[ \begin{array}{cc|c} 1 & -2 & -1 \\ -1 & 3 & 3 \end{array} \right]$$

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- no solution (such a system is called **inconsistent**),  
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- one unique solution,  
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- infinitely many solutions.  
 $\iff$  system is consistent and has at least one free variable

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- Gaussian elimination on  $\left[ \begin{array}{c|c} A & \mathbf{b} \end{array} \right]$
- LU decomposition  $A = LU$
- using matrix inverse,  $\mathbf{x} = A^{-1}\mathbf{b}$

# Matrices and vectors

- A **linear combination** of  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$  is of the form

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- $\text{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  is the set of all such linear combinations
  - Spans are always vector spaces
  - For instance, a span in  $\mathbb{R}^3$  can be  $\{\mathbf{0}\}$ , a line, a plane, or  $\mathbb{R}^3$ .

# Matrices and vectors

- The **transpose**  $A^T$  of a matrix  $A$  has rows and columns flipped.

$$\begin{bmatrix} 2 & 0 \\ 3 & 1 \\ -1 & 4 \end{bmatrix}^T = \begin{bmatrix} 2 & 3 & -1 \\ 0 & 1 & 4 \end{bmatrix}$$

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- An  $m \times n$  **matrix**  $A$  has  $m$  rows and  $n$  columns.
- The product  $A\mathbf{x}$  of a matrix times a vector is

$$\begin{bmatrix} | & | & \cdots & | \\ \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n \\ | & | & \cdots & | \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 \mathbf{a}_1 + x_2 \mathbf{a}_2 + \cdots + x_n \mathbf{a}_n$$

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- row-column rule

$$(AB)_{i,j} = (\text{row } i \text{ of } A) \cdot (\text{col } j \text{ of } B)$$

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  - Can compute  $A^{-1}$  using Gauss-Jordan method

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- $(AB)^{-1} = B^{-1}A^{-1}$
- An  $n \times n$  matrix  $A$  is invertible
  - $\iff A$  has  $n$  pivots
  - $\iff Ax = b$  has a unique solution (if true for one  $b$ , then true for all  $b$ )

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- Each elementary row operation can be encoded as multiplication with an **elementary matrix**.

$$\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & l \end{bmatrix} = \begin{bmatrix} a & b & c & d \\ e-a & f-b & g-c & h-d \\ i & j & k & l \end{bmatrix}$$

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- We can continue row reduction to obtain the (unique) RREF.

# Using Gaussian elimination

Gaussian elimination and row reductions allow us to:

- solve systems of linear equations

$$\left[ \begin{array}{cccc|c} 0 & 3 & -6 & 4 & -5 \\ 3 & -7 & 8 & 8 & 9 \\ 3 & -9 & 12 & 6 & 15 \end{array} \right] \longrightarrow \left[ \begin{array}{cccc|c} 1 & 0 & -2 & 0 & -24 \\ 0 & 1 & -2 & 0 & -7 \\ 0 & 0 & 0 & 1 & 4 \end{array} \right]$$

$$x_1 = -24 + 2x_3, \quad x_2 = -7 + 2x_3, \quad x_3 \text{ free}, \quad x_4 = 4$$



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- compute the LU decomposition  $A = LU$

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} = \begin{bmatrix} 1 & & \\ 2 & 1 & \\ -1 & -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ & -8 & -2 \\ & & 1 \end{bmatrix}$$

# Using Gaussian elimination

- compute the inverse of a matrix

to find  $\begin{bmatrix} 2 & 0 & 0 \\ -3 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}^{-1} = \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 \\ \frac{3}{2} & 1 & 0 \end{bmatrix}$ , we use Gauss-Jordan:

$$\begin{bmatrix} 2 & 0 & 0 & 1 & 0 & 0 \\ -3 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 & \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & \frac{3}{2} & 1 & 0 \end{bmatrix}$$

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(Each solution  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  gives a linear combination

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} ).$$

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- Once a particular solution  $\mathbf{x}_p$  exists, the set of all solutions is  $\mathbf{x}_p + Nul(A)$ .
- So the solution is *unique* if and only if  $Nul(A) = \mathbf{0}$ .

# Midterm

7:00PM-8:15PM, Thursday, February 19th

Students last name A-G: 114 David Kinley Hall

Students last name H-Ra: 100 Noyes Lab

Students last name Re-Zu: 112 Greg Hall

Bring [university ID](#). No books, notes, or electronic devices.

Good luck!