$$y(k) = Cov(Y_{t}, Y_{t-k}) = ...$$
 $k > 1.$ $Y_{t} = e_{t} - \theta e_{t-1}$ $Y_{t-k} = e_{t-k} - \theta e_{t-k-1}$... = 0.

 $\dots = -\theta \sigma_{\epsilon}^2$.

Therefore,
$$\rho_0=1, \qquad \qquad \rho_1=\frac{-\theta}{1+\theta^2},$$

$$\rho_k=0, \qquad k{>}1.$$

MA(q)
$$Y_t = e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2} - \dots - \theta_q e_{t-q}$$

$$\gamma(0) = Var(Y_t) = Cov(Y_t, Y_t) = ...$$

$$\begin{array}{rclcrcl} \mathbf{Y}_t & = & e_t & -\theta_1 \, e_{t-1} & -\theta_2 \, e_{t-2} & \dots & -\theta_q \, e_{t-q} \\ \mathbf{Y}_t & = & e_t & -\theta_1 \, e_{t-1} & -\theta_2 \, e_{t-2} & \dots & -\theta_q \, e_{t-q} \\ & \dots & = & \sigma_e^2 \, \big(1 + \theta_1^{\, 2} + \theta_2^{\, 2} + \dots + \theta_q^{\, 2} \big). \end{array}$$

$$\gamma(1) = \text{Cov}(Y_t, Y_{t-1}) = \dots$$

$$\begin{array}{rclcrcl} \mathbf{Y}_t & = & e_t & -\theta_1 e_{t-1} & -\theta_2 e_{t-2} & \dots & -\theta_q e_{t-q} \\ \mathbf{Y}_{t-1} & = & & e_{t-1} & -\theta_1 e_{t-2} & \dots & -\theta_{q-1} e_{t-q} & -\theta_q e_{t-q-1} \\ & \dots & = \sigma_e^2 \; (-\theta_1 + \theta_1 \theta_2 + \theta_2 \theta_3 + \dots + \theta_{q-1} \theta_q). \end{array}$$

$$\begin{split} \gamma(k) &= \mathrm{Cov}(\Upsilon_t, \Upsilon_{t-k}) = \dots \\ & \qquad \qquad k = 1, \dots, q-1 \\ & \qquad \qquad \dots = \sigma_e^{\,2} \, (-\,\theta_k + \theta_1 \theta_{k+1} + \theta_2 \theta_{k+2} + \dots + \theta_{q-k} \theta_q). \end{split}$$

$$\gamma(q) = \text{Cov}(Y_t, Y_{t-q}) = -\theta_q \sigma_e^2.$$

$$\gamma(k) = \operatorname{Cov}(Y_t, Y_{t-k}) = 0, \qquad k > q.$$

Therefore,

$$\begin{split} \rho_k &= \frac{-\theta_k + \theta_1 \theta_{k+1} + \ldots + \theta_{q-k} \theta_q}{1 + \theta_1^2 + \ldots + \theta_q^2}, \qquad k = 1, \ldots, q-1, \\ \rho_q &= \frac{-\theta_q}{1 + \theta_1^2 + \ldots + \theta_q^2}, \\ \rho_k &= 0, \qquad k > q. \end{split}$$

$$\operatorname{Corr}(\mathbf{Y}_t, \mathbf{Y}_{t+k} | \mathbf{Y}_{t+1}, \dots, \mathbf{Y}_{t+k-1})$$

Consider a regression type model

$$\mathbf{Y}_{t+k} = \boldsymbol{\phi}_{k1} \, \mathbf{Y}_{t+k-1} + \boldsymbol{\phi}_{k2} \, \mathbf{Y}_{t+k-2} + \ldots + \boldsymbol{\phi}_{kk} \, \mathbf{Y}_{t} + \boldsymbol{e}_{t+k}$$

Consider

Cov
$$(..., Y_{t+k-j})$$
, $j = 1, 2, ..., k$. Divide by γ_0 :

$$\rho_{1} = \phi_{k1}\rho_{0} + \phi_{k2}\rho_{1} + \dots + \phi_{kk}\rho_{k-1}$$

$$\rho_{2} = \phi_{k1}\rho_{1} + \phi_{k2}\rho_{0} + \dots + \phi_{kk}\rho_{k-2}$$

$$\dots$$

$$\rho_{k} = \phi_{k1}\rho_{k-1} + \phi_{k2}\rho_{k-2} + \dots + \phi_{kk}\rho_{0}$$

$$PACF(k) = Corr(Y_t, Y_{t+k} | Y_{t+1}, \dots, Y_{t+k-1}) = \phi_{kk}.$$

k = 1:

$$\rho_1 = \phi_{11} \rho_0 = \phi_{11}$$

$$\phi_{11} = \rho_1$$

k = 2:

$$\rho_{1} = \phi_{21} \rho_{0} + \phi_{22} \rho_{1}$$

$$\rho_{2} = \phi_{21} \rho_{1} + \phi_{22} \rho_{0}$$

$$\phi_{21} = \frac{\rho_{1} - \rho_{1} \rho_{2}}{1 - \rho_{1}^{2}}$$

$$\phi_{22} = \frac{\rho_{2} - \rho_{1}^{2}}{1 - \rho_{1}^{2}}$$

and so on...

AR(1)	MA(1)
$\rho_k = \phi^k$	$\rho_1 = \frac{-\theta}{1+\theta^2}$ $\rho_k = 0, \qquad k > 1$
$\phi_{11} = \rho_1 = \phi$ $\phi_{kk} = 0, k > 1$	$\phi_{kk} = \frac{-\theta^k}{1 + \theta^2 + \theta^4 + \dots + \theta^{2k}}$ $= \frac{-\theta^k (1 - \theta^2)}{1 - \theta^{2(k+1)}}$

Determine whether the following processes are stationary:

a)
$$Y_t + 0.2 Y_{t-1} = e_t - 0.8 e_{t-1} + 0.5 e_{t-2}$$

$$\Phi(B) = 1 + 0.2B$$

The root of $\Phi(z) = 0$ is z = -5, it is outside the unit circle.

 \Rightarrow This process is stationary.

b)
$$Y_{t} - 0.1 Y_{t-1} - 0.2 Y_{t-2} = e_{t} - 0.6 e_{t-1}$$

$$\Phi(B) = 1 - 0.1B - 0.2B^2 = (1 - 0.5B)(1 + 0.4B)$$

The roots of $\Phi(z) = 0$ are $z_1 = 2$ and $z_2 = -2.5$.

All roots of $\Phi(z) = 0$ are outside the unit circle.

 \Rightarrow This process is stationary.

OR

An AR(2) model is stationary if

$$-1 < \phi_2 < 1,$$
 $\phi_2 + \phi_1 < 1,$ $\phi_2 - \phi_1 < 1.$

$$-1 < 0.2 < 1,$$
 $0.2 + 0.1 < 1,$ $0.2 - 0.1 < 1.$

 \Rightarrow This process is stationary.

c)
$$Y_{t} - 0.7 Y_{t-1} - 0.6 Y_{t-2} = e_{t} + 0.9 e_{t-1} - 0.7 e_{t-2}$$

$$\Phi(B) = 1 - 0.7B - 0.6B^2 = (1 - 1.2B)(1 + 0.5B)$$

The roots of $\Phi(z) = 0$ are $z_1 = \frac{5}{6}$ and $z_2 = -2$. $z_1 = \frac{5}{6}$ is NOT outside the unit circle, it is inside the unit circle. The roots of $\Phi(z) = 0$ must ALL be outside the unit circle for the process to be stationary.

 \Rightarrow This process is NOT stationary.

An AR(2) model is stationary if

$$-1 < \phi_2 < 1, \qquad \qquad \phi_2 + \phi_1 < 1,$$

$$\phi_2 + \phi_1 < 1,$$

$$\phi_2 - \phi_1 < 1.$$

$$-1 < 0.6 < 1,$$
 $0.6 + 0.7 > 1,$

$$0.6 + 0.7 > 1$$

$$0.6 - 0.7 < 1.$$



This process is NOT stationary. \Rightarrow

d)
$$Y_{t} - 0.8 Y_{t-1} + 0.25 Y_{t-2} = e_{t}$$

$$\Phi(B) = 1 - 0.8B + 0.25B^2$$

The roots of
$$\Phi(z) = 0$$
 are $z_{1, 2} = \frac{0.8 \pm \sqrt{0.8^2 - 4 \cdot 0.25 \cdot 1}}{2 \cdot 0.25} = 1.6 \pm 1.2 i$.

All roots of $\Phi(z) = 0$ are outside the unit circle.

This process is stationary.

OR

An AR(2) model is stationary if

$$-1 < \phi_2 < 1,$$
 $\phi_2 + \phi_1 < 1,$ $\phi_2 - \phi_1 < 1.$

$$\phi_2 + \phi_1 < 1,$$

$$\phi_2 - \phi_1 < 1.$$

$$-1 < -0.25 < 1,$$
 $-0.25 + 0.8 < 1,$ $-0.25 - 0.8 < 1.$

$$-0.25 + 0.8 < 1,$$

$$-0.25 - 0.8 < 1.$$

This process is stationary.

e)
$$Y_t = e_t - 0.6 e_{t-1} - 0.4 e_{t-2} - 0.2 e_{t-3}$$

$$\Phi(B) = 1$$

No roots of $\Phi(z) = 0$ inside or on the unit circle.

 \Rightarrow This process is stationary.

f)
$$Y_t - \frac{14}{13} Y_{t-1} + \frac{10}{13} Y_{t-2} = e_t + 0.7 e_{t-1}$$

$$\Phi(B) = 1 - \frac{14}{13}B + \frac{10}{13}B^2$$

The roots of $\Phi(z) = 0$ are $z_{1, 2} = \frac{14 \pm \sqrt{14^2 - 4 \cdot 10 \cdot 13}}{2 \cdot 10} = 0.7 \pm 0.9 i$.

 $|z_{1,2}|^2 = 0.7^2 + 0.9^2 = 1.3$. All roots of $\Phi(z) = 0$ are outside the unit circle.

 \Rightarrow This process is stationary.

OR

An AR(2) model is stationary if

$$-1 < \phi_2 < 1, \qquad \phi_2 + \phi_1 < 1, \qquad \phi_2 - \phi_1 < 1.$$

$$-1 < -\frac{10}{13} < 1, \qquad -\frac{10}{13} + \frac{14}{13} < 1, \qquad -\frac{10}{13} - \frac{14}{13} < 1.$$

 \Rightarrow This process is stationary.

g)
$$Y_{t} - 0.7 Y_{t-1} - 0.3 Y_{t-2} = e_{t} + 0.5 e_{t-1}$$

$$\Phi(B) = 1 - 0.7B - 0.3B^{2} = (1 - B)(1 + 0.3B)$$

The roots of $\Phi(z) = 0$ are $z_1 = 1$ and $z_2 = -3\frac{1}{3}$. $z_1 = 1$ is NOT outside the unit circle, it is on the unit circle. The roots of $\Phi(z) = 0$ must ALL be outside the unit circle for the process to be stationary.

 \Rightarrow This process is NOT stationary. ARIMA(1,1,1)

OR

An AR(2) model is stationary if

$$-1 < \phi_2 < 1,$$
 $\phi_2 + \phi_1 < 1,$ $\phi_2 - \phi_1 < 1.$ $-1 < 0.3 < 1,$ $0.3 + 0.7 = 1,$ $0.3 - 0.7 < 1.$

 \Rightarrow This process is NOT stationary.

1. Consider the ARMA(1, 1) process

or
$$(\mathbf{Y}_t - \) = \phi(\mathbf{Y}_{t-1} - \) + e_t - \theta e_{t-1}$$

$$(\mathbf{1} - \phi \mathbf{B}) \ \dot{\mathbf{Y}}_t = (\mathbf{1} - \theta \mathbf{B}) e_t, \quad \text{where } \dot{\mathbf{Y}}_t = \mathbf{Y}_t - \ .$$
 Suppose
$$\mathbf{E}(e_t) = \mathbf{0}, \quad \mathbf{Var}(e_t) = \sigma_e^2 \quad \text{for all } t$$

$$\mathbf{E}(e_t e_s) = \mathbf{0}, \quad \text{for } t \neq s$$

$$\mathbf{E}(e_t \mathbf{Y}_s) = \mathbf{0}, \quad \text{for } s < t$$

Derive the expression for $\, \rho_k \,$ in terms of $\, \phi \,$ and $\, \theta \! . \,$

$$\begin{aligned} \operatorname{Cov}(\mathbf{Y}_t, e_t) &= \operatorname{E}[(\mathbf{Y}_{t^{--}}) e_t] \\ &= \phi \operatorname{E}[(\mathbf{Y}_{t-1} - \) e_t] + \operatorname{E}[e_t^2] - \theta \operatorname{E}[e_{t-1} e_t] \\ &= \sigma_e^2. \end{aligned}$$

$$\begin{split} \gamma(0) &= \mathrm{Var}(\mathbf{Y}_t) = \mathbb{E}[(\mathbf{Y}_{t-1})^2] \\ &= \phi^2 \, \mathbb{E}[(\mathbf{Y}_{t-1} - \)^2] + \mathbb{E}[e_t^2] + \theta^2 \, \mathbb{E}[e_{t-1}^2] \\ &\quad + 2 \, \phi \mathbb{E}[(\mathbf{Y}_{t-1} - \)e_t] - 2 \, \phi \, \theta \mathbb{E}[(\mathbf{Y}_{t-1} - \)e_{t-1}] \\ &\quad - 2 \, \theta \mathbb{E}[e_t e_{t-1}] \\ &= \phi^2 \, \gamma(0) + \sigma_e^2 + \theta^2 \, \sigma_e^2 - 2 \, \phi \, \theta \, \sigma_e^2 \, . \end{split}$$

$$\Rightarrow \qquad \gamma(0) = \sigma_e^2 \cdot \frac{\left(1 - 2\phi\theta + \theta^2\right)}{1 - \phi^2}.$$

$$\begin{split} \gamma(1) &= \text{Cov}(Y_t, Y_{t-1}) = \text{E}[(Y_{t-1})(Y_{t-1} -)] \\ &= \phi \text{E}[(Y_{t-1} -)^2] + \text{E}[e_t(Y_{t-1} -)] - \theta \text{E}[e_{t-1}(Y_{t-1} -)] \\ &= \phi \gamma(0) - \theta \sigma_e^2 \\ &= \sigma_e^2 \cdot \frac{\phi(1 - 2\phi\theta + \theta^2) - \theta(1 - \phi^2)}{1 - \phi^2} \\ &= \sigma_e^2 \cdot \frac{\phi - 2\phi^2\theta + \phi\theta^2 - \theta + \phi^2\theta}{1 - \phi^2} \\ &= \sigma_e^2 \cdot \frac{\phi - \theta - \phi^2\theta + \phi\theta^2}{1 - \phi^2} \\ &= \sigma_e^2 \cdot \frac{(\phi - \theta)(1 - \phi\theta)}{1 - \phi^2} \end{split}$$

$$\Rightarrow \rho_1 = \frac{\gamma(1)}{\gamma(0)} = \frac{(\phi - \theta)(1 - \phi\theta)}{1 - 2\phi\theta + \theta^2}.$$

k > 1

$$\begin{split} \gamma(k) &= \operatorname{Cov}(\mathbf{Y}_t, \mathbf{Y}_{t-k}) = \operatorname{E}[(\mathbf{Y}_{t^-})(\mathbf{Y}_{t-k^-})] \\ &= \phi \operatorname{E}[(\mathbf{Y}_{t-1})(\mathbf{Y}_{t-k^-})] + \operatorname{E}[e_t(\mathbf{Y}_{t-k^-})] \\ &- \theta \operatorname{E}[e_{t-1}(\mathbf{Y}_{t-k^-})] \\ &= \phi \gamma(k-1). \end{split}$$

$$\Rightarrow \rho_k = \frac{\phi^{k-1}(\phi-\theta)(1-\phi\theta)}{1-2\phi\theta+\theta^2}, \qquad k \ge 1.$$