Math 415 - Lecture 3

Existence and Uniqueness, linear combinations

Friday August 28 2015

Textbook: Chapter 1.2

Suggested Practice Exercise: Read section 1.2, do problem 1.3:9 (drawing optional)

Khan Academy Video: Linear Combinations and Span

1 Review

Existence and Uniqueness Theorem

Theorem 1 (Existence and Uniqueness Theorem). A linear system is **consistent** if and only if an echelon form of the augmented matrix has **no** row of the form

$$\begin{bmatrix} 0 & \dots & 0 & b \end{bmatrix}$$

where b is nonzero. If a linear system is consistent, then the solution contains either

- a unique solution (when there are no free variables) or
- infinitely many solutions (when there is at least one free variable).

Example 1. A consistent system can have 1 or ∞ many solutions. Look at the system with augmented matrix

$$\begin{bmatrix} 3 & 4 & | & -3 \\ 2 & 5 & | & 5 \\ -2 & -3 & | & 1 \end{bmatrix}$$

How many pivot variables can this matrix have? Do you expect the system to be consistent? Well, there are at most 2 pivots, so the last row of an echelon form should be $\begin{bmatrix} 0 & 0 & b \end{bmatrix}$. We cannot predict the value of b without doing some work. We need an echelon form.

The (reduced) echelon form of

$$\begin{bmatrix} 3 & 4 & | & -3 \\ 2 & 5 & | & 5 \\ -2 & -3 & | & 1 \end{bmatrix} \quad \text{is} \quad \begin{bmatrix} 1 & 0 & | & -5 \\ 0 & 1 & | & 3 \\ 0 & 0 & | & 0 \end{bmatrix}$$

- So what is b? Is the system consistent? b = 0 so consistent.
- So how many pivots? 2 pivots.
- How many free variables? No free variables.
- How many solutions? Exactly one!

Look now at the system with augmented matrix

$$\begin{bmatrix} 3 & 4 & | & -3 \\ 3 & 4 & | & -3 \\ 6 & 8 & | & -6 \end{bmatrix}$$

- How many free variables can this matrix have? One or two. Need to calculate.
- What is the Echelon form? $\begin{bmatrix} 3 & 4 & | & -3 \\ 0 & 0 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}.$
- Is the system consistent? Yes!
- How many free variables? Exactly one free variable!
- How many solutions? ∞ ly many!

1.1 Recap

Recap: Using Row Reduction to Solve Linear Systems

Use the following algorithm:

- 1. Write the augmented matrix of the system.
- 2. Use the row reduction algorithm to obtain an equivalent augmented matrix in echelon form. Decide whether the system is consistent. If not, stop; otherwise go to the next step.
- 3. Continue row reduction to obtain the reduced echelon form.
- 4. Write the system of equations corresponding to the matrix obtained in step 3.
- 5. State the solution by expressing each pivot variable in terms of the free variables and declare the free variables.

1.2 Questions

Questions to check understanding

- On an exam, you are asked to find all solutions to a system of linear equations. You find exactly two solutions. Should you be worried? YES!
- True or false?
 - There is no more than one pivot in any row. TRUE!
 - There is no more than one pivot in any column. TRUE!
 - There cannot be more free variables than pivot variables. FALSE!
 - Why? Look at the equation

$$x_1 + x_2 + x_3 = 0.$$

How many pivot variables? Free variables?

2 Geometry of Linear Equations

Definition. A vector in \mathbb{R}^n is

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix},$$

i.e., a column with n numbers x_1, x_2, \ldots, x_n in it.

Definition. The **Sum** of
$$\mathbf{u} = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix}$$
 and $\mathbf{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$ is $\mathbf{u} + \mathbf{v} = \begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \\ \vdots \\ u_n + v_n \end{bmatrix}$.

Let c be a real number. Then we define the **Scalar Multiple** $c\bar{\mathbf{u}}$ by

$$c\mathbf{u} = \begin{bmatrix} cu_1 \\ cu_2 \\ \vdots \\ cu_n \end{bmatrix}$$

Example 2. Let
$$\mathbf{u} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$
 and $\mathbf{v} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$. Then $\mathbf{u} + \mathbf{v}$ is $\begin{bmatrix} 3 \\ 4 \end{bmatrix}$ and $2\mathbf{u}$ and $-\frac{3}{2}\mathbf{u}$ are $\begin{bmatrix} 2 \\ 6 \end{bmatrix}$ and $\begin{bmatrix} -3/2 \\ -\frac{9}{2} \end{bmatrix}$.

2.1 Linear Combinations

Definition. Given vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ in \mathbb{R}^n and given scalars c_1, c_2, \dots, c_p , the vector \mathbf{y} defined by

$$\mathbf{y} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_p \mathbf{v}_p$$

is called a **linear combination** of $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ using scalars (or weights) c_1, c_2, \dots, c_p .

Example 3. Linear combinations don't all look the same. The following are linear combinations of \mathbf{v}_1 and \mathbf{v}_2 :

- $3\mathbf{v}_1 + 2\mathbf{v}_2$,
- $\frac{1}{3}$ **v**₁,
- $\mathbf{v}_1 2\mathbf{v}_2$,
- 0.

Example 4. Let $\mathbf{v}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} -2 \\ 2 \end{bmatrix}$. Express each of the following as a linear combination of \mathbf{v}_1 and \mathbf{v}_2 :

$$\mathbf{a} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} -4 \\ 1 \end{bmatrix}, \quad \mathbf{c} = \begin{bmatrix} 6 \\ 6 \end{bmatrix}, \quad \mathbf{d} = \begin{bmatrix} 7 \\ -4 \end{bmatrix}$$

Solution. Try first $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 = \mathbf{a}$ or $c_1\begin{bmatrix} 2\\1 \end{bmatrix} + c_2\begin{bmatrix} -2\\2 \end{bmatrix} = \begin{bmatrix} 0\\3 \end{bmatrix}$. Staring at this you see that $c_1 = c_2$ and hence $\mathbf{v}_1 + \mathbf{v}_2 = \mathbf{a}$ or $\begin{bmatrix} 2\\1 \end{bmatrix} + \begin{bmatrix} -2\\2 \end{bmatrix} = \begin{bmatrix} 0\\3 \end{bmatrix}$. Try the others for your selves.

Example 5. Let
$$\mathbf{a}_1 = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$$
, $\mathbf{a}_2 = \begin{bmatrix} 4 \\ 2 \\ 14 \end{bmatrix}$, $\mathbf{a}_3 = \begin{bmatrix} 3 \\ 6 \\ 10 \end{bmatrix}$, and $\mathbf{b} = \begin{bmatrix} -1 \\ 8 \\ -5 \end{bmatrix}$.

Determine if **b** is a linear combination of $\bar{\mathbf{a}}_1$, $\bar{\mathbf{a}}_2$, and $\bar{\mathbf{a}}_3$.

Solution. Vector **b** is a linear combination of \mathbf{a}_1 , \mathbf{a}_2 , and \mathbf{a}_3 if can we find scalars (weights) x_1, x_2, x_3 such that $x_1 \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix} + x_2 \begin{bmatrix} 4 \\ 2 \\ 14 \end{bmatrix} + x_3 \begin{bmatrix} 3 \\ 6 \\ 10 \end{bmatrix} = \begin{bmatrix} -1 \\ 8 \\ -5 \end{bmatrix}$. It is easy to check that $x_1 = 1, x_2 = -2, x_3 = 2$ works, so **b** is indeed a linear combination. How to find these numbers?

How to find these numbers?: a_1 , a_2 , a_3 and b are columns of the augmented matrix

$$\begin{bmatrix} 1 & 4 & 3 & -1 \\ 0 & 2 & 6 & 8 \\ 3 & 14 & 10 & -5 \end{bmatrix}$$

$$\uparrow \quad \uparrow \quad \uparrow \quad \uparrow$$

$$\mathbf{a}_1 \quad \mathbf{a}_2 \quad \mathbf{a}_3 \quad \mathbf{b}$$

Solution to

$$x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + x_3\mathbf{a}_3 = \mathbf{b}$$

is found by solving the linear system whose augmented matrix is

$$\begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \mathbf{a}_3 & \mathbf{b} \end{bmatrix}$$
.

2.2 Linear combinations and linear systems

Motto

Solving linear systems is the same as finding linear combinations!

Theorem 2. A vector equation

$$x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \dots + x_n\mathbf{a}_n = \mathbf{b}$$

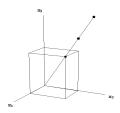
has the same solution set as the linear system whose augmented matrix is

$$\begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n & | & \mathbf{b} \end{bmatrix}$$

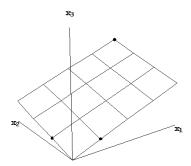
In particular, **b** can be generated by a linear combination of $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n$ if and only if there is a solution to the linear system corresponding to the augmented matrix.

2.3 Span

Example 6. Let $\mathbf{v} = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix}$. The origin $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ together with \mathbf{v} , $2\mathbf{v}$ and $1.5\mathbf{v}$ all lie on the same line.



 $\mathbf{Span}\{\mathbf{v}\}$ is the set of all vectors of the form $c\mathbf{v}$. Here, $\mathbf{Span}\{\mathbf{v}\}=$ a line through the origin.



Example 7. Label \mathbf{u} , \mathbf{v} , $\mathbf{u} + \mathbf{v}$ and $3\mathbf{u} + 4\mathbf{v}$ on the graph below. \mathbf{u} , \mathbf{v} , $\mathbf{u} + \mathbf{v}$ and $3\mathbf{u} + 4\mathbf{v}$ all lie in the same plane. $\mathbf{Span}\{\mathbf{u}, \mathbf{v}\}$ is the set of all vectors of the form $x_1\mathbf{u} + x_2\mathbf{v}$. Here, $\mathbf{Span}\{\mathbf{u}, \mathbf{v}\} = \mathbf{a}$ plane through the origin.

Definition. Suppose $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ are in \mathbb{R}^n ; then the $\mathbf{Span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$ is defined as the set of all linear combinations of $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$.

Stated another way: $\mathbf{Span}\{\mathbf{v}_1,\mathbf{v}_2,\ldots,\mathbf{v}_p\}$ is the collection of all vectors that can be written as

$$x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + \dots + x_p\mathbf{v}_p$$

where x_1, x_2, \ldots, x_p are scalars.

Example 8. Let $\mathbf{v}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$.

- (a) Find a vector in $\mathbf{Span}\{\mathbf{v}_1,\mathbf{v}_2\}$.
- (b) Describe $Span\{v_1, v_2\}$ geometrically.

Solution. (a) For instance $2\mathbf{v}_1 = \mathbf{v}_2$.

(b) $Span\{\mathbf{v}_1, \mathbf{v}_2\}$ is the collection of all vectors in the direction of \mathbf{v}_1 (or \mathbf{v}_2 !). It is a line through the origin.

So the **Span** of two vectors is a plane if and only if they don't point in the same direction.

Example 9. Let
$$\mathbf{v}_1 = \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix}$$
 and $\mathbf{v}_2 = \begin{bmatrix} 6 \\ 3 \\ 2 \end{bmatrix}$. Is $\mathbf{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$ a line or a plane?

Is v_1 a multiple of v_2 ? Do they point in the same direction?

Example 10. Let $A = \begin{bmatrix} 1 & 2 \\ 3 & 1 \\ 0 & 5 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} 8 \\ 3 \\ 17 \end{bmatrix}$. Is \mathbf{b} in the plane spanned by the columns of A?

Solution.

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 1 \\ 0 & 5 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 8 \\ 3 \\ 17 \end{bmatrix}$$

Do x_1 and x_2 exist such that

$$x_1 \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 1 \\ 5 \end{bmatrix} = \begin{bmatrix} 8 \\ 3 \\ 17 \end{bmatrix}?$$

pause Try and find the answer at home.