

Math 415 - Lecture 25

Multiple linear regression, Gram Schmidt and Orthogonal matrices

Monday October 26th 2015

Textbook reading: Chapters 3.3,3.4

Suggested practice exercises: Chapter 3.3, 3,5,6,13,22,24,25,26 and Chapter 3.4, 10,11,13,14,16,26

Khan Academy video: Another Least Squares Example, Gram-Schmidt Example

Strang lecture: Orthogonal Matrices and Gram-Schmidt Process.

1 Review

$\hat{\mathbf{x}}$ is a **least squares solution** of the system $A\mathbf{x} = \mathbf{b}$

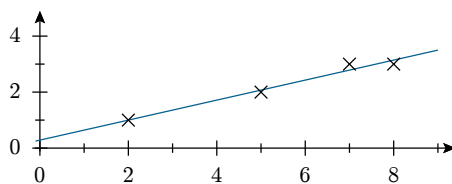
$\iff \hat{\mathbf{x}}$ is such that $A\hat{\mathbf{x}} - \mathbf{b}$ is as small as possible

$\xLeftrightarrow{FTLA} A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$ (the **normal equations**)

2 Application: fitting data

2.1 Least square lines

Example 1. Find β_1, β_2 such that the line $y = \beta_1 + \beta_2 x$ best fits the data points $(2, 1), (5, 2), (7, 3), (8, 3)$.

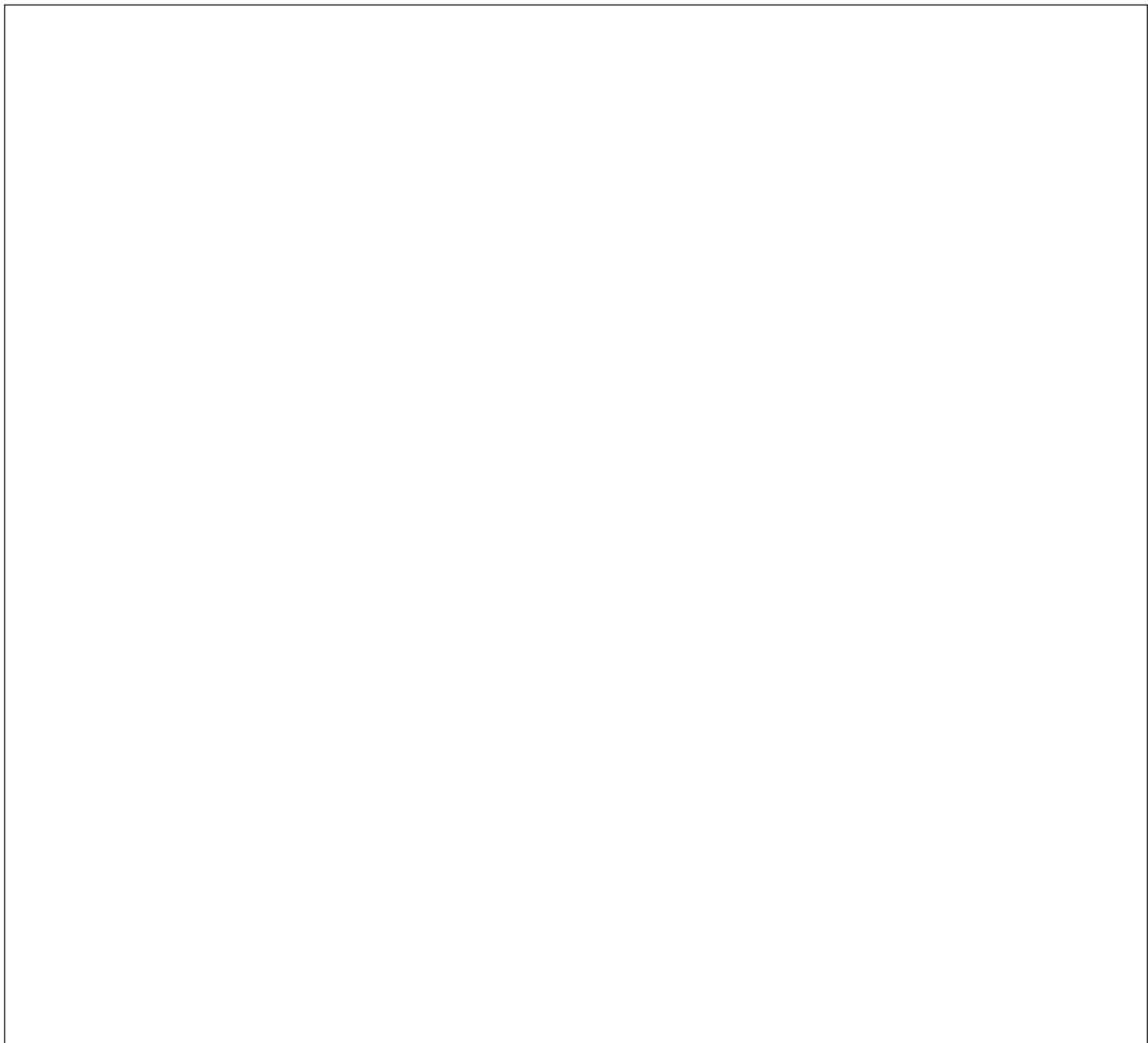


The equations $y = \beta_1 + \beta_2 x$ in matrix form:

$$\underbrace{\begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ 1 & x_3 \\ 1 & x_4 \end{bmatrix}}_{\text{design matrix } X} \underbrace{\begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix}}_{\text{observation vector } \mathbf{y}} = \underbrace{\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}}_{\text{observation vector } \mathbf{y}}$$

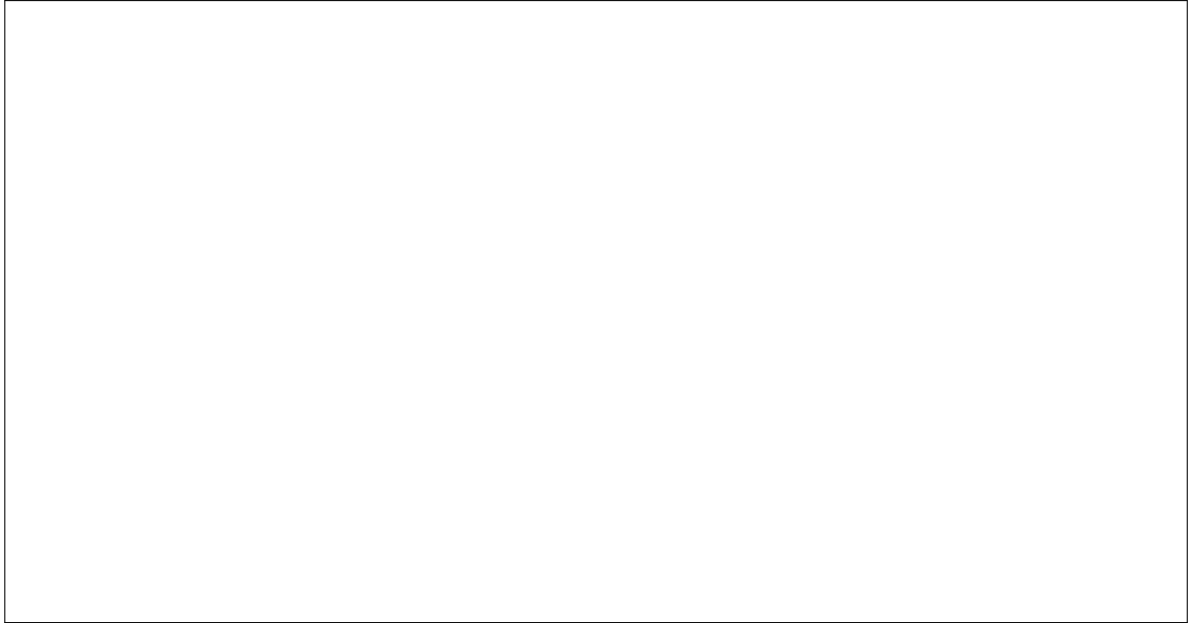
Here, we need to find a least squares solution to

$$\begin{bmatrix} 1 & 2 \\ 1 & 5 \\ 1 & 7 \\ 1 & 8 \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix}.$$



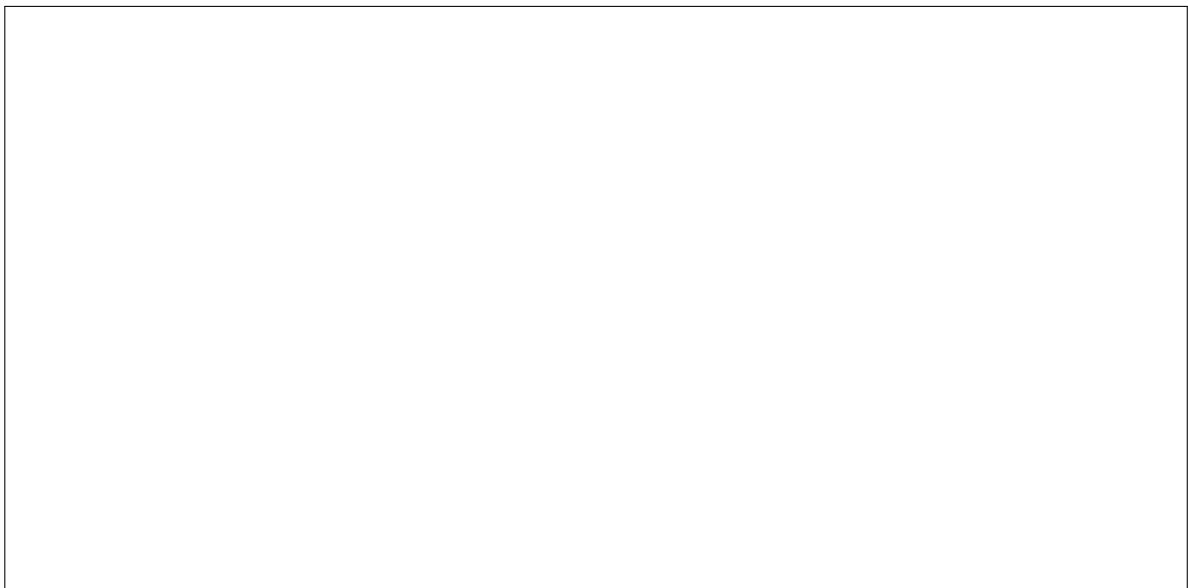
2.2 Fitting to other curves

What happens if the data just lie close to any line? We can also fit the experimental data using other curves. Try to find $\beta_1, \beta_2, \beta_3$ such that $y = \beta_1 + \beta_2 x + \beta_3 x^2$ fits the data.

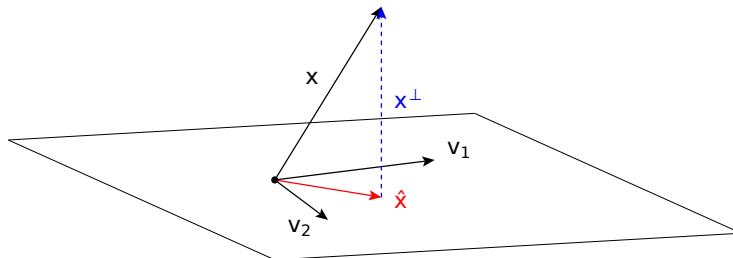


2.3 Multiple linear regression

Of course, sometimes the variable y might not just depend on a single variable x , but on two variables, say u and v . So, here you have find the least-squares solution of



3 Review



Suppose $\mathbf{v}_1, \dots, \mathbf{v}_m$ is an orthonormal basis of W . The **orthogonal projection** of \mathbf{x} onto W is :

$$\hat{\mathbf{x}} = \underbrace{\langle \mathbf{x}, \mathbf{v}_1 \rangle \mathbf{v}_1}_{\text{proj. of } \mathbf{x} \text{ onto } \mathbf{v}_1} + \dots + \underbrace{\langle \mathbf{x}, \mathbf{v}_m \rangle \mathbf{v}_m}_{\text{proj. of } \mathbf{x} \text{ onto } \mathbf{v}_m}$$

(To stay agile, we are writing $\langle \mathbf{x}, \mathbf{v}_1 \rangle = \mathbf{x} \cdot \mathbf{v}_1$ for the inner product.)

4 Gram-Schmidt

- * In calculating projections we used an *orthogonal basis* and the easy formula for the coefficients.
- * What if we are given an arbitrary basis, not orthogonal?
- * Turn the starting basis into an orthogonal (or orthonormal) basis.
- * **Gram-Schmidt Process.**

Recipe. (Gram-Schmidt orthonormalization)

Given a basis $\mathbf{a}_1, \dots, \mathbf{a}_n$, produce a **orthogonal basis** $\mathbf{b}_1, \dots, \mathbf{b}_n$ and an **orthonormal basis** $\mathbf{q}_1, \dots, \mathbf{q}_n$.

$$\begin{aligned} \mathbf{b}_1 &= \mathbf{a}_1, & \mathbf{q}_1 &= \frac{\mathbf{b}_1}{\|\mathbf{b}_1\|} \\ \mathbf{b}_2 &= \mathbf{a}_2 - \langle \mathbf{a}_2, \mathbf{q}_1 \rangle \mathbf{q}_1, & \mathbf{q}_2 &= \frac{\mathbf{b}_2}{\|\mathbf{b}_2\|} \\ \mathbf{b}_3 &= \mathbf{a}_3 - \langle \mathbf{a}_3, \mathbf{q}_1 \rangle \mathbf{q}_1 - \langle \mathbf{a}_3, \mathbf{q}_2 \rangle \mathbf{q}_2, & \mathbf{q}_3 &= \frac{\mathbf{b}_3}{\|\mathbf{b}_3\|} \\ \dots & & \dots & \end{aligned}$$

Example 2. Find an orthonormal basis for $V = \text{Span}\left\{\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}\right\}$.

Solution.

Why does Gram-Schmidt work? Recall, if W is a subspace, \mathbf{b} any vector, then

$$\hat{\mathbf{b}} \rightsquigarrow \text{projection to } W, \mathbf{b}^\perp = \mathbf{b} - \hat{\mathbf{b}} \rightsquigarrow \text{orth. to } W$$

Recipe. (Gram-Schmidt orthonormalization)

Given a basis $\mathbf{a}_1, \dots, \mathbf{a}_n$, produce a **orthogonal basis** $\mathbf{b}_1, \dots, \mathbf{b}_n$ and an **orthonormal basis** $\mathbf{q}_1, \dots, \mathbf{q}_n$.

$$\begin{aligned} \mathbf{b}_1 &= \mathbf{a}_1, & \mathbf{q}_1 &= \underbrace{\frac{\mathbf{b}_1}{\|\mathbf{b}_1\|}}_{\text{normalize}} \\ \mathbf{b}_2 &= \mathbf{a}_2 - \underbrace{\langle \mathbf{a}_2, \mathbf{q}_1 \rangle \mathbf{q}_1}_{\hat{\mathbf{a}}_2 \rightsquigarrow \text{projection to Span}\{\mathbf{q}_1\}} \underbrace{\mathbf{a}_2 - \langle \mathbf{a}_2, \mathbf{q}_1 \rangle \mathbf{q}_1}_{\mathbf{a}_2^\perp \rightsquigarrow \text{orth. to Span}\{\mathbf{q}_1\}}, & \mathbf{q}_2 &= \underbrace{\frac{\mathbf{b}_2}{\|\mathbf{b}_2\|}}_{\text{normalize}} \\ \mathbf{b}_3 &= \underbrace{\mathbf{a}_3 - (\langle \mathbf{a}_3, \mathbf{q}_1 \rangle \mathbf{q}_1 + \langle \mathbf{a}_3, \mathbf{q}_2 \rangle \mathbf{q}_2)}_{\mathbf{a}_3^\perp \text{ orth. to Span}\{\mathbf{q}_1, \mathbf{q}_2\}} & \mathbf{q}_3 &= \underbrace{\frac{\mathbf{b}_3}{\|\mathbf{b}_3\|}}_{\text{normalize}} \\ \dots & & & \dots \end{aligned}$$

Example 3. Let $V = \text{Span}\left\{\begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix}\right\}$. Find an orthonormal basis for V . Check that your basis is actually orthonormal.

Solution.

4.1 Orthogonal matrices

Theorem 1. Let $A = [\mathbf{a}_1, \dots, \mathbf{a}_n]$ be any matrix. Then $A^T A$ is the matrix of dot products of the columns of A :

$$A^T A = \begin{bmatrix} \mathbf{a}_1 \cdot \mathbf{a}_1 & \mathbf{a}_1 \cdot \mathbf{a}_2 & \mathbf{a}_1 \cdot \mathbf{a}_3 & \dots \\ \mathbf{a}_2 \cdot \mathbf{a}_1 & \mathbf{a}_2 \cdot \mathbf{a}_2 & \mathbf{a}_2 \cdot \mathbf{a}_3 & \dots \\ \mathbf{a}_3 \cdot \mathbf{a}_1 & \mathbf{a}_3 \cdot \mathbf{a}_2 & \mathbf{a}_3 \cdot \mathbf{a}_3 & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

What happens if the columns of A are orthonormal?

Theorem 2. The columns of Q are orthonormal $\iff Q^T Q = I$

Proof.



□

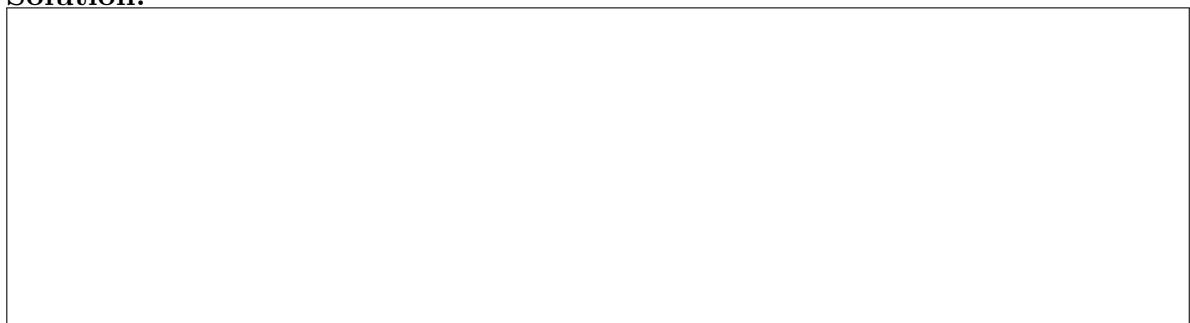
Definition. An **orthogonal matrix** is a square matrix Q with orthonormal columns.

It is historical convention to restrict to square matrices, and to say orthogonal matrix even though “orthonormal matrix” might be better.

An $n \times n$ matrix Q is orthogonal $\iff Q^T Q = I$ In other words, $Q^{-1} = Q^T$.

Example 4. $P = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$ is orthogonal. Why?

Solution.



Example 5. $Q = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ is orthogonal, Why?

Solution.

Example 6. Is $H = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$ orthogonal?

Solution.

Example 7. (Just for fun) an $n \times n$ matrix with entries ± 1 whose columns are orthogonal is called a *Hadamard matrix* of size n . A size 4 example: $\begin{bmatrix} H & H \\ H & -H \end{bmatrix} =$

$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1 \end{bmatrix}$ Continuing this construction, we get examples of size 8, 16, 32, ... It is believed that Hadamard matrices exist for all sizes $4n$. But, no example of size 668 is known yet. If you find one you will be famous!