

Math 415 - Lecture 21

Networks and linear algebra

Wednesday October 14th 2015

Textbook reading: Chapter 2.5.

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Suggested practice exercises: Chapter 2.5: 1, 2, 6.

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Strang lecture: Lecture 12: Graphs, Networks, Incidence Matrices

Review

Recall that if $V \subset \mathbb{R}^n$ is a subspace, V^\perp is the **orthogonal complement** of V , the subspace of all vectors x perp to all vectors of V .

Theorem

Fundamental Theorem of Linear Algebra.

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Directions and Equations

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Both descriptions are useful, and we will often switch between them, to answer any particular question we want to answer.

A new perspective on $A\mathbf{x} = \mathbf{b}$

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The indirect approach means:

$$\text{if } \underbrace{\mathbf{y}^T A = \mathbf{0}}_{\mathbf{y} \in \text{Nul}(A^T)}, \text{ then } \underbrace{\mathbf{y}^T \mathbf{b} = 0}_{\mathbf{b} \perp \mathbf{y}}.$$

Example

Let $A = \begin{bmatrix} 1 & 2 \\ 3 & 1 \\ 0 & 5 \end{bmatrix}$. For which \mathbf{b} does $A\mathbf{x} = \mathbf{b}$ have a solution?

Solution (old)

Write augmented matrix, get Echelon form:

$$\left[\begin{array}{cc|c} 1 & 2 & b_1 \\ 3 & 1 & b_2 \\ 0 & 5 & b_3 \end{array} \right] \longrightarrow \left[\begin{array}{cc|c} 1 & 2 & b_1 \\ 0 & -5 & -3b_1 + b_2 \\ 0 & 0 & -3b_1 + b_2 + b_3 \end{array} \right]$$

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When is this consistent? Whenever $-3b_1 + b_2 + b_3 = 0$.

Solution (new)

Indirect approach says: $A\mathbf{x} = \mathbf{b}$ solvable $\iff \mathbf{b} \perp \text{Nul}(A^T)$.

Find basis for $\text{Nul}(A^T)$:

$$\left[\begin{array}{ccc|c} 1 & 3 & 0 & 0 \\ 2 & 1 & 5 & 0 \end{array} \right] \longrightarrow \left[\begin{array}{ccc|c} 1 & 0 & 3 & 0 \\ 0 & 1 & -1 & 0 \end{array} \right]$$

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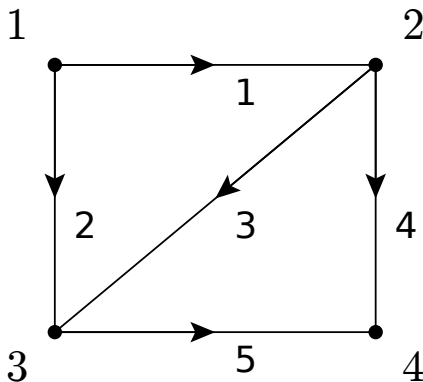
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This is the same condition as before!

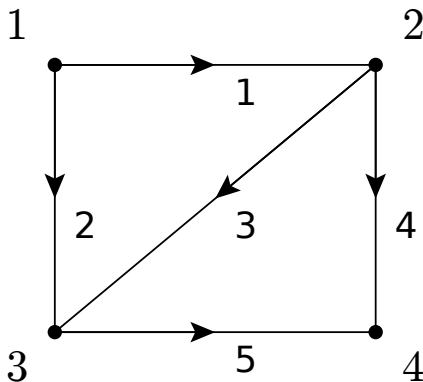
Application: Directed graphs

Set up

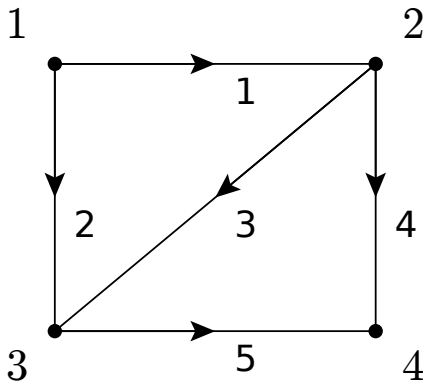
- Graphs appear in **network analysis** (e.g. internet) or **circuit analysis**.



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- Arrow indicates direction of flow



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- No edges from a node to itself



Definition

Let G be a graph with m edges and n nodes.

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$$A_{i,j} = \begin{cases} -1, & \text{if edge } i \text{ leaves node } j \\ +1, & \text{if edge } i \text{ enters node } j \\ 0, & \text{otherwise} \end{cases}$$

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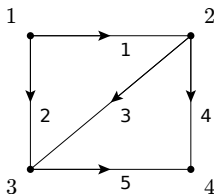
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So each row (describing an edge=arrow) contains a single -1 (the tail of the arrow), a single $+1$ (the head of the arrow), and for the rest zeroes.

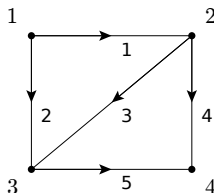
Example

Give the edge-node incidence matrix of our graph.



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Solution

$$\begin{bmatrix} -1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 1 \end{bmatrix}$$

Meaning of the null space

Theorem

$\dim(\text{Nul}(A))$ is the number of connected subgraphs.

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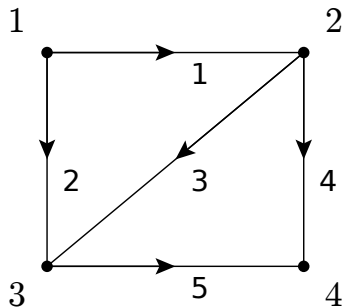
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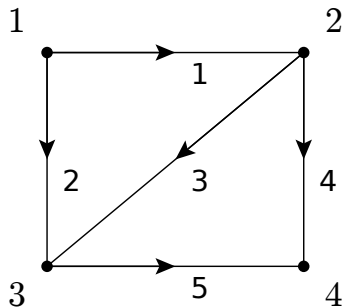
- For large graphs, disconnection may not be visually apparent
- But, we can always find out by computing $\dim(\text{Nul}(A))$ using Gaussian elimination!

Meaning of the null space



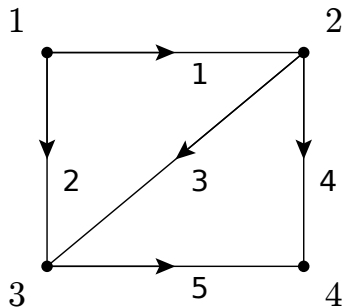
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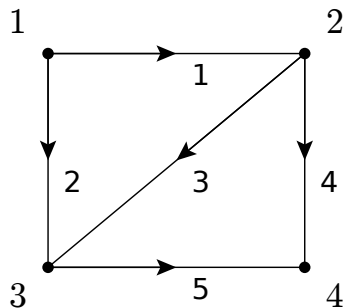
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$$A\mathbf{x} = \begin{bmatrix} -1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -x_1 + x_2 \\ -x_1 + x_3 \\ -x_2 + x_3 \\ -x_2 + x_4 \\ -x_3 + x_4 \end{bmatrix}$$

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Idea

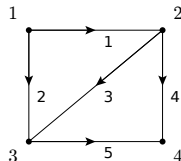
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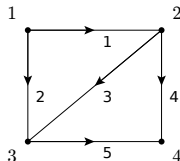
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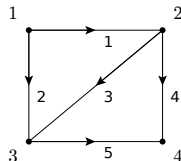
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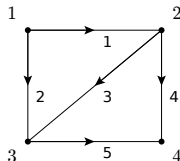


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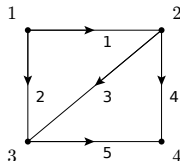
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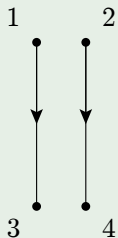


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This always happens as long as G is **connected**.

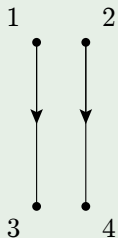
Example

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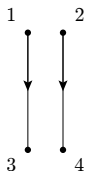


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Meaning of the null space



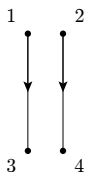
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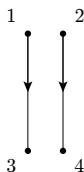
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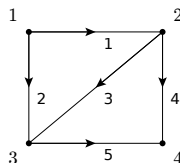
So, $Nul(A)$ has basis: $\begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$

Just to make sure, the edge-node incidence matrix is:

$$A = \begin{bmatrix} -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix}$$

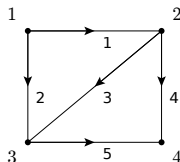
Meaning of left null space

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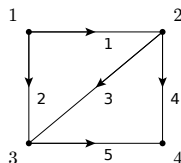
The \mathbf{y} in $\mathbf{y}^T A$ is assigning values to each edge.

Meaning of left null space



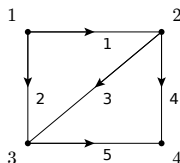
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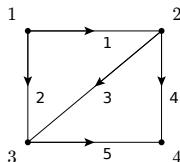
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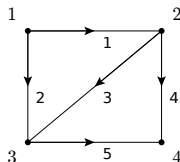


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$$A^T \mathbf{y} =$$

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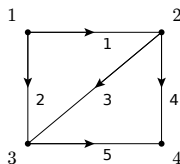


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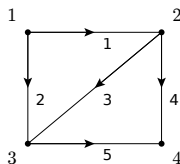
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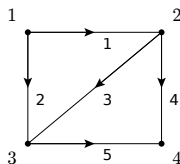


$$A^T \mathbf{y} = \begin{bmatrix} -1 & -1 & 0 & 0 & 0 \\ 1 & 0 & -1 & -1 & 0 \\ 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix} = \begin{bmatrix} -y_1 - y_2 \\ y_1 - y_3 - y_4 \\ y_2 + y_3 - y_5 \\ y_4 + y_5 \end{bmatrix}$$

Idea

So: $A^T \mathbf{y} = 0 \iff$ at each node, (directed) values assigned to edges add to zero.

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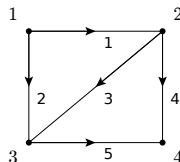


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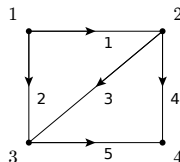
So: $A^T \mathbf{y} = 0 \iff$ at each node, (directed) values assigned to edges add to zero.

When thinking of currents, this is **Kirchhoff's first law**: at each node, incoming and outgoing currents balance. **Flow in = Flow out.**

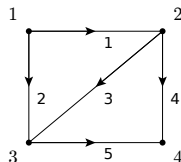


What is the simplest way to balance current?

Meaning of left null space



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Assign current in a **loop**!



What is the simplest way to balance current?

Assign current in a **loop**! We have two loops:

$$\text{edge}_1 \rightarrow \text{edge}_3 \rightarrow -\text{edge}_2 \text{ and } \text{edge}_3 \rightarrow \text{edge}_5 \rightarrow -\text{edge}_4$$

Example

Solve $A^T \mathbf{y} = 0$ for our graph. Recall

$$A^T = \begin{bmatrix} -1 & -1 & 0 & 0 & 0 \\ 1 & 0 & -1 & -1 & 0 \\ 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix}$$

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Solution

Get RREF:

$$\begin{bmatrix} -1 & -1 & 0 & 0 & 0 \\ 1 & 0 & -1 & -1 & 0 \\ 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & -1 & 0 & 1 \\ 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The parametric solution is:

$$\begin{bmatrix} y_3 - y_5 \\ -y_3 + y_5 \\ y_3 \\ -y_5 \\ y_5 \end{bmatrix}$$

So a basis for $Nul(A^T)$ is:

$$\begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$

Observation: These two basis vectors correspond to loops.

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Note: get the “simpler” loop

$$\begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \\ 1 \end{bmatrix} \text{ as } \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$

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In general, $\dim(\text{Nul}(A^T))$ is the number of (independent) loops.

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For large graphs, we now have a nice way to computationally find all loops.

Summary/Outlook

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- * The Left Null Space $Nul(A^T)$ has as dimension the number of independent loops.
- * The column space $Col(A)$ and row space $Col(A^T)$ also have “geometric” meaning in terms of the network, see the book and Strang’s lecture.

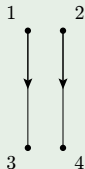
Practice problems

Problem 1

Problem 1

Example

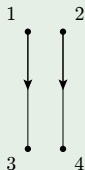
Give a basis for $\text{Nul}(A^T)$ for the following graph:



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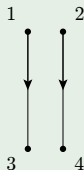
Solution

This graph contains no loops, so

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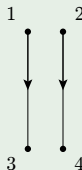
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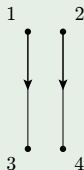


Solution

This graph contains no loops, so $Nul(A^T) = \{0\}$. $Nul(A^T)$ has the [empty set](#) as basis.

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Give a basis for $Nul(A^T)$ for the following graph:



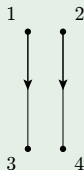
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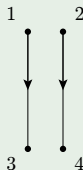
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Indeed, $Nul(A^T) = \{0\}$.

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$$A = \begin{bmatrix} 1 & -1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 1 & 0 & -1 \end{bmatrix}$$

Give a basis for $Nul(A)$ and $Nul(A^T)$.

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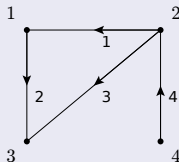
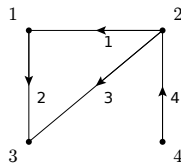


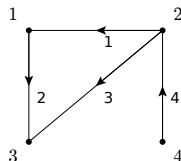
Figure : The graph

Problem 2



If $Ax = 0$, then

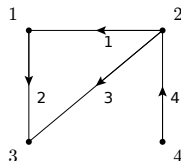
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If $Ax = 0$, then $x_1 = x_2 = x_3 = x_4$ (all connected by edges.)

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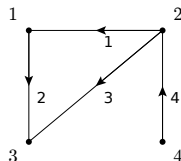
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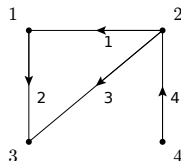


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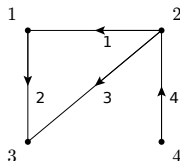


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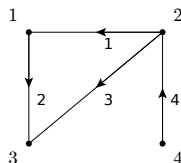


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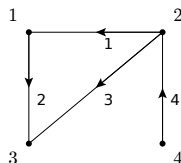
(This graph is connected, so only 1 connected subgraph, so $\dim(Nul(A)) = 1$.)

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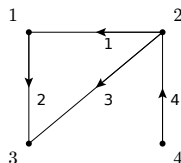
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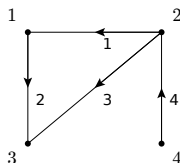
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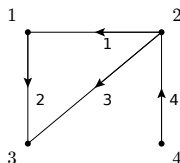


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