

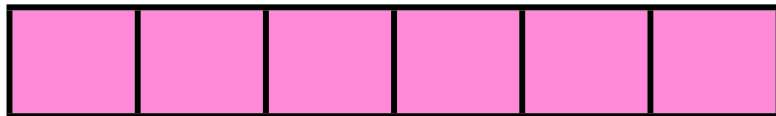
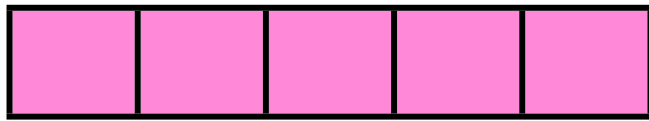
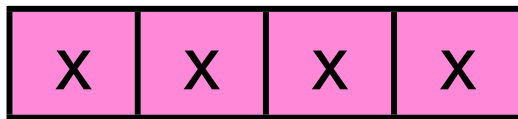
# Announcements

MP3 available, due 2/22, 11:59p.

TODAY: array resizing schemes  
ADT - Queues

## Stack array based implementation: (what if array fills?)

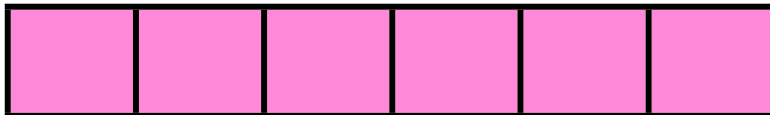
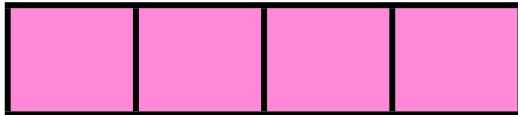
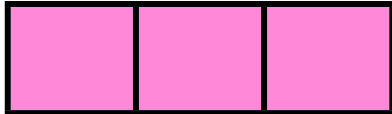
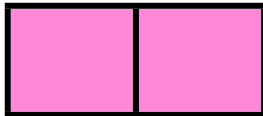
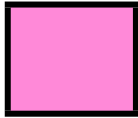
Analysis holds for array based implementations of Lists, Stacks, Queues, Heaps...



**General Idea:** upon an insert (push), if the array is full, create a larger space and copy the data into it.

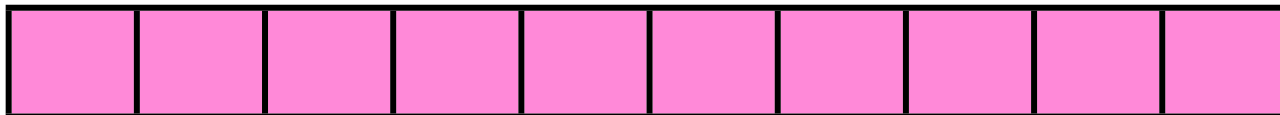
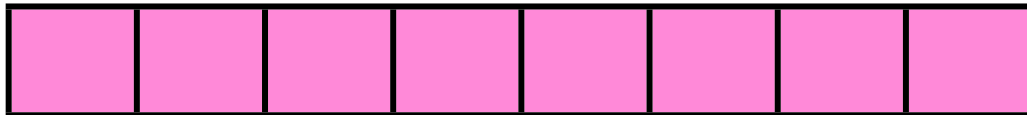
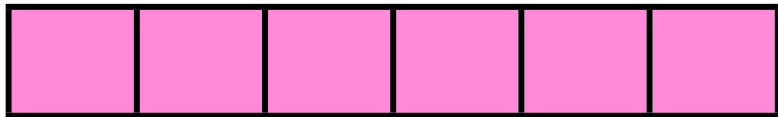
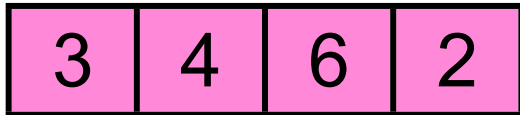
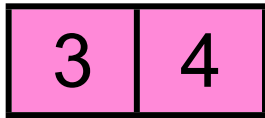
**Main question:** What's the resizing scheme? We examine 3.

Stack array based implementation: (what if array fills?)



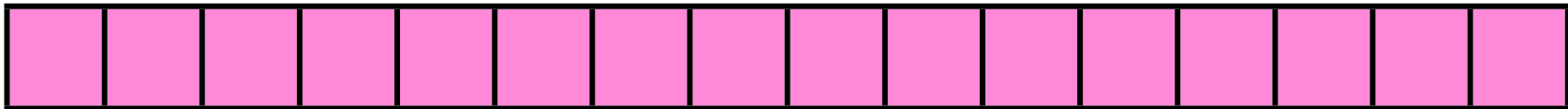
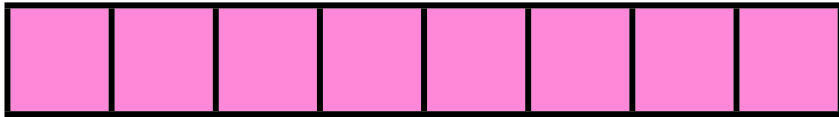
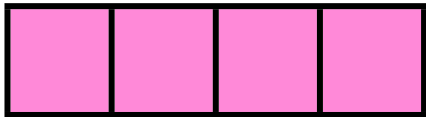
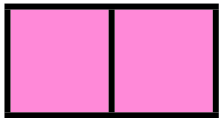
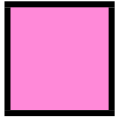
How does this scheme do on a sequence of  $n$  pushes?

Stack array based implementation: (what if array fills?)



How does this scheme do on a sequence of  $n$  pushes?

Stack array based implementation: (what if array fills?)



How does this scheme do on a sequence of  $n$  pushes?

Summary:

Linked list based implementation of a stack:

Constant time push and pop.

Array based implementation of a stack:

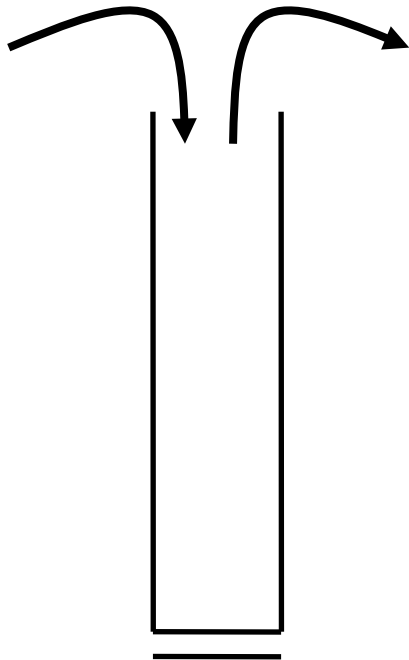
\_\_\_\_\_ time pop.

\_\_\_\_\_ time push if capacity exists,

Cost over  $O(n)$  pushes is \_\_\_\_\_ for an AVERAGE of  
\_\_\_\_\_ per push.

Why consider an array?

# Queues:



Queue ADT:

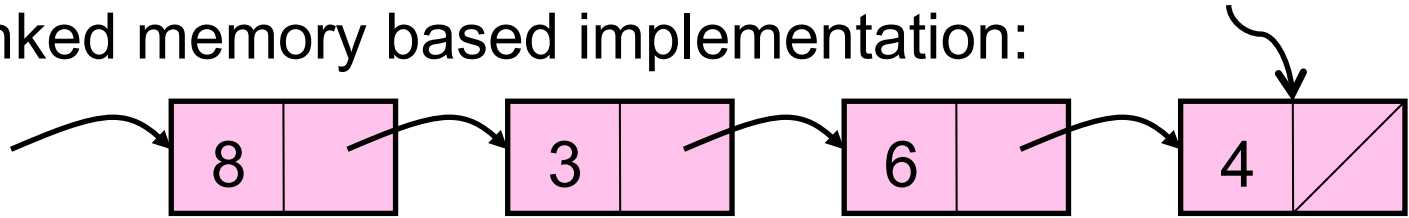
enqueue

dequeue

isEmpty



## Queue—linked memory based implementation:



```
template<class SIT>
class Queue {
public:
    // ctors dtor
    bool empty() const;
    void enqueue(const SIT & e);
    SIT dequeue();
private:
    struct queueNode {
        SIT data;
        queueNode * next;
    };
    queueNode * entry;
    queueNode * exit;
    int size;
};
```

Which pointer is “entry” and which is “exit”?

What is running time of enqueue?

What is running time of dequeue?



## Queue array based implementation:

```
template<class SIT>
class Queue {
public:
    Queue();
    ~Queue(); // etc.
    bool empty() const;
    void enqueue(const SIT & e);
    SIT dequeue();
private:
    int capacity;
    int size;
    SIT * items;
    // some other stuff...
};
```

```
template<class SIT>
Queue<SIT>::Queue() {
    capacity = 8;
    size = 0;
    items = new SIT[capacity];
}
```

## Queue array based implementation:

```
template<class SIT>
```

```
class Queue {
```

```
public:
```

```
    Queue();
```

```
    ~Queue(); // etc.
```

```
    bool empty() const;
```

```
    void enqueue(const SIT & e);
```

```
    SIT dequeue();
```

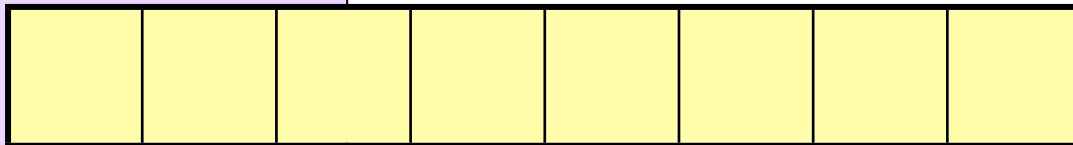
```
private:
```

```
    int capacity;
```

```
    int size;
```

```
    SIT * items;
```

```
};
```



enqueue(3);

enqueue(8);

enqueue(4);

dequeue();

enqueue(7);

dequeue();

dequeue();

enqueue(2);

enqueue(1);

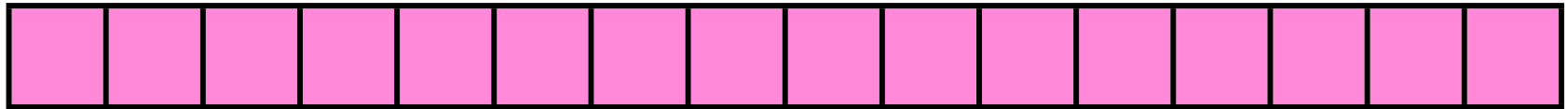
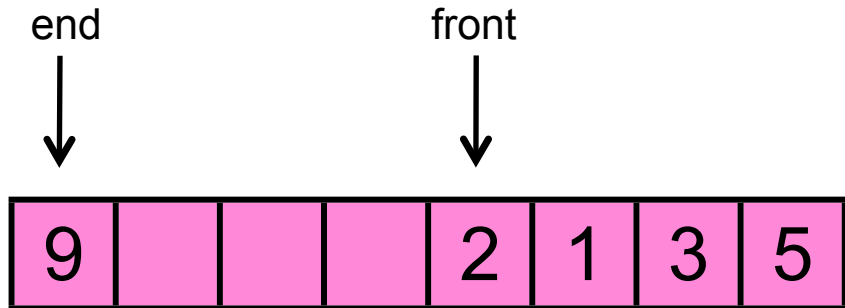
enqueue(3);

enqueue(5);

dequeue();

enqueue(9);

## What if array fills?:



Another constrained access linear structure - Deque:



Deque ADT:

pushFront

pushRear

popFront

popRear