

Worksheet 7 for October 13th and 15th

1. Let $A = \begin{bmatrix} 1 & 2 & 1 \\ 4 & 8 & 2 \\ 1 & 2 & 5 \end{bmatrix}$.

- Find an echelon form U of A . What are the column spaces $\text{Col}(A)$, $\text{Col}(U)$? Are they equal?
- Find a basis for $\text{Col}(U)$ and a basis for $\text{Col}(A)$.
- What are the row spaces $\text{Col}(A^T)$, and $\text{Col}(U^T)$. Are they equal?
- Find a basis for the row space of A , $\text{Col}(A^T)$.

2. Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be the linear transformation with

$$T\left(\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right) = \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix}, \quad T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

- Consider the basis $\mathcal{B}_1 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ of \mathbb{R}^2 and the basis $\mathcal{B}_2 = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ of

\mathbb{R}^3 . Determine the matrix A which represents T with respect to the bases \mathcal{B}_1 and \mathcal{B}_2 . Do you have $T(\mathbf{x}) = A\mathbf{x}$ for all $\mathbf{x} \in \mathbb{R}^2$?

- Consider the basis $\mathcal{C}_1 := \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ of \mathbb{R}^2 and the basis $\mathcal{C}_2 = \left\{ \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

of \mathbb{R}^3 . Determine the matrix B which represents T with respect to the bases \mathcal{C}_1 and \mathcal{C}_2 .

Compute $T(\mathbf{v})$ where the coordinate vector of \mathbf{v} with respect to the basis \mathcal{C}_1 is $\mathbf{v}_{\mathcal{C}_1} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$.

3. In this problem we consider the bases $\mathcal{B} = \{1, t, t^2, t^3\}$ of \mathbb{P}_3 and $\mathcal{C} = \{1, t, t^2, t^3, t^4\}$ of \mathbb{P}_4 .

- Let $I : \mathbb{P}_3 \rightarrow \mathbb{P}_4$ be the linear transformation that maps a polynomial $p(t)$ to the polynomial

$$I(p(t)) := \int_0^t p(s) ds,$$

(e.g., $I(t^2 + 2t) = \int_0^t (s^2 + 2s) ds = [\frac{1}{3}s^3 + s^2]_0^t = \frac{1}{3}t^3 + t^2 \in \mathbb{P}_4$). Determine the matrix which represents I with respect to the bases \mathcal{B} and \mathcal{C} .

- Let $J : \mathbb{P}^3 \rightarrow \mathbb{P}^4$ be the linear transformation that maps a polynomial $p(t)$ to the polynomial

$$J(p(t)) := tp(t) + p'(t).$$

Determine the matrix which represents J with respect to the bases \mathcal{B} and \mathcal{C} .

Tutoring Room (443 Altgeld Hall): Mon 4-6 PM, Tue 5-7 PM, Wed 6-8 PM

Midterm Dates: September 29th, October 22nd, November 19th (All Midterms 7-8:15 PM, see learn.illinois.edu for locations)

4. Let $\mathbf{v} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$. Find the length of \mathbf{v} . Find a vector \mathbf{u} in the direction of \mathbf{v} that has length 1. Find a vector \mathbf{w} that is orthogonal to \mathbf{v} .

5. True or False? Justify your answers.

(a) The map $T: \mathbb{R}^2 \rightarrow \mathbb{R}$ given by $T\left(\begin{bmatrix} a \\ b \end{bmatrix}\right) = \sqrt{a^2 + b^2}$ is a linear transformation.

(b) The map $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by $T\left(\begin{bmatrix} a \\ b \end{bmatrix}\right) = \begin{bmatrix} -b \\ a \end{bmatrix}$ is a linear transformation.

(c) If \mathbf{u} and \mathbf{v} in \mathbb{R}^2 are such that $\mathbf{u} \cdot \mathbf{v} = 0$ then \mathbf{u} and \mathbf{v} are perpendicular (geometrically) to each other. (Hint: Plot \mathbf{u} and \mathbf{v} as rays coming out of the origin, and the “hypotenuse” $\mathbf{u} - \mathbf{v}$. The Pythagorean theorem will hold if this is a right triangle.)

(d) Let V be a subspace of \mathbb{R}^n and \mathbf{u}, \mathbf{v} be two vectors in V , then $\mathbf{v} - \frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u}$ is orthogonal to \mathbf{u} .

(e) Let $T: V \rightarrow W$ be a linear transformation and $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ be vectors in V . If $T(\mathbf{v}_1), T(\mathbf{v}_2), \dots, T(\mathbf{v}_n)$ are linearly independent then $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ are also linearly independent.

(f) Let $T: V \rightarrow W$ be a linear transformation and $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ be vectors in V . If $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ are linearly independent then $T(\mathbf{v}_1), T(\mathbf{v}_2), \dots, T(\mathbf{v}_n)$ are also linearly independent.

6. Let $\mathbf{u}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$, and $\mathbf{v} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$. Find real numbers c_1, c_2 such that

$$\mathbf{v} = c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2.$$

7. Let $B = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix}$.

- (a) Find a basis for $\text{Nul}(B)$.
- (b) Find two linear independent vectors that are orthogonal to $\text{Nul}(B)$.
- (c) Is there a non-zero vector in \mathbb{R}^2 orthogonal to $\text{Col}(B)$?

8. Consider the three vectors

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 5 \end{bmatrix}.$$

- (a) Check that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ form an orthogonal set of vectors and conclude that they form a basis for \mathbb{R}^3 .
- (b) Construct an orthonormal basis \mathcal{B} for \mathbb{R}^3 by normalizing the vectors in $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$.
- (c) Compute the coordinate vector $[\mathbf{v}]_{\mathcal{B}}$ for the following vectors (hint: use the fact that \mathcal{B} is an orthonormal basis):

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

The following may be useful in the above problems:

Definition. Two vectors $\mathbf{v}, \mathbf{w} \in \mathbb{R}^n$ are **orthogonal** if $\mathbf{v}^T \mathbf{w} = 0$ (where \mathbf{v}^T is the transpose of \mathbf{v} as an $n \times 1$ matrix).

Definition. A vector $\mathbf{v} \in \mathbb{R}^n$ is **orthogonal to a subspace** V of \mathbb{R}^n if \mathbf{v} is orthogonal to every $\mathbf{w} \in V$.