from here: http://nipunbatra.github.io/2014/05/denoising/)

```
In [1]:
```

```
import numpy as np
import matplotlib.pyplot as plt
import seaborn
%matplotlib inline
```

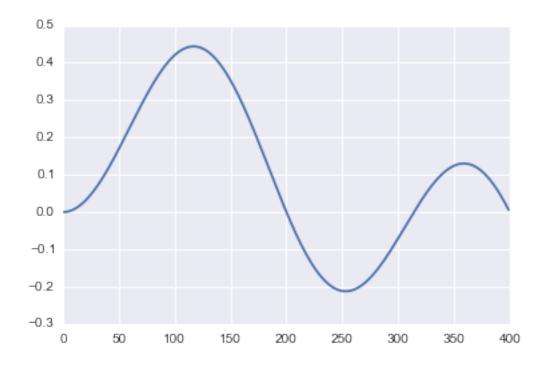
True Data

```
In [2]:
```

```
n=400
t=np.array(range(n))
ex=0.5*np.sin(np.dot(2*np.pi/n,t))*np.sin(0.01*t)
plt.plot(ex)
```

Out[2]:

[<matplotlib.lines.Line2D at 0x10f87f4a8>]



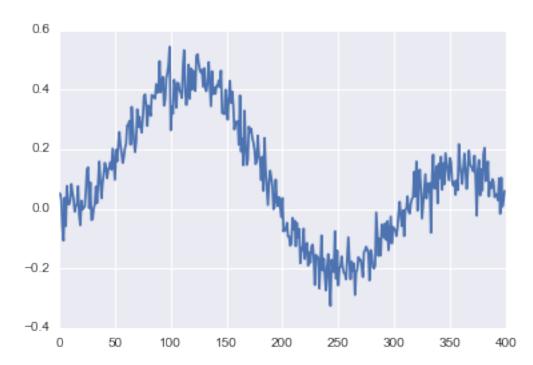
Noisy Data

```
In [3]:
```

```
corr=ex+0.05*np.random.normal(0,1,n)
plt.plot(corr)
```

Out[3]:

[<matplotlib.lines.Line2D at 0x10f9a1240>]



What do we want?

- 1. We want to clean the data so that it's "close" to the noisy data
- 2. We want the cleaned data to be "smooth"

Constraint 1

We really want

$$\left\|x-x_{corr}
ight\|^2$$

to be minimized.

In terms of least-squarse (Ax=b) this means that

$$A_{first} = I \qquad b_{first} = x_{corr}$$

Constraint 2

For the smooth data we can ask that

$$\mu \sum_{k=1}^{n-1} (x_{k+1} - x_k)^2$$

is minimized

In terms of least-squares, this means that

$$A_{second} = egin{bmatrix} -1 & 1 & 0 & \dots \ 0 & -1 & 1 & \dots \ \dots & 0 & -1 & 1 \end{bmatrix}$$

and

$$b = 0$$

```
In [9]:
```

```
d1=np.eye(n-1,n)
d1=np.roll(d1,1)
print(d1)
```

```
[[ 0.
      1.
          0. ...,
                   0.
                     0.
                          0.1
          1. ...,
[ 0.
      0.
                   0.
                      0.
                          0.]
      0. 0. ...,
                   0.
[ 0.
                      0.
                          0.]
      0. 0. ..., 1. 0.
                         0.]
 [ 0.
[ 0. 0. 0. ..., 0. 1.
                         0.]
      0. 0. ...,
                  0. 0.
[ 0.
                          1.]]
```

In [30]:

```
root_mu=100
d2=-np.eye(n-1,n)
a_second=root_mu*(d1+d2)
print(a_second)
print(a_second.shape)
```

```
[-100.100.
                0. ...,
                            0.
                                  0.
                                        0.]
    0. -100.
              100. ...,
                            0.
                                  0.
                                        0.]
    0. 0. -100. ...,
                            0.
                                  0.
                                        0.]
          0.
                0. ..., 100.
                                  0.
    0.
                                        0.]
                0. ..., -100. 100.
    0.
          0.
                                        0.1
          0.
               0. ..., 0. -100.
    0.
                                      100.]]
(399, 400)
```

```
a_first=np.eye(n)
A=np.vstack((a_first,a_second))

In [32]:

corr=corr.reshape((n,1))
b_2=np.zeros((n-1,1))
b=np.vstack((corr,b_2))

In [33]:

print(A.shape)
print(b.shape)

(799, 400)
(799, 1)
Now solve the least squares problem
```

In [31]:

In [34]:

In [35]:

sol = la.lstsq(A, b)

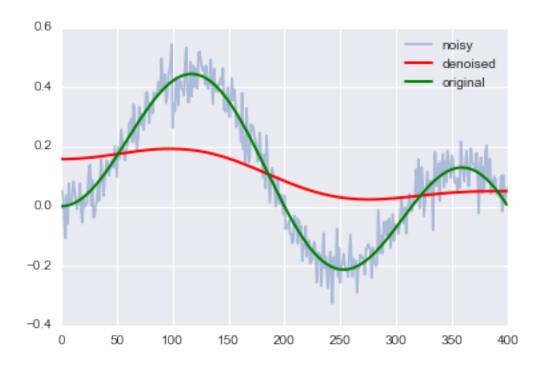
import numpy.linalg.linalg as la

In [36]:

```
plt.plot(corr, label='noisy', alpha=0.4)
plt.plot(sol[0], 'r', linewidth=2, label='denoised')
plt.plot(ex, 'g', linewidth=2, label='original')
plt.legend()
```

Out[36]:

<matplotlib.legend.Legend at 0x11174b278>



In []: