

# Math 415 - Lecture 3

Existence and Uniqueness, linear combinations

Friday August 28 2015

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Textbook: Chapter 1.2

Suggested Practice Exercise: Read section 1.2, do problem 1.3:9  
(drawing optional)

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Khan Academy Video: Linear Combinations and Span

## Review

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- a unique solution (when there are no free variables) or
- infinitely many solutions (when there is at least one free variable).

# Examples

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- How many solutions? Exactly one!

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- How many solutions?  $\infty$  many!

Recap



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4. Write the system of equations corresponding to the matrix obtained in step 3.
5. State the solution by expressing each pivot variable in terms of the free variables and declare the free variables.

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**FALSE!**
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How many pivot variables? Free variables?

## Geometry of Linear Equations

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i.e., a column with  $n$  numbers  $x_1, x_2, \dots, x_n$  in it.

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Let  $c$  be a real number. Then we define the **Scalar Multiple**  $c\mathbf{u}$  by

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### Example

Let  $\mathbf{u} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$  and  $\mathbf{v} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ . Then  $\mathbf{u} + \mathbf{v}$  is

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## Linear Combinations

## Definition

Given vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$  in  $\mathbb{R}^n$  and given **scalars**  $c_1, c_2, \dots, c_p$ , the vector  $\mathbf{y}$  defined by

$$\mathbf{y} = c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \cdots + c_p\mathbf{v}_p$$

is called a **linear combination** of  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$  using scalars (or weights)  $c_1, c_2, \dots, c_p$ .



## Example

Linear combinations don't all look the same. The following are linear combinations of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ :

- $3\mathbf{v}_1 + 2\mathbf{v}_2$ ,
- $\frac{1}{3}\mathbf{v}_1$ ,
- $\mathbf{v}_1 - 2\mathbf{v}_2$ ,
- $\mathbf{0}$ .

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Let  $\mathbf{v}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$  and  $\mathbf{v}_2 = \begin{bmatrix} -2 \\ 2 \end{bmatrix}$ . Express each of the following as a linear combination of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ :

$$\mathbf{a} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} -4 \\ 1 \end{bmatrix}, \quad \mathbf{c} = \begin{bmatrix} 6 \\ 6 \end{bmatrix}, \quad \mathbf{d} = \begin{bmatrix} 7 \\ -4 \end{bmatrix}$$

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### Solution

Try first  $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 = \mathbf{a}$  or  $c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -2 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$ .

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## Example

Let  $\mathbf{a}_1 = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$ ,  $\mathbf{a}_2 = \begin{bmatrix} 4 \\ 2 \\ 14 \end{bmatrix}$ ,  $\mathbf{a}_3 = \begin{bmatrix} 3 \\ 6 \\ 10 \end{bmatrix}$ , and  $\mathbf{b} = \begin{bmatrix} -1 \\ 8 \\ -5 \end{bmatrix}$ .

Determine if  $\mathbf{b}$  is a linear combination of  $\mathbf{a}_1$ ,  $\mathbf{a}_2$ , and  $\mathbf{a}_3$ .

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Vector  $\mathbf{b}$  is a linear combination of  $\mathbf{a}_1$ ,  $\mathbf{a}_2$ , and  $\mathbf{a}_3$  if can we find scalars (weights)  $x_1, x_2, x_3$  such that

## Example

Let  $\mathbf{a}_1 = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$ ,  $\mathbf{a}_2 = \begin{bmatrix} 4 \\ 2 \\ 14 \end{bmatrix}$ ,  $\mathbf{a}_3 = \begin{bmatrix} 3 \\ 6 \\ 10 \end{bmatrix}$ , and  $\mathbf{b} = \begin{bmatrix} -1 \\ 8 \\ -5 \end{bmatrix}$ .

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Solution to

$$x_1 \mathbf{a}_1 + x_2 \mathbf{a}_2 + x_3 \mathbf{a}_3 = \mathbf{b}$$

is found by solving the linear system whose augmented matrix is

$$\left[ \begin{array}{ccc|c} \mathbf{a}_1 & \mathbf{a}_2 & \mathbf{a}_3 & \mathbf{b} \end{array} \right].$$

## Linear combinations and linear systems

## Motto

Solving linear systems is the same as finding linear combinations!

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## Theorem

*A vector equation*

$$x_1 \mathbf{a}_1 + x_2 \mathbf{a}_2 + \cdots + x_n \mathbf{a}_n = \mathbf{b}$$

*has the same solution set as the linear system whose augmented matrix is*

$$\left[ \begin{array}{cccc|c} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n & \mathbf{b} \end{array} \right]$$

*In particular,  $\mathbf{b}$  can be generated by a linear combination of  $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n$  if and only if there is a solution to the linear system corresponding to the augmented matrix.*

Span



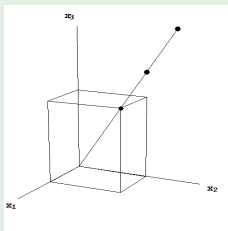


## Example

Let  $\mathbf{v} = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix}$ . The origin  $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$  together with  $\mathbf{v}$ ,  $2\mathbf{v}$  and  $1.5\mathbf{v}$  all lie on the same line.

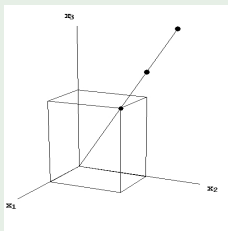
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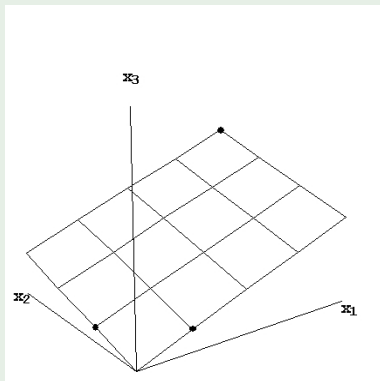
**Span** $\{\mathbf{v}\}$  is the set of all vectors of the form  $c\mathbf{v}$ . Here, **Span** $\{\mathbf{v}\} =$  a line through the origin.

## Example

Label  $\mathbf{u}$ ,  $\mathbf{v}$ ,  $\mathbf{u} + \mathbf{v}$  and  $3\mathbf{u} + 4\mathbf{v}$  on the graph below.

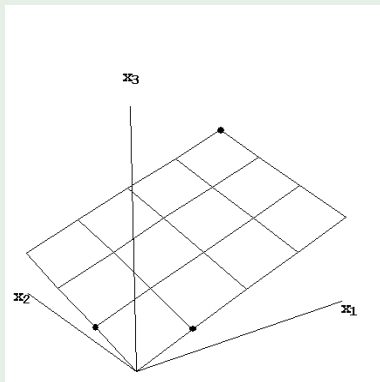
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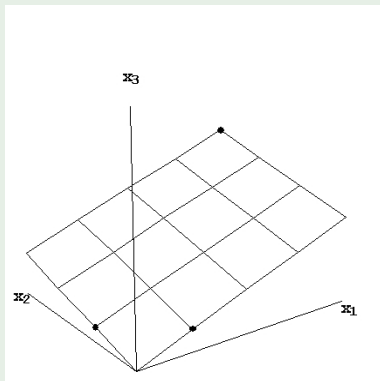
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$\mathbf{u}$ ,  $\mathbf{v}$ ,  $\mathbf{u} + \mathbf{v}$  and  $3\mathbf{u} + 4\mathbf{v}$  all lie in the same plane.  $\text{Span}\{\mathbf{u}, \mathbf{v}\}$  is the set of all vectors of the form  $x_1\mathbf{u} + x_2\mathbf{v}$ . Here,  $\text{Span}\{\mathbf{u}, \mathbf{v}\} =$  a plane through the origin.



## Definition

Suppose  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$  are in  $\mathbb{R}^n$ ; then the **Span** $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$  is defined as the set of all linear combinations of  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ .

*Stated another way:* **Span** $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$  is the collection of all vectors that can be written as

$$x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + \cdots + x_p\mathbf{v}_p$$

where  $x_1, x_2, \dots, x_p$  are scalars.

## Example

Let  $\mathbf{v}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$  and  $\mathbf{v}_2 = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$ .

- (a) Find a vector in  $\mathbf{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$ .
- (b) Describe  $\mathbf{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$  geometrically.

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Let  $\mathbf{v}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$  and  $\mathbf{v}_2 = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$ .

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### Solution

- (a) For instance  $2\mathbf{v}_1 = \mathbf{v}_2$ .
- (b)  $\mathbf{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$  is the collection of all vectors in the direction of  $\mathbf{v}_1$  (or  $\mathbf{v}_2$ !). It is a line through the origin.

So the **Span** of two vectors is a plane if and only if

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### Example

Let  $\mathbf{v}_1 = \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix}$  and  $\mathbf{v}_2 = \begin{bmatrix} 6 \\ 3 \\ 2 \end{bmatrix}$ . Is  $\mathbf{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$  a line or a plane?



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Is  $\mathbf{v}_1$  a multiple of  $\mathbf{v}_2$ ?

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Is  $\mathbf{v}_1$  a multiple of  $\mathbf{v}_2$ ? Do they point in the same direction?

### Example

Let  $A = \begin{bmatrix} 1 & 2 \\ 3 & 1 \\ 0 & 5 \end{bmatrix}$  and  $\mathbf{b} = \begin{bmatrix} 8 \\ 3 \\ 17 \end{bmatrix}$ . Is  $\mathbf{b}$  in the plane spanned by the columns of  $A$ ?

# Example of Span?

## Solution

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Do  $x_1$  and  $x_2$  exist such that

$$x_1 \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 1 \\ 5 \end{bmatrix} = \begin{bmatrix} 8 \\ 3 \\ 17 \end{bmatrix} ?$$

pause Try and find the answer at home.