

Math 415 - Lecture 35

Quadratic forms

Monday November 30th 2015

Textbook reading: Chapter 6.1

Suggested practice exercises: Chapter 6.1, # 2, 3, 17

Strang lecture: Lecture 27: Positive definite matrices and minima

1 Review

Spectral theorem:

- A is a **symmetric** matrix if $A^T = A$. e.g. $\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 5 & 5 \end{bmatrix}$
- Any $n \times n$ symmetric matrix A has n **real** eigenvalues and an **orthonormal** eigenbasis $\{\mathbf{q}_1, \dots, \mathbf{q}_n\}$.
- So, we can write

$$A = QDQ^T$$

where

$$D = \underbrace{\begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}}_{\text{matrix of eigenvalues}} \quad \text{and} \quad Q = \underbrace{\begin{bmatrix} | & & | \\ \mathbf{q}_1 & \cdots & \mathbf{q}_n \\ | & & | \end{bmatrix}}_{\text{matrix of eigenvectors}}$$

2 Quadratic forms

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be a differentiable function with critical point at $\mathbf{0}$. This means that all partial derivatives at $\mathbf{0}$ vanish. Is $\mathbf{0}$ a **max**, **min**, or **neither**?

Definition. A **quadratic form** $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is a polynomial (in n variables) with every term degree two.

e.g., for $n = 2$

$$f(x, y) = 3x^2 + 4xy - 5y^2$$

Example 1. Let

$$f(x, y) = \begin{bmatrix} x \\ y \end{bmatrix} \cdot \begin{bmatrix} 3 & 2 \\ 2 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Expand $f(x, y)$ as a polynomial in x and y . The dot denotes the dot product!

Solution.

Theorem 1. Any quadratic form $f(x_1, x_2, \dots, x_n) : \mathbb{R}^n \rightarrow \mathbb{R}$ can be written

$$f(\mathbf{x}) = \mathbf{x} \cdot A\mathbf{x} = \mathbf{x}^T A\mathbf{x}$$

for a symmetric matrix A .

We see symmetric matrices show up “in the wild!”

Example 2. Write $f(x, y, z) = 5x^2 + 7y^2 + 3z^2 + 2xy - 2yz$ as $\begin{bmatrix} x \\ y \\ z \end{bmatrix} \cdot A \begin{bmatrix} x \\ y \\ z \end{bmatrix}$ where A is symmetric.

Solution.

2.1 Principal axes for a quadratic form

Intermezzo: From Eigenbasis to Standard Basis and back.

- A symmetric, so $A = QDQ^T$.

- If $x \in \mathbb{R}^n$ and $x_Q = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$ is the coordinate vector of x in the Q basis, then $x = c_1q_1 + c_2q_2 + \cdots + c_nq_n = Qx_Q$.

- This means that to find the Q coordinate vector for x , multiply by $Q^{-1} = Q^T$:

$$\boxed{x_Q = Q^T x}$$

There is always a “nicest possible” coordinate system for each quadratic form. Just use an eigenbasis of A .

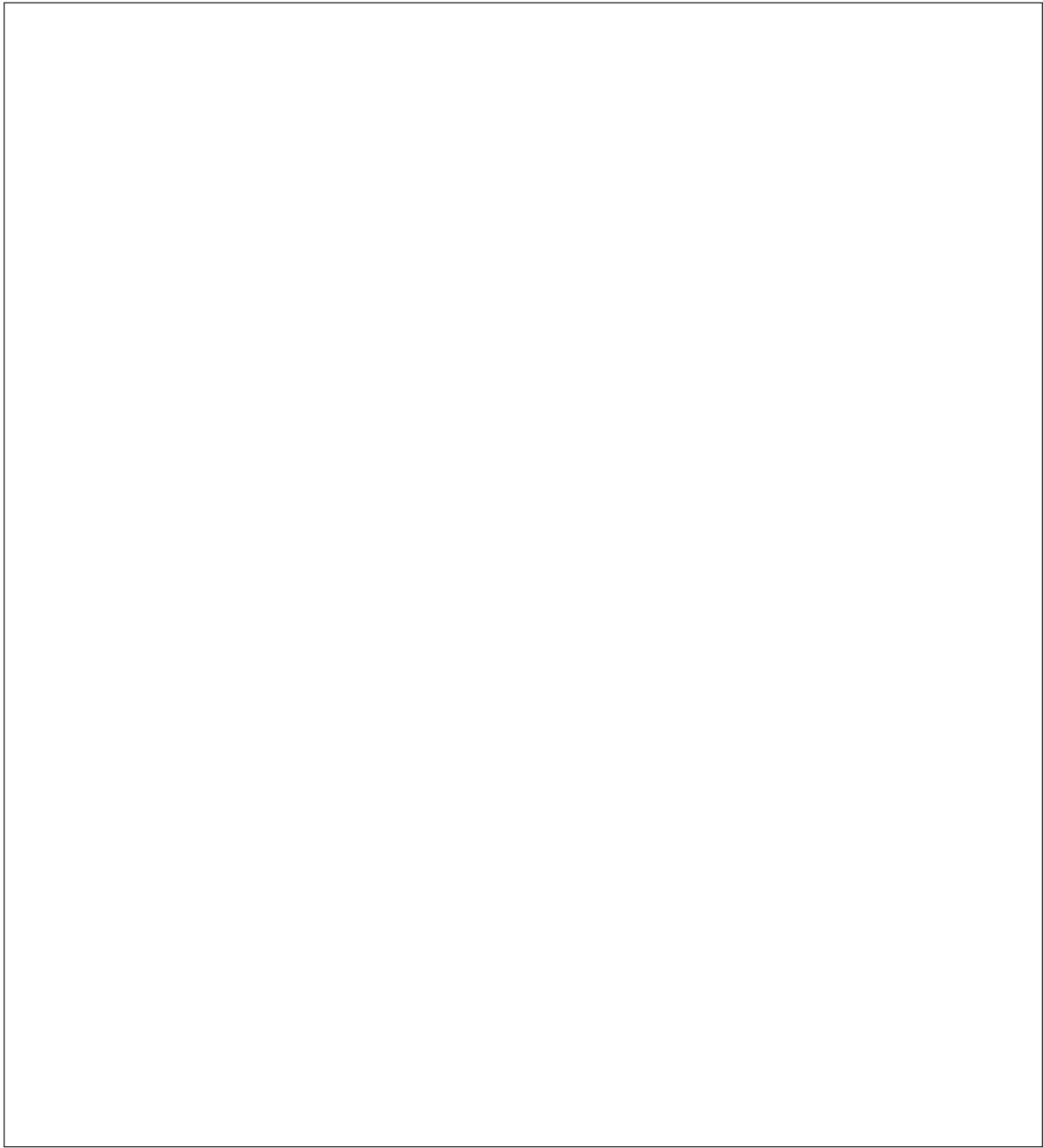
Theorem 2. *Let A be a symmetric matrix, $\mathbf{v}_1, \dots, \mathbf{v}_n$ an orthonormal basis of eigenvectors with eigenvalues $\lambda_1, \dots, \lambda_n$. Write*

$$\mathbf{x} = c_1 \mathbf{v}_1 + \dots + c_n \mathbf{v}_n$$

Then,

$$q(\mathbf{x}) := \mathbf{x}^T A \mathbf{x} = \lambda_1 (c_1)^2 + \dots + \lambda_n (c_n)^2$$

Proof.



□

Example 3. Let $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $\mathbf{x} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$. Let $q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$.

- Find the eigenvalues λ_1, λ_2 and **orthonormal** eigenbasis $\{\mathbf{v}_1, \mathbf{v}_2\}$ for A .
- Compute $q(\mathbf{x})$ using the formula $q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$.
- Compute $q(\mathbf{x})$ using the theorem ($q(\mathbf{x}) = \lambda_1(c_1)^2 + \lambda_2(c_2)^2$.)

Solution.

We have $\mathbf{x} = c_1 \mathbf{v}_1 + \cdots + c_n \mathbf{v}_n$ and

$$q(\mathbf{x}) = \lambda_1(c_1)^2 + \cdots + \lambda_n(c_n)^2$$

- So up to coordinate change, q is a **weighted sum of squares**
- The eigenvectors $\mathbf{v}_1, \dots, \mathbf{v}_n$ are called **principal axes**
- Three cases:
 1. If all $\lambda_i > 0$, then $q(\mathbf{x}) > 0$ for all $\mathbf{x} \neq \mathbf{0}$
 2. If all $\lambda_i < 0$, then $q(\mathbf{x}) < 0$ for all $\mathbf{x} \neq \mathbf{0}$
 3. If some $\lambda_i > 0$, some $\lambda_j < 0$, $q(\mathbf{x})$ will have both positive and negative values.

2.2 Completing the squares

Basic Question. Let A be a symmetric matrix, and $q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$. Is $q(\mathbf{x})$ always ≥ 0 ? Or always ≤ 0 ? How to decide? Write $q(\mathbf{x})$ as a sum of squares!

Example 4. Let $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$, so that $q(\mathbf{x}) = x^2 + 4xy + y^2$. Write $q(\mathbf{x})$ as a sum of squares. Is $q(\mathbf{x})$ always positive?

Solution.

* $q(\mathbf{x}) = x^2 + 4xy + y^2 = (x + 2y)^2 - 3y^2$.

* Sometimes you get something positive, sometimes something negative.

There are many ways of writing $q(\mathbf{x})$ as a sum of squares. Today we are using eigenvalues to do this.