

Worksheet 8 for October 20th and 22ndth

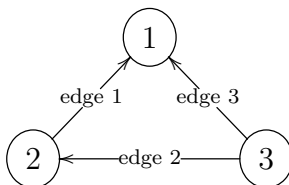
1. Let

$$A = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{bmatrix}.$$

- Draw a directed graph with numbered edges and nodes, whose edge-node incidence matrix is A .
- Find a basis for the solutions to $A\mathbf{x} = 0$ in two ways: by using the matrix A , and then by using a property of the graph.
- Find a basis for the solutions to $A^T\mathbf{y} = 0$ in two ways: by using the matrix A , and then by using a property of the graph.
- * Conclude from the fundamental theorem that a vector \mathbf{b} is in the column space of A if and only if it satisfies $b_1 + b_2 - b_3 = 0$. What does this condition mean when the b 's are potential differences?
- * Conclude from the fundamental theorem that a vector \mathbf{f} is in the row space of A if and only if satisfies $f_1 + f_2 + f_3 = 0$. What does that mean when the f 's are net currents into the nodes?

(*): Questions (d) and (e) will not be on the Midterm.

Solution. (a)



- From matrix: we transform A into the row reduced echelon form:

$$A = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{bmatrix} \xrightarrow{R3 \rightarrow R3 - R1} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 1 & -1 \end{bmatrix} \xrightarrow{R3 \rightarrow R3 - R2, R1 \rightarrow R1 + R2} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

So,

$$\text{Nul}(A) = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : x_1 = x_3, x_2 = x_3 \right\} = \left\{ \begin{bmatrix} x_3 \\ x_3 \\ x_3 \end{bmatrix} : x_3 \in \mathbb{R} \right\} = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

$$\text{Thus, a basis for } \text{Nul}(A) \text{ is } \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}.$$

$$\text{Using graph, since the graph is connected a basis for } \text{Nul}(A) \text{ is } \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}.$$

Tutoring Room (443 Altgeld Hall): Mon 4-6 PM, Tue 5-7 PM, Wed 6-8 PM

Midterm Dates: September 29th, October 22nd, November 19th (All Midterms 7-8:15 PM, see learn.illinois.edu for locations)

(c) From matrix: we transform A^T into the row reduced echelon form:

$$A = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 0 & -1 & -1 \end{bmatrix} \xrightarrow{R2 \rightarrow R2 + R1} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & -1 & -1 \end{bmatrix} \xrightarrow{R3 \rightarrow R3 + R2} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

So,

$$\text{Nul}(A) = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : x_1 = -x_3, x_2 = -x_3 \right\} = \left\{ \begin{bmatrix} -x_3 \\ -x_3 \\ x_3 \end{bmatrix} : x_3 \in \mathbb{R} \right\} = \text{Span} \left\{ \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \right\}$$

Thus, a basis for $\text{Nul}(A)$ is $\left\{ \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \right\}$.

Using graph, there is only one loop: $\text{edge}_1, -\text{edge}_3, \text{edge}_2$.

So, a basis for $\text{Nul}(A^T)$ is $\left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \right\}$.

(d) \mathbf{b} is in $\text{Col}(A)$ if and only if \mathbf{b} is orthogonal to $\text{Nul}(A^T)$, i.e. :

$$\mathbf{b} \cdot \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} = b_1 + b_2 - b_3 = 0$$

This means sum of potential differences around a loop is zero, Kirchhoff's voltage law.

(e) \mathbf{f} is in $\text{Col}(A^T)$ if and only if \mathbf{f} is orthogonal to $\text{Nul}(A)$, i.e. :

$$\mathbf{f} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = f_1 + f_2 + f_3 = 0$$

This means sum of net currents over connect subgraphs is zero. □

2. Consider the matrix:

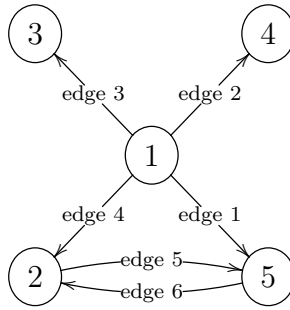
$$A = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 1 & 0 \\ -1 & 0 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & -1 \end{bmatrix}$$

(a) Draw a directed graph with numbered edges and nodes, whose edge-node incidence matrix is A .

(b) Use a property of the graph to find a basis for $\text{Nul}(A)$.

(c) Use a property of the graph to find a basis for $\text{Nul}(A^T)$.

Solution. (a)



(b) Since the graph is connected a basis for $\text{Nul}(A)$ is $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right\}$.

(c) There are two (independent) loops: $\text{edge}_1, \text{edge}_6, -\text{edge}_4$ and $\text{edge}_5, \text{edge}_6$.

So a basis for $\text{Nul}(A^T)$ is $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\}$.

□

3. Let $\mathbf{v} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$. Find the projections $\hat{\mathbf{a}}, \hat{\mathbf{b}}, \hat{\mathbf{c}}$ of the vectors

$$\mathbf{a} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix}, \quad \mathbf{c} = \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}$$

onto the \mathbf{v} . Interpret your results geometrically.

Solution. We have,

$$\hat{\mathbf{a}} = \frac{\mathbf{a} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \mathbf{v} = \frac{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \frac{6}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix},$$

$$\hat{\mathbf{b}} = \frac{\mathbf{b} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \mathbf{v} = \frac{\begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \frac{0}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix},$$

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$$\hat{\mathbf{c}} = \frac{\mathbf{c} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \mathbf{v} = \frac{\begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \frac{6}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} . \quad \square$$