

# Deadlock Solutions: Prevention

CS 241

March 31, 2014

University of Illinois

# Announcement

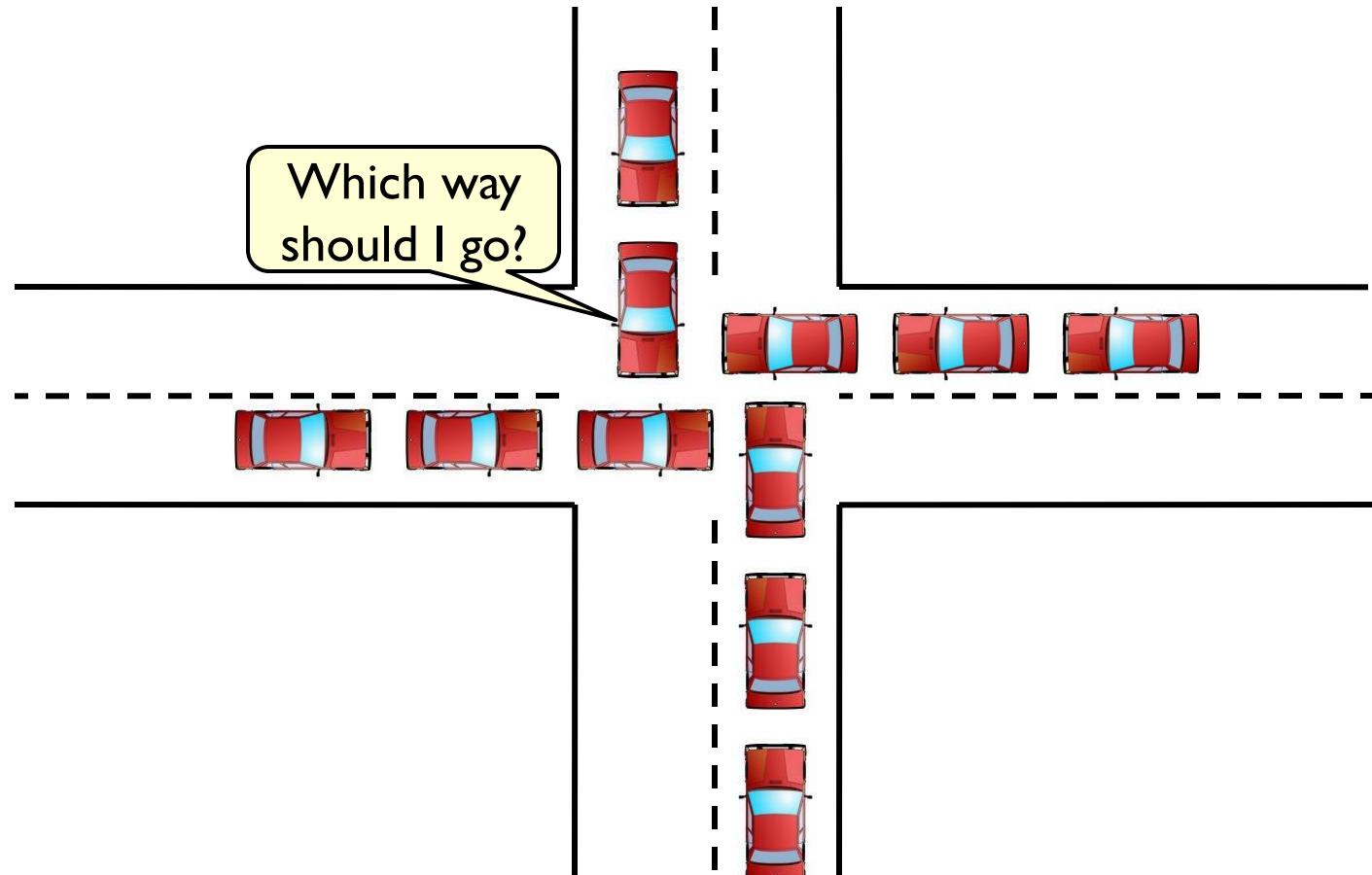
Brighten's office hours today, 12-1

# Deadlock: definition

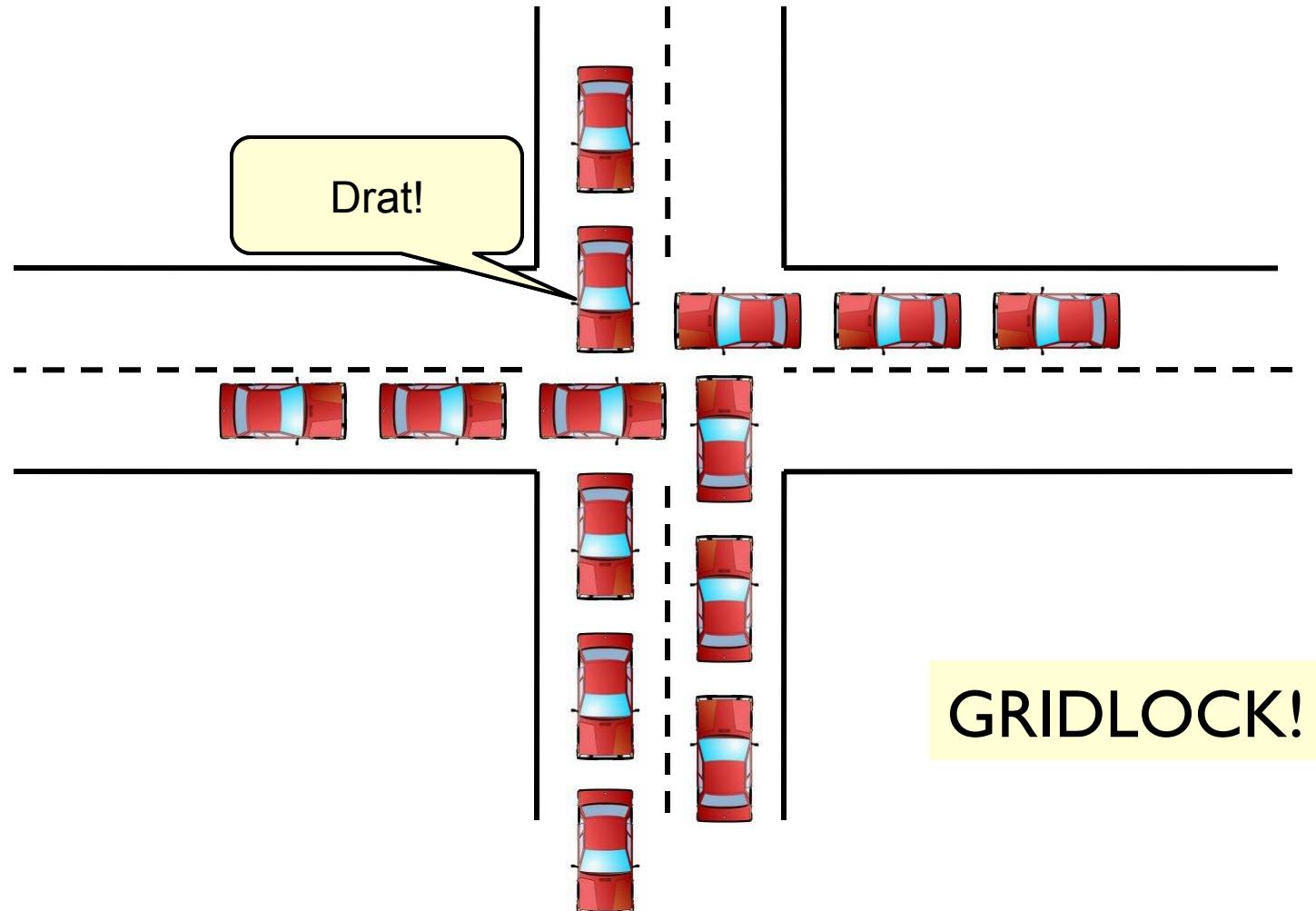
There exists a cycle of processes such that each process cannot proceed until the next process takes some specific action.

Result: all processes in the cycle are stuck!

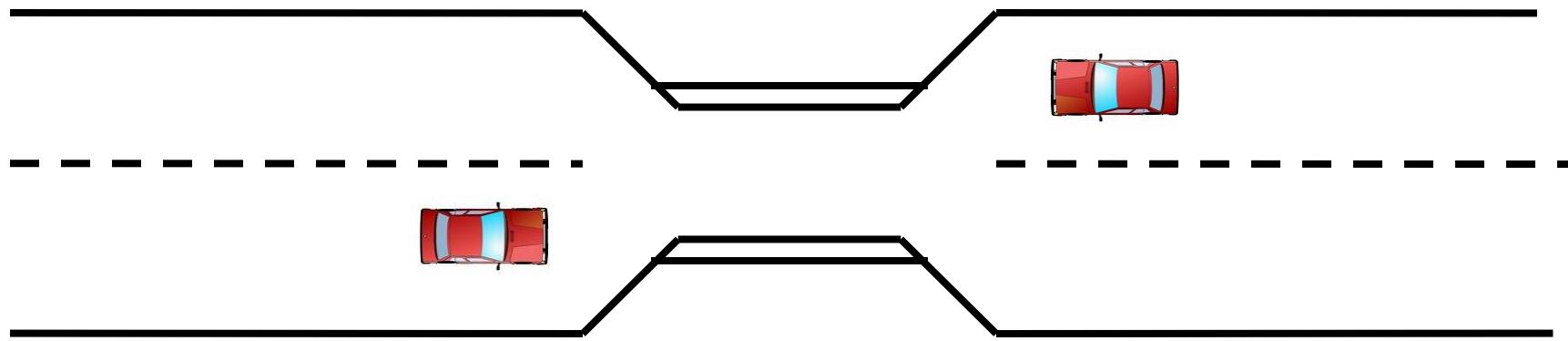
# Deadlock in the real world



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# Deadlock: One-lane Bridge

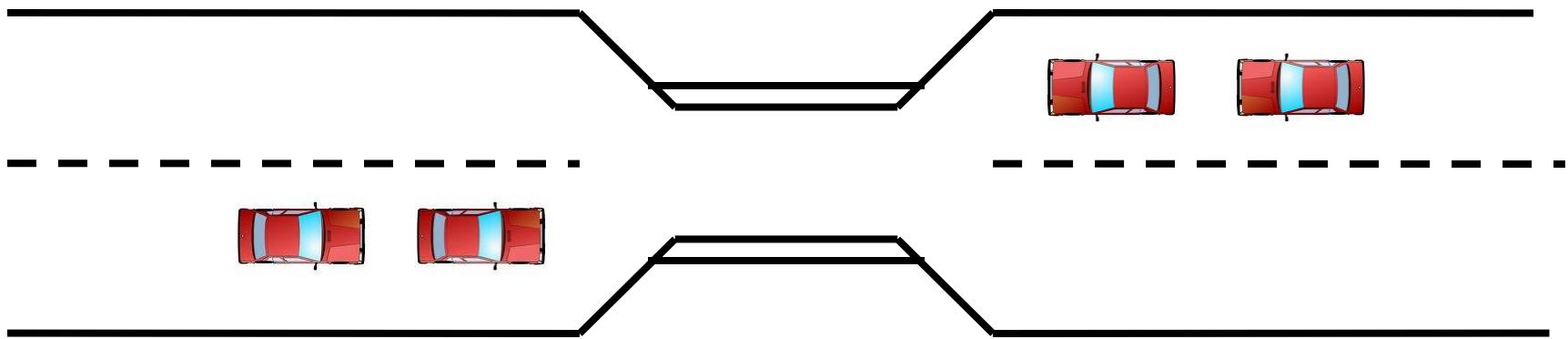


Traffic only in one direction

Each section of a bridge can be viewed as a resource

What can happen?

# Deadlock: One-lane Bridge



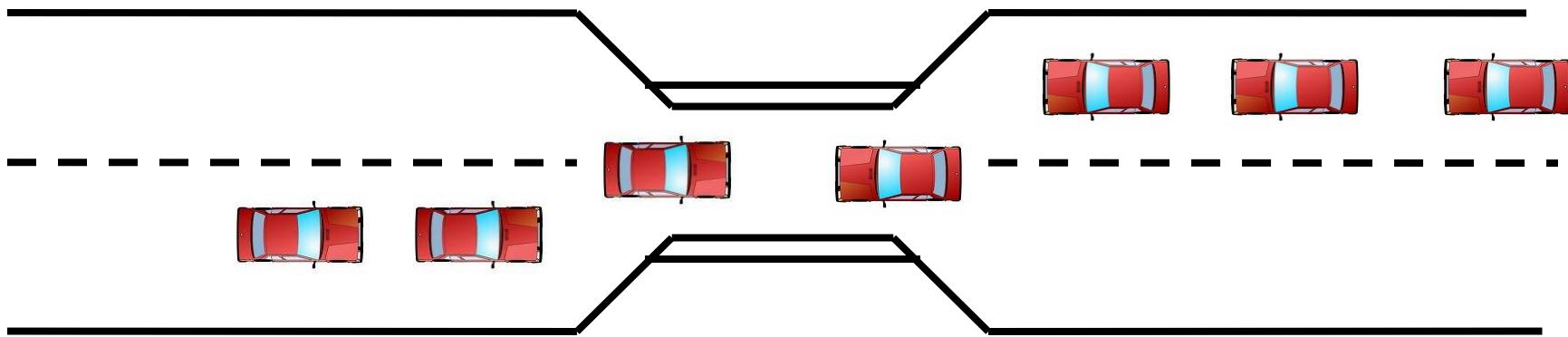
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Each section of a bridge can be viewed as a resource

Deadlock

- Resolved if cars back up (preempt resources and rollback)
- Several cars may have to be backed up

# Deadlock: One-lane Bridge



Traffic only in one direction

Each section of a bridge can be viewed as a resource

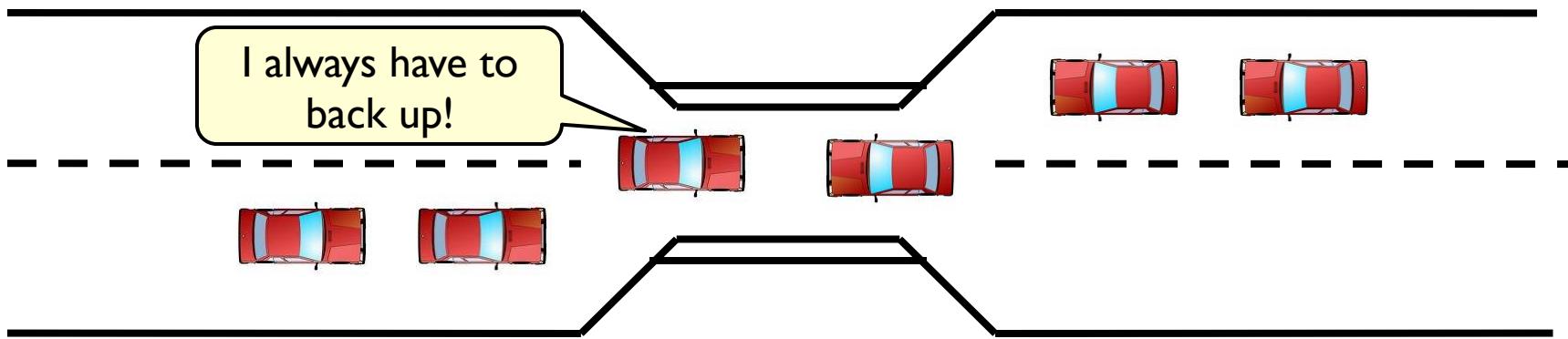
Deadlock

- Resolved if cars back up (preempt resources and rollback)
- Several cars may have to be backed up

But, starvation is possible

- e.g., if the rule is that Westbound cars always go first when present

# Deadlock: One-lane Bridge



## Deadlock vs. Starvation

- Starvation = Indefinitely postponed
  - Delayed repeatedly over a long period of time while the attention of the system is given to other processes
  - Logically, the process may proceed but the system never gives it the CPU (unfortunate scheduling)
- Deadlock = no hope
  - All processes blocked; scheduling change won't help

# Deadlock solutions

## Prevention

- Design system so that deadlock is impossible

## Avoidance

- Steer around deadlock with smart scheduling

## Detection & recovery

- Check for deadlock periodically
- Recover by killing a deadlocked processes and releasing its resources

## Do nothing

- Prevention, avoidance, and detection/recovery are expensive
- If deadlock is rare, is it worth the overhead?
- Manual intervention (kill processes, reboot) if needed



# Deadlock Prevention

# Deadlock prevention

Goal 1: devise resource allocation rules which make circular wait impossible

- Resources include mutex locks, semaphores, pages of memory, ...
- ...but you can think about just mutex locks for now

Goal 2: make sure useful behavior is still possible!

- The rules will necessarily be conservative
  - Rule out some behavior that would not cause deadlock
- But they shouldn't be to be *too* conservative
  - We still need to get useful work done

# Rule #1: No Mutual Exclusion

For deadlock to happen: processes must claim exclusive control of the resources they require

How to break it?

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For deadlock to happen: processes must claim exclusive control of the resources they require

How to break it?

- Non-exclusive access only
  - Read-only access
- Battle won!
  - War lost
  - Very bad at Goal #2

# Rule #2: Allow preemption

A lock can be taken away from current owner

- **Let it go:** If a process holding some resources is denied a further request, that process must release its original resources
- **Or take it all away:** OS preempts current resource owner, gives resource to new process/thread requesting it

Breaks circular wait

- ...because we don't have to wait

Reasonable strategy sometimes

- e.g. if resource is memory: “preempt” = page to disk

Not so convenient for synchronization resources

- e.g., locks in multithreaded application
- What if current owner is in the middle of a critical section updating pointers? Data structures might be left in inconsistent state!

# Rule #3: No hold and wait

When waiting for a resource, must not hold others

- So, process can only have one resource locked
- Or, it must request all resources at the beginning
- Or, before asking for more: give up everything you have and request it all at one time

Breaks circular wait

- In resource allocation diagram: process with an outgoing link must have no incoming links
- Therefore, cannot have a loop!

# Rule #3: No hold and wait

## Constraining (mediocre job on Goal #2)

- Better than Rules #1 and #2, but...
- Often need more than one resource
- Hard to predict at the beginning what resources you'll need
- Releasing and re-requesting is inefficient, complicates programming, might lead to starvation

# Rule #4: request resources in order

Must request resources in increasing order

- Impose ordering on resources (any ordering will do)
- If holding resource  $i$ , can only request resources  $> i$

Less constraining (decent job on Goal #2)

- Strictly easier to satisfy than “No hold and wait”: If we can request all resources at once, then we can request them in increasing order
- But now, we don’t need to request them all at once
- Can pick the arbitrary ordering for convenience to the application
- Still might be inconvenient at times

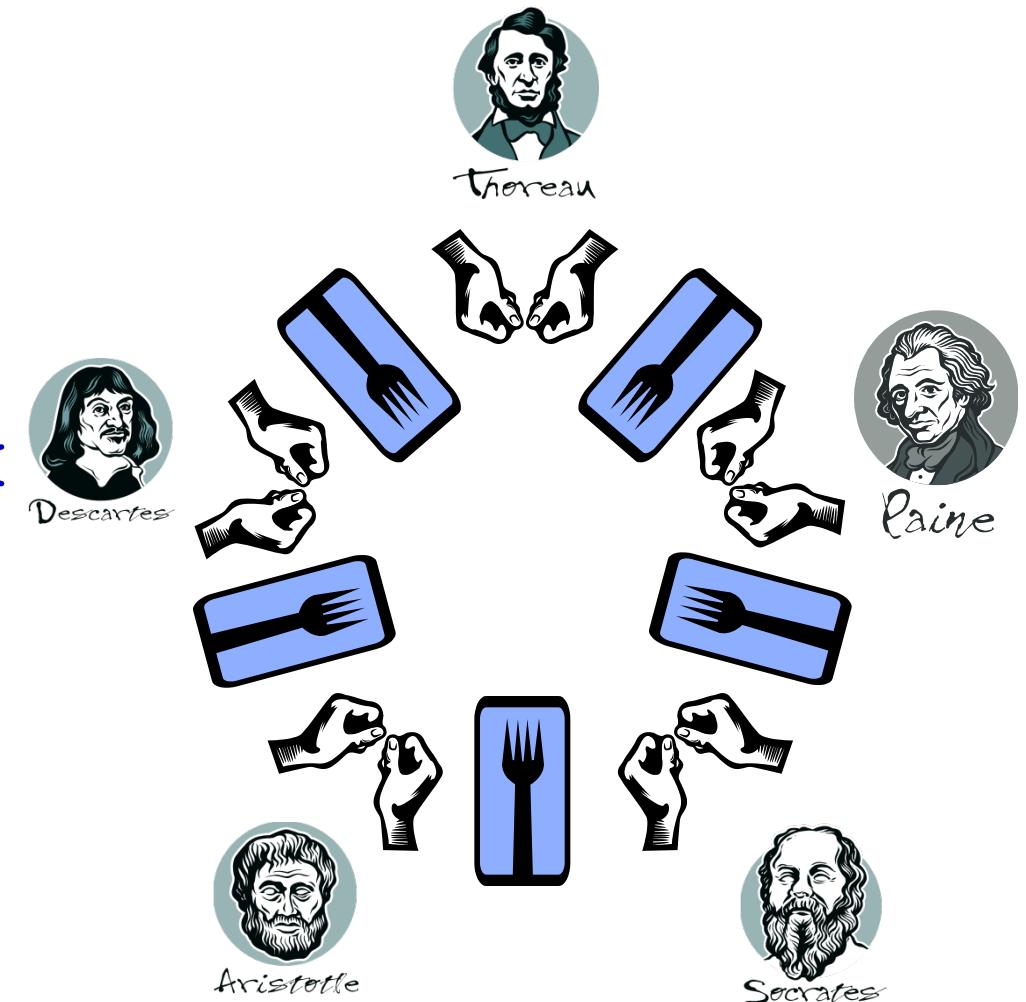
But why is it guaranteed to preclude circular wait?

# Dining Philosophers solution with unnumbered resources

Back to the trivial broken  
“solution”...

```
# define N 5

void philosopher (int i) {
    while (TRUE) {
        think();
        take_fork(i);
        take_fork((i+1)%N);
        eat(); /* yummy */
        put_fork(i);
        put_fork((i+1)%N);
    }
}
```

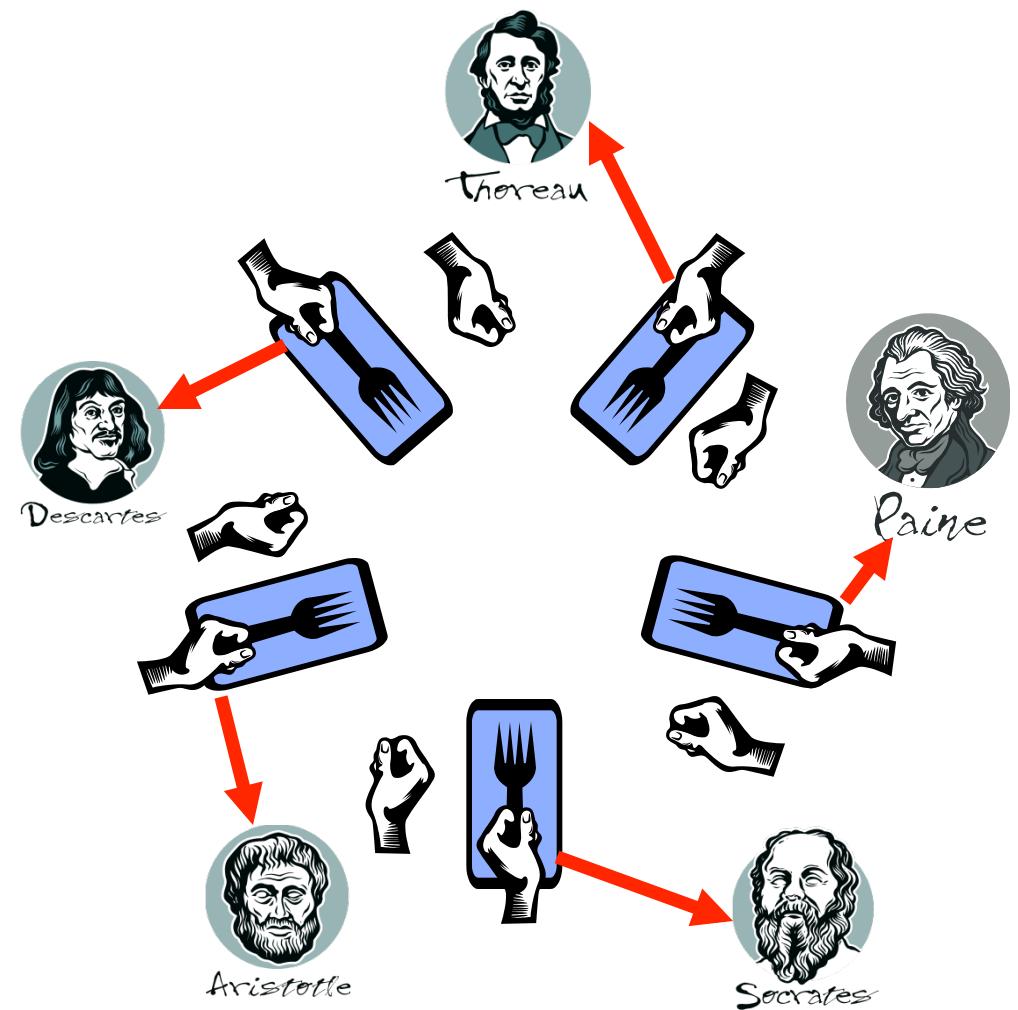


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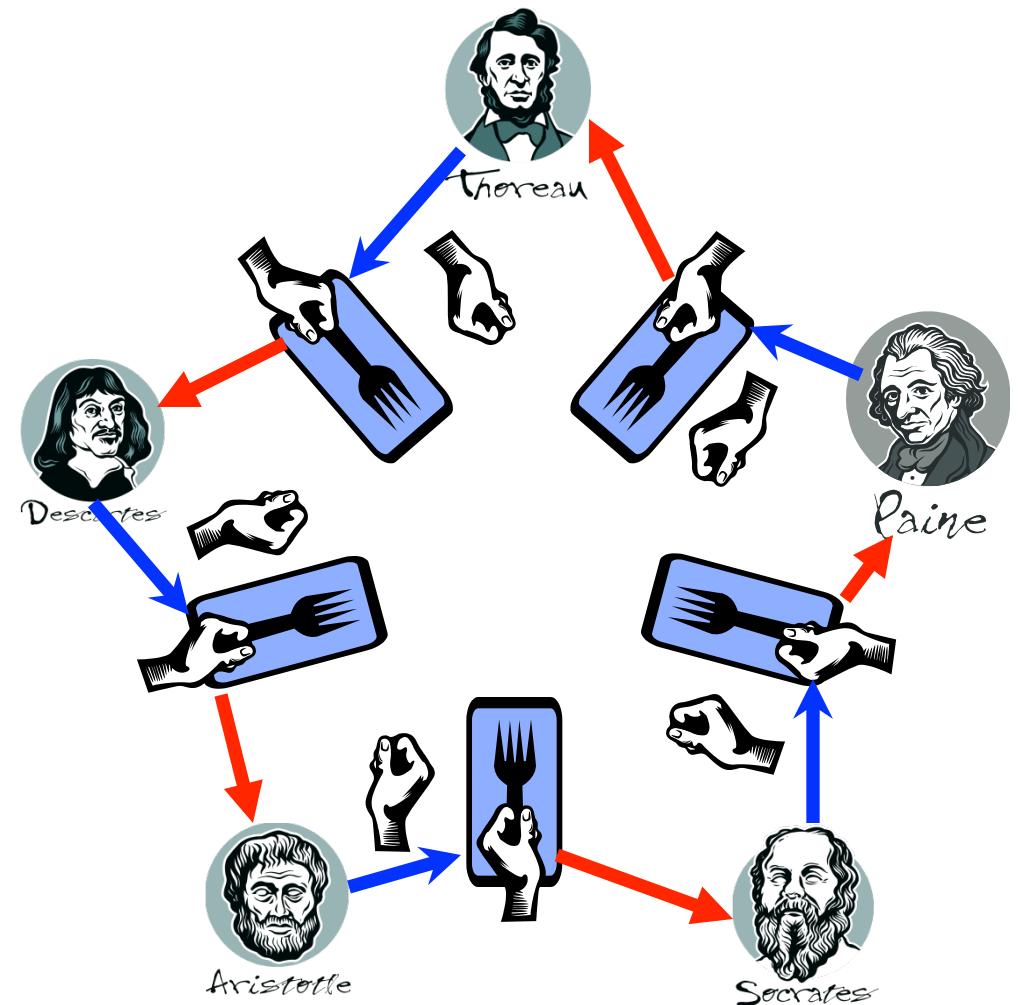


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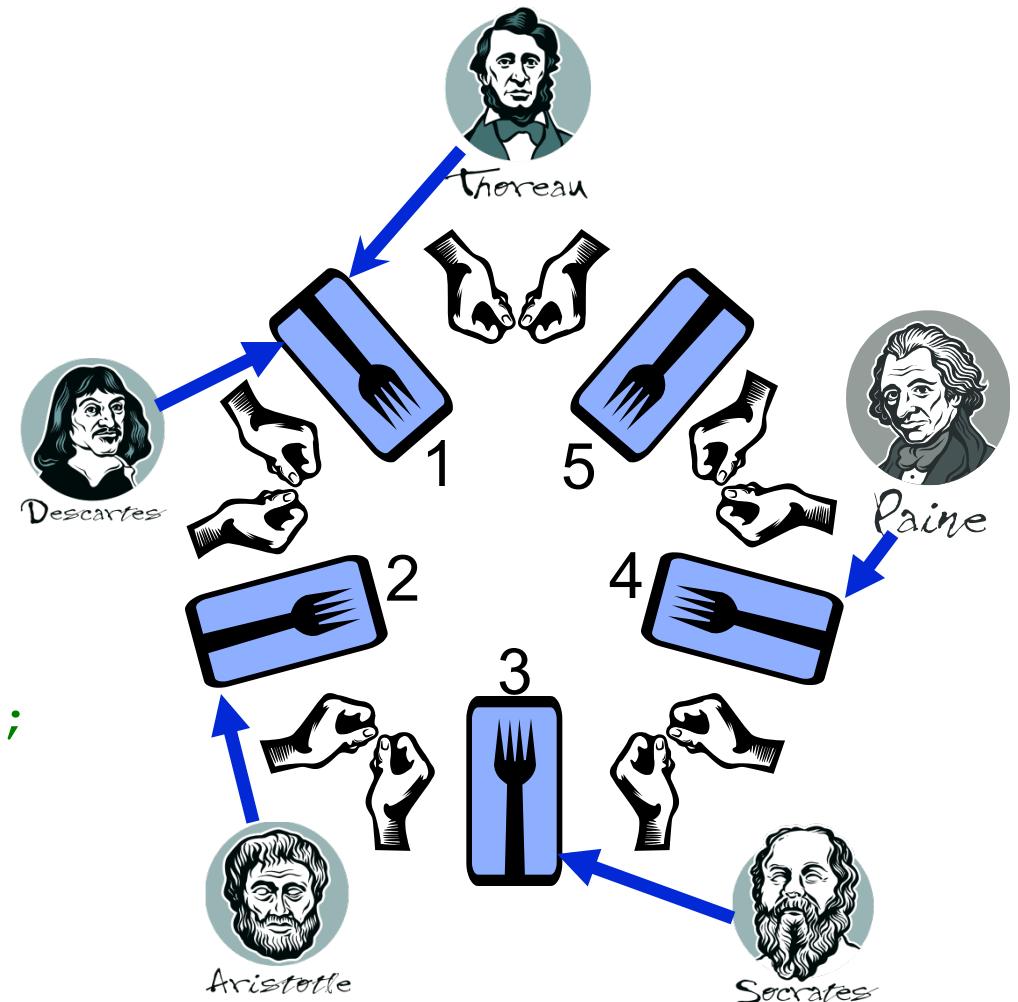
# Dining Philosophers solution with numbered resources

Instead, number resources

First request lower numbered fork

```
# define N 5

void philosopher (int i) {
    while (TRUE) {
        think();
        take_fork(LOWER(i));
        take_fork(HIGHER(i));
        eat(); /* yummy */
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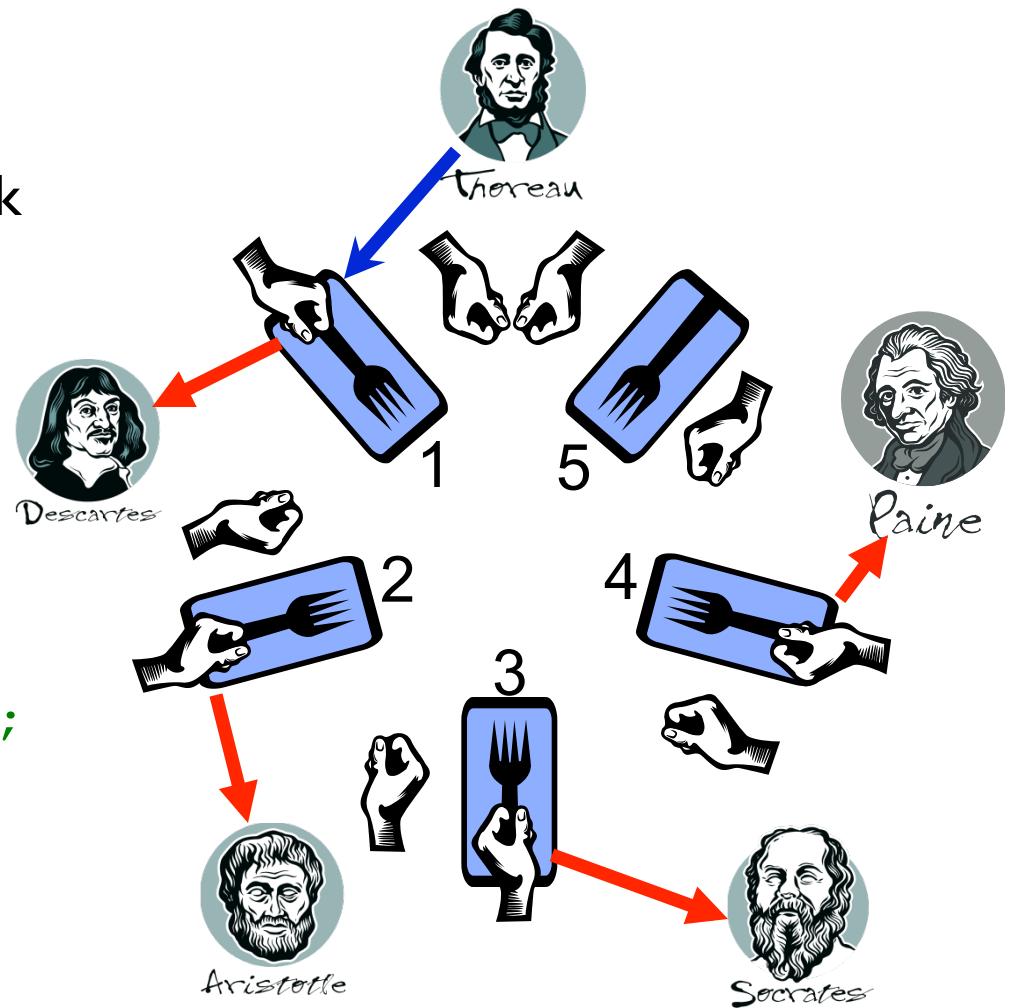
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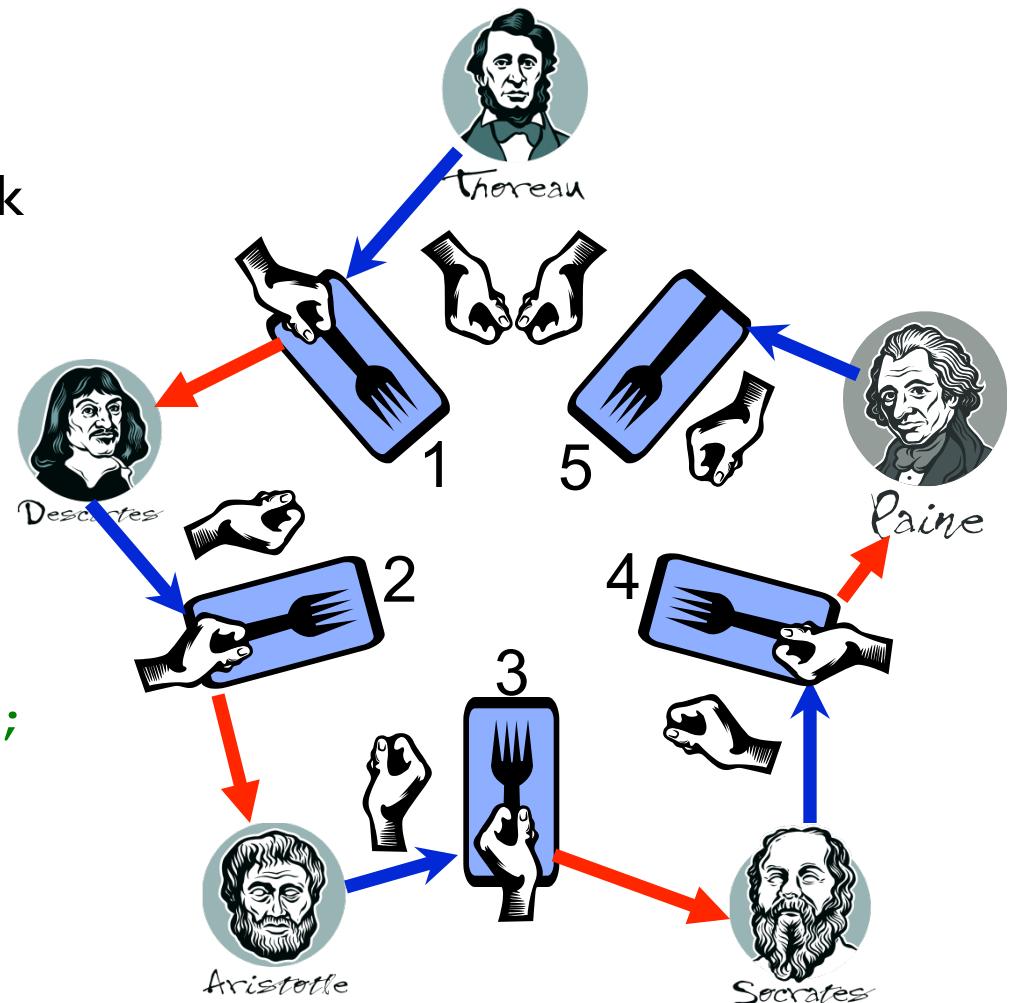
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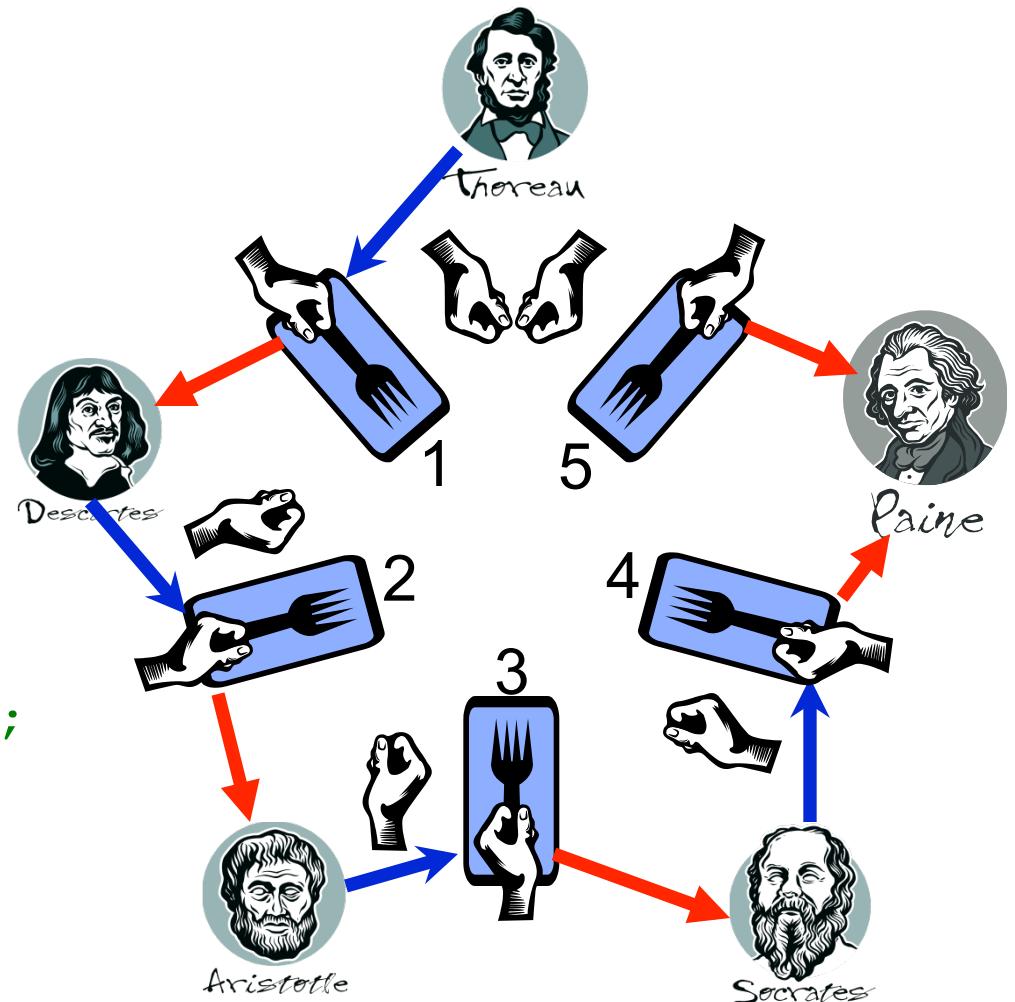
# Dining Philosophers solution with numbered resources

Instead, number resources...

One philosopher can eat!

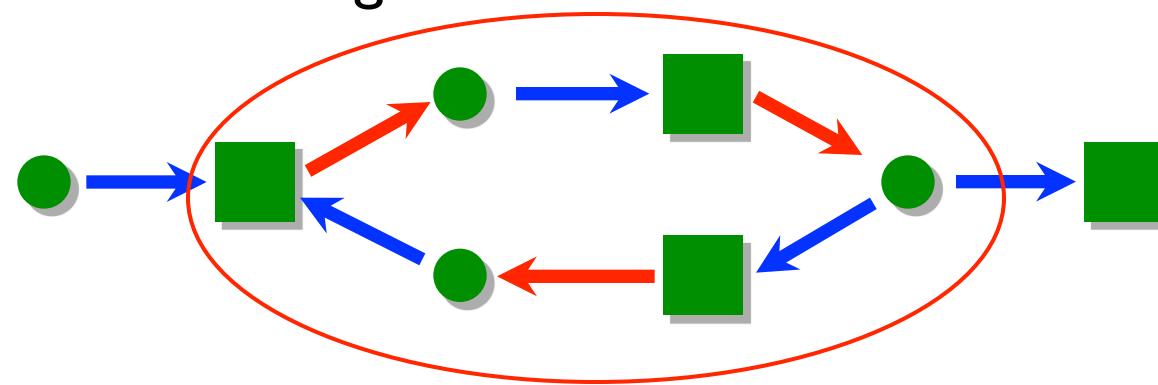
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# Ordered resource requests prevent deadlock

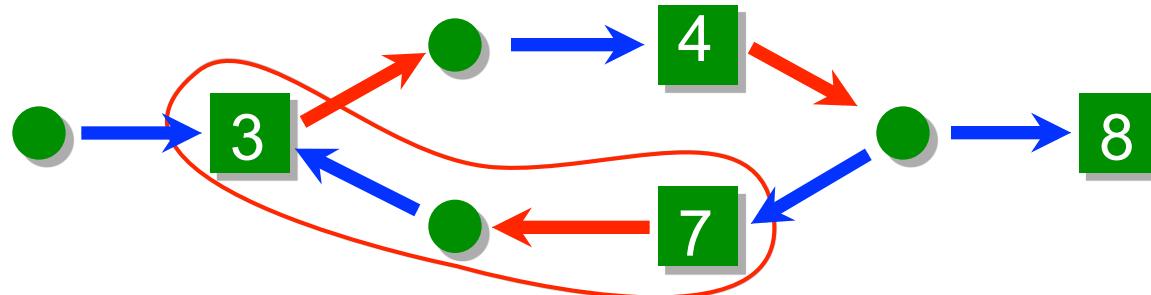
Without numbering



Cycle!

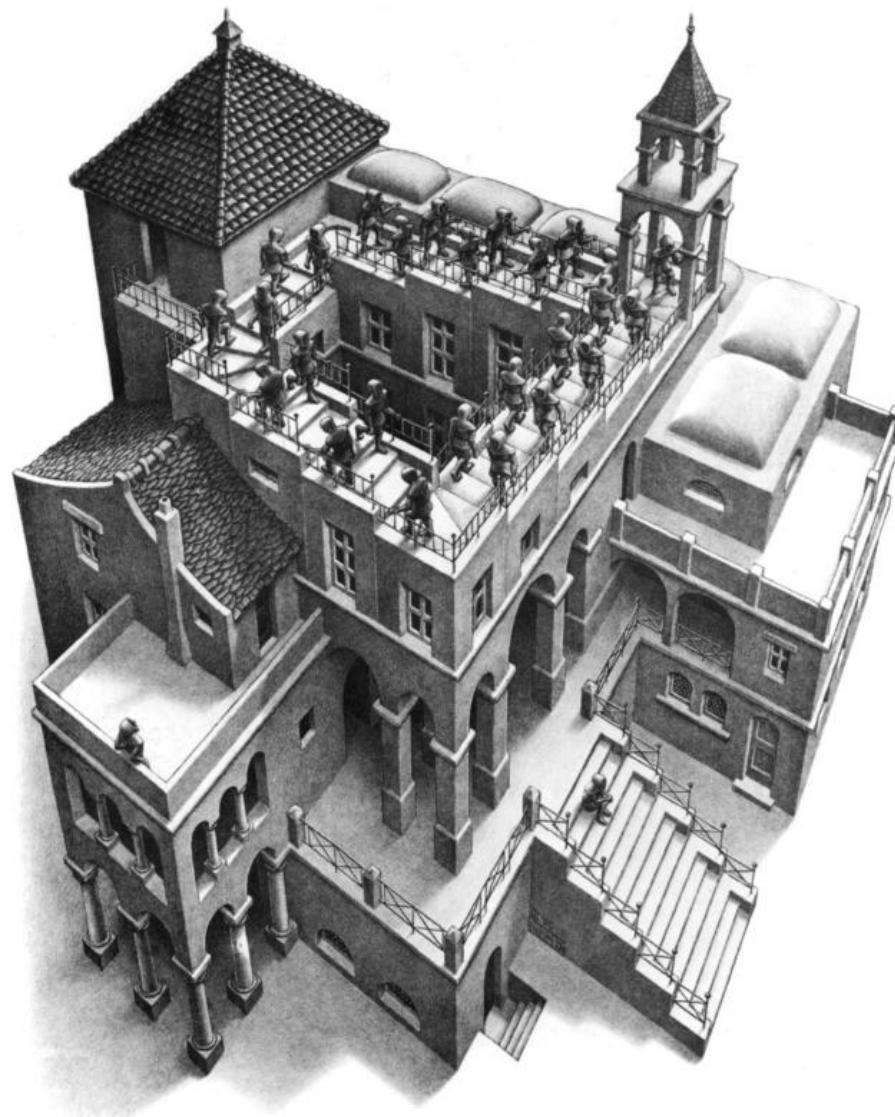
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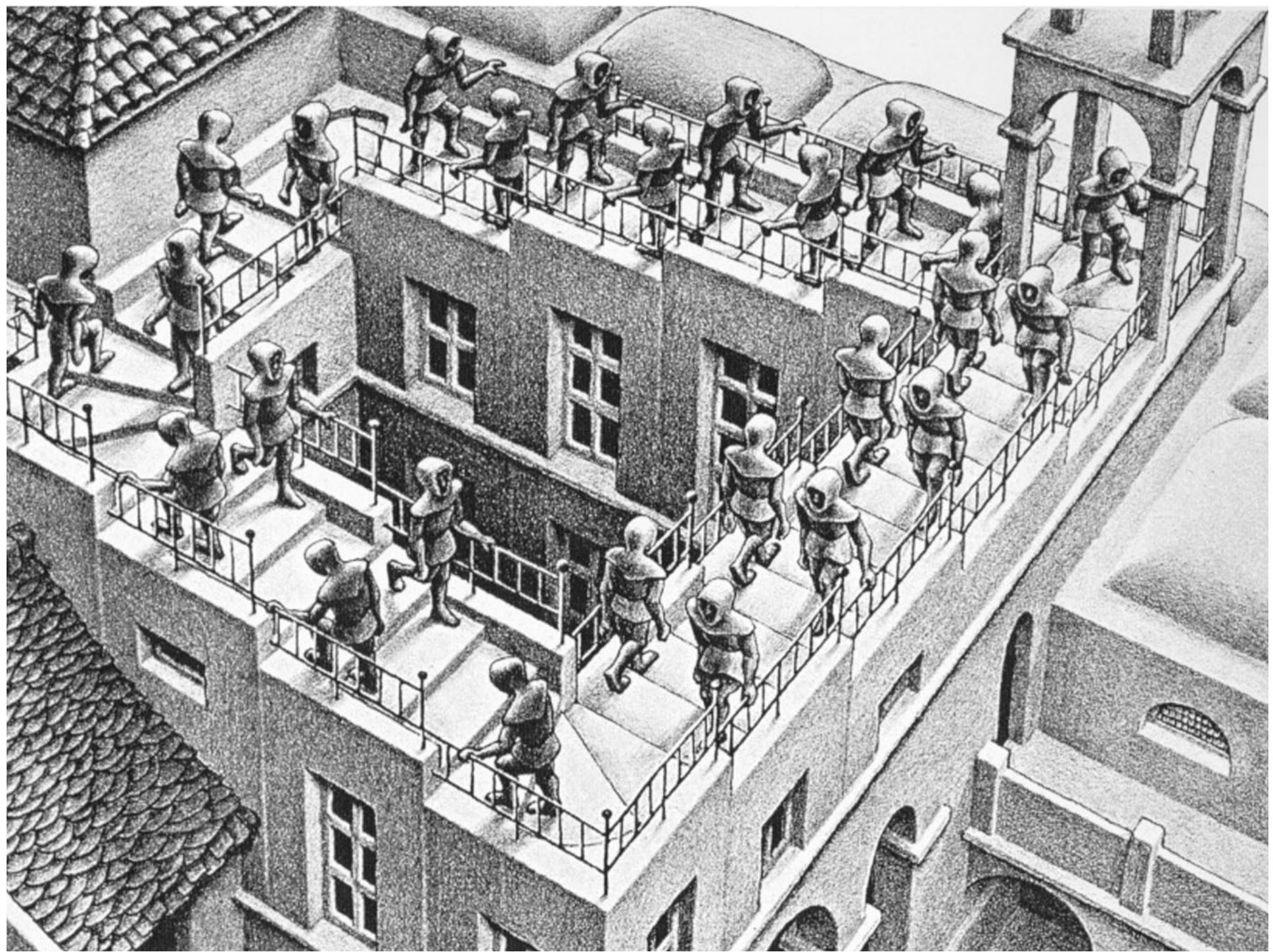
With numbering



Ordering violation:  
Process holds 7,  
is requesting 3

# Proof by M.C. Escher





# Summary: Deadlock prevention methods

## #1: No mutual exclusion

- Thank you, Captain Obvious

## #2: Allow preemption

- OS can revoke resources from current owner

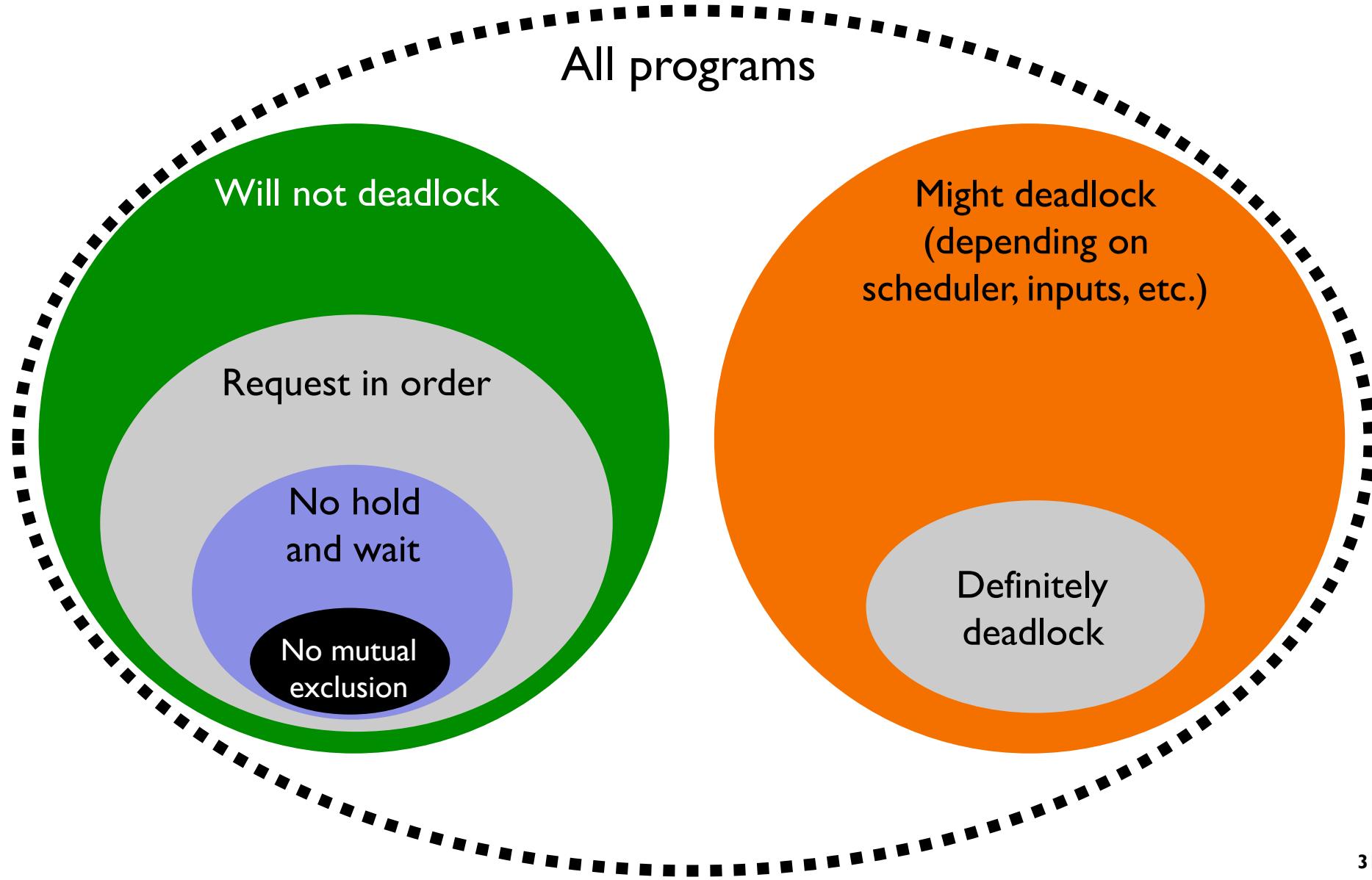
## #3: No hold and wait

- When waiting for a resource, must not currently hold any resource

## #4: Request resources in order

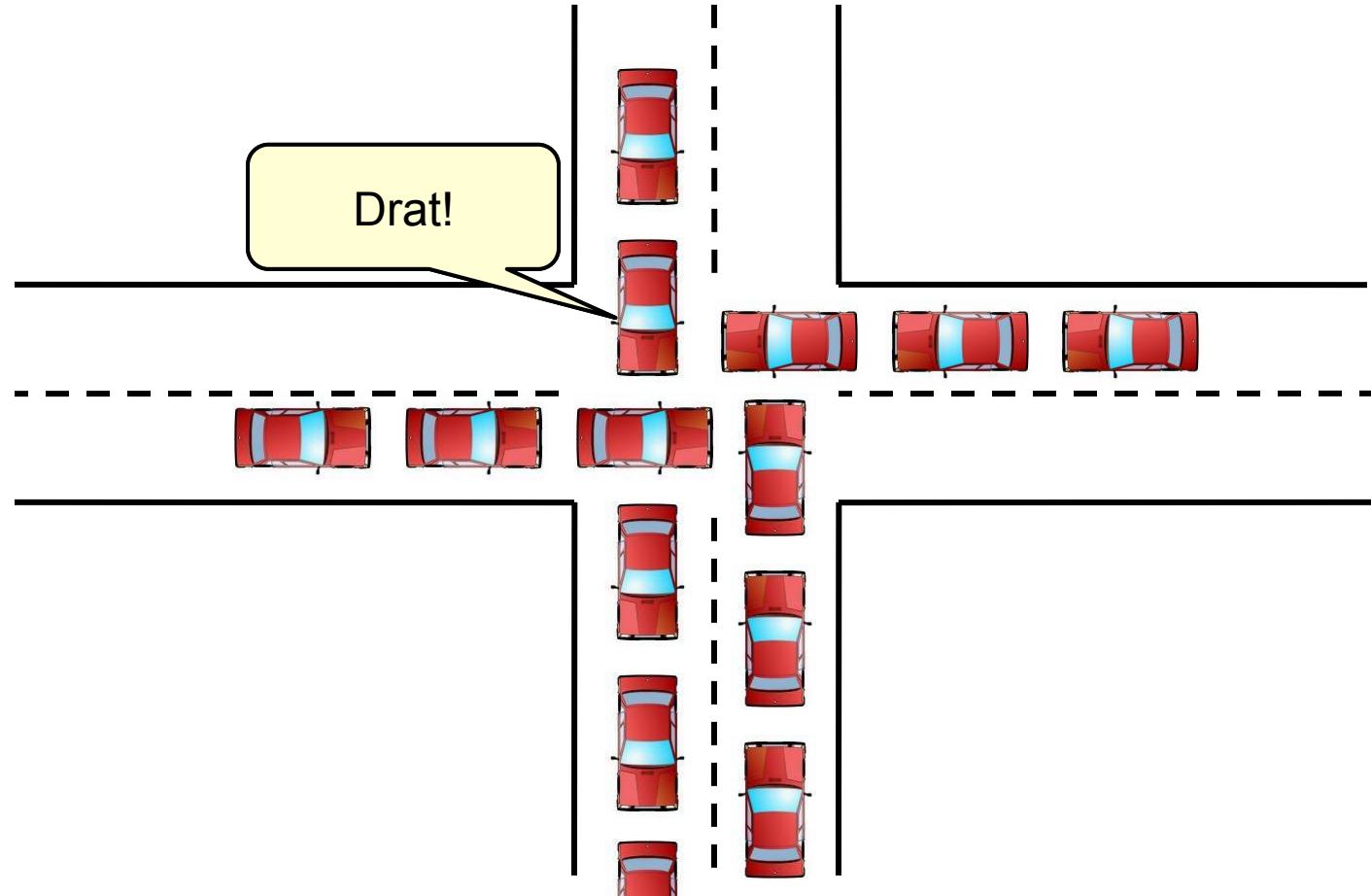
- When waiting for resource  $i$ , must not currently hold any resource  $j > i$
- As you can see: If your program satisfies #3 then it satisfies #4

# “Request In Order” is more permissive



# Q: What's the rule of the road?

What's the law? Does it resemble one of the rules we saw?



# Summary

## Deadlock prevention

- Imposes rules on what system can do
- These rules are conservative
- Most useful technique: ordered resources
- Application can do it; no special OS support

## Next: dealing with deadlocks other ways

- Avoidance
- Detection & recovery

# Deadlock Avoidance

# Deadlock Avoidance

Idea: Steer around deadlock with smart scheduling

Assume OS knows:

- Number of available units of each resource
  - Each individual mutex lock is a resource with one unit available
  - Each individual semaphore is a resource with possibly multiple units available
- For each process, current amount of each resource it owns
- For each process, maximum amount of each resource it might ever need
  - For a mutex this means: Will the process ever lock the mutex?

Assume processes are independent

- If one blocks, others can finish if they have enough resources

# How to guide the system down a safe path of execution

Helper function: is a given state **safe**?

- **Safe** = there's definitely a way to finish the processes without deadlock

When a resource allocation request arrives

- Pretend that we approve the request
- Call function: Would we then be safe?
- If safe,
  - Approve request
- Otherwise,
  - Block process until its request can be safely approved
  - Some other process is scheduled in the meantime

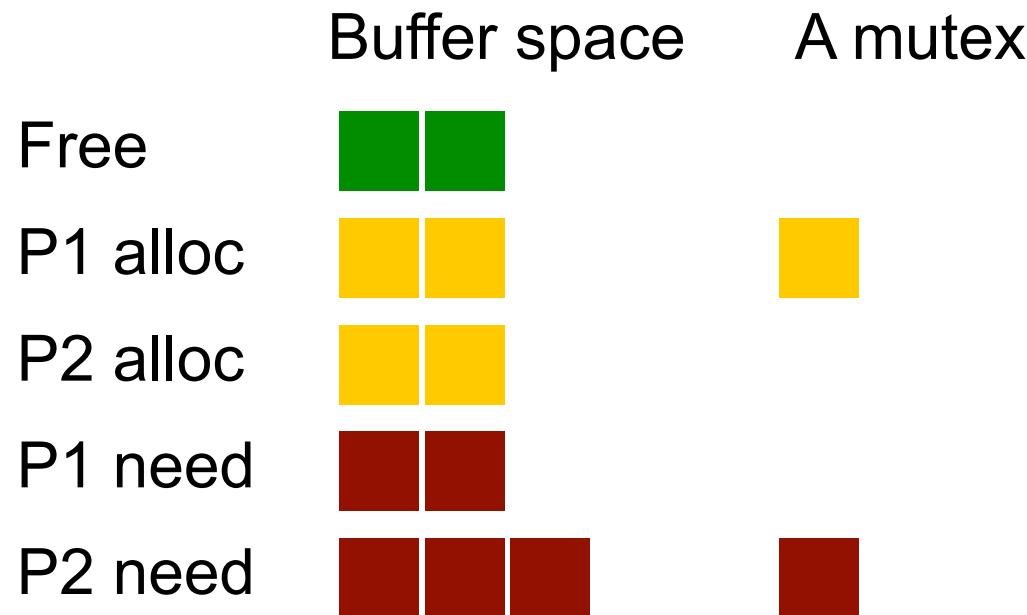
This is called the Banker's Algorithm

- Dijkstra, 1965

# What is a state?

For each resource,

- Current amount **available**
- Current amount **allocated** to each process
- Future amount **needed** by each process (maximum)



# When is a state safe?

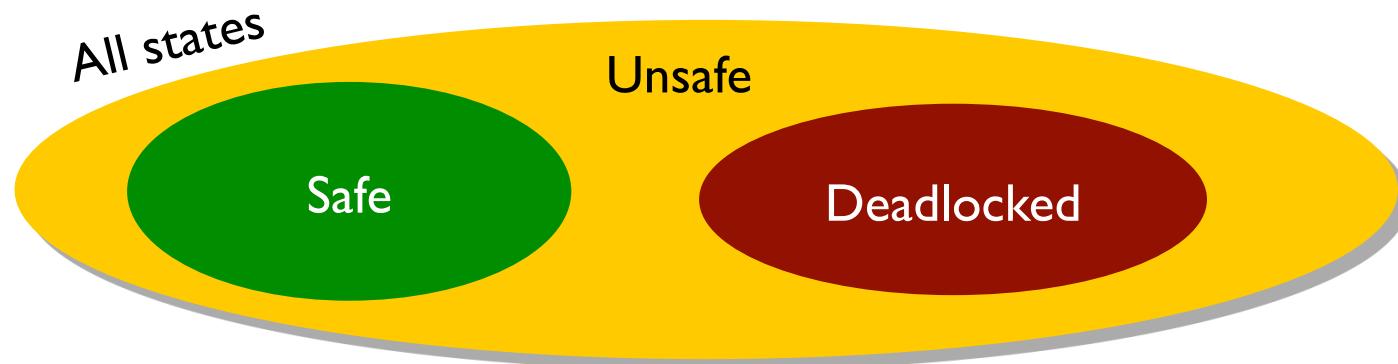
There is an execution order that can finish

In general, that's hard to predict

- So, we're conservative: find sufficient conditions for safety
- i.e., make some pessimistic assumptions

Pessimistic assumptions:

- A process might request its maximum resources at any time
- A process will never release its resources until it's done



# Computing safety

“There is an execution order that can finish”

Search for an order  $P_1, P_2, P_3, \dots$  such that:

- $P_1$  can finish using what it has plus what's free
- $P_2$  can finish using what it has + what's free + what  $P_1$  releases when it finishes
- $P_3$  can finish using what it has + what's free + what  $P_1$  and  $P_2$  will release when they finish
- ...

# Computing safety

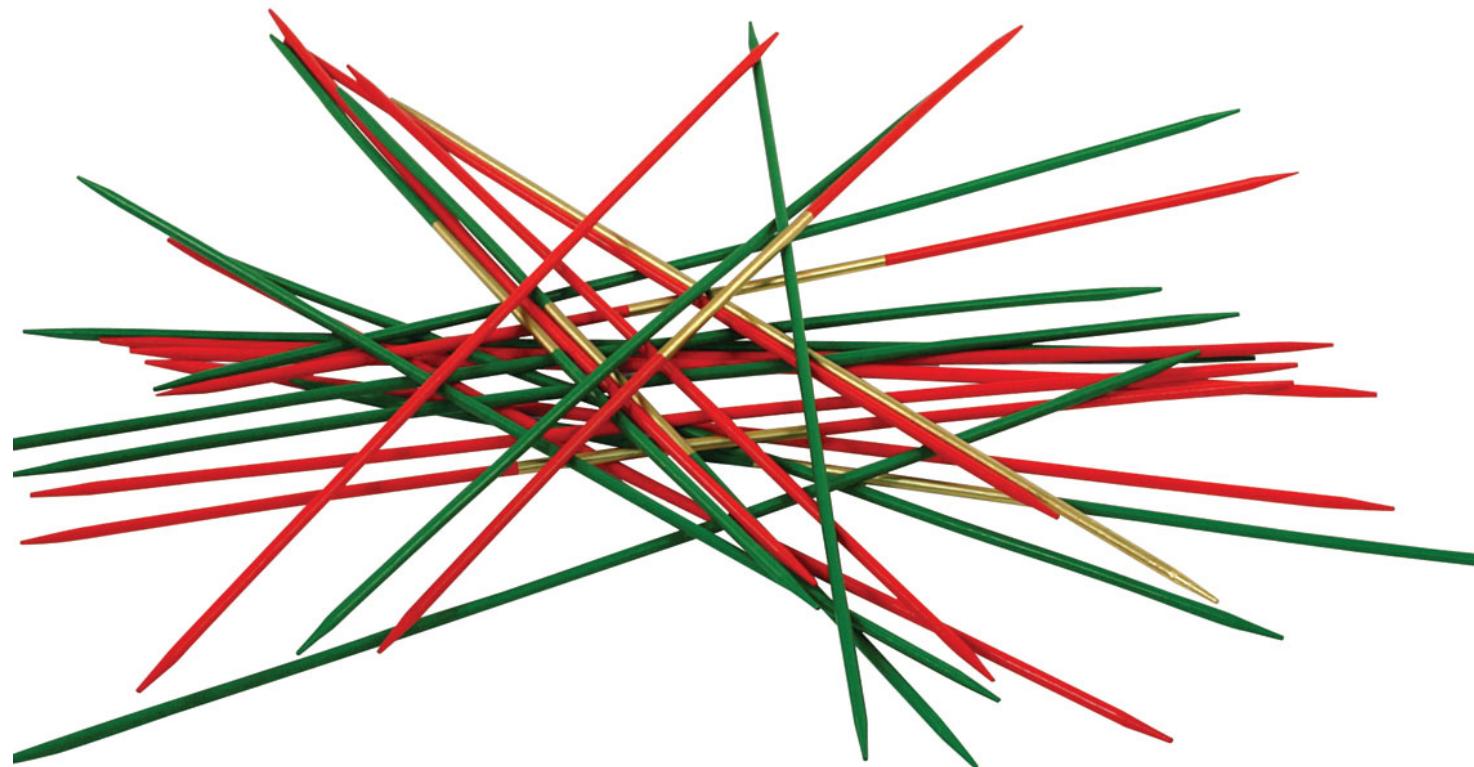
“There is an execution order that can finish”

More specifically... Search for an order P1, P2, P3, ... such that:

- P1’s max resource needs  $\leq$  what it has + what’s free
- P2’s max resource needs  $\leq$  what it has + what’s free + what P1 will release when it finishes
- P3’s max resource needs  $\leq$  what it has + what’s free + what P1 and P2 will release when they finish
- ...

But how do we find that order?

# Inspiration



# Playing Pickup Sticks with Processes

Pick up a stick on top

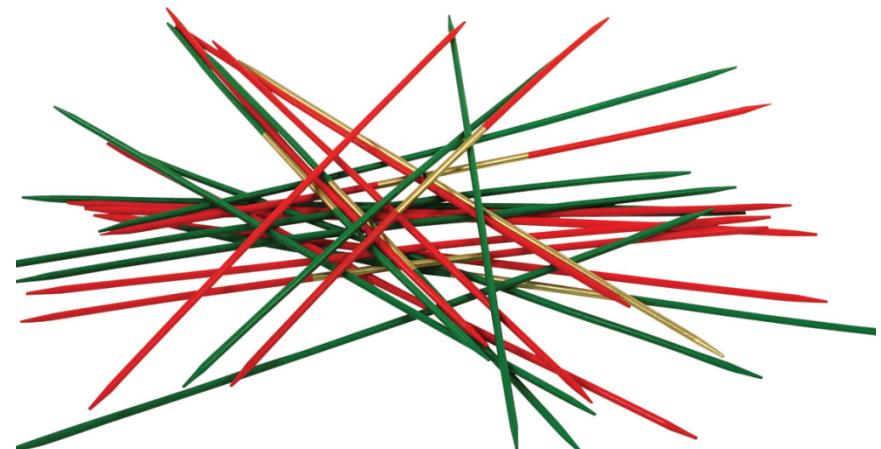
- = Find a process that can finish with what it has plus what's free

Remove stick

- = Process finishes & releases its resources

Repeat until...

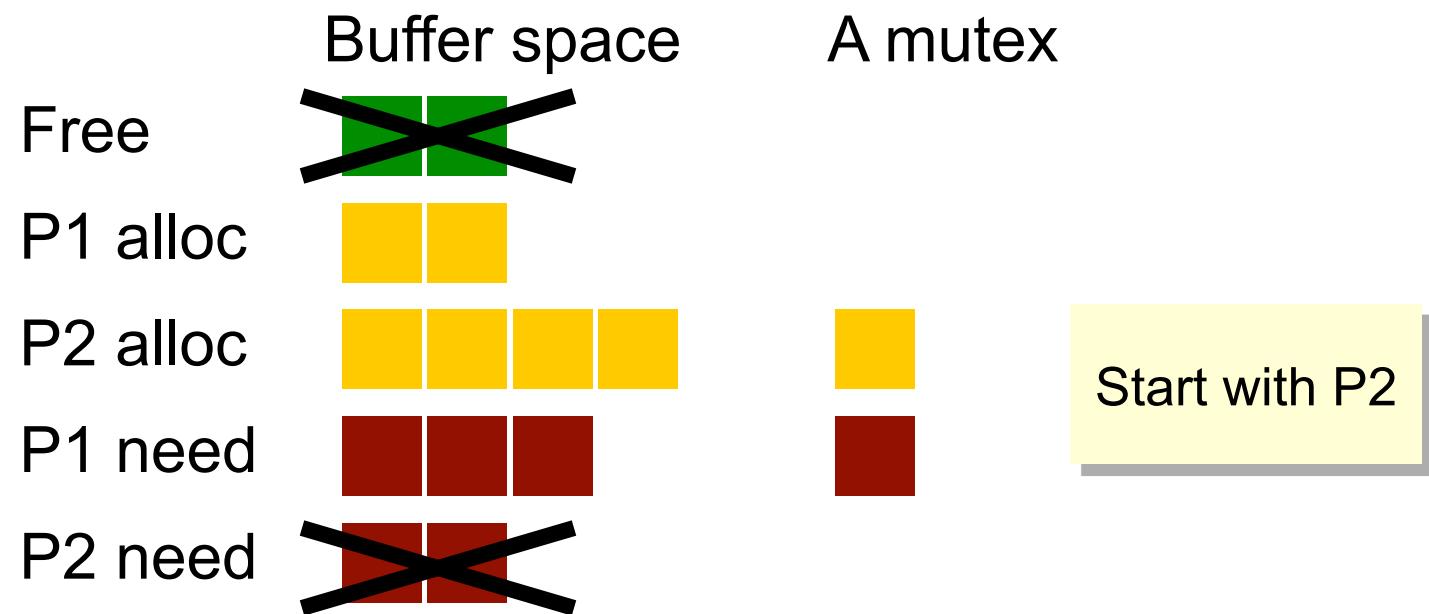
- ...all processes have finished
  - **Answer: safe**
- ...or we get stuck
  - **Answer: unsafe**



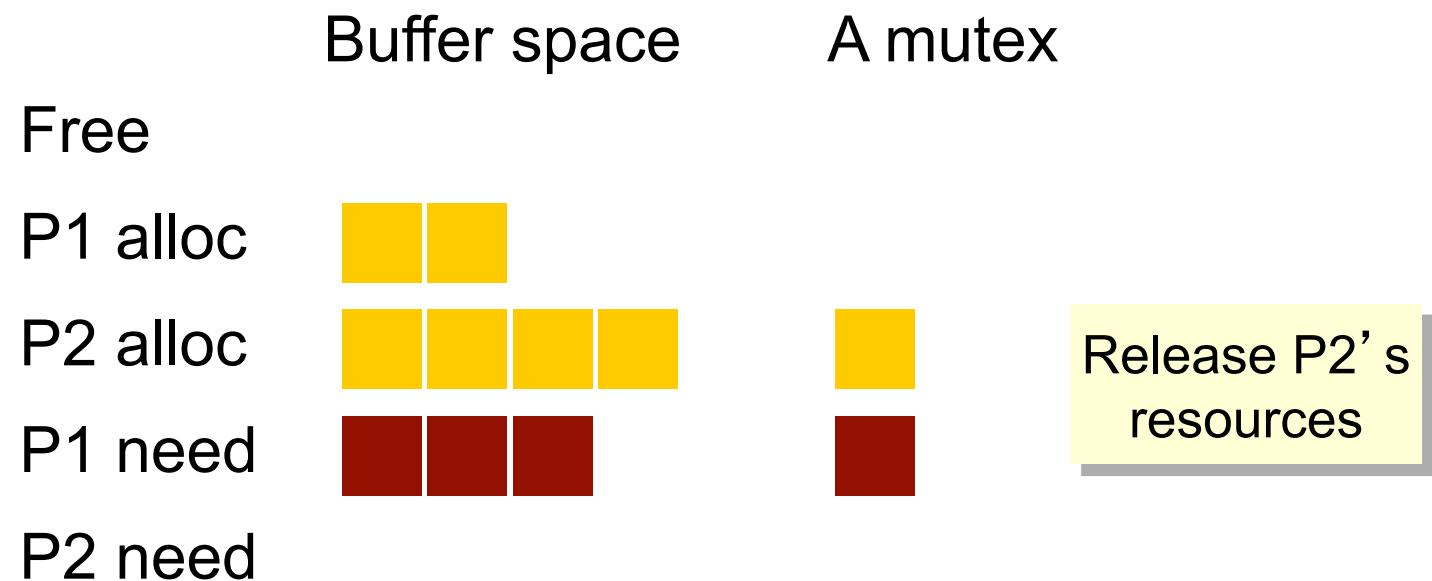
# Try it: is this state safe?



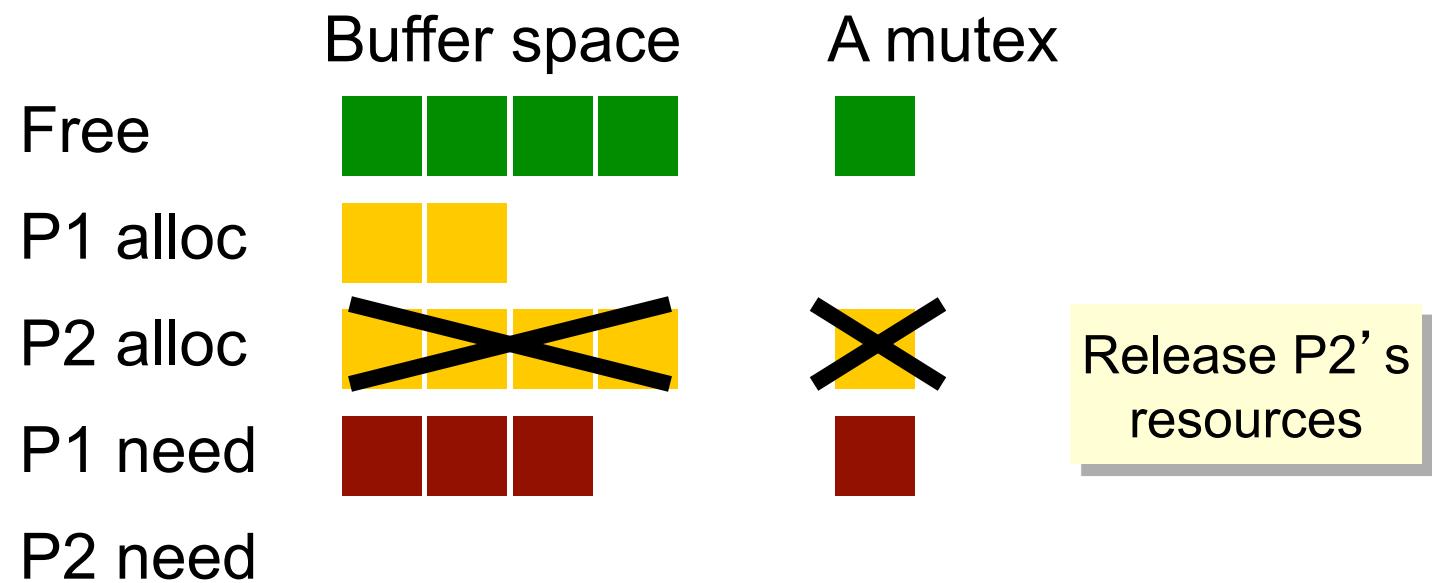
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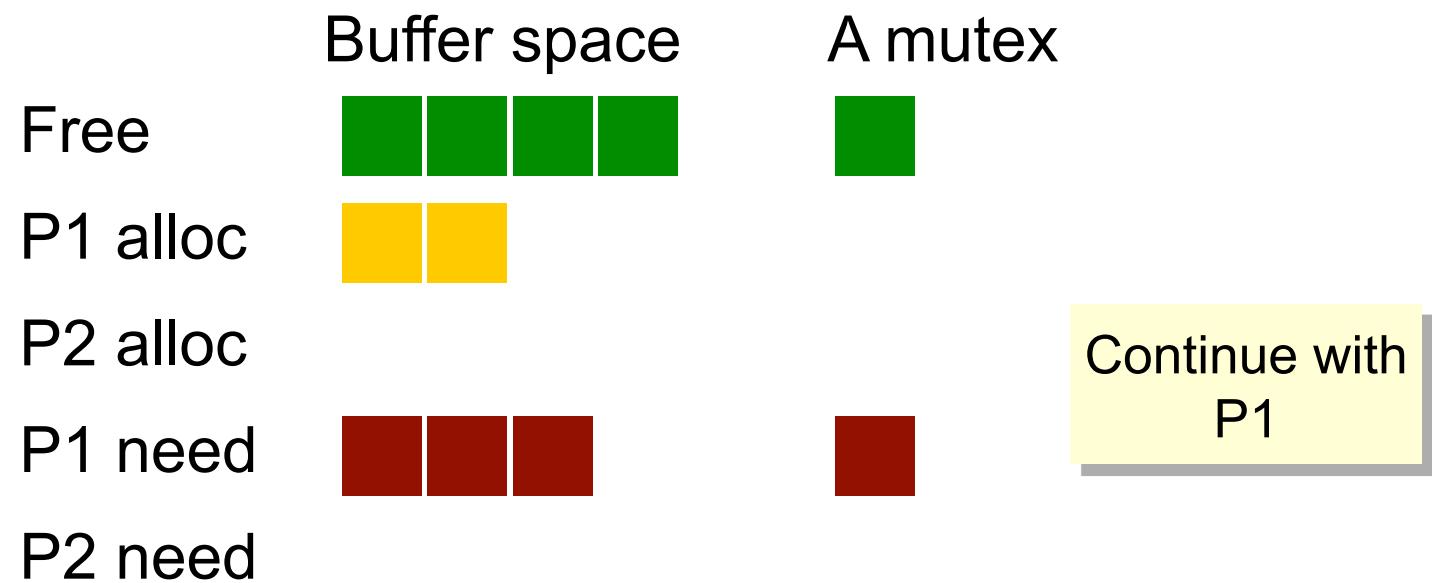
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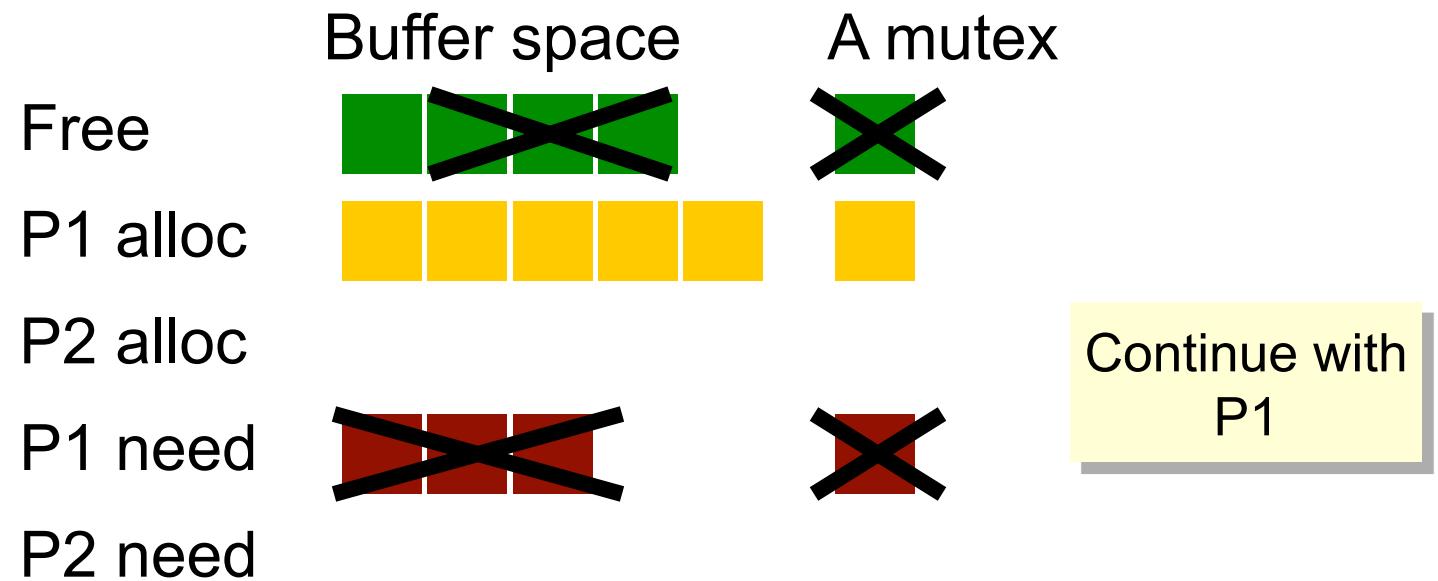
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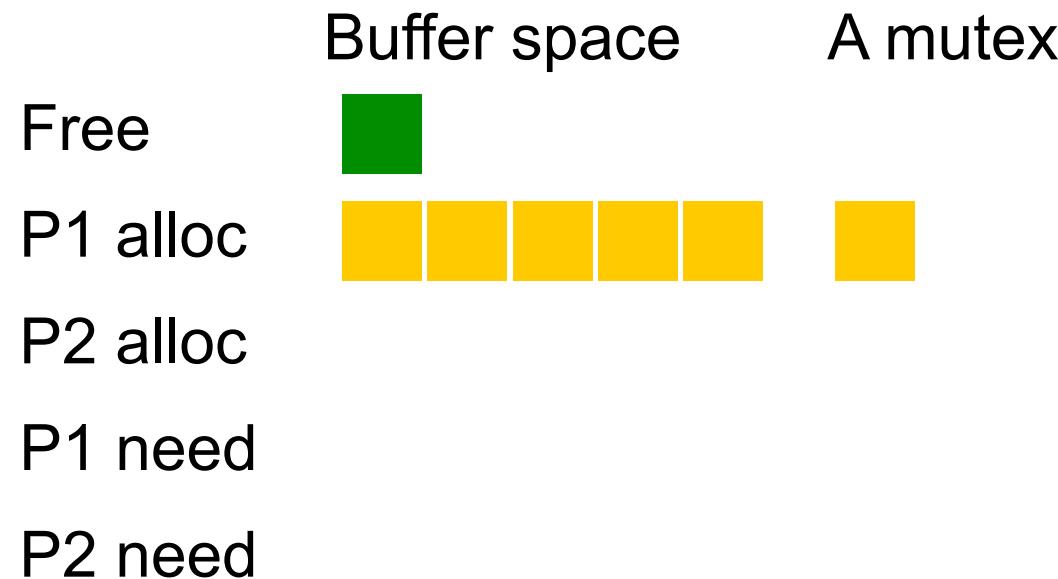
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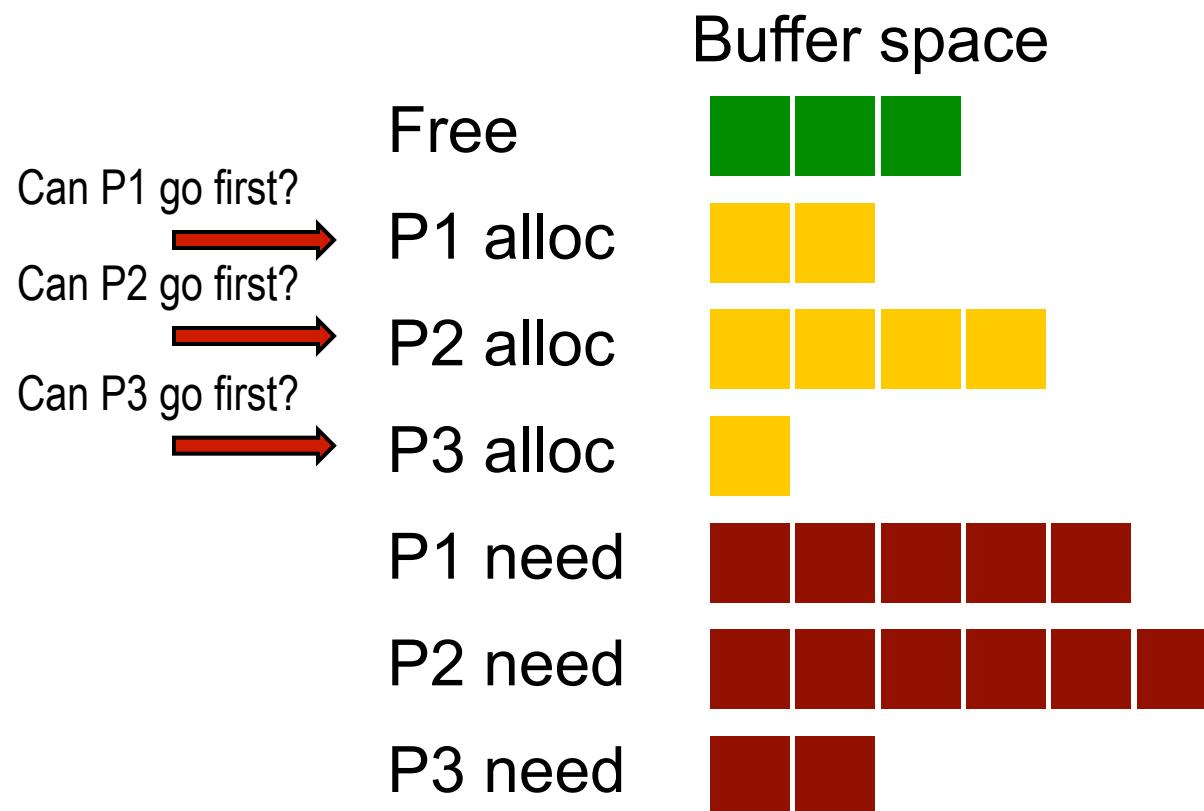


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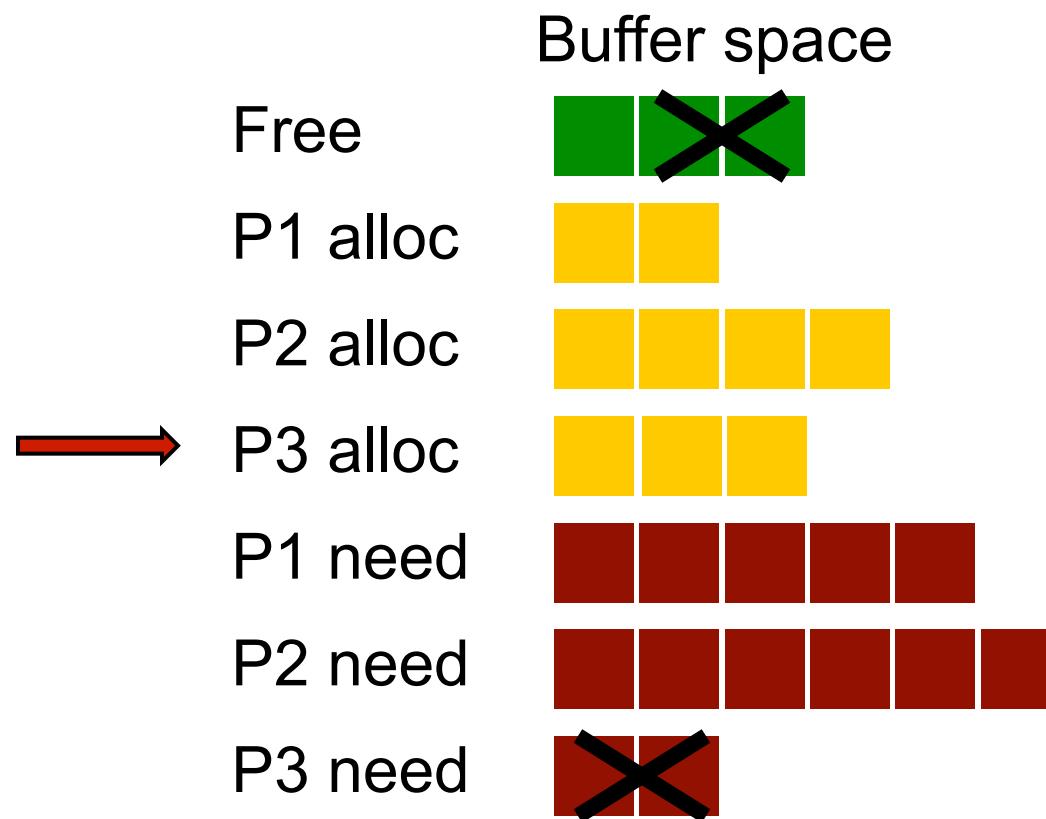


Yes, it's safe:  
Order is P2,  
P1

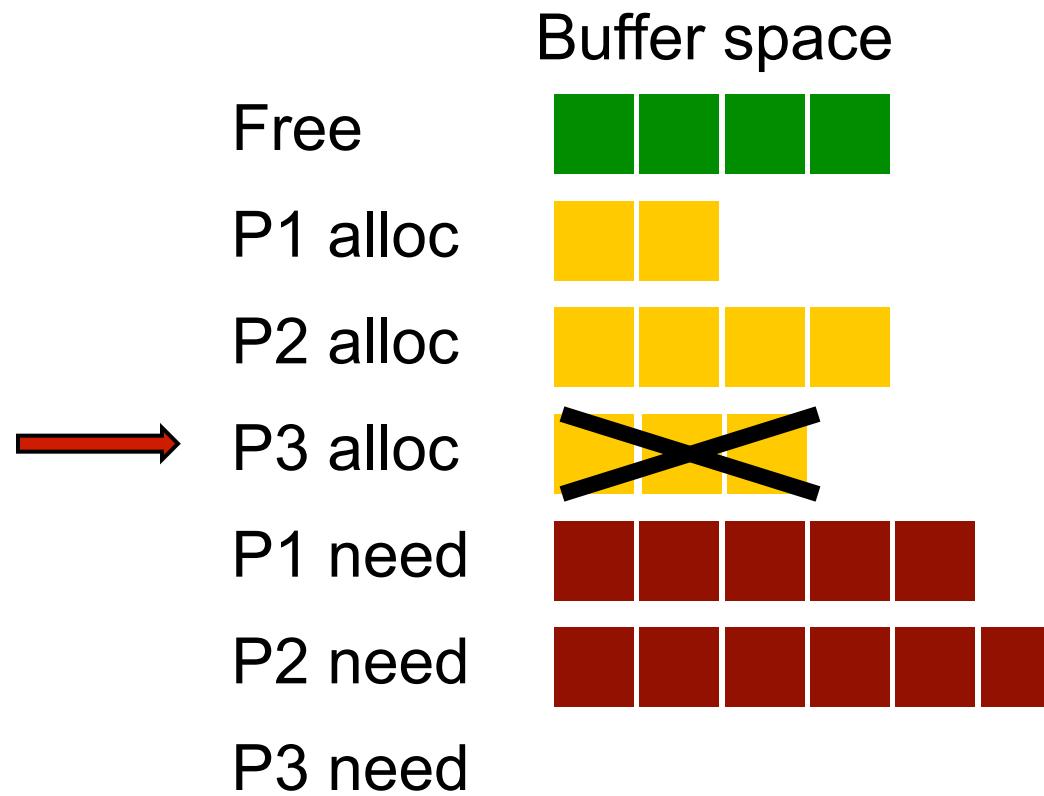
## Example 2: Is this state safe?



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