# Ahad Rauf

ahadrauf@berkeley.edu | (925) 400-3352 linkedin.com/in/ahadrauf | github.com/ahadrauf

**EDUCATION** 

# University of California, Berkeley

Aug 2016 - June 2020

B.S., Electrical Engineering and Computer Science (EECS), GPA: 3.953

 Relevant Courses: Introduction to Robotics (EECS C106A), Introduction to MEMS (EE 147), Introduction to Embedded Systems (EE 149), Feedback Control Systems (EE C128), Analog Integrated Circuits (EE 140), Signals and Systems (EE 120), Computer Architecture (CS 61C)

**WORK EXPERIENCE** 

## **Robotics Engineering Internship**

May 2018 - Aug 2018

OURS Technology, Inc.

- Developed a high precision automatic testing system for on-chip optical waveguides
- Designed the entire testing pipeline, including machine learning object detection for chip detection, 200-nm precision scanning for accurate waveguide-fiber alignment, and multithreaded data processing for efficient 8-axis motion control
- Configured company GPU servers for efficient machine learning support and LDAP network access
- Wrote bash and Python scripts to remotely diagnose motion control hardware failures

# **Robotics Engineering Internship**

Sept 2017 – Dec 2017

Elysian Labs

- Customized drones for research into efficient autonomous tracking systems
- Designed a low-power IR receiver and noise filter to accurately locate the transmitter from far away, as well as a sensor that could be used to automatically adjust the drone's path to avoid obstacles
- Developed a drone swarm simulation software to model optimal task distribution for up to 1000 drones during common group flight maneuvers

**RESEARCH** 

## **Device Physics Research Assistant**

Jan 2018 - Dec 2018

Advisors: Niklas Roschewsky, Sayeef Salahuddin

- Designed 3-mask ferromagnetic resonance stack to measure the DC voltage generated by Al/Pt/Py spin pumping; optimized mask layout and processing for high-efficiency operation
- Proposed and constructed a new quadrupole magnet testing station for generating highly uniform magnetic fields up to 150 mT with controllable orientation

# **Machine Learning Research Assistant**

Jan 2018 – May 2018

Advisors: Ke Li, Jitendra Malik

- Explored new neural net configurations to enhance image quality and variation when generating novel images given a high-dimensional data distribution
- Improved progressive training of generative adversarial networks (GANs) to reduce training time and remove potential sources of instability

HONORS

# **Dorm Ex Machina Competition**

Sept 2016 - Nov 2016

Robotics @Berkeley Club, UC Berkeley

- Designed and built robotic trash can to promote responsible waste disposal in line with UC
  Berkeley's Zero Waste Project; streamlined disposal through robotic sensing and voice activation
- Received "Most Useful Product" award for exceptional focus on environmental awareness
- Customized noise reduction algorithms to improve voice recognition reliability by 25%

## Cal Alumni Association Leadership Award

May 2016

• Chosen based on effective leadership in academics and extracurricular activities

# Regents' and Chancellor's Scholarship

March 2016

Highest UC Berkeley merit award recognizing top 2% of incoming students

## Verizon Innovative App Challenge Best in Region Award

Jan 2015

- Awarded for creativity in designing mobile apps to enhance early childhood education
- Ranked among the top 12 high school participants in the nation

# **TECHNICAL SKILLS**

- Proficient at C++, Java, Python, MATLAB, ROS, and Linux
- Skilled at Cadence-based circuit design and Autodesk Fusion 360-based CAD design