Atif Harooni

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FXPFRIFNCF

ENGINEERING SERVICES | MECHANICAL SYSTEM DESIGNER Aug 2016 - June 2020 | Toronto, ON

- Principle Mechanical Designer for ESI's Mobile Robots Group.
 Successfully delivered robots for Logistics, Medical, Surveillance, Personal, and EOD use.
- Simulated loading on ESI's Robotic Arm to determine static and dynamic forces during normal operation.
- Travelled internationally to evaluate manufacturing facilities, conduct market research, and gather design specifications from customers
- Designed motion control system for parking enforcement robot in collaboration with the University of Ontario Institute of Technology
- Was interviewed on national TV about ESI's history and products, and appeared in promotional material.

LIBURDI ENGINEERING | TURBINE DESIGN CO-OP

Sep 2014 - Dec 2014 | Hamilton, ON

- Created a 2D CFD analysis of a Hot-Gas Turbine to show performance can be optimized by modifying Inlet Vane, and Blade Geometry.
- Improved weld quality by modeling surface temperature of a welding shielding gas trail-cup during operation. Operators used this model to optimize their toolpaths and generate welds with lower oxidation.

ABC GROUP INC. | MANUFACTURING ENGINEERING CO-OP Jan 2014 - April 2014 | Toronto, ON

- Managed projects and R&D related activities pertaining to injection/extrusion blow moulded components.
- Tested and validated material properties of HVAC ducts, to ensure that they adhered to OEM specifications.

B&W CANADA | NUCLEAR DESIGN ENGINEER CO-OP May 2013 - Aug 2013 | Cambridge, ON

- Prepared calculations that determined Thermal-Hydraulic characteristics of a Nuclear Steam Generator.
- Determine heat duty of a steam generator at end of life conditions with maximum tube plugging.

MORGAN SOLAR | DESIGN ENGINEER CO-OP

Sep 2012 - Dec 2012 | Toronto, ON

- Improved tracking accuracy of Savanna™ Dual-Axis Tracker by redesigning critical structures for greater stiffness.
- Conducted FEA to determine the stress response and deflection on the solar tracker during max wind loads.

XSTRATA | PROJECT ENGINEERING CO-OP

Jan 2012 - April 2012 | Sudbury, ON

- Managed planning, design, and completion of capital construction projects, and maintenance projects.
- Reduced slurry pump downtime by installing impellers with DLC coating.

EDUCATION

UNIVERSITY OF WATERLOO

BACHELOR OF APPLIED SCIENCE IN MECHANICAL ENGINEERING (HONOURS) Sep 2010 - April 2015 | Waterloo, ON

COURSEWORK

Robotic Manipulators: Kinematic & Dynamic Control
Numerical Control of Machine Tools
CFD for Engineering Design
Experimental Methods in Fluids
Fluid Power Control Systems
Industrial Metallurgy

SKILLS

CAD

Solidworks • ProEngineer(Creo)
Inventor • AuotCAD

PROGRAMMING

Python • C++ • Matlab • ROS Simulink • Labview

DESIGN EXPERIENCE

CNC • Injection Molding • Sheet Metal Additive Manufacturing • DFM • DFA ANSYS • GD&T

PROJECTS

Robotic Arm: Golf Putter

Programmed a Robotic Arm to use a vision system to play golf.

Argon Shielding System for Metal Powder Welds

Designed rig for making consistent metal welds using powdered zirconium.

OTHER

Research Assistant | UW

Aug 2015 - June 2016 | Waterloo, ON Investigated Additive Manufacturing Methods for Powdered Zirconium.

Research Assistant | UW

May 2011 - Aug 2011 | Waterloo, ON Developed educational demos for 1st Year Engineering Students