

# Rothe's Method with Neumann Conditions

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## 1 Introduction

In this document, we implement Rothe's method to solve the 1D heat equation on the unit interval, with large diffusion coefficient,  $1/\epsilon$ ,  $\epsilon \ll 1$ , and non-zero Neumann BCs. We use order 2 accurate centered finite-differences to discretize in space and BDF2 formula to discretize in time.

We present a numerical example where the time-step is  $\Delta t \gg \epsilon$  and perform a grid refinement study to check whether Rothe's method remains order 2 accurate as  $\epsilon \rightarrow 0$ .

## 2 The problem

Let  $u(x, t)$  solve the following heat equation problem on the domain  $\Omega = [0, 1]$ ,

$$\begin{cases} \epsilon u_t - \Delta u = 0, & x \in \Omega \times (0, T], \\ \partial_n u = f, & x \in \partial\Omega \times (0, T], \\ u(x, 0) = 0, & x \in \Omega. \end{cases} \quad (2.1)$$

Here,  $\epsilon \ll 1$ ,  $T$  is a final time, and  $f$  represents known Neumann data. The notation  $\partial_n u$  represents the derivatives in the direction of the normal vector at the boundary.

## 3 Rothe's method

Rothe's method applies a temporal discretization to the differential equation in (2.1) to arrive at a sequence of elliptic equations which are then solved using boundary integral methods.

Leaving the space variable continuous, we discretize the heat equation in (2.1) in time using BDF2. Let  $t^n = n\Delta t$ , with  $n = 0, \dots, N_t$ ,  $u^n \approx u(\cdot, t^n)$ . Here,  $N_t$  represents the number of time steps. We have

$$u^{n+1} - \frac{4}{3}u^n + \frac{1}{3}u^{n-1} = \frac{2}{3}\frac{\Delta t}{\epsilon}(u_{xx})^{n+1},$$

so that

$$(u_{xx})^{n+1} - \frac{3\epsilon}{2\Delta t}u^{n+1} = \frac{-2\epsilon}{\Delta t}u^n + \frac{\epsilon}{2\Delta t}u^{n-1}. \quad (3.1)$$

At each time-step, we solve an elliptic equation to find  $u^{n+1}$ , a total of  $N_t$  elliptic solves.

We approximate the solution at the first time-step  $t = \Delta t$  using

$$u(x, \Delta t) = u_0(x) + \frac{\Delta t}{\epsilon \Delta x^2}(u_0(x + \Delta x) - 2u_0(x) + u_0(x - \Delta x)) + \mathcal{O}(\Delta t^2), \quad \text{as } \Delta t \rightarrow 0, \quad (3.2)$$

where  $\Delta x$  is the spatial step size.

## 4 Treatment of Neumann BCs

Let  $x_i = i\Delta x$  represent the discretization in space with  $i = -1, 0, \dots, N_x, N_x + 1$ . Here we introduce one *ghost* grid point at each end of the interval to treat the Neumann conditions using a centered discretization. Let  $u_i^n \approx u(x_i, t^n)$ . The discretization of the Neumann conditions at  $x = 0$  and  $x = 1$ , takes the form

$$\begin{aligned} -D_{0x}u_0^n &= f_l(x, t^n), & x = 0, \\ D_{0x}u_{N_x}^n &= f_r(x, t^n), & x = 1, \end{aligned}$$

where  $D_{0x}u_i^n = (u_{i+1}^n - u_{i-1}^n)/(2\Delta x)$ ,  $f_l$  and  $f_r$  represent given Neumann data on the left and right boundaries respectively. We can then evaluate the solution at the ghost grid points using the following

$$\begin{aligned} u_{-1}^n &= u_1^n + 2\Delta x f_l(x, t^n), & x = 0, \\ u_{N_x+1}^n &= u_{N_x-1}^n + 2\Delta x f_r(x, t^n), & x = 1. \end{aligned}$$

## 5 Implementation

For the implementation, we use the exact solution

$$u_e(x, t) = A \cos(\sqrt{\epsilon}x + a)e^{-t} + B \sin(\sqrt{\epsilon}x + a)e^{-t}, \quad x \in [0, 1], t \in [0, T], \quad (5.1)$$

for testing. We set  $A = 200$ ,  $B = 100$ ,  $a = -1.123$ , and  $T = 1$ . We use second-order centered finite-differences to solve the elliptic equations in (3.1), and perform a grid refinement study. We measure the error using the maximum norm

For  $\epsilon = 10^{-4}$ , we obtain the following results

|  |         |         |              |                 |                |  |  |  |  |
|--|---------|---------|--------------|-----------------|----------------|--|--|--|--|
| Using the Rothe method with Neumann BC and eps = 1.0e-04 |         |         |              |                 |                |  |  |  |  |
| t=1.0000e+00:  | Nx= 10  | Nt= 10  | dt=1.000e-01 | maxErr=2.19e-02 |                |  |  |  |  |
| t=1.0000e+00:  | Nx= 20  | Nt= 20  | dt=5.000e-02 | maxErr=5.65e-03 | order=1.95e+00 |  |  |  |  |
| t=1.0000e+00:  | Nx= 40  | Nt= 40  | dt=2.500e-02 | maxErr=1.43e-03 | order=1.98e+00 |  |  |  |  |
| t=1.0000e+00:  | Nx= 80  | Nt= 80  | dt=1.250e-02 | maxErr=3.61e-04 | order=1.99e+00 |  |  |  |  |
| t=1.0000e+00:  | Nx=160  | Nt= 160 | dt=6.250e-03 | maxErr=9.07e-05 | order=1.99e+00 |  |  |  |  |
| t=1.0000e+00:  | Nx=320  | Nt= 320 | dt=3.125e-03 | maxErr=2.30e-05 | order=1.98e+00 |  |  |  |  |
| t=1.0000e+00:  | Nx=640  | Nt= 640 | dt=1.563e-03 | maxErr=6.35e-06 | order=1.85e+00 |  |  |  |  |
| t=1.0000e+00:  | Nx=1280 | Nt=1280 | dt=7.813e-04 | maxErr=1.05e-07 | order=5.91e+00 |  |  |  |  |

In the output table above, **Nx** refers to the number of grid points, **Nt** denotes the number of time-steps, **dt** corresponds to the time step  $\Delta t$ , **maxErr** is the error in the maximum norm and **order** denotes the overall order of accuracy. The same follows for the other tables presented in this section.

The results confirm the expected order 2 accuracy of the scheme.

For  $\epsilon = 10^{-6}$ , we obtain the following results

|  |         |         |            |                  |                 |                |  |  |  |
|--|---------|---------|------------|------------------|-----------------|----------------|--|--|--|
| Using the Rothe method with Neumann BC and eps = 1.0e-06 |         |         |            |                  |                 |                |  |  |  |
| eps=1.0e-06, t=1.0e+00:                                  | Nx= 10  | Nt= 10  | dt=1.0e-01 | maxErr=3.10e-02, | condNum=3.5e+08 |                |  |  |  |
| eps=1.0e-06, t=1.0e+00:                                  | Nx= 20  | Nt= 20  | dt=5.0e-02 | maxErr=7.99e-03, | condNum=1.2e+09 | order=1.95e+00 |  |  |  |
| eps=1.0e-06, t=1.0e+00:                                  | Nx= 40  | Nt= 40  | dt=2.5e-02 | maxErr=2.03e-03, | condNum=4.6e+09 | order=1.98e+00 |  |  |  |
| eps=1.0e-06, t=1.0e+00:                                  | Nx= 80  | Nt= 80  | dt=1.3e-02 | maxErr=5.14e-04, | condNum=1.8e+10 | order=1.98e+00 |  |  |  |
| eps=1.0e-06, t=1.0e+00:                                  | Nx= 160 | Nt= 160 | dt=6.3e-03 | maxErr=1.35e-04, | condNum=7.0e+10 | order=1.93e+00 |  |  |  |
| eps=1.0e-06, t=1.0e+00:                                  | Nx= 320 | Nt= 320 | dt=3.1e-03 | maxErr=1.92e-05, | condNum=2.8e+11 | order=2.81e+00 |  |  |  |

|   |
|---|
| eps=1.0e-06, t=1.0e+00: Nx= 640 Nt= 640 dt=1.6e-03 maxErr=1.49e-05, condNum=1.1e+12 order=3.69e-01  |
| eps=1.0e-06, t=1.0e+00: Nx=1280 Nt=1280 dt=7.8e-04 maxErr=6.13e-04, condNum=4.4e+12 order=-5.37e+00 |
| eps=1.0e-06, t=1.0e+00: Nx=2560 Nt=2560 dt=3.9e-04 maxErr=3.24e-04, condNum=1.7e+13 order=9.22e-01  |

In the above results, `condNum` refers to the condition number of the implicit matrix used to solve the elliptic equations numerically.

We see order 2 accurate convergence at coarse resolutions. The condition number increases as we increase the resolution, and thus the error increases at the finer resolutions.

For  $\epsilon = 10^{-8}$ , we obtain the following results

|   |  |
|---|--|
| Using the Rothe method with Neumann BC and eps = 1.0e-08  |  |
| eps=1.0e-08, t=1.0e+00: Nx= 10 Nt= 10 dt=1.0e-01 maxErr=3.19e-02, condNum=3.5e+10                   |  |
| eps=1.0e-08, t=1.0e+00: Nx= 20 Nt= 20 dt=5.0e-02 maxErr=8.24e-03, condNum=1.2e+11 order=1.95e+00    |  |
| eps=1.0e-08, t=1.0e+00: Nx= 40 Nt= 40 dt=2.5e-02 maxErr=2.11e-03, condNum=4.6e+11 order=1.96e+00    |  |
| eps=1.0e-08, t=1.0e+00: Nx= 80 Nt= 80 dt=1.3e-02 maxErr=5.82e-04, condNum=1.8e+12 order=1.86e+00    |  |
| eps=1.0e-08, t=1.0e+00: Nx= 160 Nt= 160 dt=6.3e-03 maxErr=2.70e-04, condNum=7.0e+12 order=1.11e+00  |  |
| eps=1.0e-08, t=1.0e+00: Nx= 320 Nt= 320 dt=3.1e-03 maxErr=3.24e-03, condNum=2.8e+13 order=-3.58e+00 |  |
| eps=1.0e-08, t=1.0e+00: Nx= 640 Nt= 640 dt=1.6e-03 maxErr=3.89e-03, condNum=1.1e+14 order=-2.63e-01 |  |
| eps=1.0e-08, t=1.0e+00: Nx=1280 Nt=1280 dt=7.8e-04 maxErr=4.92e-02, condNum=4.4e+14 order=-3.66e+00 |  |
| eps=1.0e-08, t=1.0e+00: Nx=2560 Nt=2560 dt=3.9e-04 maxErr=1.66e-01, condNum=1.7e+15 order=-1.75e+00 |  |

Decreasing the value of  $\epsilon$  appears to cause the condition number of the matrix used in the solve to become worse at the finer resolutions.

We fix  $N_x = 100$ ,  $\Delta t = 0.1$ , vary  $\epsilon$  and measure the error

|   |  |
|---|--|
| Using the Rothe method with Neumann BC                                |  |
| eps=1.0e-02, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=6.89e-02 |  |
| eps=1.0e-03, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=8.08e-05 |  |
| eps=1.0e-04, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=2.19e-02 |  |
| eps=1.0e-05, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=2.88e-02 |  |
| eps=1.0e-06, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=3.10e-02 |  |
| eps=1.0e-07, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=3.17e-02 |  |
| eps=1.0e-08, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=3.21e-02 |  |
| eps=1.0e-09, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=3.19e-02 |  |
| eps=1.0e-10, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=1.61e-02 |  |
| eps=1.0e-11, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=4.73e-02 |  |
| eps=1.0e-12, t=1.0000e+00: Nx=100 Nt= 10 dt=1.000e-01 maxErr=6.26e-01 |  |

Unlike the case with Dirichlet boundary conditions where the error decreases as  $\epsilon$  decreases, the case with a Neumann condition appears to settle at an error of order  $10^{-2}$  as we decrease the value of  $\epsilon$ .

## 6 Conclusion and remarks

Using a simple 1D test case, we test the effectiveness of Rothe's method when the diffusion coefficient becomes very large, i.e.  $1/\epsilon$ ,  $\epsilon \ll 1$ . We find that the performance of the Rothe's method becomes worse as  $\epsilon$  decreases and this may be due to the worsening of the condition number of the implicit matrix used in the solve.

## 6.1 Next steps:

- Use boundary integral equations methods to solve the resulting equations after the time discretization in Rothe's method (3.1) instead of finite differences. Would that improve the convergence as  $\epsilon$  becomes small?
- Implement the Quasi-static asymptotic method with a Neumann boundary condition and see if there is an improvement in the error for small epsilon.

## References

- [1] Alex H. Barnett. Quasistatic correction in powers of reciprocal diffusivity for heat initial boundary value problems. unpublished, September 21 2023.