```
In [3]:
        import torch
        import torch.nn as nn # nn stuff and loss
        import torch.optim as optim # optimization
        import torch.nn.functional as F # relu, tanh, functions with no params (nn also ha
        from torch.utils.data import DataLoader # helps create mini-batches of data to tra
        import torchvision.transforms as transforms # helpful transforms
        from customImageSet import CustomImageDataset
        from load_dataset import CImgDataset
        class CNN(nn.Module):
            def init (
                self, input_size=1, num_classes=40
            ): # input size 784 since 28x28 images
                super(CNN, self).__init__()
                self.conv1 = nn.Conv2d(
                    in_channels=input_size,
                    out_channels=10,
                    kernel_size=(3, 3),
                    stride=(1, 1),
                    padding=(1, 1),
                ) # stride and padding are standard
                self.pool = nn.MaxPool2d(kernel_size=(2, 2), stride=(2, 2))
                self.conv2 = nn.Conv2d(
                    in channels=10,
                    out_channels=num_classes, # out_channels here controls col of mat1
                    kernel_size=(3, 3),
                    stride=(1, 1),
                    padding=(1, 1),
                self.fc1 = nn.Linear(18, num classes) # fully connected layer, row of mat2
            def forward(self, x):
                x = F.relu(self.conv1(x))
                x = self.pool(x)
                x = F.relu(self.conv2(x))
                x = self.pool(x)
                x = x.reshape(x.shape[0], -1) # number of examples sent in
                x = self.fc1(x)
                return x
        # Set device
        device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
        def train model():
            # Hyperparameters
            input_size = 1 # row of mat2
            num classes = 2
            learning rate = 0.001
            batch_size = 25 # controls row of map1 if correct size or less, controls how m
            # so lower is more accurate but slower
            num_epochs = 50
```

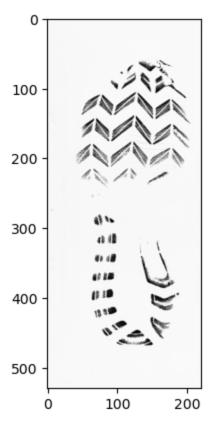
```
# Load data
   # Since going to load as image, convert to tensor
    # dataset = CustomImageDataset(root_dir="D:/test/data", transform=transforms.To
    dataset = CImgDataset("../test.zip")
    train_set, test_set = torch.utils.data.random_split(
        dataset, [0.8, 0.2]
    ) # first is row of map1
   train_loader = DataLoader(dataset=train_set, batch_size=batch_size, shuffle=Tru
   test_loader = DataLoader(dataset=test_set, batch_size=batch_size, shuffle=True)
    # Initialize network
   model = CNN(input_size=input_size, num_classes=num_classes).to(device)
    # model = CNN()
   x = torch.randn(100, 1, 25, 25)
   # Loss and optimizer
   criterion = nn.CrossEntropyLoss() # could try MSELoss
   optimizer = optim.Adam(model.parameters(), lr=learning_rate)
    # Train network
    for epoch in range(
        num_epochs
    ): # one epoch = network has seen all images in dataset
        for batch_idx, (data, targets) in enumerate(train_loader):
            # get data to cuda if possible
            data = data.to(device=device)
            targets = targets.to(device=device)
            # forward
            scores = model(data)
            loss = criterion(scores, targets)
            # backward
            optimizer.zero_grad() # set gradients to 0 for each batch to not store
            loss.backward()
            # gradient descent or adam step
            optimizer.step()
    return model, train_loader, test_loader
# Check training accuracy
def check_accuracy(loader, model, is_training):
    if is_training:
        print("Checking accuracy on training data")
        print("Checking accuracy on test data")
    num_correct = 0
   num_samples = 0
   model.eval()
    with torch.no_grad():
```

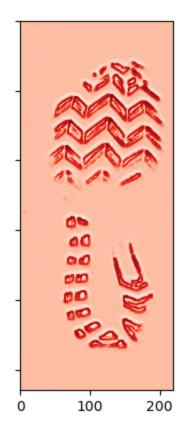
```
for x, y in loader:
                     x = x.to(device=device)
                     y = y.to(device=device)
                     scores = model(x)
                     # Shape of scores is 64 (originally) images * 10
                     # Want to know which one is the maximum of those 10 digits.
                     # I.e. if max value is first one, digit 0.
                     _, predictions = scores.max(1) # max of second dimension
                     num_correct += (predictions == y).sum()
                     num_samples += predictions.size(0) # size of first dimension
                     f"Got {num_correct} / {num_samples} with accuracy {float(num_correct)/f
             model.train()
             # return float(num_correct)/float(num_samples)*100
         def main():
             model, train_loader, test_loader = train_model()
             check_accuracy(train_loader, model, True)
             check_accuracy(test_loader, model, False)
             torch.save(model.state_dict(), "../model_weights_convolutional_example")
             model = CNN(input_size=1, num_classes=2).to(device)
             model.load_state_dict(torch.load("../model_weights_convolutional_example"))
             model.eval()
             check_accuracy(test_loader, model, False)
         if __name__ == '__main__':
             main()
        CUDA is available? True
        16567 images in dataset
        Checking accuracy on training data
        Got 10949 / 13254 with accuracy 82.61
        Checking accuracy on test data
        Got 2748 / 3313 with accuracy 82.95
        Checking accuracy on test data
        Got 2739 / 3313 with accuracy 82.67
In [25]: import numpy as np
         import skimage.io as skio
         import skimage.color as skcolor
         import skimage.transform as sktrans
         import matplotlib.pyplot as plt
         import torch
         from pathlib import Path
         import imageio
         from linear_NN import NN as MOD1
         from convolutional_NN import CNN as MOD2
```

```
from recurrent_NN import RNN as MOD3
from recurrent_GRU_NN import RNN as MOD4
from recurrent LSTM NN import RNN as MOD5
from bidirectional_LSTM_NN import BidirectionalRNN as MOD6
class ModelMaker:
    def __init__(self, initfunc, wts_file, reshape=False):
        self.starter = initfunc
        self.net = initfunc()
        self.net.load_state_dict(torch.load(wts_file, map_location=torch.device("cp
        self.net.eval()
        self.reshape = reshape
        #print(self.net)
    def __call__(self, image):
        x = torch.from_numpy(image)
        # print(x.shape)
        # if there is an error it's likely due to shaping issues
        # add an unsqueeze(0) above if convolutional
        # don't if bidirectional
        if self.reshape:
            x = x.reshape(1, -1)
        else:
            x = x.unsqueeze(0).unsqueeze(0)
        res = self.net(x)
        res_max = torch.max(res)
        res_arg = torch.argmax(res)
        if res_arg == 0:
            res_max *= -1
        return res_max.detach().numpy()
MOD1.make = lambda: MOD1(input_size=225, num_classes=2)
MOD2.make = lambda: MOD2(input_size=1, num_classes=2)
MOD3.make = lambda: MOD3(15, 256, 3, 2, 15)
MOD4.make = lambda: MOD4(15, 256, 3, 2, 15)
MOD5.make = lambda: MOD5(15, 256, 3, 2, 15)
MOD6.make = lambda: MOD6(15, 256, 3, 2)
def run_on_image(maker, img_name, nn_type, num_epochs=None):
    #img = skcolor.rgb2gray(skio.imread(img_name)[:, :, :3])
    img = skio.imread(img_name)
    if len(img.shape) == 3 and img.shape[2] >= 3:
        img = skcolor.rgb2gray(img[:, :, :3])
    tform = sktrans.EuclideanTransform(rotation=0, translation=(7, 7))
    padded_image = np.float32(
        sktrans.warp(
            img,
            tform.inverse,
            output_shape=(img.shape[0] + 14, img.shape[1] + 14),
            mode="reflect",
        )
    )
    fig, axs = plt.subplots(1, 2, sharex=True, sharey=True)
```

```
#plt.rcParams['figure.figsize'] = 220, 530
    axs[0].imshow(img, "Greys_r")
    res = np.zeros(img.shape, dtype=np.float32)
   for i in range(img.shape[0]):
        for j in range(img.shape[1]):
            # print(i,j)
            i2 = i + 7
            j2 = j + 7
            sub_image = padded_image[i2 - 7 : i2 + 8, j2 - 7 : j2 + 8]
            res[i, j] = maker(sub_image)
    axs[1].imshow(res, "Reds")
    plt.show()
    plt.imshow(res, "Reds", aspect='equal')
   name = Path(img_name).stem
    plt.axis("off")
    if (num_epochs):
        plt.imsave("../heatmaps/" + name + "_" + nn_type + "_epochs_" + str(num_epo
    else:
        plt.imsave("../heatmaps/" + name + "_" + nn_type + ".png", res, cmap="Reds"
    \#res = np.maximum(res, 0.95*np.max(res))
    res = res * 1.0 * (res > 0.85 * np.max((res)))
   plt.imshow(res, "Reds")
    plt.show()
    plt.imshow(img, "Greys")
    plt.imshow(res, "Reds", alpha=0.6)
   plt.gcf().set_size_inches(220 / 77, 530 / 77) # 77 is the golden number takes
   plt.axis("off")
    if (num_epochs):
        plt.savefig("../heatmaps/" + name + "_" + nn_type + "_epochs_"
                    + str(num_epochs) + "_compare.png", bbox_inches='tight', pad_in
    else:
        plt.savefig("../heatmaps/" + name + "_" + nn_type + "_compare.png", bbox_in
    plt.show()
def main():
   wts_file = "../model_weights_convolutional"
   make = ModelMaker(MOD2.make, wts_file, False)
   f = "../002_07_L_01.png"
    print("Creating heatmap...")
    run_on_image(make, f, wts_file[17:])
if __name__ == "__main__":
   main()
```

Creating heatmap...







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In [ ]:

7/17/2024, 1:46 PM