



AUBURN UNIVERSITY

SAMUEL GINN
COLLEGE OF ENGINEERING

3D Modeling of Detached Metal Whiskers

Group # 8

ORR

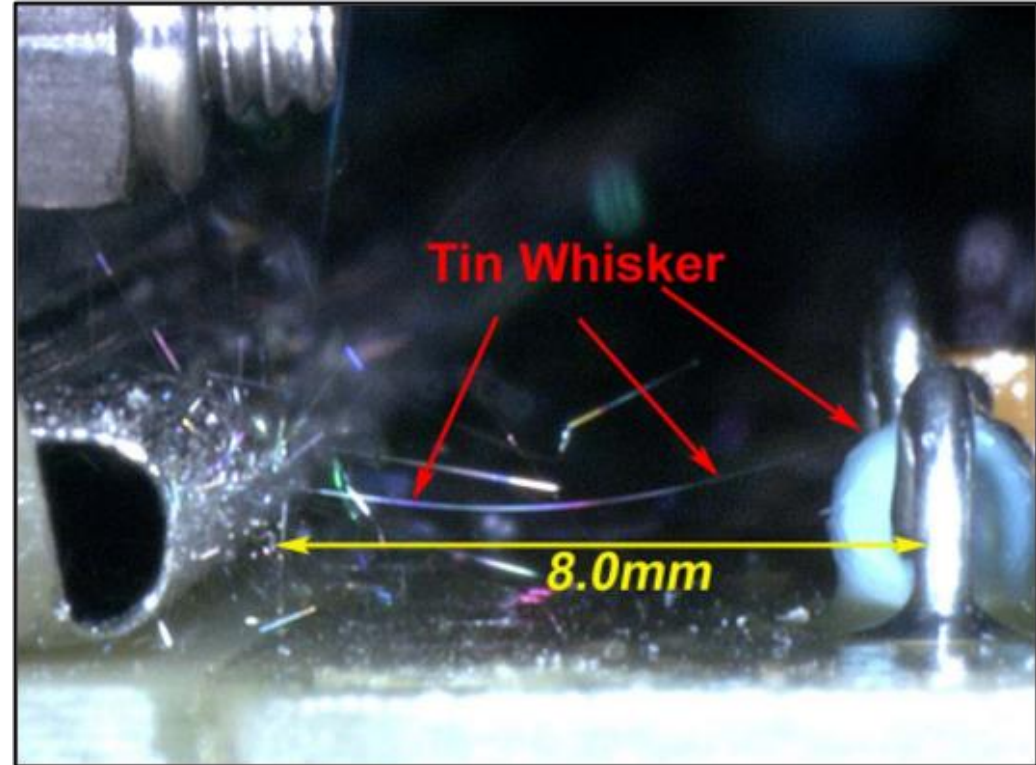
MANAGER: Graham Duke
SCRIBE: Connor Massey
Meredith Osborne, Andrew Smith

List of Abbreviations

NASA	National Aeronautics and Space Administration
MDA	Missile Defense Agency
CCA	Circuit Card Assembly
CAD	Computer Aided Design
MCS	Monte Carlo Simulation
WP	Working Principle
PCB	Printed Circuit Board
UI	User Interface

Introduction / Problem Statement

- What are metal whiskers?
 - Microscopic, metal filaments (tin, zinc, cadmium)
 - Length: few microns to >10 mm
 - Thickness: submicron to tens of microns
 - Create bridges between exposed conductors
- Objective:
 - Risk-identifying simulation of detached whiskers bridging conductors
 - Visual identification
 - Statistical identification



Whisker Bridging

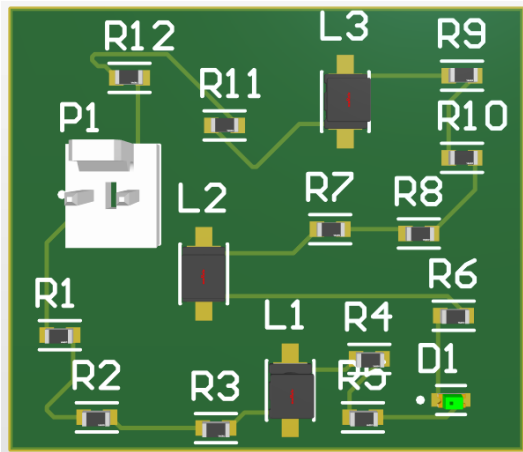
Design Specifications

- Rigid Cylindrical Model of Whisker
- Detached and Airborne Whiskers
- Physical and Statistical Simulation
 - Unity
 - MCS
- Simulate Environmental Effects on Detached Whiskers
 - Variety of forces
 - Gravitational acceleration
- Import User CCA Models
- Range of User Inputs
- Single Script

Design Implementations

CCA Processing

- Overall plan for importing CCAs remained constant
- Altium used for test CCAs
- .mtl and .obj files created from Altium, inserted into Unity



CCA Designed in Altium

Material Identification

- Automated process (CDR – manual)
- Code scans for input material
- Trigger tag applied to all surfaces with material name
 - If whisker contacts ≥ 2 triggers, bridge

Whisker Properties Conductive Materials		
Length Mu [um]	Length Sigma [um]	# Of Whiskers
5	1.15	Enter value...
Width Mu [um]	Width Sigma [um]	Conductive Material Selection
1.17	0.67	copper
Whisker Material		
Tin		
Distribution Select		
LogNormal		

Conductive Material Input Box

Design Implementations

Distribution Selection

- Applied principals from CDR
- User selects desired distribution from dropdown menu
- Coded switch statement to change distribution function
 - Mu and sigma processed accordingly

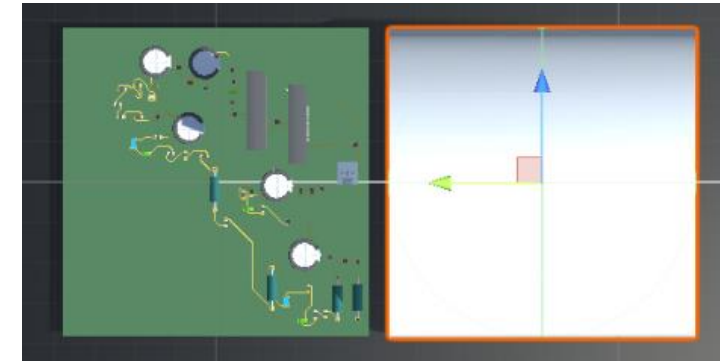
```
private float GenerateLogNormalValue(float mu_log, float sigma_log)
{
    float normalVal = RandomFromDistribution.RandomNormalDistribution(mu_log, sigma_log);
    float logNormalVal = Mathf.Exp(normalVal);
    return logNormalVal;
}

private float GenerateNormalValue(float mu_norm, float sigma_norm)
{
    return RandomFromDistribution.RandomNormalDistribution(mu_norm, sigma_norm);
}
```

Distribution Functions

Whisker Scaling

- Arbitrary unit system in Unity
- Whiskers must be in micrometers (μm)
- Internal code configures inputs to μm
- Proof:
 - Used Altium boards as reference
 - Test inputs to match board dimensions



3" x 3" Board for Whisker Comparison

Design Implementations

Material Selection

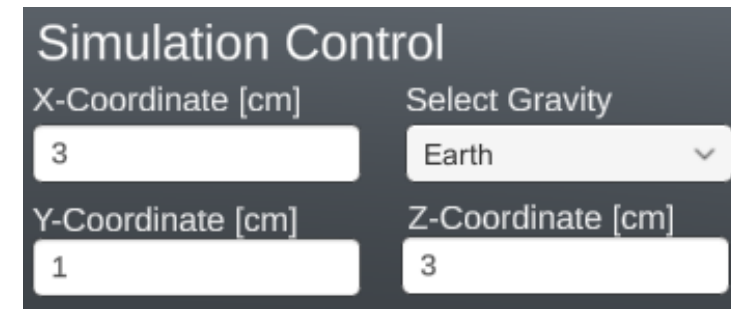
- Applied principals from CDR
- User selects one of three preset materials from dropdown menu
- Code applies corresponding material properties to calculate whisker physics
- Calculate the following (per whisker)
 - Mass
 - Resistance
 - Friction Force

```
public Dictionary<MaterialType, MaterialProperties> materialProperties = new Di
{ //density (kg/um^3), resistivity (ohm*um), coefficient of friction (unitless)
  { MaterialType.Tin, new MaterialProperties(7.3e-15f, 1.09e-1f, 0.32f) },
  { MaterialType.Zinc, new MaterialProperties(7.14e-15f, 5.9e-2f, 0.6f) },
  { MaterialType.Cadmium, new MaterialProperties(8.65e-15f, 7.0e-2f, 0.5f) }
};
```

Material Properties Dictionary

Drop Location

- User inputs X, Y, and Z coordinates to specify a drop location for whiskers
- Spawn area deviates from origin (0,0,0) in positive and negative direction



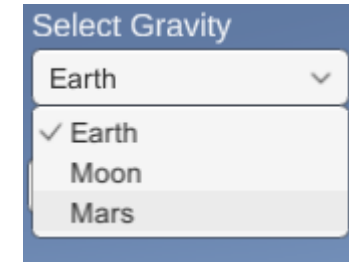
The image shows a 'Simulation Control' panel with four input fields. The 'X-Coordinate [cm]' field contains the value '3'. The 'Y-Coordinate [cm]' field contains the value '1'. The 'Z-Coordinate [cm]' field contains the value '3'. The 'Select Gravity' dropdown menu is set to 'Earth'.

Drop-Location Coordinate Inputs

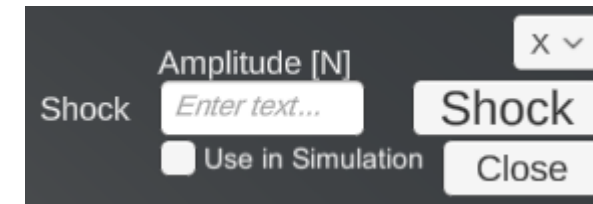
Design Implementations

External Forces

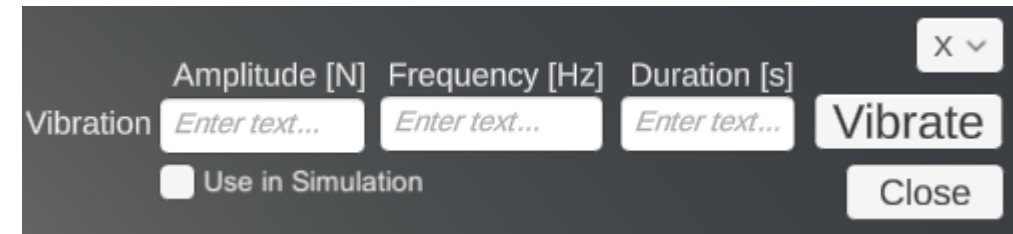
- Three external forces implemented
 - Gravitational acceleration
 - Select between Earth, Moon, or Mars
 - Mechanical shock
 - Half-sine pulse
 - Apply uniaxially (X, Y, Z)
 - Constant vibration
 - Full-sine pulse
 - Apply uniaxially (X, Y, Z)
- Shock and vibration repeated in each iteration



Gravity User Interface



Shock User Interface



Vibration User Interface

Design Implementations

Simulation Results

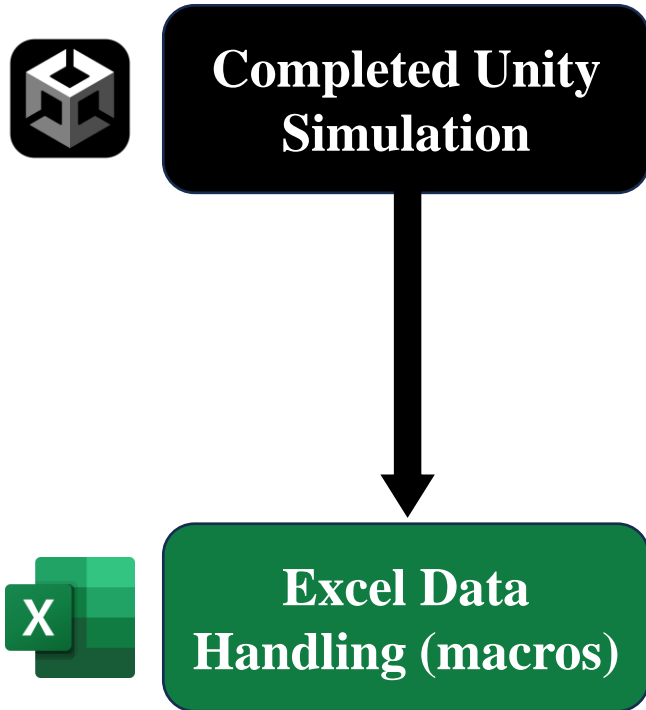
- Heat map of conductor bridging frequency
- Save simulation results to store length, diameter, resistance of:
 - All generated whiskers per iteration
 - All bridged whiskers per iteration

- Probability calculations (risk assessment)

$$\text{Individual Probability} = \frac{\# \text{ of bridged whiskers}}{\# \text{ of whiskers generated}} \cdot 100 \quad (1)$$

$$\text{Overall Probability} = \frac{\# \text{ of bridged iterations}}{\# \text{ of iterations ran}} \cdot 100 \quad (2)$$

- Four histograms generated
 - Bridging frequency for length, diameter, length:diameter ratio, and resistance



Method of Operation

Simulation Accessibility

GitHub

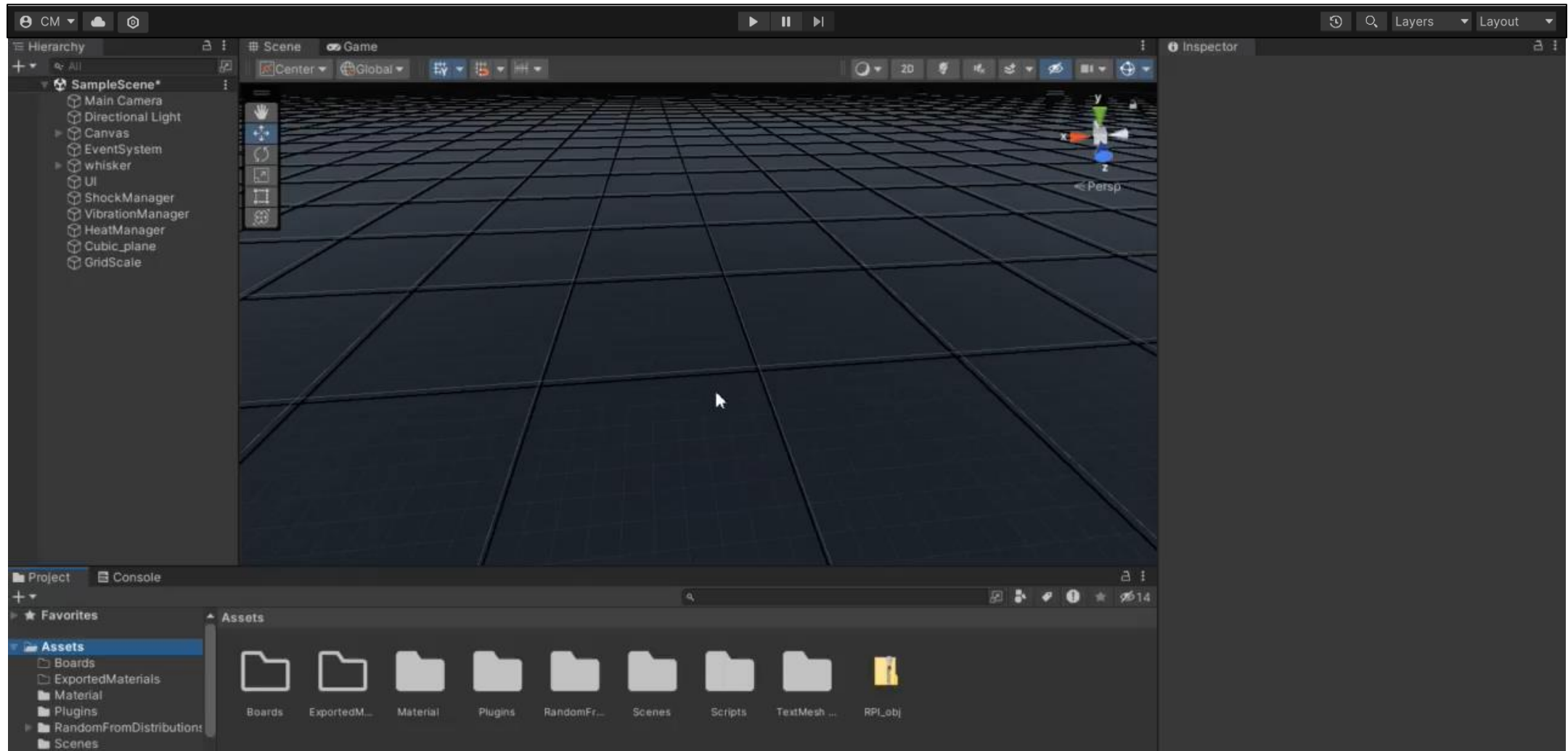
- Version control and software management
- Ease of access to repositories of any size
- Repositories can be cloned to any device through the GitHub Desktop app or downloaded through the website
- Instructions are given in the User Manual

Unity

- Simulation runs entirely off the Unity Game Engine
 - Users must download the Unity Hub and the Unity Editor to begin
- Repositories cloned from GitHub can be added to the Unity Hub, allowing easy access to the simulation
- Unity Editor used to develop and host the simulation

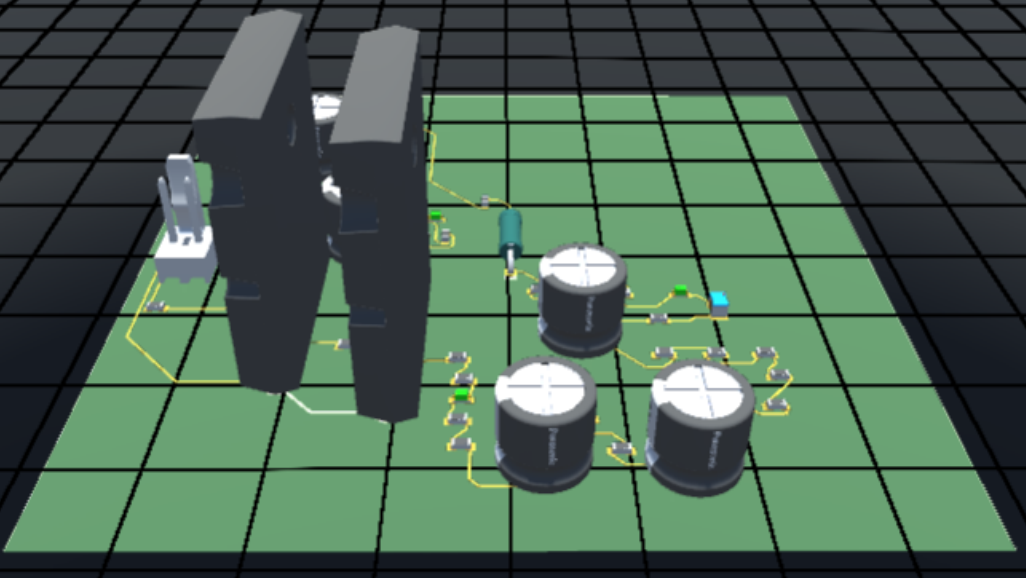
Method of Operation

Importing Board Models



Method of Operation

User Interface



Whisker Properties | Conductive Materials

Length Mu [μm]	Length Sigma [μm]	# Of Whiskers
<input type="text" value="5"/>	<input type="text" value="1.15"/>	<input type="text" value="50"/>
Width Mu [μm]	Width Sigma [μm]	Conductive Material Selection
<input type="text" value="1.17"/>	<input type="text" value="0.67"/>	<input type="text" value="Enter text..."/>
Whisker Material		
<input type="text" value="Tin"/>		
Distribution Select		
<input type="text" value="LogNormal"/>		

Simulation Control

X-Coordinate [cm]	Select Gravity
<input type="text" value="3"/>	<input type="text" value="Earth"/>
Y-Coordinate [cm]	Z-Coordinate [cm]
<input type="text" value="1"/>	<input type="text" value="3"/>

Monte Carlo | Data

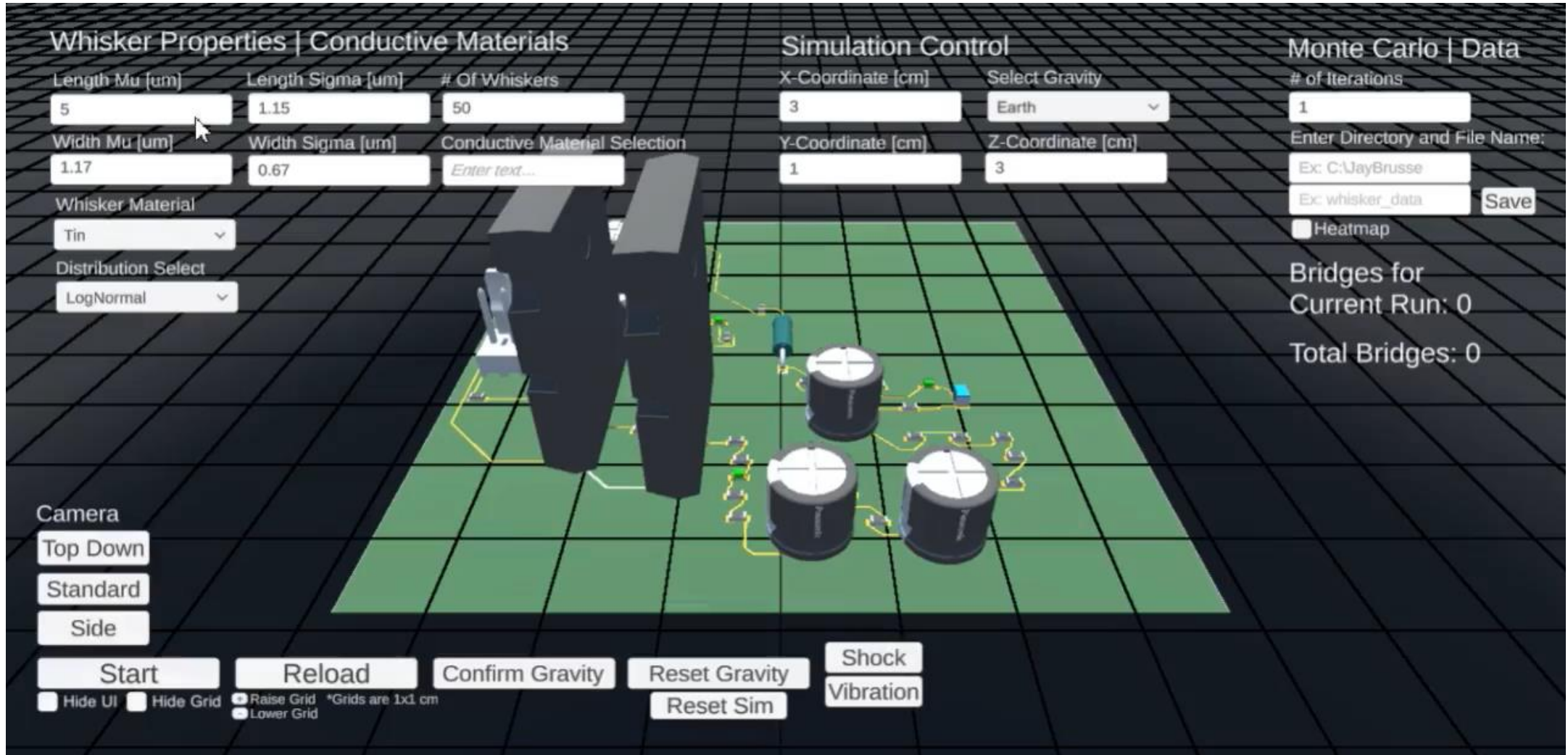
of Iterations
<input type="text" value="1"/>
Enter Directory and File Name:
<input type="text" value="Ex: C:\JayBrusse"/>
<input type="text" value="Ex: whisker_data"/>
<input type="button" value="Save"/>
<input type="checkbox"/> Heatmap
Bridges for Current Run: 0
Total Bridges: 0

Camera

☐ Hide UI ☐ Hide Grid ☐ Raise Grid ☐ Lower Grid *Grids are 1x1 cm

Method of Operation

Running the Simulation



The screenshot shows a simulation interface for whisker properties and control. The central area displays a 3D model of a whisker assembly on a green grid. The interface is divided into several panels:

- Whisker Properties | Conductive Materials**
 - Length Mu [um]: 5
 - Length Sigma [um]: 1.15
 - # Of Whiskers: 50
 - Width Mu [um]: 1.17
 - Width Sigma [um]: 0.67
 - Conductive Material Selection: Enter text...
 - Whisker Material: Tin
 - Distribution Select: LogNormal
- Simulation Control**
 - X-Coordinate [cm]: 3
 - Y-Coordinate [cm]: 1
 - Select Gravity: Earth
 - Z-Coordinate [cm]: 3
- Monte Carlo | Data**
 - # of Iterations: 1
 - Enter Directory and File Name:
 - Ex: C:\JayBrusse
 - Ex: whisker_data
 - Save
 - Heatmap
 - Bridges for Current Run: 0
 - Total Bridges: 0
- Camera**
 - Top Down
 - Standard
 - Side
- Buttons**
 - Start
 - Reload
 - Confirm Gravity
 - Reset Gravity
 - Reset Sim
 - Shock
 - Vibration
- Grid Controls**
 - Hide UI
 - Hide Grid
 - Raise Grid
 - Lower Grid
 - *Grids are 1x1 cm

Method of Operation

External Force Application & Heat Map

The interface is divided into several sections for configuring a simulation. The central area shows a 3D visualization of two vertical whiskers on a green grid, with electrical components like capacitors and resistors connected to them.

Whisker Properties | Conductive Materials

Length Mu [um]	Length Sigma [um]	# Of Whiskers
4500	500	75
Width Mu [um]	Width Sigma [um]	Conductive Material Selection
150	50	copper

Whisker Material:

Distribution Select:

Simulation Control

X-Coordinate [cm]	Select Gravity
3.5	Earth
Y-Coordinate [cm]	Z-Coordinate [cm]
1	3.5

Monte Carlo | Data

of Iterations:

Enter Directory and File Name:

D:\Data

whisker_shock

☐ Heatmap

Bridges for Current Run: 0

Total Bridges: 0

Camera

Simulation Controls

☐ Hide UI ☐ Hide Grid ☐ Raise Grid ☐ Lower Grid *Grids are 1x1 cm

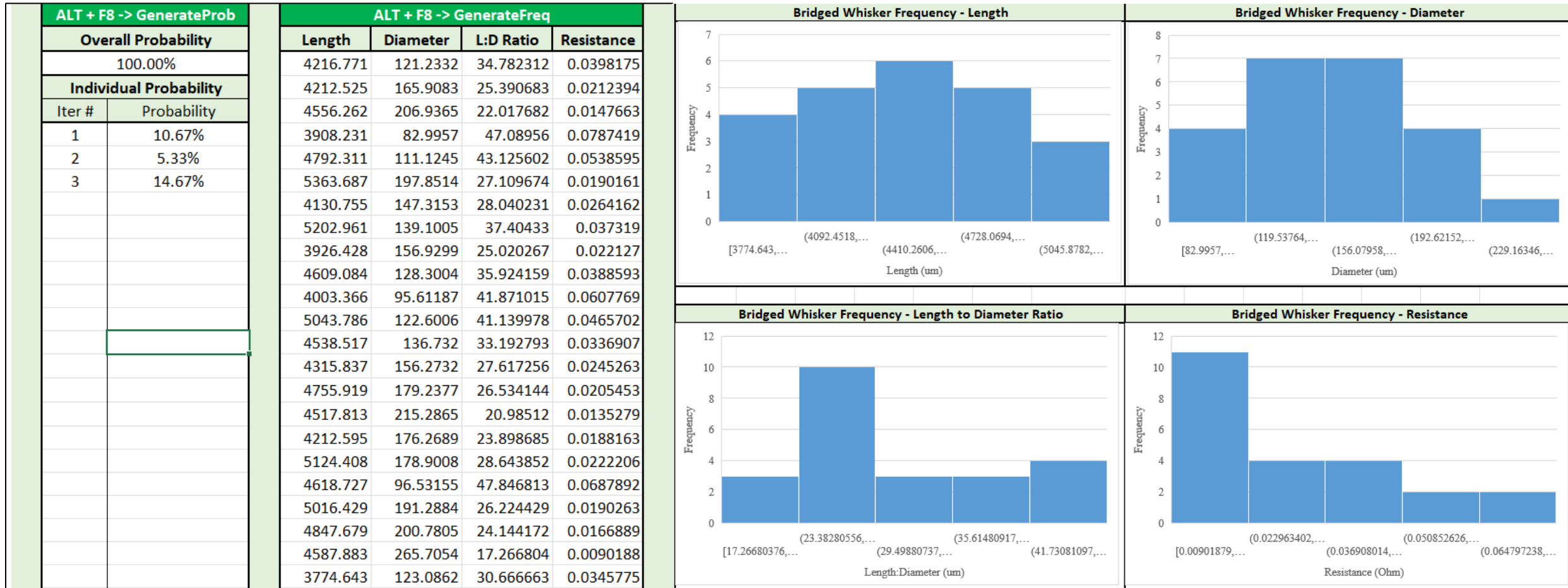
Shock Settings

Shock ☐ Amplitude [N]

☐ Use in Simulation

Method of Operation

Results Analysis

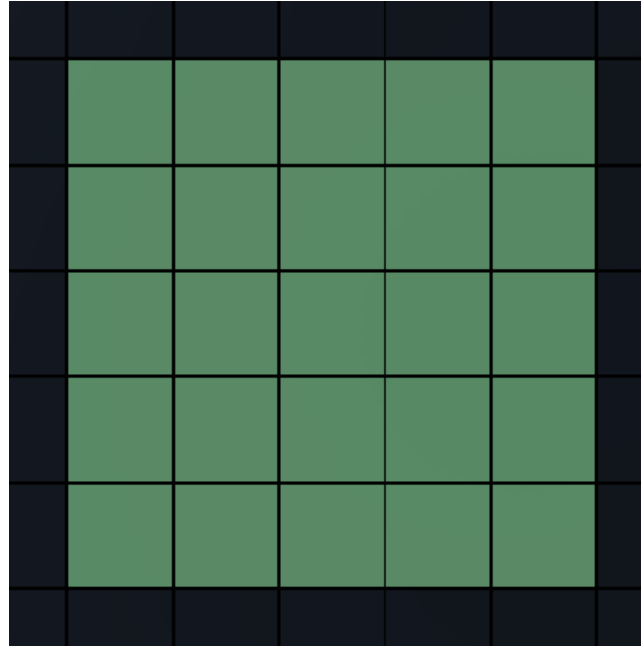


Macro Generated Tables and Histograms

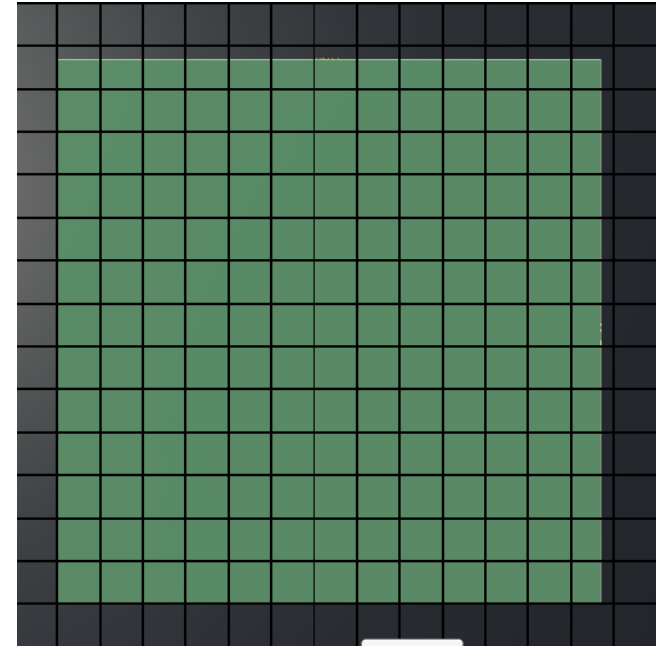
Testing and Analysis

Varied CCA Designs – Board Scaling

- Boards must be scaled to match whisker scale
- Unity uses arbitrary dimensions
- Grid tool implemented
 - 1 cm x 1 cm units
 - Visual reference for whiskers size comparison
 - Toggle on/off
- Unit system independent



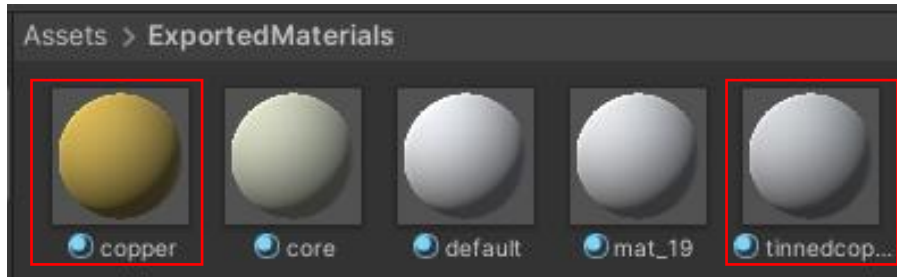
Blank 5 cm x 5 cm Board



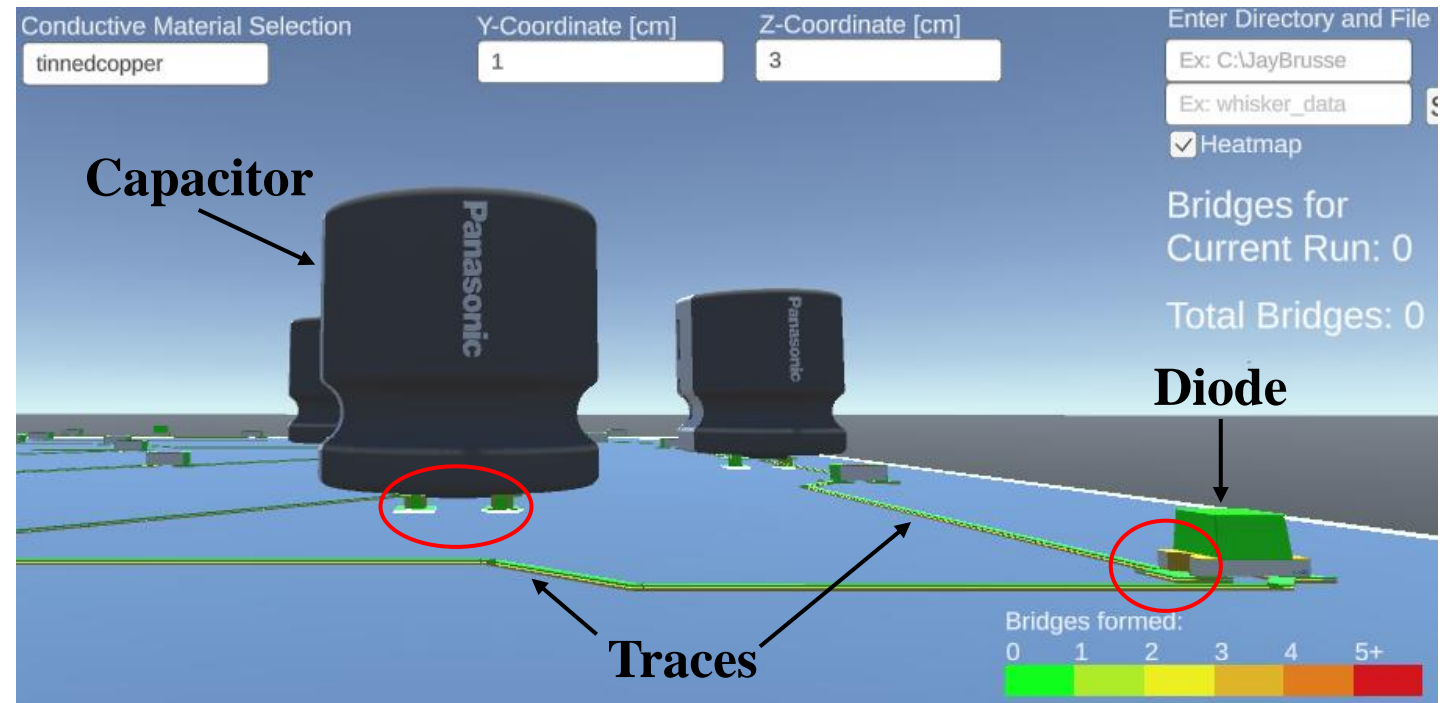
Blank 5 in x 5 in Board

Testing and Analysis

Varied CCA Designs – Conductive Material Input



Exposed Conductive Materials



Simulation Material Identification

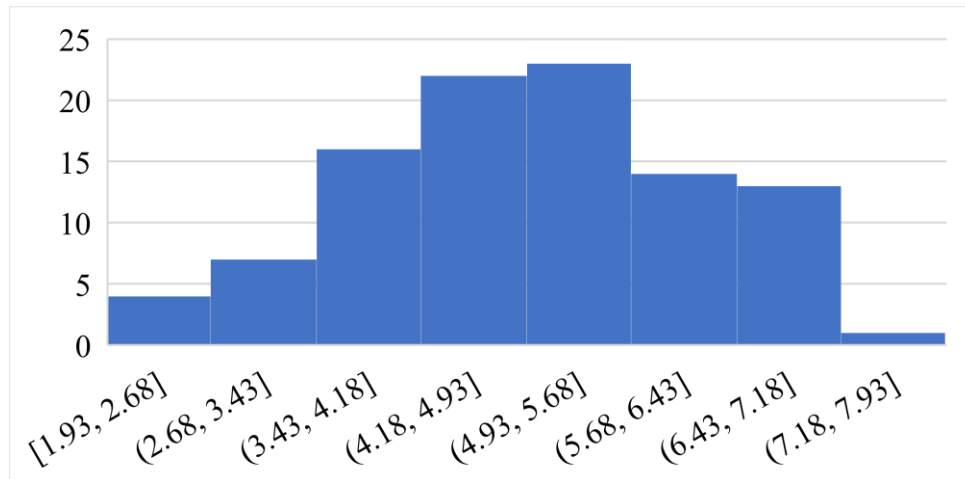
Testing and Analysis

Distribution Validation

Whisker Properties | Conductive Materials

Length Mu [um]	Length Sigma [um]	# Of Whiskers
5	1.15	100
Width Mu [um]	Width Sigma [um]	Conductive Material Selection
1.17	0.67	copper
Whisker Material		
Tin		
Distribution Select		
Normal		

Normal Distribution Inputs

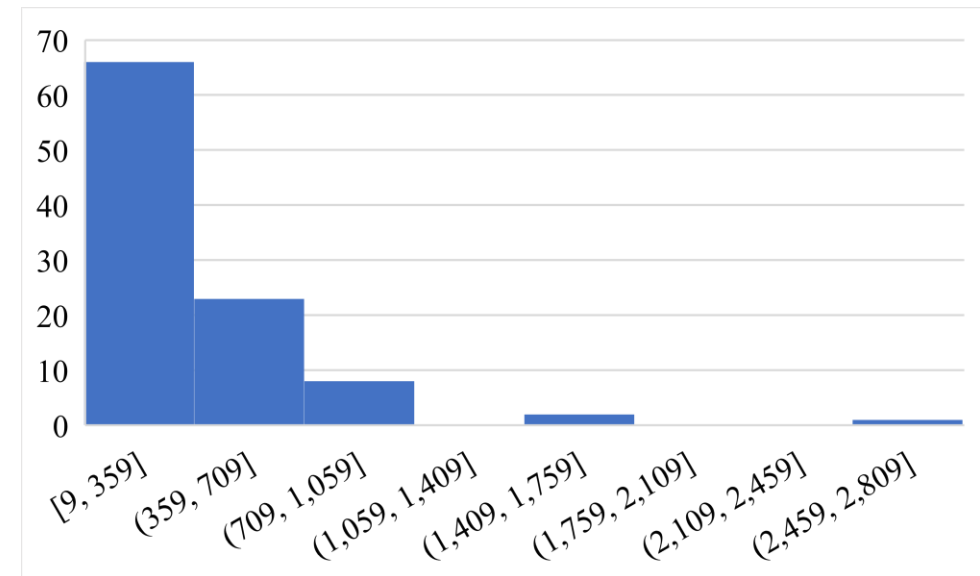


Length Normal Distribution

Whisker Properties | Conductive Materials

Length Mu [um]	Length Sigma [um]	# Of Whiskers
5	1.15	100
Width Mu [um]	Width Sigma [um]	Conductive Material Selection
1.17	0.67	copper
Whisker Material		
Tin		
Distribution Select		
LogNormal		

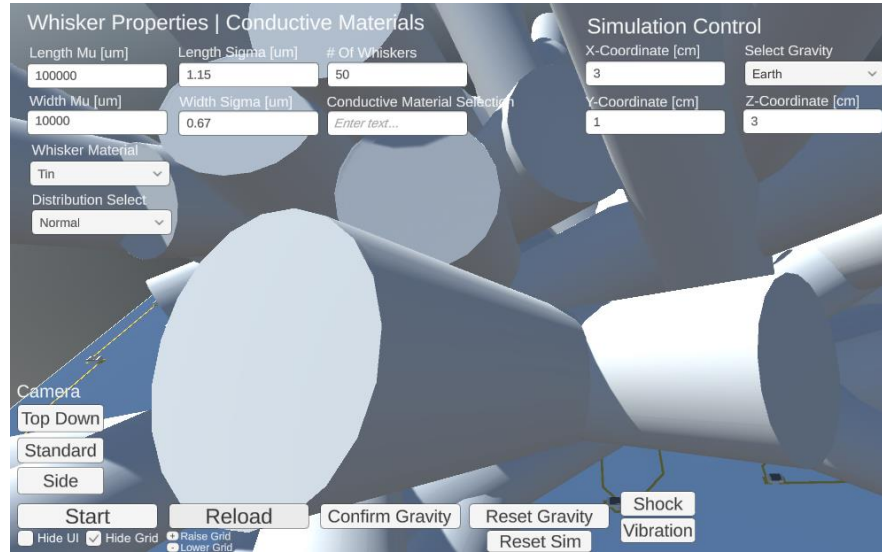
Lognormal Distribution Inputs



Length Lognormal Distribution

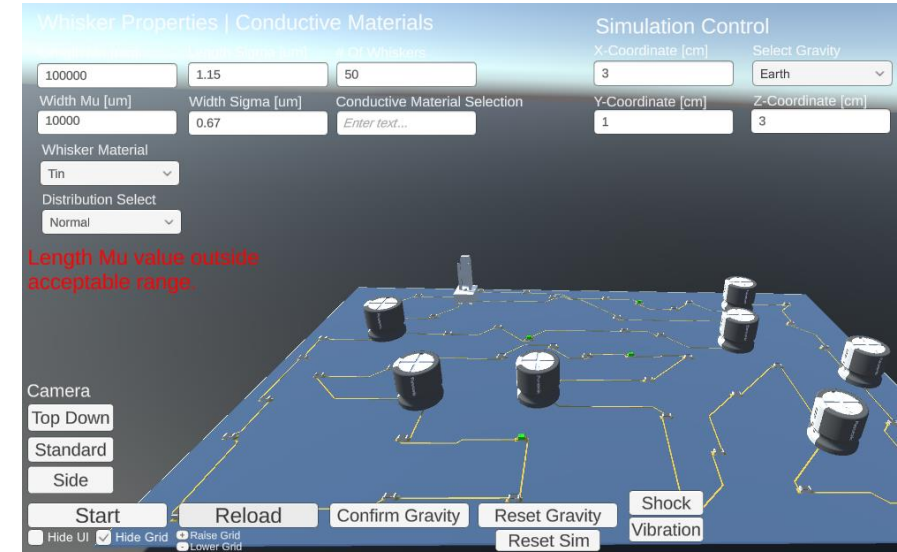
Testing and Analysis

Numerical Input Handling



Improper Whisker Input Results

- Performance issues
 - Close spawning
 - Rapid collisions
 - Slowed response
- Requires force shutdown

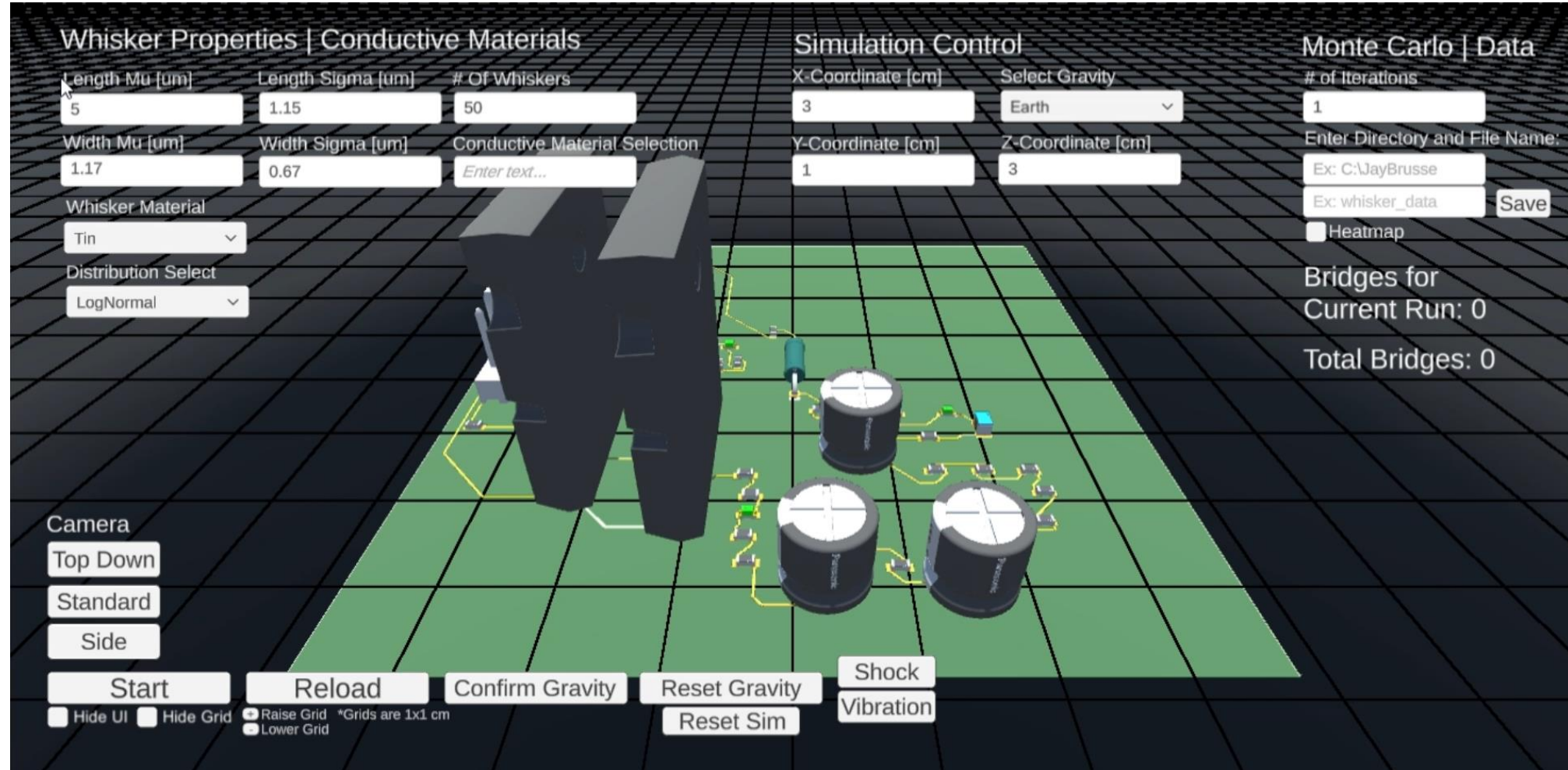


Error Handling for Improper Inputs

- If-else Statements
 - Prevent actions
 - Error message
- Ensures user does not have to exit scene

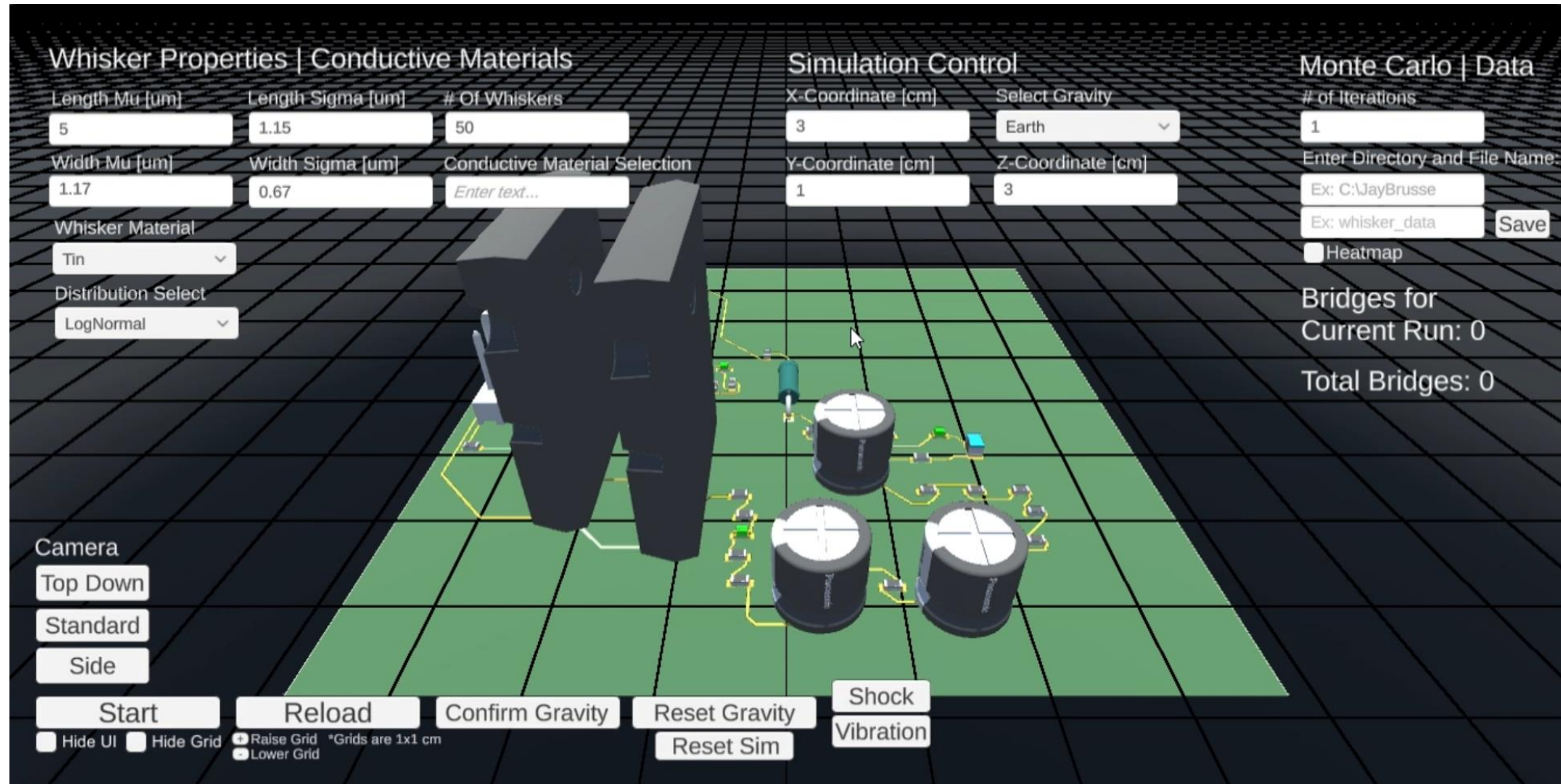
Testing and Analysis

External Force Effects – Perpendicular Force



Testing and Analysis

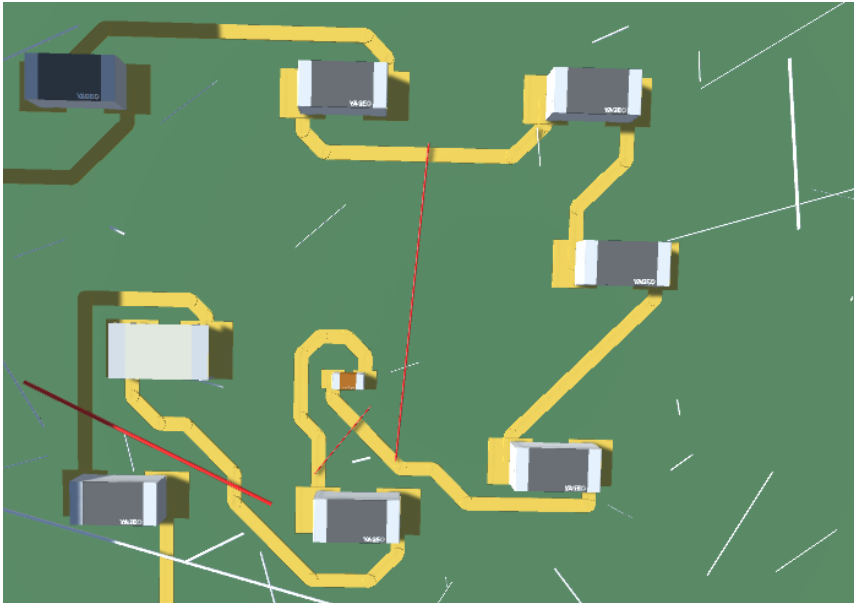
External Force Effects – Parallel Force



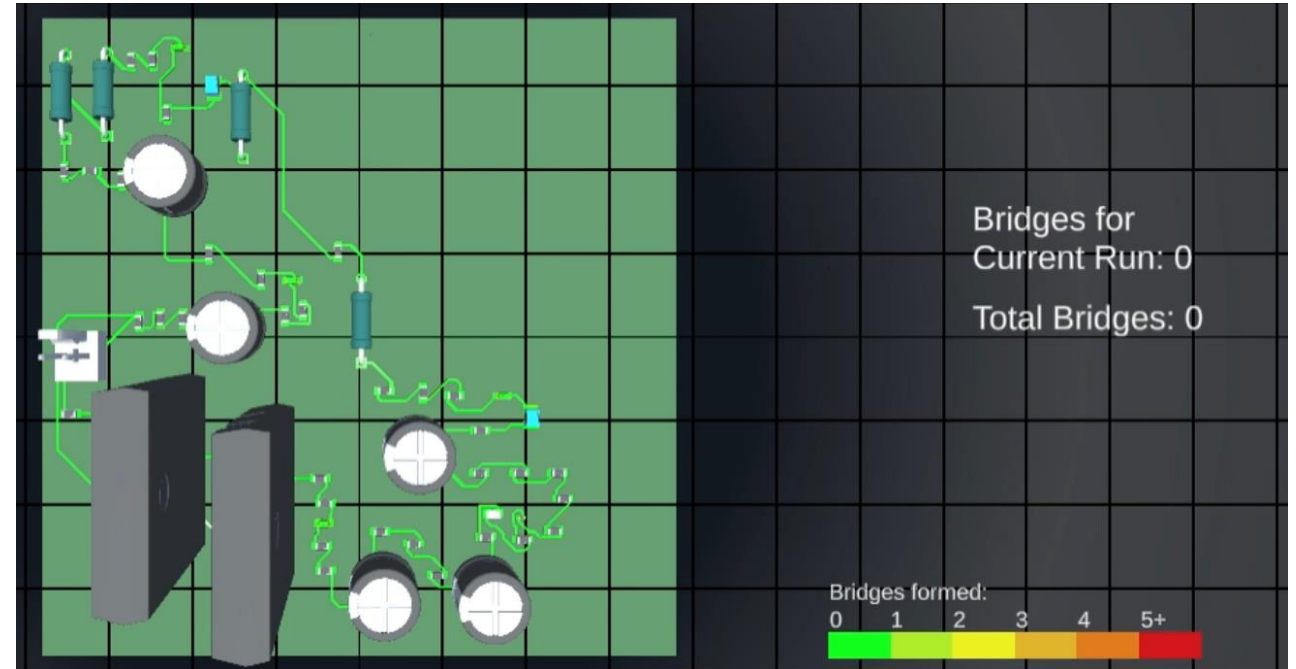
[2]

Testing and Analysis

Bridging Registration



Bridging Contact



Heat Map Test (10 Iterations, 2x Speed)

Testing and Analysis

Results Assessment

Whisker Properties | Conductive Materials

Length Mu [um]	Length Sigma [um]	# Of Whiskers
<input type="text" value="5"/>	<input type="text" value="1.15"/>	<input type="text" value="Enter value..."/>
Width Mu [um]	Width Sigma [um]	Conductive Material Selection
<input type="text" value="1.17"/>	<input type="text" value="0.67"/>	<input type="text" value="copper"/>
Whisker Material		
<input type="text" value="Tin"/>		
Distribution Select		
<input type="text" value="LogNormal"/>		

Simulation Control

X-Coordinate [cm]	Select Gravity
<input type="text" value="3"/>	<input type="text" value="Earth"/>
Y-Coordinate [cm]	Z-Coordinate [cm]
<input type="text" value="1"/>	<input type="text" value="3"/>

Monte Carlo | Data

of Iterations
<input type="text" value="3"/>
Enter Directory and File Name:
<input type="text" value="Senior Design 2\3D Sim"/>
<input type="text" value="qty_test1"/>
<input checked="" type="checkbox"/> Heatmap
Save
Bridges for Current Run: 0
Total Bridges: 0

Camera

☐ Hide UI

☒ Hide Grid

Bridges formed:

0

1

2

3

4

5+

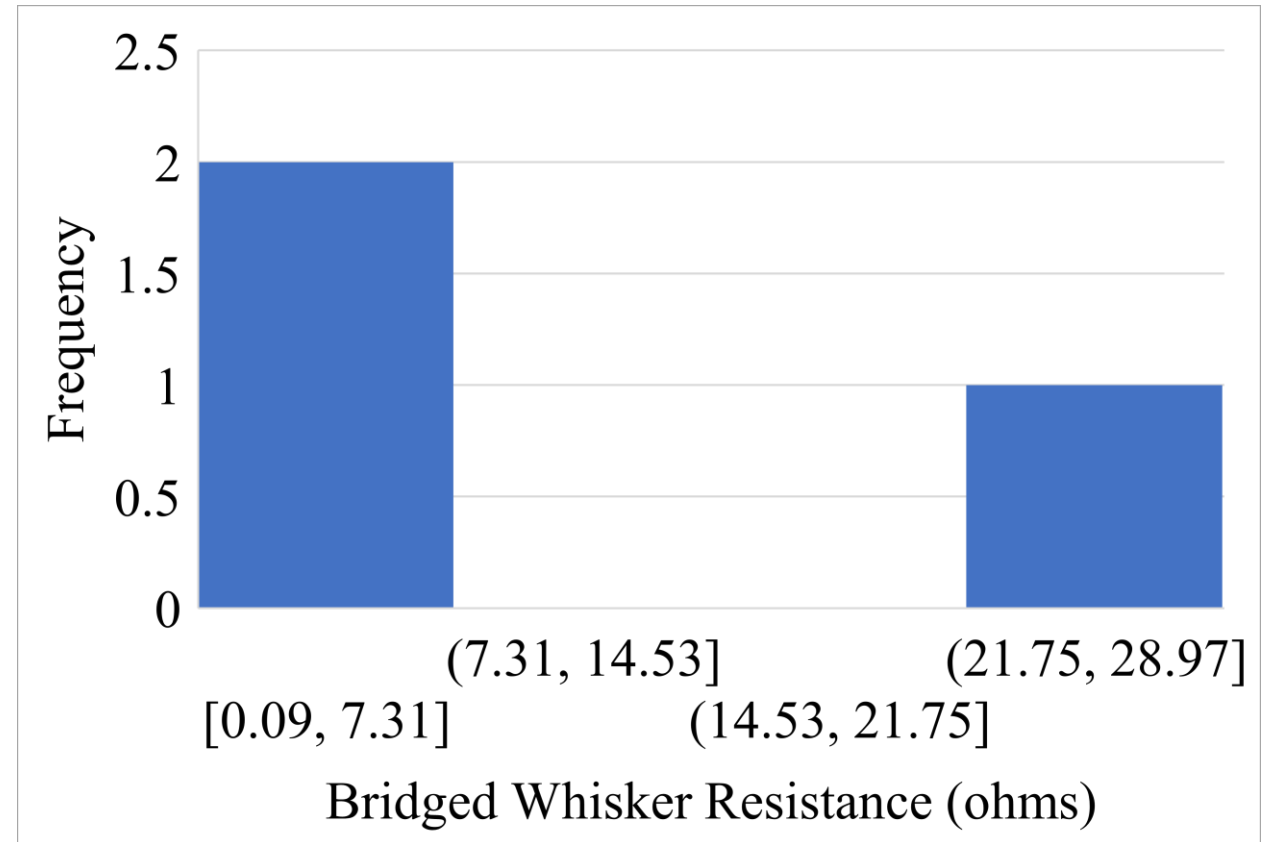
Test Initial Inputs

Testing and Analysis

Results Assessment – Small Whisker Storm (Qty: 50)

ALT + F8 -> GenerateProb	
Overall Probability	
66.67%	
Individual Probability	
Iter #	Probability
1	2.00%
2	4.00%
3	0.00%

Small Quantity Bridging Probability



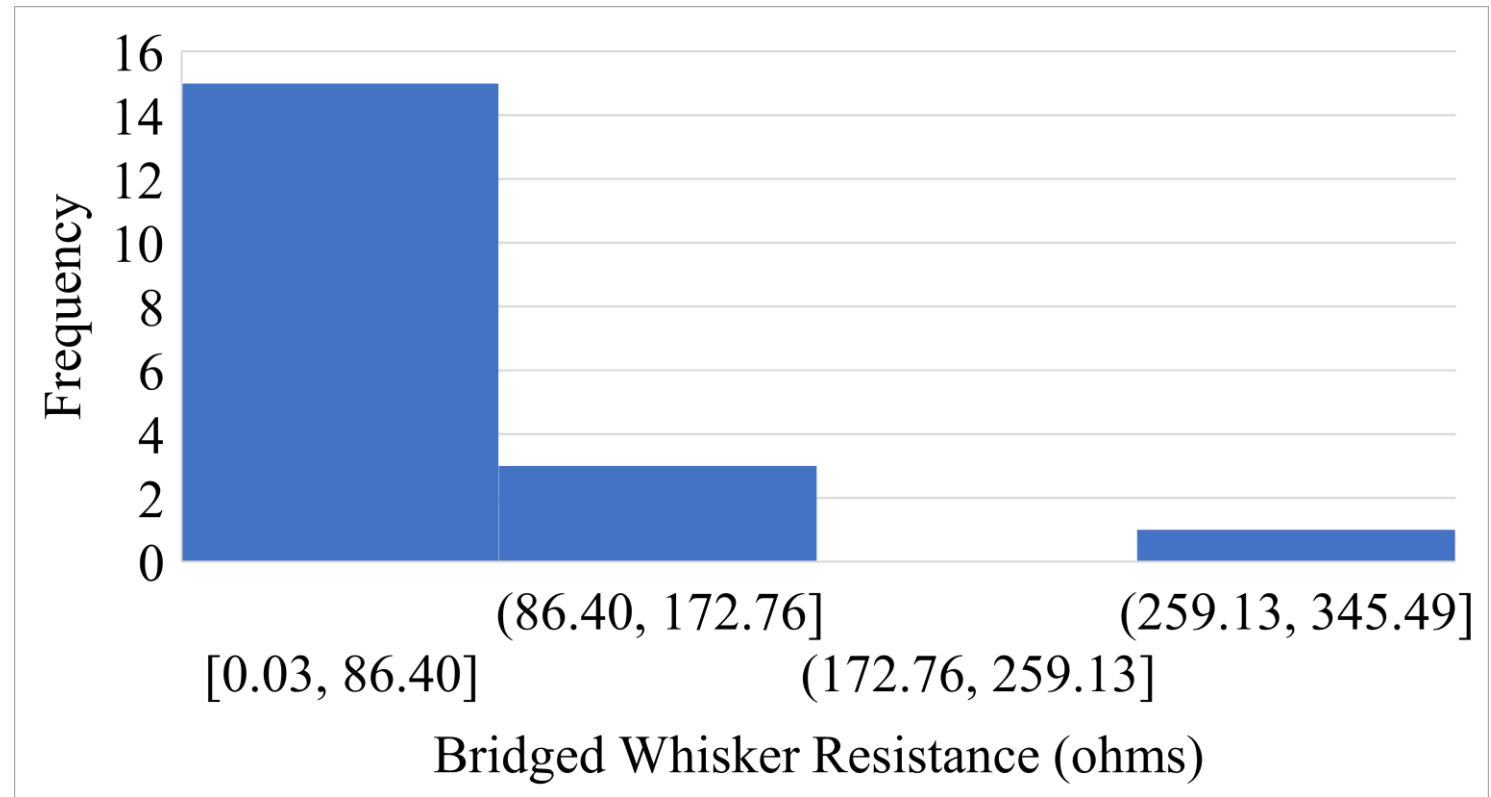
Small Quantity Bridging Resistance Frequency

Testing and Analysis

Results Assessment – Large Whisker Storm (Qty: 500)

ALT + F8 -> GenerateProb	
Overall Probability	
100.00%	
Individual Probability	
Iter #	Probability
1	1.80%
2	1.00%
3	1.00%

Large Quantity Bridging Probability



Large Quantity Bridging Resistance Frequency

Further Development

Simulation Errors & Suggested Improvements

Ideas for Further Development

Source of Error	Proposed Solutions
Exposed Traces	<ul style="list-style-type: none"> • Short Term – Remove traces (Un-route Tool) • Long Term – Research different processing and/or collider process to see if possible
Component “Grouping”	<ul style="list-style-type: none"> • Research working with different file types
Uniform and Constant Cross Section	<ul style="list-style-type: none"> • Research different modeling capabilities in Unity to see if solutions possible • Potential – Poly Shape tool
Whisker Resistance	<ul style="list-style-type: none"> • Research different modeling capabilities in Unity to see if solutions possible • Potential – Vectors

[3,4,5]

Further Development

Simulation Errors & Suggested Improvements

Ideas for Further Development

Source of Error	Proposed Solutions
Shock Accuracy	<ul style="list-style-type: none"> • Research different modeling capabilities in Unity to see if solutions possible • Potential – Using time differential (2D version)
File Type Issues - .obj	<ul style="list-style-type: none"> • Short Term – Replace component for one of similar makeup • Long Term – Research different processing and/or file types • Potential - Flipping Normals
Material Names	<ul style="list-style-type: none"> • Use different software • Research different post processing for names to see if possible
Rigidity	<ul style="list-style-type: none"> • Research different modeling capabilities to see if solutions possible

[6,7]

Conclusion

Design Specifications Met

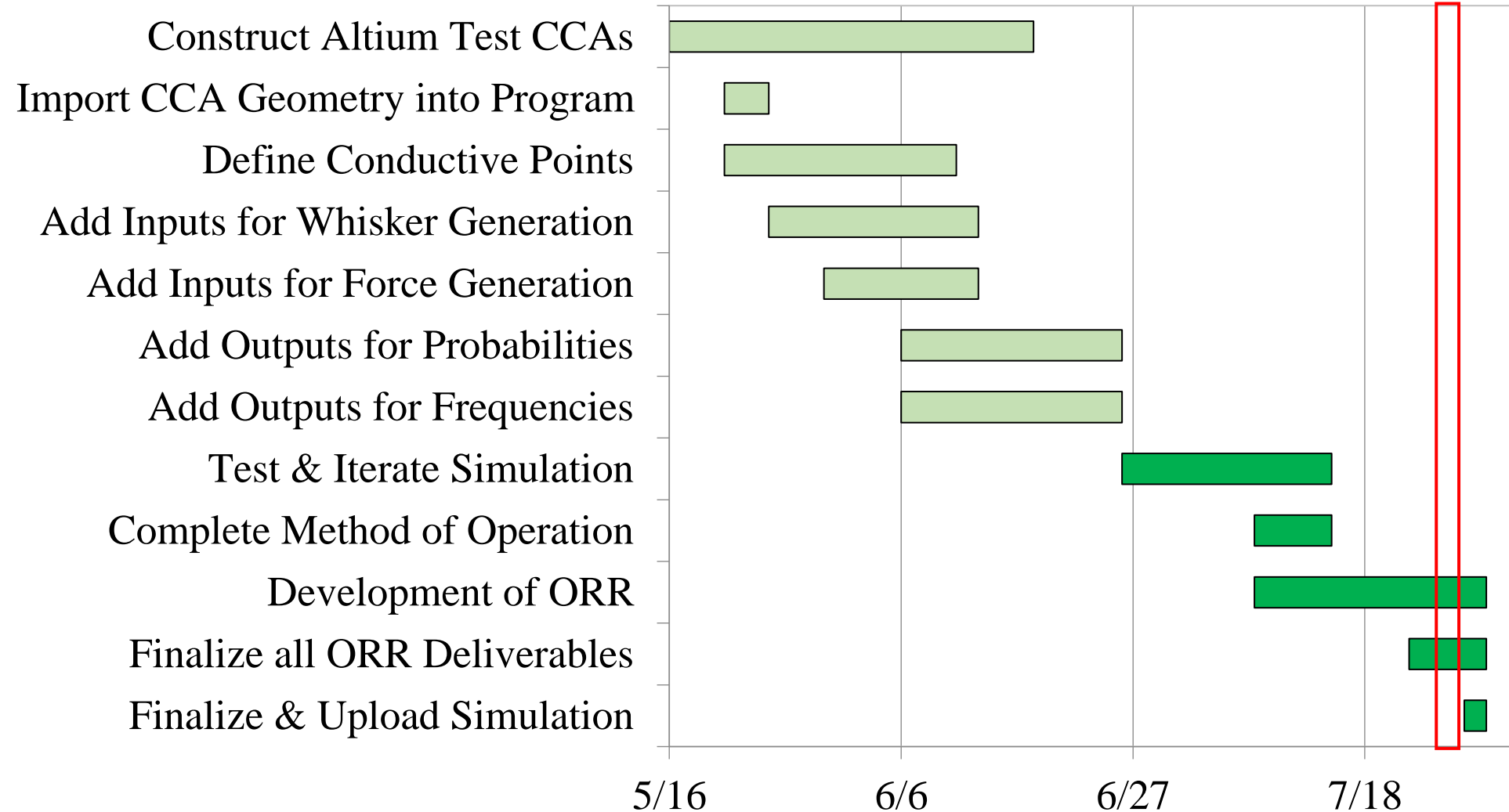
- CCA importing & interaction
- Normal and lognormal dimensional distribution
- Drop location of airborne whiskers
- External forces through sine waves
- Physical results – heatmap
- Statistical results – probability & frequency histograms
- Single script – C#
 - \approx 1500 lines of code

Continued Development

- Team 1 suggestions
 - Explore file types
 - Improve material ID
 - Realistic whiskers
- Team 2 improvements
 - Physical boundaries
 - Node & whisker ID
 - Enhanced data tracking

Gantt Chart

7/25/2024



References

1. Panashchenko, L. (2012) *The Art of Metal Whisker Appreciation: A Practical Guide for Electronics Professionals*, NASA. https://nepp.nasa.gov/whisker/reference/tech_papers/2012-Panaschenko-IPC-Art-of-Metal-Whisker-Appreciation.pdf (accessed Feb. 1 2024).
2. “Tablecloth whip-off Trick,” Steve Spangler, <https://stevespangler.com/experiments/tablecloth-science-trick/#:~:text=Plain%20and%20simple%2C%20Tablecloth,the%20object%20to%20move%20it>. (accessed Jul. 23, 2024).
3. P.M. Games, “Probulder Unity | drawing 3D shapes with polyshape tool,” Youtube, <https://www.youtube.com/watch?v=lr9cU0ejY8U> (accessed Jul. 23, 2024).
4. “Modifying existing routes,” Altium Documentation, <https://www.altium.com/documentation/altium-designer/modifying-existing-routes-pcb#routing-aware-move-component> (accessed Jul. 22, 2024).
5. Wintersbane, Finding vector3 position of GameObject – Questions & Answers – Unity Discussions, <https://discussions.unity.com/t/finding-vector3-position-of-gameobject/148031> (accessed Jul. 24, 2024).

References

6. Ekta-Mehta-D, “Electric shock wave effect 2D – Questions & Answers – Unity Discussions,” Unity Discussions, <https://discussions.unity.com/t/electric-shock-wave-effect-2d/71778> (accessed Jul. 24, 2024).
7. “Why do my object files look weird when imported to unity?,” Stack Overflow, <https://stackoverflow.com/questions/72842393/why-do-my-object-files-look-weird-when-imported-to-unity> (accessed Jul. 23, 2024).

Questions?

A special thanks to our advisors...

Dr. Donna Havrisik

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Dr. George Flowers

Jake Botello