```
disp("Question 01.")
Question 01.
% Defining symbolic variables
syms x y k
% Finding critical points
eqns1 = [(x-4*y) == 0, (-x+y) == 0];
eqns1
eqns1 = (x - 4y = 0 y - x = 0)
[x1 y1] = solve(eqns1, [x y]);
[x1 y1]
ans = (0 \ 0)
% Finding matrix for eigenvalues
eqns2 = ((+1-k)*(+1-k))-((-1)*(-4)) == 0;
eqns2
eqns2 = (k-1)^2 - 4 = 0
k = solve(eqns2, k);
k
k =
% Critical point is stable spiral point since eigenvalues have negative real part
% Plotting phase plane trajectories
for a = -0.5:0.1:0.5
    Y0 = [-1;a];
    [T,Y] = ode45(@eqns3,[0 10],Y0);
    plot(Y(:,1),Y(:,2),'blue -')
    hold on
end
for a = -0.5:0.1:0.5
```

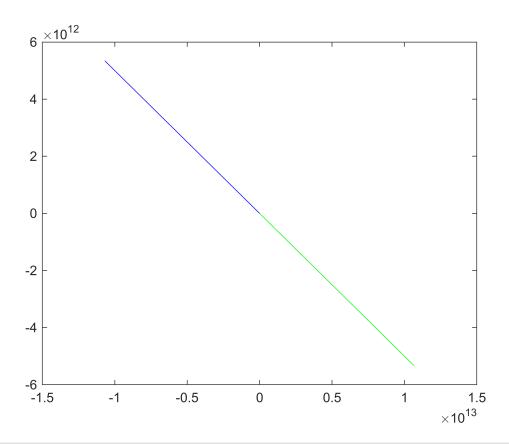
```
Y0 = [1;a];

[T,Y] = ode45(@eqns3,[0 10],Y0);

plot(Y(:,1),Y(:,2),'green -')

hold on

end
```



% Defining function for equations

```
function F = eqns3(t,y)
   F=[y(1)-4*y(2); -y(1)+y(2)];
end
```