

日期	(週數) 主題
2/22	1. 嵌入式應用介紹
3/8	3. 樹莓派介紹與設定
3/15	4. 樹莓派應用(倒車雷達)
3/22	5. 樹莓派應用(人體活動偵測)
3/29	6. 樹莓派應用(人體活動偵測)
4/12	8. 網路攝影機 IP cam
4/19	9. 網路攝影機 + 影像辨識
4/26	10. 網路攝影機 + 機器學習影像辨識
5/3	11. Midterm (Project分組)
5/10	12. 語音助理. Google assistant
5/17	13. 網路應用、推播廣告(beacon)
5/24	14. 其他嵌入式系統
5/31	15. Final Project – Proposal
6/14	17. Final Project prepare, Q&A, 補demo
6/21,28	18,19. Final Project demonstration (陽明, 交大) TBD





Last week

- □ 1. PI camera
- □ 2. IP cam

This week

- □ 1. PI camera
- 2. Facial detection (with opency)



嵌入式系統設計概論與實作

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Outline

- □ 嵌入式應用:網路攝影機
 - □ 觀看Raspberry Pi Camera的圖片
 - □影像辨識 (opencv)
 - 圖片旋轉, 裁切, 縮放
 - ■人臉識別

觀看Raspberry Pi Camera的圖



- python -m SimpleHTTPServer 8000
- winscp
- □ vnc

- Create Wi-Fi hotspot on PI
- View image in terminal

Create Wi-Fi hotspot on Pl

- wget https://raw.githubusercontent.com/raspberrypitw/sh/master/dual_mode.sh
- chmod +x dual_mode.sh
- sudo ./dual_mode.sh on # it will install related packages and reboot
- sudo ./dual_mode.sh off # it will reboot



View image in terminal

- Insanely fast image printing in your terminal
 - git clone https://github.com/posva/catimg
 - cd catimg/
 - cmake.
 - sudo make install
- Usage: catimg xxxxxxxx.jpg -w 80

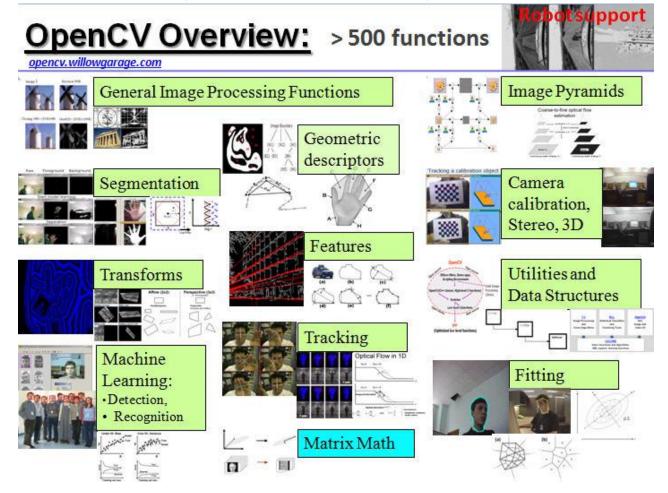






opencv

Open Source Computer Vision Library



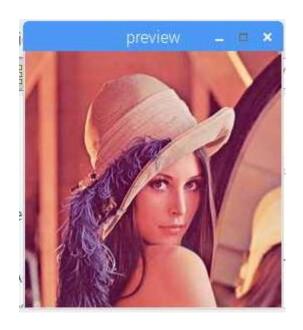
preview

Sample code



import cv2
import numpy as np
img = cv2.imread('lena256rgb.jpg')

cv2.imshow('preview', img)
cv2.waitKey(0)
cv2.destroyAllWindows()





translation

Applies an affine transformation to an image.

```
import cv2
import numpy as np
img = cv2.imread('lena256rgb.jpg')
rows, cols = img.shape[:2]
M = np.float32([[1,0,100], [0,1,50]])
translation = cv2.warpAffine(img, M, (cols, rows))
cv2.imshow('Translation', translation)
cv2.waitKey(0)
cv2.destroyAllWindows()
```



rotation

Calculates an affine matrix of 2D rotation.

```
import cv2
import numpy as np
img = cv2.imread("lena256rgb.jpg")
rows, cols = img.shape[:2]
M = cv2.getRotationMatrix2D((cols/2, rows/2), 45, 1)
rotation = cv2.warpAffine(img, M, (cols, rows))
cv2.imshow('Rotation', rotation)
cv2.waitKey(0)
cv2.destroyAllWindows()
```



https://docs.opencv.org/2.4/modules/imgproc/doc/geometric_transformations.html

resize

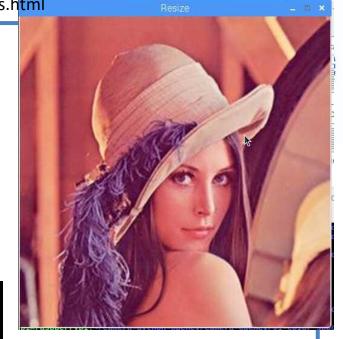
Resizes an image.

```
import cv2
import numpy as np

img = cv2.imread("lena256rgb.jpg")
rows, cols = img.shape[:2]

resize = cv2.resize(img, (2*rows, 2*cols), interpolation = cv2.INTER_CUBIC)
cv2.imshow('Resize', resize)
cv2.waitKey(0)

cv2.destroyAllWindows()
```



crop

Sample code

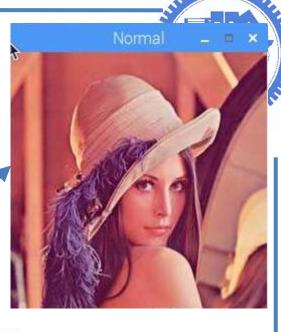
```
import cv2
import numpy as np

img = cv2.imread("lena256rgb.jpg")
cv2.imshow("Normal", img)
cv2.waitKey(0)

face = img[95:195, 100:180]
cv2.imshow("Face", face)
cv2.waitKey(0)
```

body = img[20:, 35:210]
cv2.imshow("Body", body)
cv2.waitKey(0)

cv2.destroyAllWindows()







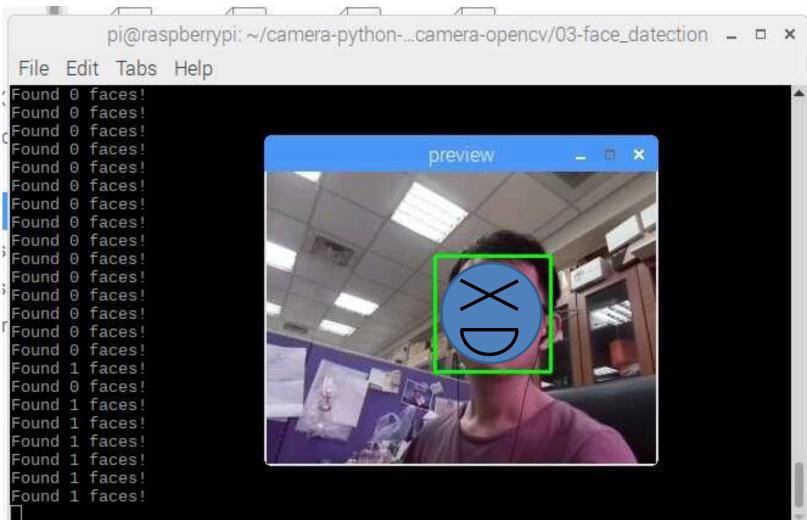


Install opency

- Command
 - sudo apt-get install python-opency
 - Download sample code and unzip it
- Two sample code
 - Analyze image
 - python image_face_detect.py your_img haarcascade_frontalface_default.xml
 - Analyze camera
 - python camera_face_detect.py haarcascade_frontalface_default.xml



Facial detection







```
import sys
import cv2
cascPath = sys.argv[1]
faceCascade = cv2.CascadeClassifier(cascPath)
if cv2. version .startswith('2'):
  PROP_FRAME_WIDTH = cv2.cv.CV_CAP_PROP_FRAME_WIDTH
  PROP_FRAME_HEIGHT = cv2.cv.CV_CAP_PROP_FRAME_HEIGHT
  HAAR FLAGS = cv2.cv.CV HAAR SCALE IMAGE
cap = cv2.VideoCapture(0)
cap.set(PROP FRAME WIDTH, 320)
cap.set(PROP_FRAME_HEIGHT, 240)
```





```
while True:
 # Capture frame-by-frame
 ret, frame = cap.read()
  gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
  faces = faceCascade.detectMultiScale(
    gray,
    scaleFactor=1.1,
    minNeighbors=5,
    minSize=(30, 30),
    flags=HAAR_FLAGS
```





```
print "Found {0} faces!".format(len(faces))
  # Draw a rectangle around the faces
  for (x, y, w, h) in faces:
    cv2.rectangle(frame, (x, y), (x+w, y+h), (0, 255, 0), 2)
  # Display the resulting frame
  cv2.imshow("preview", frame)
  if cv2.waitKey(1) \& 0xFF == ord("q"):
    break
# When everything is done, release the capture
cap.release()
cv2.destroyAllWindows()
```

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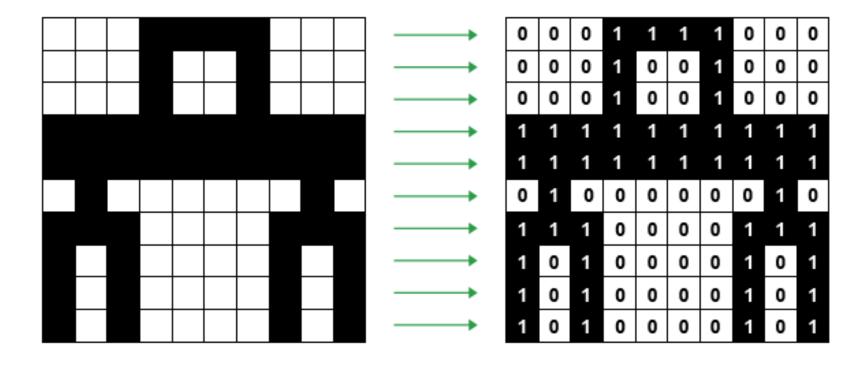
Cascade Classification

- Haar Feature-based Cascade Classifier for Object
 Detection
 - The object detector described below has been initially proposed by Paul Viola [Viola01] and improved by Rainer Lienhart [Lienhart02].
 - a classifier is trained with a few hundred sample views of a particular object (i.e., a face or a car), called positive examples
 - Output 1: the region is likely to show the object (i.e., face/car)
 - Output 0: otherwise



Bitmap images

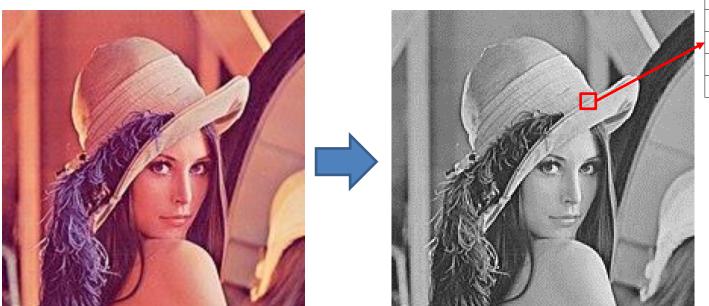
Example: black-and-white image





Bitmap images

- Example: grayscale picture
 - 8 bits per pixel
 - □ This pixel depth allows 256 different intensities



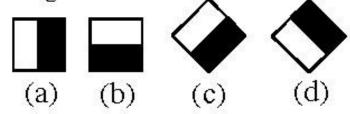
154	108	198	216	52
61	168	148	52	45
72	80	55	134	39
89	129	232	204	155
156	99	118	125	83

Fig source: https://zh.wikipedia.org/wiki/%E8%90%8A%E5%A8%9C%E5%9C%96

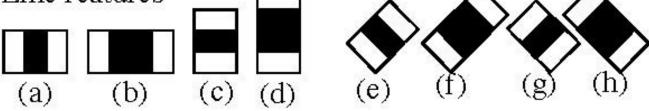


Haar-Like Features

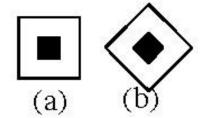
1. Edge features



2. Line features



3. Center-surround features



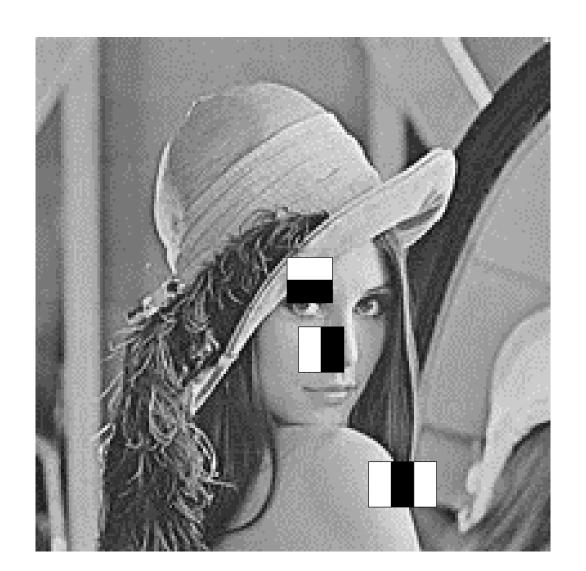


Find features

- □ Pick a scale (ex: 24x24 pixels) for the feature
- Slide it across the image
- Compute the average pixel values under the white area and the black area
- If the difference between the areas is above some threshold,
 the feature matches



Find features





Find features

- 1. Calculate the average of white/black pixel
- 2. Calculate the difference

0	0	1	1
0	0	1	1
0	0	1	1
0	0	1	1

0	0	1	1
0	0	1	1
0	0	1	1
0	0	1	1

$$\Delta = black - whilte = 1$$

image

Edge feature

0.1	0.2	0.6	0.8
0.2	0.3	0.8	0.6
0.2	0.1	0.6	0.8
0.2	0.1	0.8	0.9

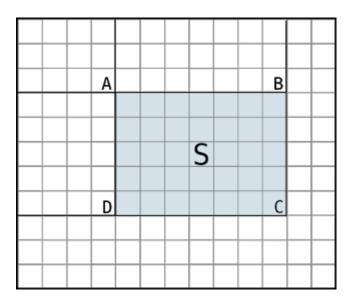
$$\Delta = \frac{0.6 + 0.8 + \dots}{8} - \frac{0.1 + 0.2 + \dots}{8}$$
$$= 0.7375 - 0.175 = 0.56$$

Edge feature

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Integral Image

- a quick and effective way of calculating the sum of values (pixel values) of a rectangular subset of a grid
- It can also used for calculating the average intensity within a given image.



Sum = Value(C) - Value(B) - Value(D) + Value(A)



Integral Image

0.1	0.2	0.6	0.8
0.2	0.3	0.8	0.6
0.2	0.1	0.6	0.8
0.2	0.1	0.8	0.9



0.1	0.3	0.9	0.8
0.3	0.8	2.2	3.6
0.5	1.1	3.1	5.3
0.7	1.4	4.2	7.3

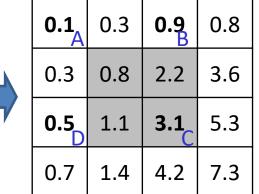
Original image

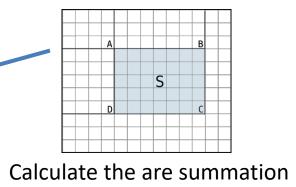
integral image



Integral Image

0.1	0.2	0.6	0.8
0.2	0.3	0.8	0.6
0.2	0.1	0.6	0.8
0.2	0.1	0.8	0.9





0.1	0.3	0.9	0.8
0.3	0.8	2.2	3.6
0.5	1.1	3.1	5.3
0.7	1.4	4.2	7.3

0.1	0.3	0.9 _B	0.8
0.3	0.8	2.2	3.6
0.5	1.1	3.1	5.3
0.7	1.4	4.2	7.3

0.1 _A	0.3	0.9	0.8
0.3	0.8	2.2	3.6
0.5	1.1	3.1	5.3
0.7	1.4	4.2	7.3

0.1	0.3	0.9	0.8
0.3	0.8	2.2	3.6
0.5	1.1	3.1	5.3
0.7	1.4	4.2	7.3



Discussion

- How to calculate the area summation by integral image?
 - 1. Write down the value of integral image
 - 2. Sum = Value(C) Value(B) + Value(A) Value(D) = ?????

0.1	0.2	0.3	0.5	0.8
0.2	0.2	0.3	0.7	0.9
0.1	0.2	0.4	0.7	0.9
0.3	0.1	0.2	0.8	0.2
0.1	0.2	0.4	0.6	0.1



		7	
•	•	•	



AdaBoost

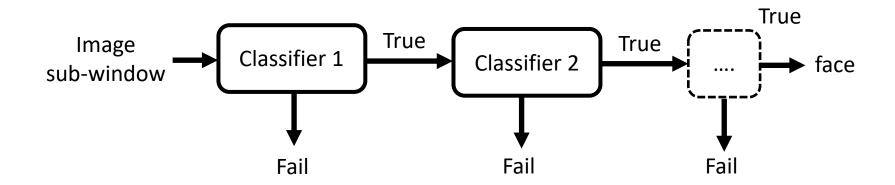
- Adaptive Boosting
 - Try out multiple weak classifiers over several rounds
 - Select the best weak classifier in each round and combining the best weak classifiers to create a strong classifier

Data point	Classifier 1	Classifier 2	Classifier 3	•••
P_1	Pass	Fail	Fail	•••
P ₂	Pass	Pass	Pass	•••
P ₃	Fail	Pass	Pass	•••
•••	•••	•••	•••	•••



Cascades

- Haar cascades consists of a series of weak classifiers
 - barely better than 50% correct
 - If an area passes a single classifier, go to the next classifier; otherwise, area doesn't match





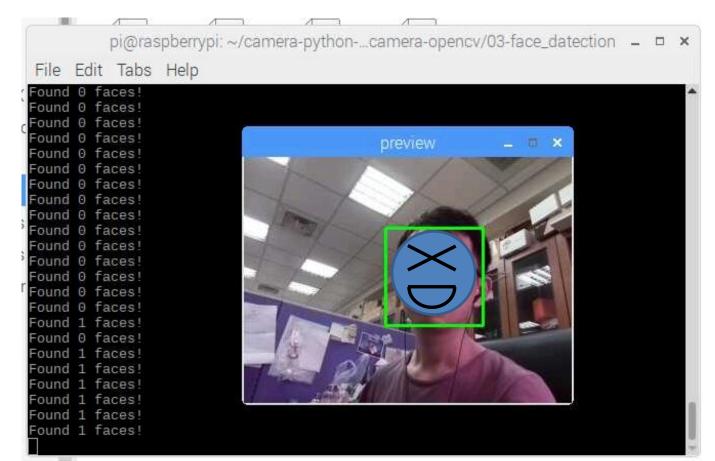
Recall the code

```
while True:
 # Capture frame-by-frame
 ret, frame = cap.read()
  gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
  faces = faceCascade.detectMultiScale(
    gray,
    scaleFactor=1.1,
    minNeighbors=5,
    minSize=(30, 30),
    flags=HAAR_FLAGS
```



Face detection on PI

python camera_face_detect.py haarcascade_frontalface_default.xml



https://docs.opencv.org/2.4/modules/objdetect/doc/cascade_classification.html

Related parameters



- cascade Haar classifier cascade (OpenCV 1.x API only). It can be loaded from XML or YAML file using Load(). When the cascade is not needed anymore, release it using cvReleaseHaarClassifierCascade(&cascade).
- □ **image** Matrix of the type CV 8U containing an image where objects are detected.
- □ **objects** Vector of rectangles where each rectangle contains the detected object.
- scaleFactor Parameter specifying how much the image size is reduced at each image scale.
- minNeighbors Parameter specifying how many neighbors each candidate rectangle should have to retain it.
- flags Parameter with the same meaning for an old cascade as in the function cvHaarDetectObjects. It is not used for a new cascade.
- minSize Minimum possible object size. Objects smaller than that are ignored.
- maxSize Maximum possible object size. Objects larger than that are ignored.

Try to use different parameters, you will get different results.



Last week

MJPG on PI



Hello Stream

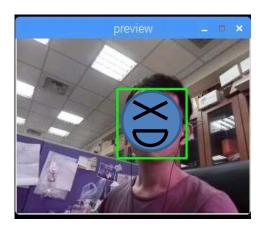


No stream? You might need: sudo modprobe bcm2835-v4l2

Quiz



- Based on the sample code:
 - 1. MJPG on PI
 - 2. Facial detection
- Combine them together!





Hello Stream



We can use browser to watch the facial detection results.



Summary

- Practice Lab (opency example, facial detection)
- Write down the answer for discussion
 - □ **Discussion** (Deadline: Before 4/26, 12:00)
 - How to calculate the area summation by integral image?
- Write code for Quiz 1, then demonstrate it to TAs
 - Quiz1: MJPG + facial detection
 - Deadline: Before 4/19, 15:10
 - Late Demo: Before 4/26, 15:10



Reference

- Online resource
 - Facial Detection
 - https://www.youtube.com/watch?v=sWTvK72-SPU
 - Computer Vision Haar-Features
 - https://www.youtube.com/watch?v=F5rysk51txQ
 - Computer Vision Integral Images
 - https://www.youtube.com/watch?v=x41KFOFGnUE
 - Recognition Part II: Face Detection via AdaBoost
 - https://courses.cs.washington.edu/courses/cse455/16wi/notes/15_ FaceDetection.pdf



Reference

- [Viola01] Paul Viola and Michael J. Jones. Rapid Object Detection using a Boosted Cascade of Simple Features. IEEE CVPR, 2001.
 - http://research.microsoft.com/enus/um/people/viola/Pubs/Detect/violaJones_CVPR2001.pdf
- [Lienhart02] Rainer Lienhart and Jochen Maydt. An Extended Set of Haar-like Features for Rapid Object Detection. IEEE ICIP, Vol. 1, pp. 900-903, Sep. 2002.
 - http://www.multimedia-computing.de/mediawiki//images/5/52/MRL-TR-May02-revised-Dec02.pdf