

Fast R-CNN

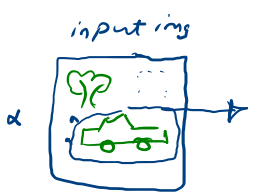
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# Review

RoI → Region of interest.

end to end

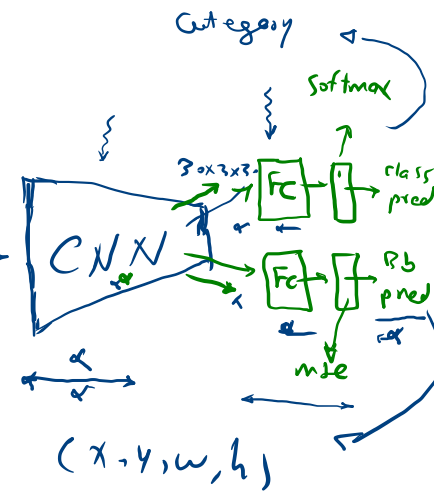
224x224



selective search region proposal

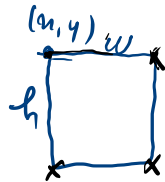


warp!  
fixed sizing!



R-CNN

2000 RoI → Back X  
NMS



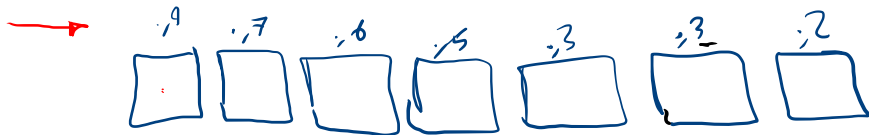
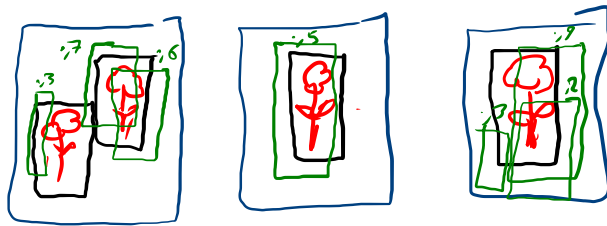
$$\frac{\text{loss}}{\alpha} = \underbrace{L_{cls}}_{\text{cross entropy}} + \underbrace{L_{loc}}_{L2_{smooth}}$$

$$\frac{\text{Train}}{\alpha}$$

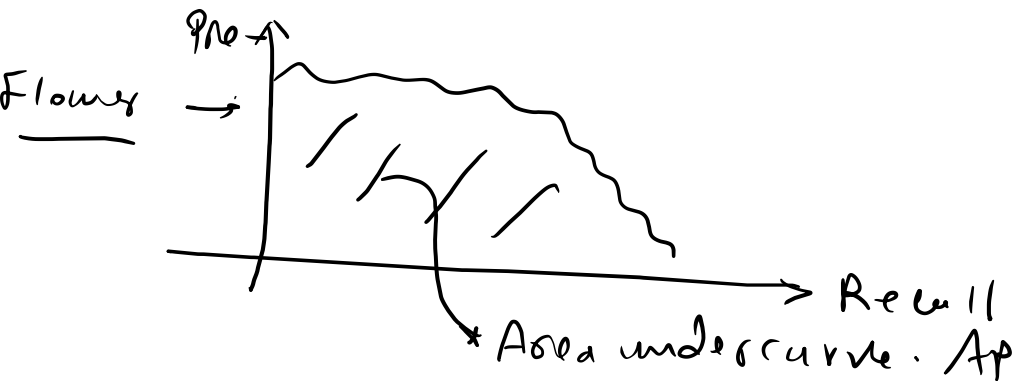
## Metrics

1. FPS  $\rightarrow$  frame per second.
2. mAP  $\checkmark \rightarrow$  mean Average precision.  $[0, \underline{100}]$   
 $\xleftarrow{\text{Test}}$   
 $\xrightarrow{\text{mAp}}$   
acc<sub>cls</sub>

map



$\sum v > .5$    .8   .90   .7   .4   .7   .1   .6



$\sum v > .5 \rightarrow TP$   
 $\sum v < .5 \rightarrow FP$   $\xrightarrow{\text{if } \sum v > .5}$   $FP$   
 $\xrightarrow{\text{if } \sum v < .5}$   $TN$

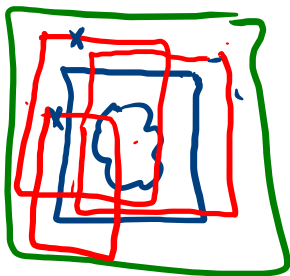
problem

Train: So long.

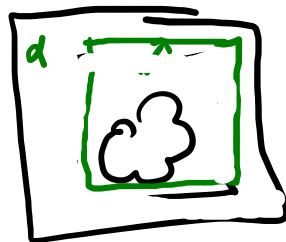
Test: ✓

25 <sup>5</sup> From

Selective Search

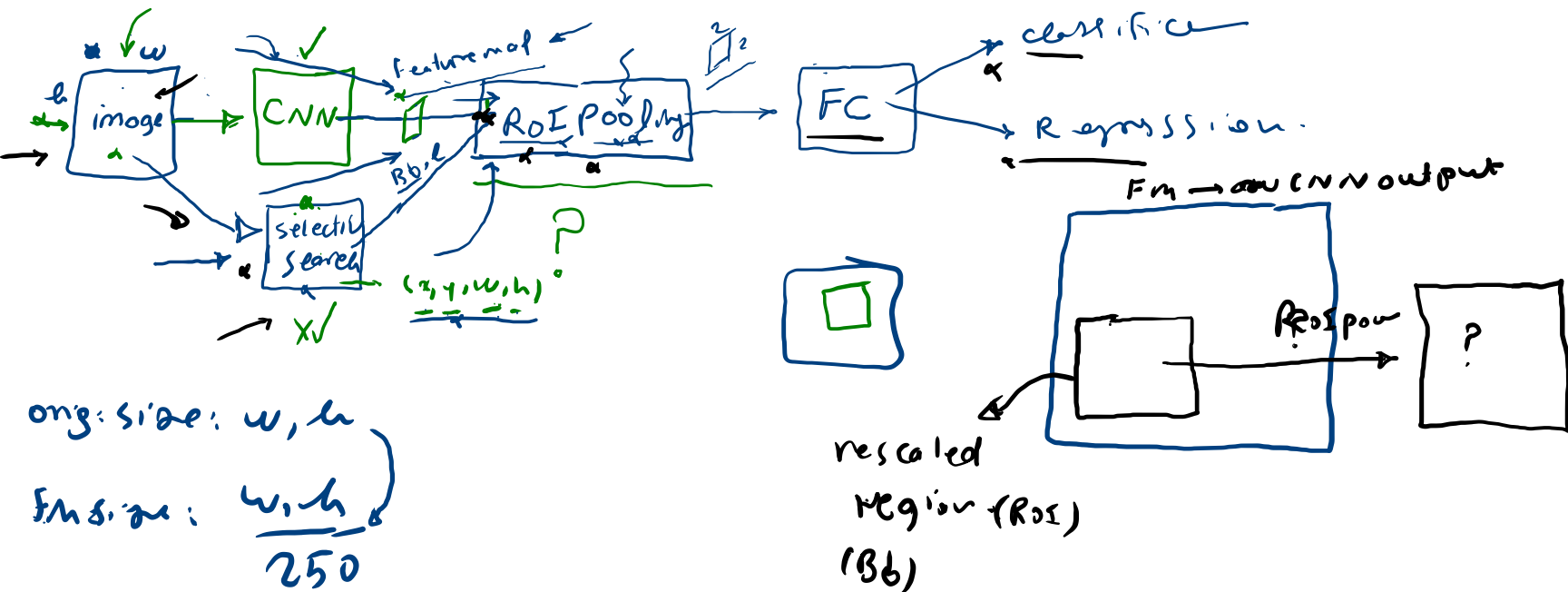


$\frac{NMS}{\alpha} \rightarrow \underline{sov} \rightarrow \underline{\text{ground truth}}$



# Fast RCNN

1/1 ↑  $\omega$   
20



4

80	70	30	9
140	13	7	8
30	81	153	200
34	17	6	0

CNN  
Output  
(Feature)  
map

output size =  $2 \times 2$

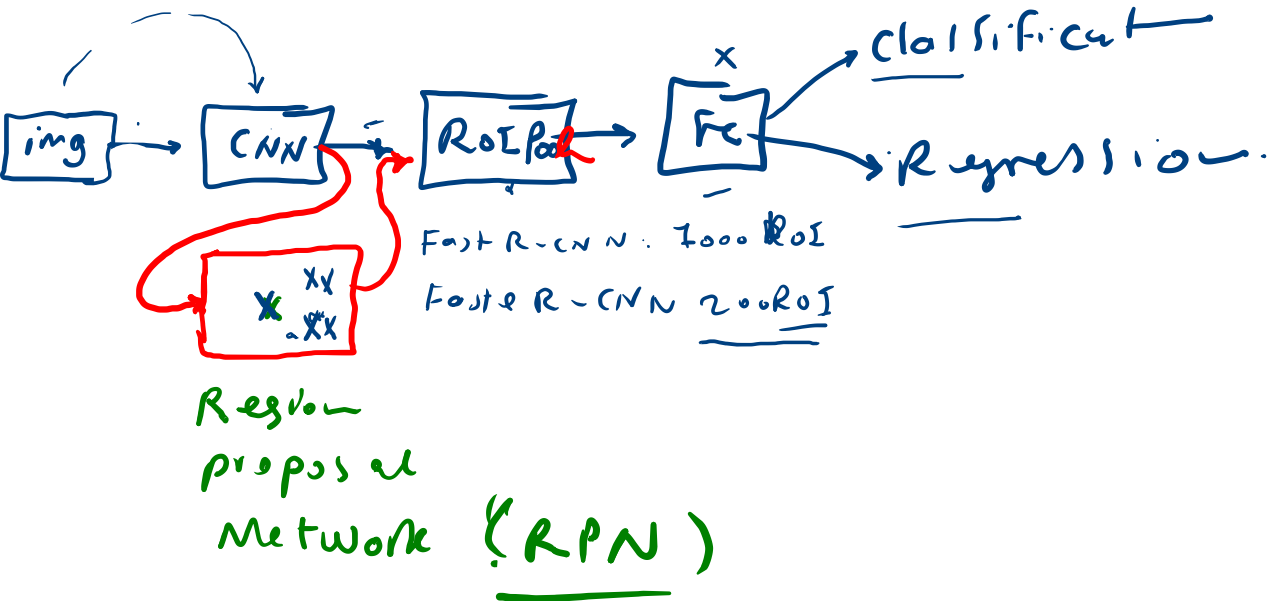
\* pooling window:  $3 \times 3$   
 (overlup  $\Rightarrow$  NO X)

153	200
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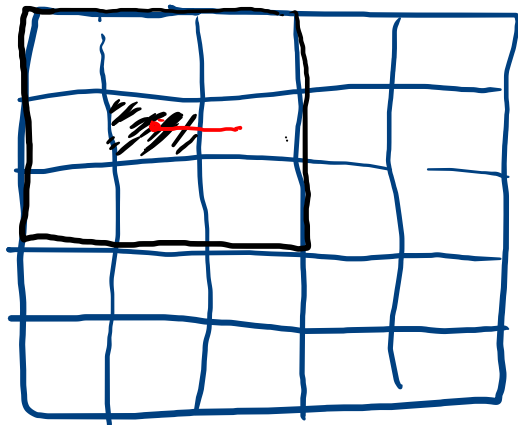
34	0
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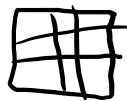
# a Faster R-CNN



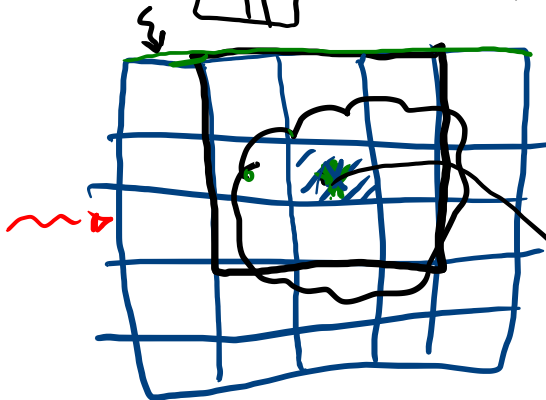
RPN :



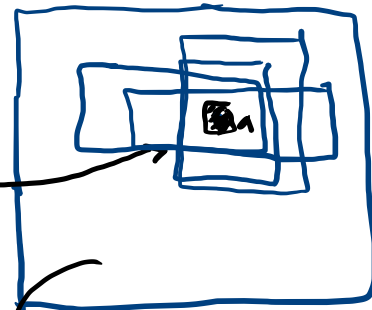
Anchor



کد پیچیده با سازه‌های ثابت!



بلوک



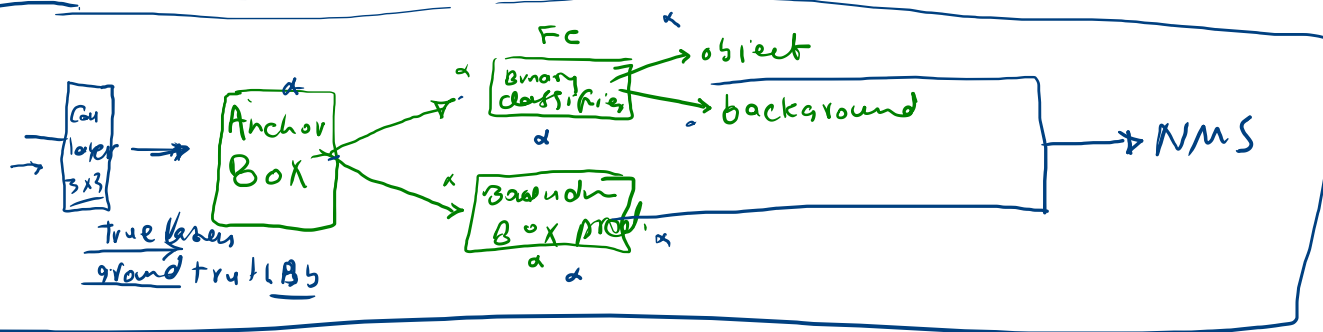
← NMS

RPV کلاسیک segmentation ✓ Anchor ; in  $\alpha$  ✓

RPV

Fast  
RCNN

vs Fast RCNN





Search region

RPN نسبت

$\alpha$  درگیری

Bb هر توپون مکرر شود!

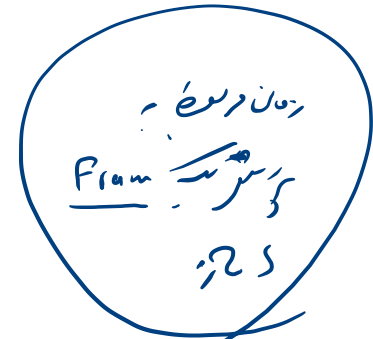
Anchor Box

به دستاورد از دیگر

Bb یا ROI با کیفیت زیری

Back or Bb pred. classification

$\alpha$  با دست



ROI در مکرر

advantages

ROI در با کیفیت زیری

PASCAL

R-CNN



66 %

1X

Fast R-CNN

66,9 %

25X

Faster R-CNN

66,9 %

25,0X

The End