

economics letters

Economics Letters 100 (2008) 208-212

www.elsevier.com/locate/econbase

Measuring business cycles: A wavelet analysis of economic time series

Motohiro Yogo *

Finance Department, The Wharton School, University of Pennsylvania, 3620 Locust Walk, Philadelphia, PA 19104, USA
National Bureau of Economic Research, Cambridge, MA 02138, USA

Received 24 May 2005; received in revised form 8 January 2008; accepted 14 January 2008 Available online 25 January 2008

Abstract

Multiresolution wavelet analysis is a natural way to decompose an economic time series into trend, cycle, and noise. The method is illustrated with GDP data. The business-cycle component of the wavelet-filtered series closely resembles the series filtered by the approximate bandpass filter.

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Keywords: Band-pass filter; Business cycle; Linear filter; Trend; Wavelets

JEL classification: C5; E3

1. Introduction

Multiresolution wavelet analysis is a useful tool for studying the time and frequency properties of an economic time series. Using a wavelet filter, a time series x(t) can be decomposed as

$$x(t) = x_0(t) + \sum_{j=0}^{3} y_j(t), \tag{1}$$

where $x_0(t)$ denotes cycles with periodicity greater than 32 periods and $y_j(t)$ denotes cycles with periodicity between 2^{4-j} and 2^{5-j} periods. If the sampling frequency is quarterly, $x_0(t)$ is the long-run trend (periodicity greater than 32 quarters). $y_0(t)$, $y_1(t)$, and $y_2(t)$ are the business-cycle components (periodicity of 16-32, 8-16, and 4-8 quarters, respectively). $y_3(t)$ is high frequency noise (periodicity less than 4 quarters).

Applying wavelet analysis to the US real GDP in the postwar period (1947:1–2003:2), the business-cycle component (i.e. $\sum_{j=0}^{2} y_j(t)$) closely resembles the series filtered by the approximate bandpass filter (Baxter and King, 1999). In that sense, wavelet filtering is an alternative to bandpass filtering. However, wavelet analysis provides better resolution in the time

domain since wavelet basis functions are time-localized (in addition to being scale-localized), which is useful for capturing the changing volatility of the business cycle. The wavelet-filtered series reveal that most of the business-cycle volatility before the 1960s was due to cycles of 8–16 quarters. Most of the volatility in the 1970s was due to lower frequency cycles of 16–32 quarters. Since the early 1980s, the volatility has been relatively small at all frequencies, which is consistent with recent evidence (Kim and Nelson, 1999; McConnell and Perez-Quiros, 2000).

Section 2 provides a brief overview of multiresolution wavelet analysis, highlighting properties that are relevant for the empirical application. The reader is referred to Strang and Nguyen (1997) for details. Section 3 applies the methods to study the time and frequency properties of real GDP. The MATLAB code used in the analysis is available from the author's webpage.

2. Multiresolution wavelet analysis

2.1. Overview

The design of wavelets begins with a two-channel perfect reconstruction filter bank. The lowpass and highpass analysis filters are $\{h_0(k)\}_{k=0}^{\tilde{N}}$ and $\{h_1(k)\}_{k=0}^{N}$. The lowpass and highpass

^{*} Tel.: +1 215 898 3609; fax: +1 215 898 6200. E-mail address: yogo@wharton.upenn.edu.

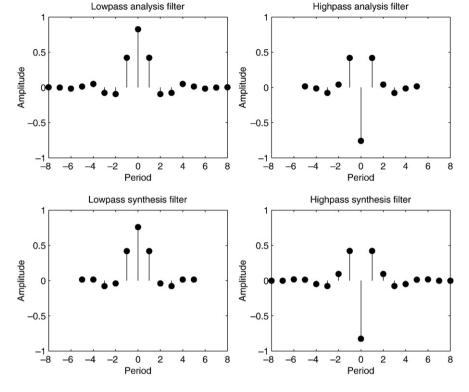


Fig. 1. Impulse response of the analysis and synthesis filters in the biorthogonal 17/11 filter bank.

synthesis filters are $\{f_0(k)\}_{k=0}^N$ and $\{f_1(k)\}_{k=0}^{\tilde{N}}$. The analysis scaling function $\tilde{\phi}(t)$ is defined by the analysis dilation equation,

$$\tilde{\phi}(t) = \sum_{k=0}^{\tilde{N}} 2h_0(k)\tilde{\phi}(2t - k) \tag{2}$$

The analysis wavelet $\tilde{w}(t)$ is defined by the analysis wavelet equation.

$$\tilde{w}(t) = \sum_{k=0}^{N} 2h_1(k)\tilde{\phi}(2t - k).$$
(3)

The corresponding synthesis dilation and wavelet equations are

$$\phi(t) = \sum_{k=0}^{N} 2f_0(k)\phi(2t - k), \tag{4}$$

$$w(t) = \sum_{k=0}^{\tilde{N}} 2f_1(k)\phi(2t - k).$$
 (5)

Let $\tilde{\phi}_{jk}(t) = 2^{j/2}\tilde{\phi}\left(2^{j}t - k\right)$ and $\tilde{w}_{jk}(t) = 2^{j/2}\tilde{w}\left(2^{j}t - k\right)$ be the analysis scaling function and wavelet at scale j and location k. The corresponding synthesis scaling function and wavelet are denoted by $\phi_{jk}(t)$ and $w_{jk}(t)$. The J-level wavelet decomposition of a continuous time signal x(t) is

$$x(t) = \sum_{k} \tilde{a}_{0k} \phi_{0k}(t) + \sum_{j=0}^{J-1} \sum_{k} \tilde{b}_{jk} w_{jk}(t),$$
 (6)

where

$$\tilde{a}_{0k} = \int x(t)\tilde{\phi}_{0k}(t)dt,\tag{7}$$

$$\tilde{b}_{ik} = \int x(t)\tilde{w}_{ik}(t)dt. \tag{8}$$

Let $H_0(\omega)$ and $H_1(\omega)$ be the frequency responses of the lowpass and highpass analysis filters. The filter relating the scaling coefficients \tilde{a}_{0k} to the original signal has a frequency response

$$A_0(\omega) = \prod_{l=0}^{J-1} H_0(2^l \omega). \tag{9}$$

In other words, the filter is a lowpass filter with an approximate passband $|\omega| \in [0,\pi/2^J]$. The filter relating the wavelet coefficients \tilde{b}_{jk} at level J to the original signal has a frequency response

$$B_j(\omega) = H_1(2^{J-j-1}\omega) \prod_{l=0}^{J-j-2} H_0(2^l\omega),$$
 (10)

which is a bandpass filter with an approximate passband $|\omega| \in [\pi/2^{J-j}, \pi/2^{J-j-1}]$ (Percival and Walden, 2000, pp. 96–97).

Let $F_0(\omega)$ be the frequency response of the lowpass synthesis filter. When $F_0(\omega)$ has p zeros at π , the analysis wavelet has p vanishing moments. Consequently, polynomials of degree p-1 can be expressed as a linear combination of the synthesis scaling functions $\phi_{0k}(t)$. In order to filter out the linear trend in non-stationary economic time series such as real GDP, $p \ge 2$ is a necessary criteria in choosing wavelet filters.

¹ See Strang and Nguyen (1997, Chapter 4.1) for the conditions that the filters must satisfy for perfect reconstruction.

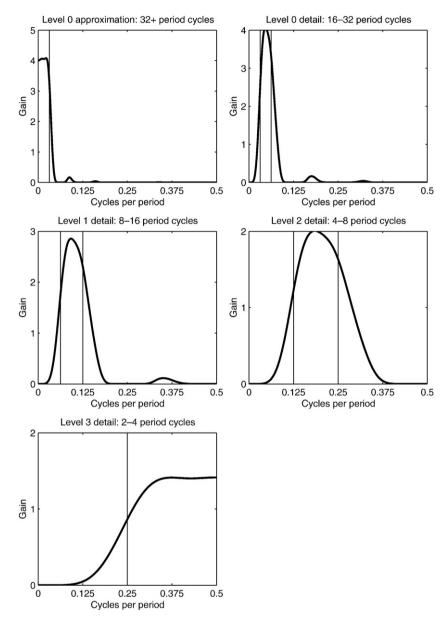


Fig. 2. Frequency response of the biorthogonal 17/11 wavelet filter.

2.2. Biorthogonal 17/11 wavelet filter

In analyzing economic time series, the timing of events at various frequencies is important. This motivates the use of biorthogonal, rather than orthogonal, wavelet filters, which have linear phase (zero phase when centered). Within the family of biorthogonal filters, the filter must be sufficiently long to avoid undesirable artifacts in the filtered series. Based on experimentation, starting with shorter filters, I have found that the 17/11 filter works well in practice. The rest of this section highlights the relevant facts about this filter.

Fig. 1 shows the impulse response of the analysis and synthesis filters in the biorthogonal 17/11 filter bank. The filters are symmetric, resulting in zero phase. The highpass analysis (synthesis) filter is the alternating flip of the lowpass synthesis

(analysis) filter, assuring perfect reconstruction. The lowpass analysis filter $H_0(\omega)$ has 8 zeros at π , and the lowpass synthesis filter $F_0(\omega)$ has 6 zeros at π . The analysis wavelet therefore has 6 vanishing moments, and the synthesis scaling function can replicate polynomials of degree 5.

Fig. 2 shows the frequency response of the biorthogonal wavelet filter. Frequency is in units of cycles per period, which is radian frequency normalized by 2π . Then periodicity is simply the inverse of frequency. At level 0 approximation, the wavelet filter is a lowpass filter with a stopband of approximately 32 periods (see Eq. (9)). The level 0, 1, and 2 details correspond to bandpass filters of approximately 16-32, 8-16, and 4-8 periods, respectively (see Eq. (10)). The level 3 detail corresponds to a highpass filter with a stopband of approximately 4 periods. Thus, a 4-level wavelet decomposition is a natural way

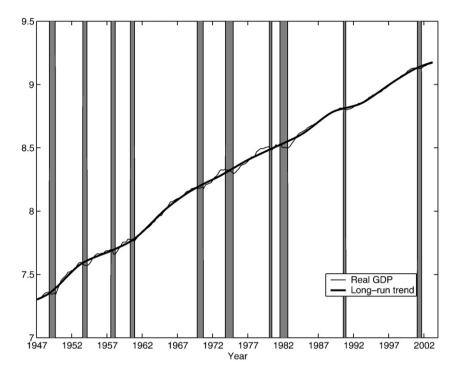


Fig. 3. Log real GDP and long-run trend. Shaded regions are NBER recessions.

to filter an economic time series into trend (periodicity greater than 32 quarters), cycle (periodicity of 4–32 quarters), and noise (periodicity less than 4 quarters), whose sum is the original series by the perfect reconstruction property of the underlying filter bank (see Eq. (1)).²

3. Measuring business cycles

I now apply multiresolution wavelet analysis, using the biorthogonal 17/11 filter, to study the business-cycle component of real GDP. Fig. 3 plots quarterly log real GDP and its long-run trend since 1947. The shaded regions of the figure correspond to recessions, from peak to trough, as determined by the National Bureau of Economic Research (NBER). The long-run trend is the level 0 approximation of the wavelet decomposition, corresponding to cycles with periodicity greater than 32 quarters. The plot shows that recessions are periods of sustained zero or negative growth in real GDP. Since the mid-1980s, GDP has not deviated far from its long-run trend.

The top three panels of Fig. 4 shows the first three levels of detail in the wavelet decomposition. Levels 0 through 2 contain the business-cycle components of GDP, corresponding to 16–32, 8–16, and 4–8 quarter cycles. (Level 3 detail, which corresponds to high frequency noise with cycles less than 4 quarters, is not reported.) The wavelet analysis reveals interesting changes in the volatility of the business-cycle component at various

scales. At the scale corresponding to 16–32 quarter cycles, the largest business-cycle fluctuations occurred in the 1970s through the early 1980s, with deviations exceeding 2.5% of the long-run trend. At higher scales corresponding to 8–16 and 4–8 quarter cycles, the largest volatility occurred before the 1960s. Since the mid-1980s, the business-cycle fluctuations of GDP have been relatively small. The source of the recent decline in business-cycle volatility is a subject of current debate (see Stock and Watson, 2003, and references therein).

The sum of the three business-cycle components is shown in the bottom panel of Fig. 4. As a comparison, the figure also shows real GDP filtered by the approximate bandpass filter. The two filtered series are remarkably similar. The local minima of the filtered series generally correspond to the NBER troughs. The peaks of the filtered series usually occur a few quarters before the NBER peak, which is a consequence of the slow-down in GDP growth before the onset of a recession. The only recession that both the wavelet filter and the bandpass filter miss is the 1980 recession, which began in January and ended in July. First, the duration of this recession is short. Second, Fig. 3 shows that GDP was well above the long-run trend before the slowdown, so GDP did not fall much below the trend during the recession.

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² Baxter and King (1999) define the business cycle as cycles with periodicity of 6–32 quarters. Since the scales in wavelet filters are dyadic, I use 4 instead of 6 quarters in the definition. The difference is obscured in practice because these finite impulse response filters are only approximations to ideal brick wall filters.

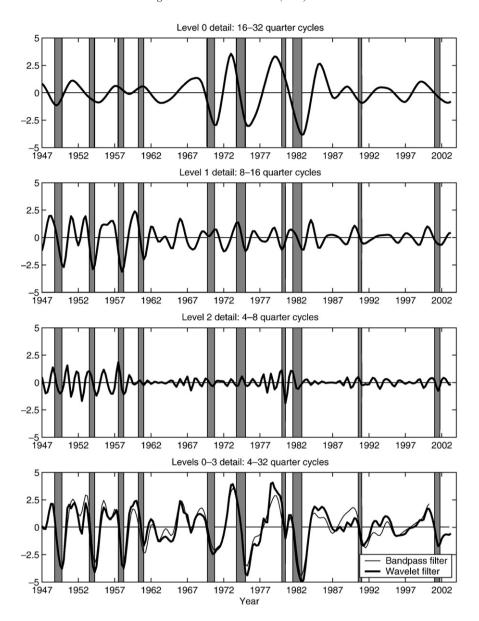


Fig. 4. Business-cycle component of log real GDP, measured as percent deviation from the long-run trend. Shaded regions are NBER recessions.

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