

CALCULUS-III

(BY SIR AHMAD)

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Stoke's Theorem:

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Statement

According to this theorem line integral of vector function around the closed curve of a surface is equal to the surface integral of curl of a vector function over that ~~closed~~ surface.

$$\oint \vec{V} \cdot d\vec{L} = \oint_S \text{curl } \vec{V} \cdot d\vec{S}$$

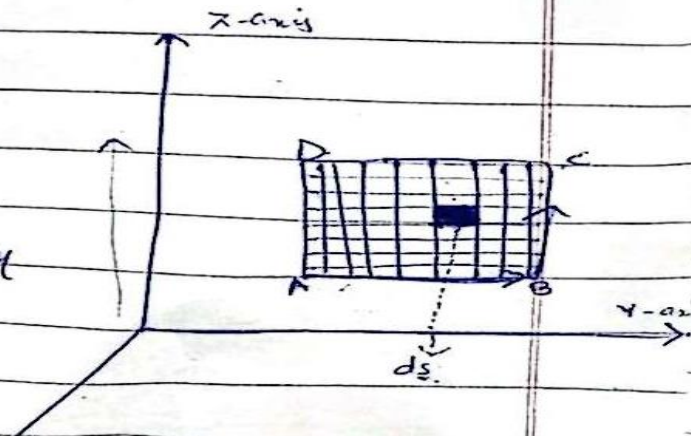
If \vec{V} is the vector function then Stoke's Law can be written as.

Explanation:

Consider of surface enclosed by a curve ABCD. We divided into large number of small meshes - let the area of each mesh is \vec{ds} as curl \vec{v} is the line integral per unit area. So line integral is around the boundary of element of area.

$$\vec{ds} = \text{Curl } \vec{v} \cdot \vec{ds}$$

Suppose that we take the line integral of all the meshes within the curve ABCD will be taken twice in



opposite direction.

So it will be cancelled with each other. We take line integral along only curv ABCD.

let \vec{v} is the vector function which can be written as

$$\vec{v} = v_x \hat{i} + v_y \hat{j} + v_z \hat{k}$$

Line integral of this vector function can be written as

$$\oint \vec{v} \cdot d\vec{l} = \oint_{x\text{-axis}} \vec{v} \cdot d\vec{l} + \oint_{y\text{-axis}} \vec{v} \cdot d\vec{l} + \oint_{z\text{-axis}} \vec{v} \cdot d\vec{l} \Rightarrow \text{Main Equation}$$

$$\oint_{x\text{-axis}} \vec{v} \cdot d\vec{l} = \int_A^B \vec{v} \cdot d\vec{l} + \int_B^C \vec{v} \cdot d\vec{l} + \int_C^D \vec{v} \cdot d\vec{l} + \int_D^A \vec{v} \cdot d\vec{l}$$

$$= \int_A^B v dl \cos 0 + \int_B^C v dl \cos 0 + \int_C^D v dl \cos 0 + \int_D^A v dl \cos 0$$

$$\oint \vec{v} \cdot d\vec{l} = \int_A^B v dl \cos(0) + \int_B^C v dl \cos(0) + \int_C^D v dl \cos(0) + \int_D^A v dl \cos(0)$$

$$\oint \vec{v} \cdot d\vec{l} = \int_A^B v dl + \int_B^C v dl - \int_C^D v dl - \int_D^A v dl$$

$$\Rightarrow \text{The velocity along line } \overline{AB} = v_y - \frac{dv_y}{dz} \frac{dz}{2}$$

$$\Rightarrow \text{The velocity along line } \overline{BC} = v_z + \frac{dv_z}{dy} \frac{dy}{2}$$

$$\Rightarrow \text{The velocity along line } \overline{CD} = v_y + \frac{dv_y}{dz} \frac{dz}{2}$$

$$\Rightarrow \text{The velocity along line } \overline{DA} = v_z - \frac{dv_z}{dy} \frac{dy}{2}$$

$$\oint \vec{v} \cdot d\vec{l} = \int_A^B \left(v_y - \frac{dv_y}{dz} \frac{dz}{2} \right) dl + \int_B^C \left(v_z + \frac{dv_z}{dy} \frac{dy}{2} \right) dl - \int_C^D \left(v_y + \frac{dv_y}{dz} \frac{dz}{2} \right) dl - \int_D^A \left(v_z - \frac{dv_z}{dy} \frac{dy}{2} \right) dl$$

$$\int_A^B dl = dy$$

$$\int_B^C dl = dz$$

$$\oint_{\text{rect}} \vec{v} \cdot d\vec{l} = \left(v_y - \frac{dv_y}{dz} \frac{dz}{2} \right) dy + \left(v_z + \frac{dv_z}{dy} \frac{dy}{2} \right) dz - \left(v_y + \frac{dv_y}{dz} \frac{dz}{2} \right) dy - \left(v_z - \frac{dv_z}{dy} \frac{dy}{2} \right) dz$$

$$= v_y dy - \frac{dv_y}{dz} \frac{dz}{2} dy + v_z dz + \frac{dv_z}{dy} \frac{dy}{2} dz$$

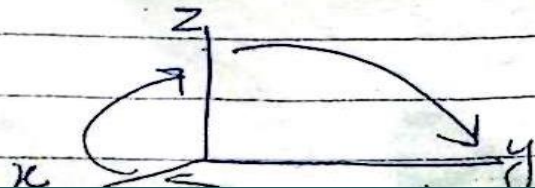
$$- v_y dy - \frac{dv_y}{dz} \frac{dz}{2} dy - v_z dz + \frac{dv_z}{dy} \frac{dy}{2} dz$$

$$= - \cancel{2} \frac{dv_y}{dz} \frac{dz}{2} dy + \cancel{2} \frac{dv_z}{dy} \frac{dy}{2} dz$$

$$= dy dz \left(\frac{dv_z}{dy} - \frac{dv_y}{dz} \right)$$

$$\oint_{\text{rect}} \vec{v} \cdot d\vec{l} = \left(\frac{dv_z}{dy} - \frac{dv_y}{dz} \right) dS_x$$

\Rightarrow Rotation is clockwise.



$$\int_a^b dl = dy$$

$$\int_a^c dl = dz$$

$$\int_c^b dl = dy$$

$$\int_b^a dl = dz$$

Similarly line integral of
 \vec{v} along y-axis & z axis is
 respectively

$$\oint_{y\text{-axis}} \vec{v} \cdot d\vec{l} = \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) dsy$$

$$\oint_{z\text{-axis}} \vec{v} \cdot d\vec{l} = \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) dsz$$

Main Equation Becomes

$$\oint \vec{v} \cdot d\vec{l} = \oint_{x\text{-axis}} \vec{v} \cdot d\vec{l} + \oint_{y\text{-axis}} \vec{v} \cdot d\vec{l} + \oint_{z\text{-axis}} \vec{v} \cdot d\vec{l}$$

$$= \oint_s \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) dsx + \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) dsy + \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) dsz$$

Answer

$$= \oint_S \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix} \cdot (ds_x \hat{i} + ds_y \hat{j} + ds_z \hat{k})$$

$$\oint \vec{v} \cdot d\vec{l} = \oint_S (\vec{\nabla} \times \vec{v}) \cdot d\vec{s}$$

$$\oint \vec{v} \cdot d\vec{l} = \oint_S \text{curl } \vec{v} \cdot d\vec{s}$$

Hence Stokes's theorem is proved.

Example No:01

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Stokes's Theorem

Q. No. (01)

Use Stokes Theorem

where

$$F = F(x, y, z) = xz\hat{i} + yz\hat{j} + xy\hat{k}$$

S is the part of the Sphere

$x^2 + y^2 + z^2 = 4$ that lies inside the cylinder $x^2 + y^2 = 1$ and above the xy-plane.

Sol:

$$x^2 + y^2 + z^2 = 4 \quad \text{and} \quad x^2 + y^2 = 1$$

$$\text{So } z^2 = 4 - 1$$

$$z = 3$$

$$z = \sqrt{3}$$

$$\text{So } \mathbf{r}(t) = \cos t \hat{i} + \sin t \hat{j} + \sqrt{3} \hat{k} \quad 0 \leq t \leq 2\pi$$

$$\mathbf{r}'(t) = -\sin t \hat{i} + \cos t \hat{j}$$

Also we have

$$f(\mathbf{r}(t)) = \sqrt{3} \cos t \hat{i} + \sqrt{3} \sin t \hat{j} + \cos t \sin t \hat{k}$$

Apply Stoke's Theorem

$$\iint_S \text{Curl } f \cdot d\mathbf{s} = \int_C f \cdot d\mathbf{r}$$

$$= \int_0^{2\pi} f(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$$

$$= \int_0^{2\pi} (-\sqrt{3} \cos t \sin t + \sqrt{3} \sin t \cos t) dt$$

$$= \sqrt{3} \int_0^{2\pi} 0 dt$$

$$= \underline{\underline{0 \text{ Ans}}}$$

Gauss's Divergence Theorem:

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Statement:

The surface integral of a vector point function around a closed surface is equal to volume integral of divergence of that vector point function over that surface enclosing a particular volume.

Mathematically form:

$$\oint_S \vec{v} \cdot d\vec{s} = \oint_V \text{div} \cdot \vec{v}$$

Let v is the vector point function which should be well-defined, continuous and differentiable.

Explanation:

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Let \vec{V} is the vector point function which can be written as

$$\vec{V} = V_x \hat{i} + V_y \hat{j} + V_z \hat{k}$$

As we know

$$\vec{\nabla} = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}$$

So Divergence of vector point function can be written as

$$\begin{aligned}\operatorname{div} \vec{V} &= \vec{\nabla} \cdot \vec{V} \\ &= \left(\frac{d}{dx} \hat{i} + \frac{d}{dy} \hat{j} + \frac{d}{dz} \hat{k} \right) \cdot (v_x \hat{i} + v_y \hat{j} + v_z \hat{k}) \\ &= \frac{dv_x}{dx} + \frac{dv_y}{dy} + \frac{dv_z}{dz}\end{aligned}$$

The volume integral of $\operatorname{div} \vec{V}$ is

$$\int_V \operatorname{div} \vec{V} dV = \int_V \left(\frac{dv_x}{dx} + \frac{dv_y}{dy} + \frac{dv_z}{dz} \right) dV$$

$$\int_V \vec{\nabla} \cdot \vec{V} dV = \iiint \left(\frac{dv_x}{dx} + \frac{dv_y}{dy} + \frac{dv_z}{dz} \right) dx dy dz$$

$$\int_V \vec{\nabla} \cdot \vec{V} dV = \iiint \frac{dv_x}{dx} dx dy dz + \iiint \frac{dv_y}{dy} dx dy dz + \iiint \frac{dv_z}{dz} dx dy dz$$

Since for single variable.

$$\frac{d}{dx} \rightarrow \frac{d}{d}$$

$$= \iiint \frac{dv_x}{dx} dx dy dz + \iiint \frac{dv_y}{dy} dx dy dz + \iiint \frac{dv_z}{dz} dx dy dz$$

$$= \int dv_x \iint dy dz + \int dv_y \iint dx dz + \int dv_z \iint dx dy$$

= (Derivative is cut the integration)

$$= v_x \iint dy dz + v_y \iint dx dz + v_z \iint dx dy$$

$$= \iint v_x dy dz + \iint v_y dx dz + \iint v_z dx dy$$

$$\int_V d\vec{r} \cdot \vec{\nabla} = \int_S v_x ds_x + \int_S v_y ds_y + \int_S v_z ds_z$$

$$= \int_S (v_x ds_x + v_y ds_y + v_z ds_z)$$

$$= \int_S (v_x \hat{i} + v_y \hat{j} + v_z \hat{k}) \cdot (ds_x \hat{i} + ds_y \hat{j} + ds_z \hat{k})$$

$$\int_V \operatorname{div} \vec{v} \cdot dV = \int_S \vec{v} \cdot d\vec{S}$$

Hence Gauss's divergence
theorem is proved.

Example No:01

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Divergence Theorem
If $\vec{A} = xz^3\hat{i} - 2x^2yz\hat{j} + 2yz^3\hat{k}$. Find divergence of A at point $(1, -1, 1)$.

Sol:

$$\vec{A} = xz^3\hat{i} - 2x^2yz\hat{j} + 2yz^3\hat{k}$$

$$\vec{\nabla} \cdot \vec{A} = ?$$

$$\vec{\nabla} \cdot \vec{A} = \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \cdot (xz^3\hat{i} - 2x^2yz\hat{j} + 2yz^3\hat{k})$$

$$= \frac{\partial}{\partial x} (xz^3) + \frac{\partial}{\partial y} (-2x^2yz) + \frac{\partial}{\partial z} (2yz^3)$$

$$\vec{\nabla} \cdot \vec{A} = z^3 - 2x^2z + 6yz^2$$

Value of $\vec{\nabla} \cdot \vec{A}$ at $(1, -1, 1)$

$$\begin{aligned}\vec{\nabla} \cdot \vec{A} &= (1)^3 - 2(1)^2 + 6(-1)(1)^2 \\ &= -9\end{aligned}$$



*Thanks For
Watching*