

# Uploading a video on YouTube

```
ove the robot to the reference point:
```

```
ot.MoveJ(target)
```

```
raw a hexagon around the reference target:
```

```
  i in range(7):
```

```
    ang = i*2*pi/6 #ang = 0, 60, 120, ..., 360
```

```
    # Calculate the new position around the refer
```

```
    x = xyz_ref[0] + R*cos(ang) # new X coordinat
```

```
    y = xyz_ref[1] + R*sin(ang) # new Y coordinat
```

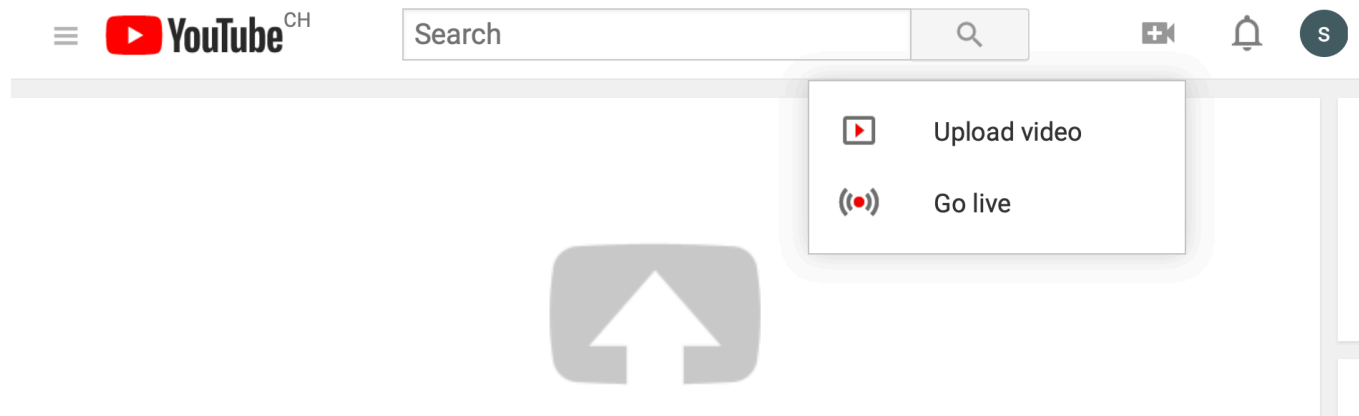
```
    z = xyz_ref[2]                # new Z coordinat
```

```
    target_pos.setPos([x,y,z])
```

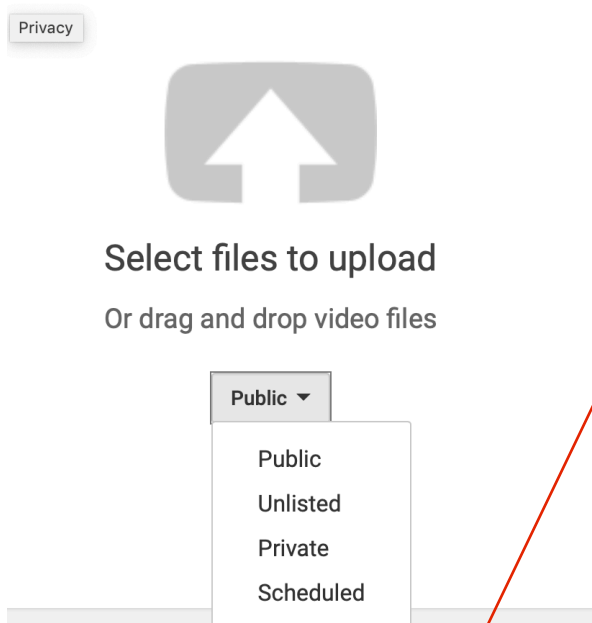
```
    # Move to the new target:
```

```
    robot.MoveL(target_pos)
```

1. After you created a video you can upload it on youtube as follows. Go to [youtube.com](https://youtube.com) and click on the upload icon on the top right.



2. Select the availability as **Public** or **Unlisted**, and then drag and drop your video. Your video will be processed and you will get the screen below.



3. On the left side, you will see the link to your video. Copy this.

4. You can put a title and tags for it.

5. You click on publish and it's done!

