### import all the necessary libraries:

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
import seaborn as sns
from sklearn.preprocessing import StandardScaler

from sklearn.linear_model import LogisticRegression
from sklearn.tree import DecisionTreeClassifier
from sklearn.ensemble import RandomForestClassifier
from sklearn.ensemble import GradientBoostingClassifier
from sklearn.neighbors import KNeighborsClassifier
from sklearn.neighbors import KNeighborsClassifier
from sklearn.metrics import accuracy_score
from sklearn.model_selection import GridSearchCV
```

## Pass the warnings:

```
In [2]: import warnings
warnings.filterwarnings('ignore')
```

# Read the dataset and store it into pandas dataframe:

```
In [3]: df = pd.read_csv('dft-road-casualty-statistics-accident-2021.csv', low_memory=False)
```

# **Exploratory Data Analysis:**

# Displayt the shape of the dataset:

```
In [4]: df.shape
Out[4]: (101087, 36)
```

# Display the data types of all columns in the data frame:

```
In [5]: df.dtypes
Out[5]: accident_index
                                                             object
         accident_year
                                                              int64
         accident_reference
                                                             object
         {\tt location\_easting\_osgr}
                                                            float64
         location_northing_osgr
                                                            float64
         longitude
                                                            float64
         latitude
                                                            float64
         police_force
                                                              int64
         {\tt accident\_severity}
                                                              int64
         number_of_vehicles
                                                              int64
         number\_of\_casualties
                                                              int64
                                                             object
         date
         day_of_week
                                                              int64
         time
                                                             object
         local_authority_district
                                                              int64
         local_authority_ons_district
                                                             object
         local_authority_highway
                                                             object
         {\tt first\_road\_class}
                                                              int64
         first_road_number
                                                              int64
         road_type
                                                              int64
         speed_limit
                                                              int64
         junction_detail
                                                              int64
         junction_control
                                                              int64
         second road class
                                                              int64
         second road number
                                                              int64
         pedestrian_crossing_human_control
                                                              int64
         pedestrian_crossing_physical_facilities
                                                              int64
         light conditions
                                                              int64
         weather_conditions
                                                              int64
         road_surface_conditions
                                                              int64
         special conditions at site
                                                              int64
         carriageway hazards
                                                              int64
         urban_or_rural_area
                                                              int64
         {\tt did\_police\_officer\_attend\_scene\_of\_accident}
                                                              int64
         trunk_road_flag
                                                              int64
         {\tt lsoa\_of\_accident\_location}
                                                             object
         dtype: object
```

#### Display the column names in the data trame:

#### display the general information about the dataset:

```
2
                                                     101087 non-null object
     accident reference
 3
     location easting osgr
                                                     101070 non-null float64
                                                     101070 non-null float64
101070 non-null float64
 4
     location_northing_osgr
 5
     longitude
                                                     101070 non-null float64
     latitude
                                                     101087 non-null int64
101087 non-null int64
 7
     police_force
 8
     accident_severity
 9
     number of vehicles
                                                     101087 non-null int64
                                                     101087 non-null int64
101087 non-null object
 10
     number_of_casualties
 11 date
 12 day of week
                                                     101087 non-null int64
                                                     101087 non-null object
101087 non-null int64
 13
     time
14
     local_authority_district
15
                                                     101087 non-null
     local_authority_ons_district
                                                                       object
 16
     local authority highway
                                                     101087 non-null
                                                                       obiect
 17 first_road_class
                                                     101087 non-null int64
                                                     101087 non-null int64
101087 non-null int64
 18 first_road_number
 19 road_type
     speed limit
                                                     101087 non-null int64
                                                     101087 non-null int64
 21 junction_detail
                                                     101087 non-null
 22
     junction_control
                                                                       int64
 23
     second road class
                                                     101087 non-null int64
                                                     101087 non-null int64
101087 non-null int64
 24
     second road number
 25
     pedestrian crossing human control
 26 pedestrian_crossing_physical_facilities
                                                     101087 non-null int64
 27
     light conditions
                                                     101087 non-null
                                                                       int64
 28 weather_conditions
                                                     101087 non-null int64
 29 road surface conditions
                                                     101087 non-null int64
 30
     special conditions at site
                                                     101087 non-null
                                                     101087 non-null int64
 31 carriageway hazards
 32 urban_or_rural_area
                                                     101087 non-null int64
 33 did_police_officer_attend_scene_of_accident 101087 non-null
                                                                       int64
                                                     101087 non-null int64
 34 trunk road flag
 35 lsoa of accident location
                                                     101087 non-null object
dtypes: float64(4), int64(25), object(7)
```

# Print the first 10 rows of the dataset:

memory usage: 27.8+ MB

In [8]: df.head(10)

| Out[8]:          | accident_index    | accident_year | accident_reference | location_easting_osgr | location_northing_osgr | longitude | latitude  | police_force | accide |
|------------------|-------------------|---------------|--------------------|-----------------------|------------------------|-----------|-----------|--------------|--------|
| 0<br>1<br>2<br>3 | 2021010287148     | 2021          | 010287148          | 521508.0              | 193079.0               | -0.246102 | 51.623425 | 1            |        |
|                  | 2021010287149     | 2021          | 010287149          | 535379.0              | 180783.0               | -0.050574 | 51.509767 | 1            |        |
|                  | 2021010287151     | 2021          | 010287151          | 529701.0              | 170398.0               | -0.136152 | 51.417769 | 1            |        |
|                  | 2021010287155     | 2021          | 010287155          | 525312.0              | 178385.0               | -0.196411 | 51.490536 | 1            |        |
| 4                | 2021010287157     | 2021          | 010287157          | 512144.0              | 171526.0               | -0.388169 | 51.431649 | 1            |        |
| 5<br>6<br>7<br>8 | 2021010287163     | 2021          | 010287163          | 536569.0              | 183334.0               | -0.032448 | 51.532404 | 1            |        |
|                  | 2021010287167     | 2021          | 010287167          | 531818.0              | 188393.0               | -0.099009 | 51.578996 | 1            |        |
|                  | 2021010287168     | 2021          | 010287168          | 541068.0              | 190017.0               | 0.035049  | 51.591350 | 1            |        |
|                  | 2021010287185     | 2021          | 010287185          | 530553.0              | 162637.0               | -0.126757 | 51.347826 | 1            |        |
| 9                | 2021010287189     | 2021          | 010287189          | 543401.0              | 186128.0               | 0.067118  | 51.555817 | 1            |        |
| 10               | ) rows × 36 colum | nns           |                    |                       |                        |           |           |              |        |

Convert date into pandas datetime object:

```
In [9]: df['date'] = pd.to_datetime(df['date'],)
```

Extract day, month and week some useful features from 'date' column:

```
In [10]: df['day'] = df['date'].dt.day
    df['month'] = df['date'].dt.month
    df['week'] = df['date'].dt.isocalendar().week
```

accident\_severity is out target variable, display the unique values in accident\_severity column:

1 = Satal, 2= Serious and 3 = Slight

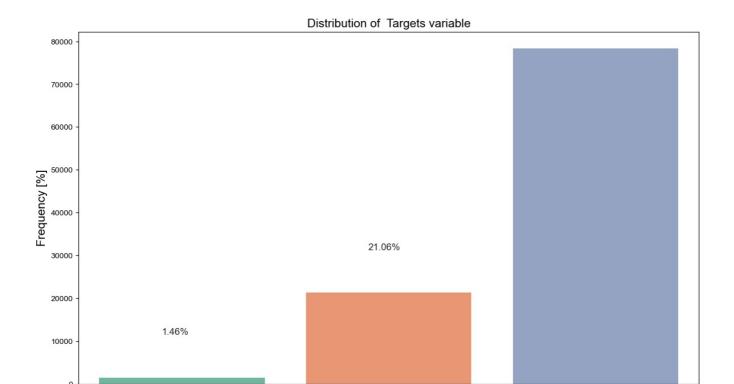
```
In [11]: df['accident_severity'].unique()
Out[11]: array([3, 2, 1], dtype=int64)
```

display the value count for the accident severity (target) variable:

# **Univariate Analysis:**

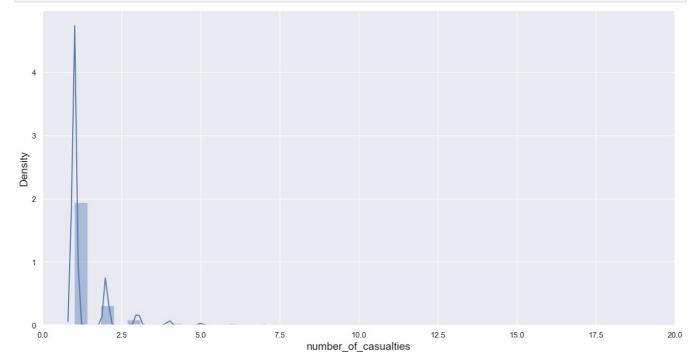
Distribution of original data by target (accident severity):

```
In [13]:
    ax = sns.countplot(x = df.accident_severity ,palette="Set2")
    sns.set(font_scale=1)
    ax.set_xlabel(' ')
    ax.set_ylabel(' ')
    fig = plt.gcf()
    fig.set_size_inches(14,8)
    for p in ax.patches:
        ax.annotate('{:.2f}%'.format(100*p.get_height()/len(df.accident_severity)), (p.get_x()+ 0.3, p.get_height())
    plt.title('Distribution of Targets variable',fontsize = 15)
    plt.xlabel('Accident Severity',fontsize = 15)
    plt.ylabel('Frequency [%]',fontsize = 15)
    plt.show()
```



Accident Severity

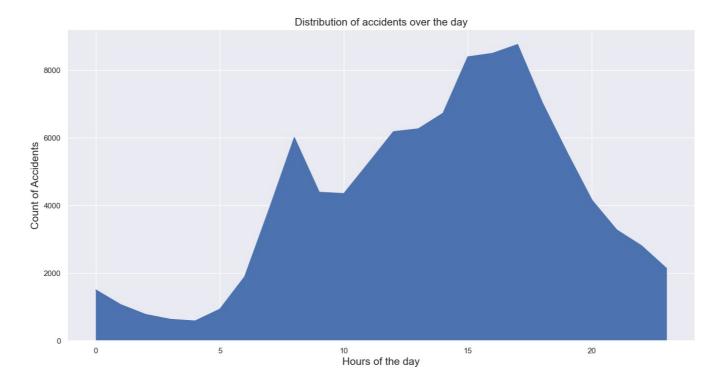
#### Number of casualties distribution



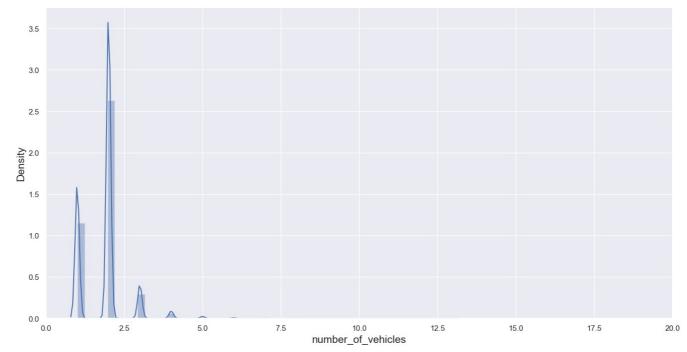
Min: 1 Max: 22 Median: 1.0

# Distribution of accidents over the day

```
In [15]: time_x = pd.to_datetime(df['time'], format='%H:%M').dt.hour
   plt.figure(figsize=(16,8))
   ax = time_x.value_counts().sort_index().plot(kind = 'area')
   ax.set_xlabel('Hours of the day', fontsize = 15)
   ax.set_ylabel('Count of Accidents', fontsize = 15)
   ax.set_title('Distribution of accidents over the day', fontsize = 15)
   plt.show()
```



# Number of vehicles distribution



Min: 1 Max: 13 Median: 2.0

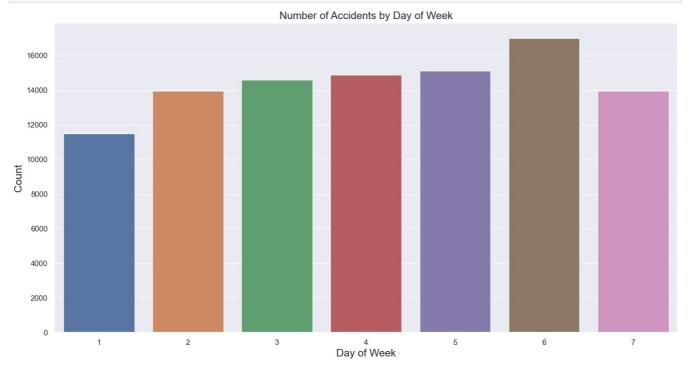
# A boxplot to show Distribution of Speed Limit:

```
import seaborn as sns
plt.figure(figsize = (16, 8))
sns.boxplot(x=df["speed_limit"])
plt.title("Distribution of Speed Limit",fontsize = 15)
plt.xlabel("Speed Limit",fontsize = 15)
plt.show()
```



# Bar chart of "day\_of\_week"

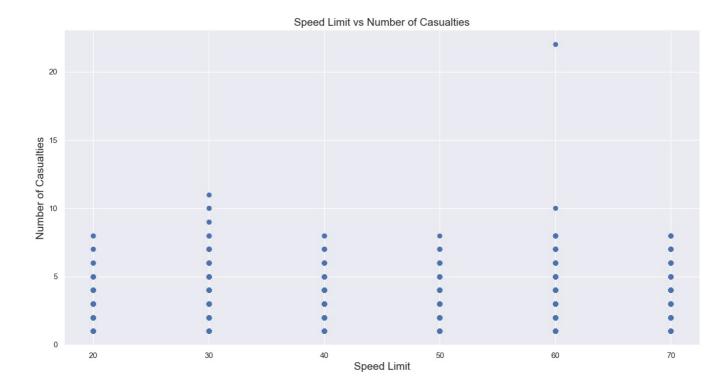
```
In [18]: plt.figure(figsize = (16, 8))
    sns.countplot(x=df["day_of_week"])
    plt.title("Number of Accidents by Day of Week",fontsize = 15)
    plt.xlabel("Day of Week",fontsize = 15)
    plt.ylabel("Count",fontsize = 15)
    plt.show()
```



# Multivariate Analysis:

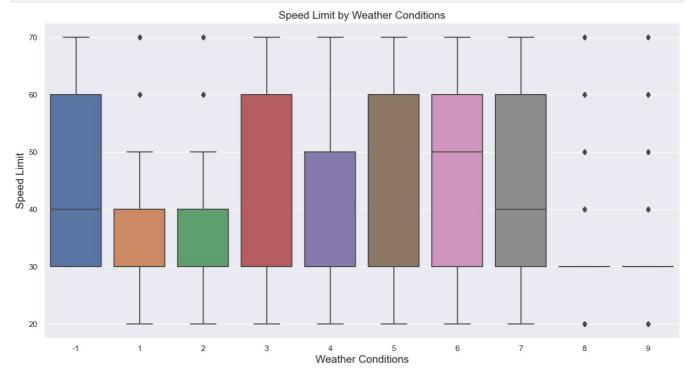
Scatter plot of "speed\_limit" vs "number\_of\_casualties"

```
In [19]: plt.figure(figsize = (16, 8))
    plt.scatter(x=df["speed_limit"], y=df["number_of_casualties"])
    plt.title("Speed Limit vs Number of Casualties",fontsize = 15)
    plt.xlabel("Speed Limit",fontsize = 15)
    plt.ylabel("Number of Casualties",fontsize = 15)
    plt.show()
```



# Box plot of "speed\_limit" by "weather\_conditions"

```
In [20]: plt.figure(figsize = (16, 8))
    sns.boxplot(x=df["weather_conditions"], y=df["speed_limit"])
    plt.title("Speed Limit by Weather Conditions",fontsize = 15)
    plt.xlabel("Weather Conditions",fontsize = 15)
    plt.ylabel("Speed Limit",fontsize = 15)
    plt.show()
```



# Drop the unnecessary columns:

```
In [21]: df.drop(['accident_index', 'accident_reference', 'local_authority_ons_district', 'local_authority_highway','tim
```

# Check are there any missing values in the data frame:

```
In [22]: df.isnull().any()
```

```
Out[22]: location_easting_osgr
                                                             True
          location_northing_osgr
                                                             True
          longitude
                                                             True
          latitude
                                                             True
          police force
                                                            False
          accident_severity
                                                            False
          number of vehicles
                                                            False
          {\tt number\_of\_casualties}
                                                            False
          day_of_week
                                                            False
          local_authority_district
                                                            False
          first road class
                                                            False
          first_road_number
                                                            False
          road_type
                                                            False
          speed_limit
                                                            False
          junction detail
                                                            False
          junction_control
                                                            False
          second road class
                                                            False
          second road number
                                                            False
          pedestrian_crossing_human_control
                                                            False
          pedestrian_crossing_physical_facilities
                                                            False
          light conditions
                                                            False
          weather conditions
                                                            False
          {\tt road\_surface\_conditions}
                                                            False
          special conditions at site
                                                            False
          carriageway hazards
                                                            False
          urban_or_rural_area
                                                            False
          did_police_officer_attend_scene_of_accident
                                                            False
                                                            False
          trunk_road_flag
                                                            False
          day
          month
                                                            False
          week
                                                            False
          dtype: bool
```

Count the number of missing values in each column of the data frame:

```
In [23]: df.isnull().sum()
         location easting osgr
                                                          17
         location northing osgr
                                                          17
                                                          17
         longitude
                                                          17
         latitude
         police force
                                                           0
         accident severity
                                                           0
         number_of_vehicles
                                                           0
         number_of_casualties
         day of week
                                                           0
         local authority district
         first_road_class
                                                           0
         first road number
                                                           0
         road type
         speed limit
                                                           0
         junction detail
                                                           0
         junction control
         second road class
         second road number
                                                           0
         pedestrian_crossing_human_control
         pedestrian_crossing_physical_facilities
         light conditions
         weather_conditions
                                                           0
         road surface conditions
         special conditions_at_site
                                                           0
         carriageway_hazards
         urban_or_rural_area
                                                           0
         did_police_officer_attend_scene_of_accident
                                                           0
         trunk road flag
         day
                                                           0
         month
                                                           0
         week
                                                           0
         dtype: int64
```

Fill the missing values in location\_easting\_osgr, location\_northing\_osgr, longitude and latitude columns:

```
In [24]: df['location_easting_osgr'] = df['location_easting_osgr'].fillna(df['location_easting_osgr'].mean())
    df['location_northing_osgr'] = df['location_northing_osgr'].fillna(df['location_northing_osgr'].mean())
    df['longitude'] = df['longitude'].fillna(df['longitude'].mode()[0])
    df['latitude'] = df['latitude'].fillna(df['latitude'].mode()[0])
```

Convert (1 = Satal, 2= Serious and 3 = Slight) to binary values (0 = Slight, 1 = Serious):

Now we have binary classification problem

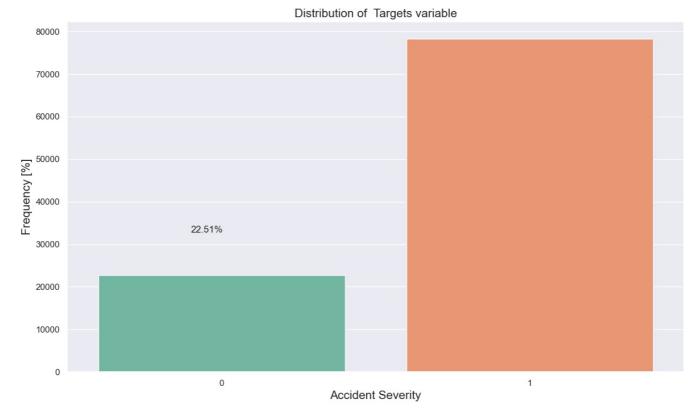
```
In [25]: df['accident_severity'] = df['accident_severity'].replace([2 , 1], 0)
    df['accident_severity'] = df['accident_severity'].replace(3, 1)
```

# Value counts of the accident severity again:

# Distribution of original data by targets

```
In [27]: ax = sns.countplot(x = df.accident_severity ,palette="Set2")
sns.set(font_scale=1)
ax.set_xlabel(' ')
ax.set_ylabel(' ')
fig = plt.gcf()
fig.set_size_inches(14,8)
for p in ax.patches:
    ax.annotate('{:.2f}%'.format(100*p.get_height()/len(df.accident_severity)), (p.get_x()+ 0.3, p.get_height())

plt.title('Distribution of Targets variable',fontsize = 15)
plt.xlabel('Accident Severity',fontsize = 15)
plt.ylabel('Frequency [%]',fontsize = 15)
plt.show()
```



#### Store features into feature matrix X and target into vector y:

```
In [28]: # Features
X = df.loc[:,df.columns != 'accident_severity']
#Target
y = df['accident_severity']
```

# Feature Selection using SelectKbest method:

import SelectKBest and f\_classif from sklear for feature seletion:

```
In [29]: from sklearn.feature_selection import SelectKBest
    from sklearn.feature_selection import f_classif
```

## Initialized SelectKBest with f\_classif test and k= 15

```
In [30]: test = SelectKBest(score_func=f_classif, k=15)
```

#### Fit the SelectKBest model:

```
In [31]: fit = test.fit(X, y)
```

#### Transform the features:

```
In [32]: filtered_features= fit.transform(X)
```

# Show the supporting variables given by SelectKBest (True/false):

```
In [33]: test.get_support()
Out[33]: array([ True,  True,  True,  True,  True,  False,  False)
```

#### Display the scores of the features assigned by the SelectkBest:

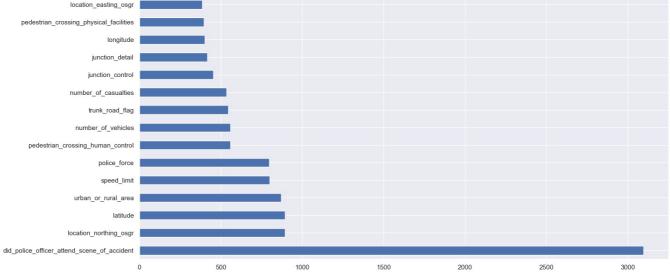
# Find the Feature importance for each feature:

```
In [35]: feat_importances = pd.Series(test.scores_, index=X.columns)
```

#### Display the feature importance using a bar chart

```
In [36]: feat_importances.nlargest(15).plot(kind='barh',figsize = (16,8))
plt.show()

location_easting_osgr
pedestrian crossing physical facilities
```



# Getting the column names:

# Selecting the relevant columns given by SelectKbest only:

```
In [38]: X_Selectkbest = X[column_names]
    X_Selectkbest.head()
```

```
latitude police_force number_of_vehicles number_of_casualties speed_limit j
  location easting osgr location northing osgr longitude
               521508.0
                                      193079.0 -0.246102 51.623425
               535379.0
                                      180783.0 -0.050574 51.509767
                                                                                                                                     30
2
               529701.0
                                      170398.0 -0.136152 51.417769
                                                                               1
                                                                                                   2
                                                                                                                                    30
                                                                                                                         4
3
               525312.0
                                      178385.0 -0.196411 51.490536
                                                                                                                                    30
               512144.0
                                      171526.0 -0.388169 51.431649
                                                                               1
                                                                                                                                    20
```

Divide the data set into training and Testing sets (training set 80%, Testing set 20%):

```
In [39]: from sklearn.model_selection import train_test_split
X_train, X_test, y_train, y_test = train_test_split(X_Selectkbest, y, test_size=0.20, random_state=0)
```

Use StandardScaler to scale the values of the dataset:

```
In [40]: SC = StandardScaler()
   X_train_scaled = SC.fit_transform(X_train)
   X_test_scaled = SC.fit_transform(X_test)
```

# **Experimental Design:**

#### Logistic Regression Model

```
In [41]: #Initialize the LogisticRegression Model
    Lg_classifier = LogisticRegression()
# Train the model on training set
    Lg_classifier.fit(X_train_scaled, y_train)
```

Out[41]: LogisticRegression()

## Make prediction and evaluation on seen data:

```
In [42]: # Make prediction on seen data
y_pred = Lg_classifier.predict(X_train_scaled)
#he Accuracy score for Logistic Regresson on seen data :
Lg_score_seen = accuracy_score(y_train, y_pred)
print('The Accuracy score for Logistic Regresson on seen data : ', Lg_score_seen)
```

The Accuracy score for Logistic Regresson on seen data: 0.774870469524787

#### Make prediction and evaluation on unseen data:

```
In [43]: # Make prediction on unseen data
y_pred = Lg_classifier.predict(X_test_scaled)
#he Accuracy score for Logistic Regresson on unseen data :
Lg_score_unseen = accuracy_score(y_test, y_pred)
print('The Accuracy score for Logistic Regresson on unseen data : ', Lg_score_unseen)
```

The Accuracy score for Logistic Regresson on unseen data: 0.7803442477000693

#### **Decision Tree Classifier Model**

```
In [44]: #Initialize the DecisionTreeClassifier Model
    Dt_classifier = DecisionTreeClassifier()
    # Train the model on training set
    Dt_classifier.fit(X_train_scaled, y_train)
Out[44]: DecisionTreeClassifier()
```

# Make prediction and evaluation on seen data:

```
In [45]: # Make prediction on seen data
y_pred = Dt_classifier.predict(X_train_scaled)
#he Accuracy score for decision tree on seen data :
Dt_score_seen = accuracy_score(y_train, y_pred)
print('The Accuracy score for decision tree on seen data : ', Dt_score_seen)
```

The Accuracy score for decision tree on seen data: 0.9999381716108768

#### Make prediction and evaluation on unseen data:

```
In [46]: # Make prediction on unseen data
```

```
y_pred = Dt_classifier.predict(X_test_scaled)
#he Accuracy score for decision tree on unseen data :
Dt_score_unseen = accuracy_score(y_test, y_pred)
print('The Accuracy score for decision tree on unseen data : ', Dt_score_unseen)
```

The Accuracy score for decision tree on unseen data: 0.6771688594321892

#### RandomForest Classifier Model

```
In [47]: #Initialize the RandomForestClassifier Model
    Rf_Classifier = RandomForestClassifier(n_estimators = 100, )
    # Train the model on training set
    Rf_Classifier.fit(X_train_scaled, y_train)
Out[47]: RandomForestClassifier()
```

# Make prediction and evaluation on seen data:

```
In [48]: # Make prediction on seen data
y_pred = Rf_Classifier.predict(X_train_scaled)
#he Accuracy score for Random Forest on seen data :
Rf_score_seen = accuracy_score(y_train, y_pred)
print('The Accuracy score for Random Forest on seen data : ', Rf_score_seen)
```

The Accuracy score for Random Forest on seen data: 0.9999381716108768

#### Make prediction and evaluation on unseen data:

```
In [49]: # Make prediction on unseen data
y_pred = Rf_Classifier.predict(X_test_scaled)
#he Accuracy score for Random Forest on unseen data :
Rf_score_unseen = accuracy_score(y_test, y_pred)
print('The Accuracy score for Random Forest on unseen data : ', Rf_score_unseen)
```

The Accuracy score for Random Forest on unseen data: 0.7588782273221881

### **Gradient Boosting Classifier Model**

```
In [50]: #Initialize the GradientBoostingClassifier Model
   Gb_Classifier = GradientBoostingClassifier()
   # Train the model on training set
   Gb_Classifier.fit(X_train_scaled, y_train)
```

Out[50]: GradientBoostingClassifier()

#### Make prediction and evaluation on seen data:

```
In [51]: # Make prediction on seen data
y_pred = Gb_Classifier.predict(X_train_scaled)
#he Accuracy score for Gradient Boosting on seen data :
Gb_score_seen = accuracy_score(y_train, y_pred)
print('The Accuracy score for Gradient Boosting on seen data : ', Gb_score_seen)
```

The Accuracy score for Gradient Boosting on seen data : 0.7768489779767278

#### Make prediction and evaluation on unseen data:

```
In [52]: # Make prediction on unseen data
y_pred = Gb_Classifier.predict(X_test_scaled)
#he Accuracy score for Gradient Boosting on unseen data :
Gb_score_unseen = accuracy_score(y_test, y_pred)
print('The Accuracy score for Gradient Boosting on unseen data : ', Gb_score_unseen)
```

The Accuracy score for Gradient Boosting on unseen data: 0.781679691364131

## XGB Classifier Model

```
In [53]: #Initialize the XGBClassifier Model
XGB_Classifier = XGBClassifier()
# Train the model on training set
XGB_Classifier.fit(X_train_scaled, y_train)
```

```
Out[53]: XGBClassifier(base_score=None, booster=None, callbacks=None, colsample_bylevel=None, colsample_bynode=None, colsample_bytree=None, early_stopping_rounds=None, enable_categorical=False, eval_metric=None, feature_types=None, gamma=None, gpu_id=None, grow_policy=None, importance_type=None, interaction_constraints=None, learning_rate=None, max_bin=None, max_cat_threshold=None, max_depth=None, max_leaves=None, min_child_weight=None, missing=nan, monotone_constraints=None, n_estimators=100, n_jobs=None, num_parallel_tree=None, predictor=None, random state=None, ...)
```

### Make prediction and evaluation on seen data:

```
In [54]: # Make prediction on seen data
y_pred = XGB_Classifier.predict(X_train_scaled)
#he Accuracy score for XGB_Classifier on seen data :
XGB_score_seen = accuracy_score(y_train, y_pred)
print('The Accuracy score for XGB_Classifier on seen data : ', XGB_score_seen)
```

The Accuracy score for XGB Classifier on seen data: 0.7921947841570935

### Make prediction and evaluation on unseen data:

```
In [55]: # Make prediction on unseen data
y_pred = XGB_Classifier.predict(X_test_scaled)
#he Accuracy score for XGB_Classifier on unseen data :
XGB_score_unseen = accuracy_score(y_test, y_pred)
print('The Accuracy score for XGB_Classifier on unseen data : ', XGB_score_unseen)
```

The Accuracy score for XGB\_Classifier on unseen data : 0.7806410129587497

#### **KNeighbors Classifier Model**

```
In [56]: #Initialize the KNeighborsClassifier Model
   KNN_Classifier = KNeighborsClassifier()
   # Train the model on KNeighborsClassifier set
   KNN_Classifier.fit(X_train_scaled, y_train)
```

Out[56]: KNeighborsClassifier()

#### Make prediction and evaluation on seen data:

```
In [57]: # Make prediction on seen data
y_pred = KNN_Classifier.predict(X_train_scaled)
#he Accuracy score for KNN classifier on seen data :
KNN_score_seen = accuracy_score(y_train, y_pred)
print('The Accuracy score for KNN_Classifier on seen data : ', KNN_score_seen)
```

The Accuracy score for KNN Classifier on seen data: 0.8085793072747283

#### Make prediction and evaluation on unseen data:

```
In [58]: # Make prediction on unseen data
y_pred = KNN_Classifier.predict(X_test_scaled)
#he Accuracy score for KNN classifier on unseen data :
KNN_score_unseen = accuracy_score(y_test, y_pred)
print('The Accuracy score for KNN_Classifier on unseen data : ', KNN_score_unseen)
```

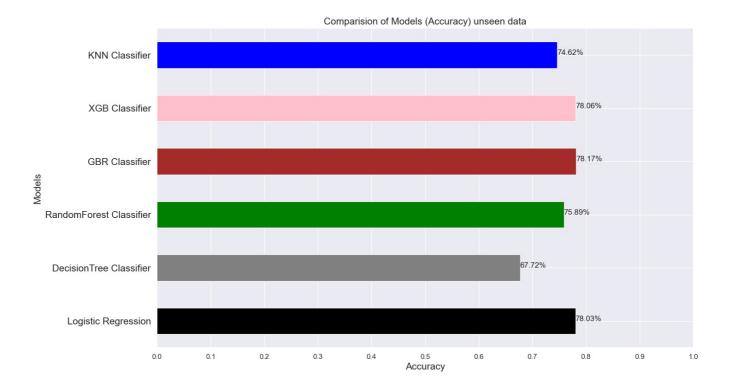
The Accuracy score for KNN Classifier on unseen data: 0.7462162429518251

#### Create two lists of model name and respective Accuracies:

```
In [59]: scores = pd.Series([Lg_score_unseen, Dt_score_unseen, Rf_score_unseen, Gb_score_unseen, XGB_score_unseen, KNN_s
Model_Names = ['Logistic Regression', 'DecisionTree Classifier', 'RandomForest Classifier', 'GBR Classifier', 'XG
```

# Comparision of Models in terms evaluation metric (accuracy Score):

```
In [60]: ax = scores.plot(kind = 'barh',figsize=(15,9),color=['black','gray','green','brown','pink','blue','red'])
    ax.set_title('Comparision of Models (Accuracy) unseen data',fontsize=15)
    ax.set_xticks([0.0,0.1,0.2,0.3,0.4,0.5,0.6,0.7,0.8,0.9,1.0])
    ax.set_yticklabels(Model_Names,fontsize=15,)
    ax.set_ylabel("Models",fontsize=15)
    ax.set_xlabel("Accuracy",fontsize=15)
    [ax.text(v, i, '{:.2f}%'.format(100*v)) for i, v in enumerate(scores)];
    plt.show()
```



# Evaluation and further modelling improvements

Hyper parameter Tuning for Highest performing Model (Logistic Regression)

```
In [61]: # Create logistic regression object
lr = LogisticRegression()

# Set hyperparameters to tune
hyperparameters = {
    'penalty': ['ll', 'l2'],
    'C': [0.01, 0.1, 1, 10, 100],
    'solver': ['liblinear']
}
```

# Create GridSearchCV object and fit it on training data:

#### Print best hyperparameters and best score

```
In [63]: # Print best hyperparameters and best score
    print('Best parameters:', clf.best_params_)
    print('Best score:', clf.best_score_)

Best parameters: {'C': 10, 'penalty': 'l2', 'solver': 'liblinear'}
    Best score: 0.7748951929440493
In []:
```

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