

ELECTRICAL ENGINEER

AHMAD DIDIK SETIYADI

GET IN CONTACT

Mobile : +6282227833820 Github : github.com/ahmaddidiks Email : didik@student.undip.ac.id LinkedIn : linkedin.com/in/ahmaddidiks

Blog : adidiks.com Address : Boyolali, Indonesia

PERSONAL PROFILE

I am an Electrical Engineer from Diponegoro University with hands-on experience in robotics especially humanoid robot. I mastered in invers kinematics and trajectory planning of manipulator robot, control system, AVR and ESP32 microcontroller.

I really love coding especially in Python and C++.

AREAS OF EXPERTISE

- Robotics especially in humanoid robot kinematics
- Inverse kinematics and trajectory planning of manipulator robot
- Robot Operating System (ROS)
- C, C++, Matlab and Python experience
- Printed circuit board (PCB) design with Eagle AutoCAD
- Working knowledge of Modern Control such as Fuzzy control, Neural Network, and Machine Learning

OTHER SKILLS

- The ability to handle and lead project especially in robotics
- · Excellent problem solver
- The ability to analyze complex technical problem

WORK EXPERIENCE

PART TIME

CV. REDESMA TECHNOLOGIES | 2021

• Team Support of Injector Tester PLTD Telukbetung
In this project, my team and I repair electrical wiring and image processing
performance that analyze the performance of injector spray with open CV then
generated it into a PDF report.

· IoT Wind Turbine PJB Rembang

In this project, I built a controller of an IoT system of wind turbine with Adafruit IO and the data sensors will be saved into micro SD memory.

Blood Shaker Poltekkes Semarang

In this project, I built a controller of a Blood Shaker by input from users. The motor is controlled by a PID controller.

Automatic Oil Leveling PLTD Telukbetung

In this project, I built a prototype that can measure Oil levels in a tank automatically using a lidar sensor and raspberry pi. In this prototype, the user can operate the prototype with a GUI app built with python.

INTERNSHIP

PT. Berdikari Makmur Jaya | 2020

 Built medical assistant robot called 'Dipo-Mecaro (Medical Assistant Robot)'

In this project, I contributed to calculating the transfer function of the PG45 motor with Matlab System Identifier. with the calculated transfer function I made a PG45 motor PID controller with Matlab PID tuner then I implemented the results of the PID parameters to the motor control program on Arduino.

EDUCATION HISTORY

DIPONEGORO UNIVERSITY

Bachelor of Electrical Engineering, 2021

 Final Project: 4 DOF Manipulator Robot with inverse kinematics and trajectory planning using Robot Operating System (ROS) | 2021

In this final project, I built a manipulator robot that can pick and place a test tube which is used to help medical personnel in dealing with COVID19 outbreak

• Grenovator ASTRA AGEN Student Comunity | 2020

In this community, I contributed to two projects. In the first project, I and the team implemented 400 WP solar panel energy to light up a bridge in Muncar, Temanggung. In the second I and the selected team implemented solar energy to light up the entire space of Pranaraksa Astra in Cikunir

- 3rd Runner Up Winner Indonesian Humanoid Soccer Robot Competition Region 1 | 2020
 In this competition, we got 4th place in the technical challenge with a new robot algorithm that we've been building for a year
- Humanoid Soccer Robot Team Lead | 2020

In this team, I was the leader of building a new robot and the algorithm of the robot. We moved to ROS (Robot Operating System) for the robot environment and used YOLO for our image processing

• 4th Runner Up Winner National Paper Competition in UNNES | 2019

In this competition, we created a prototype to detect bacteria on human fingers by image processing. from the results of image processing, we can see that our hands are clean or not from bacteria

- 3rd Runner Up Winner Indonesian Humanoid Soccer Robot Competition Region 3 | 2019

 This is the first time our team has won in this competition and I contributed to making walking gait and other movements dataset
- Motion Programmer Humanoid Soccer Robot Team | 2019
 In this team, I contributed to making walking gait and other movements dataset using inverse kinematics and motion planning
- Bronze Medal Thailand Invertor's Day | 2019

In this competition, we made a prototype for cleaning up wastewater of batik industries in Pekalongan using an electrolysis mechanism

- Internal Champion Team of Forum Study Teknik (FST) | 2019
 In this part, I and the team Encouraged and guided junior members to have a competitive mindset
- Contingent of PIMNAS (Pekan Ilmiah Mahasiswa Nasional) 31 Undip | 2018

In this competition, I and the team made a prototype of a tool for increasing the motorcycle's security system. We made this prototype because of the problem at that time on campus that there were a lot of motorcycle thefts

- 2nd Winner of Soccer Robot Competition in UGM | 2018
- In this competition, I and the team made wheeled soccer robots that can be controlled by a joystick with BlueTooth communication
- Junior Research Division Member of Forum Study Teknik (FST) | 2018

In this part, I learned a lot about research and research-based organizations, I and the other member got the assignment to make a research event at the engineering faculty