# LAB 1: Time-Domain Analysis of Discrete-Time Systems -Part 1

# Objective

In lab 1, you will learn about the concepts of discrete-time signals. You will apply a different transformation to discrete signals, plot the signals and learn how to find the energy and power of a signal. Also, you will find the equation of a discrete system and recursively compute zero-input, zero-state and total system responses.

## Preparation

- Read chapter 3 of the textbook (*Linear Signals and Systems*) by B.P. Lathi.
- For this lab, you may use *anonymous* functions in Matlab to write simple functions. For example, the function *Cube* returns the cube of the input x.

Cube = 
$$@(x)(x^3)$$
;  
 $x = 0: 0.05: 10;$   
 $Plot(x, Cube(x))$ 

• To plot discrete signals, use *stem* command from MATLAB.

# Lab Assignment

### A. Signal transformation

- 1) In this assignment, you will perform shifting and time reversal transformations on a discrete time signal. Use MATLAB to plot the following discrete time signals.
  - I.  $\delta[n-3]$
  - II. u[n+1]
  - III.  $x[n] = \cos\left(\frac{\pi n}{5}\right)u[n]$
  - IV.  $x_1[n] = x[n-3]$

$$V. \qquad x_2[n] = x[-n]$$

Explain what transformations are performed in  $x_1[n]$ ,  $x_2[n]$ .

- 2) In this part, you will study the effects of scaling on a discrete time signal. Plot the signals in the interval [-10,70] and explain the effect of transformation on  $y_1[n]$  and  $y_2[n]$  given below.
  - 1.  $y[n] = 5e^{-\frac{n}{8}}(u[n] u[n-10])$
  - II.  $y_1[n] = y[3n]$
  - III.  $y_2[n] = y[\frac{n}{3}]$
- 3) In this assignment, you will investigate that sampling of a continuous signal and applying a linear transformation after will not always generate the same result as if first applying the transformation and then executing sampling. For this purpose, consider the continuous signal z(t)

$$z(t) = 5e^{-\frac{t}{8}}(u(t) - u(t-10)), t = -10:0.1:70.$$

- I. First, find  $y_3(t) = z(\frac{t}{3})$  and then plot the discrete signal  $y_3[n]$ .
- II. Explain why  $y_2[n]$  obtained in part 2(III) above and  $y_3[n]$  obtained in here are not the same.

Note: When defining signal z(t) make sure to use continuous u(t).

#### B. Recursive Solution of difference equation

In this assignment, you will write a system equation for a real-world problem and understand the meanings of zero-input, zero-state, and total system responses.

1) A person makes a deposit (the input) in a bank regularly every month from January. The bank pays 2% interest on the account balance. Find the equation relating the output y[n] (the balance) to the input x[n] (the deposit). Consider the account balance at the beginning of the year is \$2000. (Use example 3.6 from the text book for help.)

- 2) If no deposit is made in the new year, what will be the output y[n]. Use MATLAB to recursively compute the zero input response y[n] and plot it.
- 3) If the person deposits x[n] = 100n dollars each month, and n is the month number (for example, for February n=2), what will be the total response y[n]. Use MATLAB to recursively compute and plot y[n].

#### C. Design a filter: N-point maximum filter

In this assignment, you will design a causal N-point maximum filter. This filter finds the maximum of the signal among N points  $\{x[n], x[n-1], ..., x[n-(N-1)]\}$  and assigns it to the output y[n].

- 1) Write a MATLAB function that performs maximum filtering on an input vector x with length M. The inputs of the maximum function are vector x and scalar N. To create a length-M output vector y, initially pad the input vector with N-1 zeros. i.e. the output y[n] would have the same length as input x[n]. You can use MATLAB command MAX for this assignment.
- 2) Apply maximum filter on the input x[n] defined as below, where the length of the input is 45. Separately plot the results for N=4, N=8 and N=12.

$$x[n] = \cos\left(\frac{\pi n}{5}\right) + \delta[n - 20] - \delta[n - 35]$$

3) Explain how the response changes for different values of N.

#### D. Energy and power of a discrete signal

- 1) Write a MATLAB function that receives a finite length vector x[n] and returns the energy and power of the vector.
- 2) Calculate the energy and power of the signal x[n] illustrated below (Fig.P3.1-1 (c) of the text book).

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